CS 4613 HW 3 Fall 2023 E. K. Wong

Total # questions = 4. Total # points = 60. Figures 1 to 3 are on pages 2 and 3.

- **1.** [10 points] (a) What are the *time complexity* and *space complexity* if the regular Depth-First Search algorithm in Chapter 3 is used to solve constrain satisfaction problems? (b) What are the *time complexity* and *space complexity* if the Backtracking-Search Algorithm in Figure 2 below is used to solve constrain satisfaction problems? Define the parameters you used for both parts (a) and (b).
- **2.** [15 points] In the map coloring problem in Figure 1 below, suppose the people in region NT do not like the *red* and *green* colors. The domain for NT therefore contains only the *blue* color, and the domains for all other regions contain the colors *red*, *green* and *blue*. Apply the Backtracking-Search algorithm in Figure 2 below to solve this problem and draw the search tree produced. When applying the algorithm, use the *minimum remaining value* and *degree heuristics* for selecting variables in the SELECT-UNASSIGNED-VARIABLE function. For the ORDER-DOMAIN-VALUES function, simply order the values in the order *red*, *green* and *blue* instead of using heuristics. You can skip the INFERENCE function when applying the Backtracking-Search algorithm.
- **3.** [15 points] Given the specifications of the cryptarithmetic problem below, where x1 and x2 are auxiliary variables representing the carry overs. Assuming the Backtracking-Search algorithm in Figure 2 is used to solve this problem, use the *minimum remaining values* and *degree heuristics* to select the variable to work on at each level of the search tree. You can skip the INFERENCE function in the Backtracking-Search algorithm. Let the root node be at level 0. List the variables selected at levels 1 to *n* of the search tree, where *n* is the number of variables in this problem. Show all work to get full credits. (You do not have to draw a search tree and find the solution to this problem. Just determine the variable selected at each level using the two heuristics.)

## Variables: x2x1 ONE + ONE TWO

## Domains:

- O: {2,4}
- T: {2,3,4,5,6,7,8,9}
- N, E and W:

{0,1,2,3,4,5,6,7,8,9}

• x1 and x2:  $\{0,1\}$ 

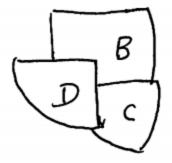
Constraints:

Alldiff(O,N,E,T,W) E + E = 10\*x1 + O x1 + N + N = 10\*x2 + Wx2 + O + O = T

- **4.** [20 points] Given the map coloring problem below, the goal is to color regions B, C and D so that no two adjacent regions have the same color. The initial domain values for the three regions are given in the table below.
  - (a) Region C has only the color R in its domain. We can therefore assign the color R to region C. Apply Forward Checking (one time) to update the domain values of region C's neighbors.
  - (b) Apply the *AC-3* algorithm in Figure 3 to the three regions with initial domain values given in the top row of the table below. List the initial content of the *queue* after it is initialized with all the arcs in the CSP. List the domain values of each region after the algorithm stops.

(Note: (a) and (b) above are independent sub-problems. You are to start with the initial domain values in the top row of the table below for each sub-problem.)

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	В	U	D
Initial domain values	RG	R	RGB
After Forward Checking			
After AC-3			



Figure 1. Map of Australia

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```
function BACKTRACKING-SEARCH(csp) returns a solution or failure
  return BACKTRACK(csp, \{\})
function BACKTRACK(csp, assignment) returns a solution or failure
  if assignment is complete then return assignment
  var \leftarrow \text{Select-Unassigned-Variable}(csp, assignment)
  for each value in Order-Domain-Values(csp, var, assignment) do
      if value is consistent with assignment then
        add \{var = value\} to assignment
        inferences \leftarrow Inference(csp, var, assignment)
        if inferences \neq failure then
           add inferences to csp
           result \leftarrow BACKTRACK(csp, assignment)
           if result \neq failure then return result
           remove inferences from csp
        remove \{var = value\} from assignment
  return failure
```

Figure 2. The Backtracking-Search Algorithm for CSPs

```
function AC-3(csp) returns false if an inconsistency is found and true otherwise
  queue \leftarrow a queue of arcs, initially all the arcs in csp
  while queue is not empty do
     (X_i, X_i) \leftarrow Pop(queue)
     if REVISE(csp, X_i, X_i) then
       if size of D_i = 0 then return false
       for each X_k in X_i.NEIGHBORS - \{X_i\} do
          add (X_k, X_i) to queue
  return true
function REVISE(csp, X_i, X_j) returns true iff we revise the domain of X_i
  revised \leftarrow false
  for each x in D_i do
     if no value y in D_i allows (x,y) to satisfy the constraint between X_i and X_j then
       delete x from D_i
       revised \leftarrow true
  return revised
                                                                                            ١
```

Figure 3. The AC-3 algorithm.