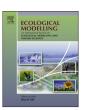
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Incorporating food-web parameter uncertainty into Ecopath-derived ecological network indicators



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ABSTRACT

Ecological network analysis (ENA) provides numerous ecosystem level indices offering a valuable approach to compare and categorize the ecological structure and function of ecosystems. The inclusion of ENA methods in Ecopath with Ecosim (EwE) has insured their continued contribution to ecosystembased management. In EwE, ENA-derived ecological conclusions are currently based on single values of ENA indices calculated from a unique input flow matrix. Here, we document an easy-to-use routine that allows EWE users to incorporate uncertainty in EWE input data into the calculation of ENA indices. This routine, named ENAtool, is a suite of Matlab functions that performs three main steps: (1) import of an existing Ecopath model and its associated parameter uncertainty values in the form of uncertainty intervals into Matlab; (2) generation of an ensemble of Ecopath models with the same structure as the original, and with parameter values varying based on the prescribed uncertainty limits; and (3) calculation of a set of 13 ENA indices for each ensemble member (one set of flow values) and of summary statistics across the whole ensemble. This novel routine offers the opportunity to calculate ENA indices ranges and confidence intervals, and thus to perform quantitative data analyses. An application of ENAtool on a pre-existing Ecopath model of the Bay of Biscay continental shelf is presented, with a focus on the robustness of previously published ENA-based ecological traits of this ecosystem when the newly introduced uncertainty values are added. We also describe the sensitivity of the ENAtool results to both the number of ensemble members used and to the uncertainty interval set around each input parameter. Ecological conclusions derived from EwE, particularly those regarding the comparison of structural and functional elements for a range of ecosystem types or the assessment of ecosystem properties along gradients of environmental conditions or anthropogenic disturbances, will gain in statistical interpretability.

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1. Introduction

Marine ecosystems are affected by climate change (Beaugrand, 2004; Hoegh-Guldberg and Bruno, 2010) and by other natural or human-caused disturbances (Pauly et al., 1998; Borja et al., 2010). Ecosystem models are useful to get a better understanding of the structure and function of a system and for predicting how it may change over time when facing single or multiple pressures (Plagànyi, 2007). Ecopath with Ecosim (EwE) is a widely used modelling approach to represent marine food webs (Polovina, 1984; Christensen and Walters, 2004; Christensen et al., 2008). Since its

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development in the early 1980s, about 400 EwE models representing a wide variety of ecosystems worldwide have been published (Colléter et al., 2013a,b). Coupling EwE models to Ecological Network Analysis (ENA; Ulanowicz, 1986) was proposed as a relevant method to estimate energy flows and to characterize emergent properties of food webs, i.e. characteristics not directly observable that can only be detected by analysis of within-system interactions (Christensen and Pauly, 1992). ENA is a suite of tools that include input-output analysis, trophic structure analysis, pathway analysis, biogeochemical cycle analysis, and information analysis (Dame and Christian, 2006; Borrett and Lau, 2014). The main challenge for ENA is to capture the properties of entire food web in terms of a limited number of indices. In the scope of the European Marine Strategic Framework Directive (MSFD; http://ec.europa.eu; Directive 2008/56/EC), the EU Member States have to report on the environmental status of the seas under their jurisdiction and to work on achieving "Good Environmental Status" (GES) using food-web indicators as one possible metric. In this direction, nine food-web indicators are currently under evaluation as potential indicators of GES; the Ecological Network Analysis indices are among these candidate indicators (Rombouts et al., 2013; Niquil et al., 2014).

The EwE network analysis plugin has been employed in many instances, notably to study the stability of ecosystems and their response to perturbations (Patricio et al., 2006; Lobry et al., 2008; Baeta et al., 2011; Selleslagh et al., 2012) or, more recently, to assess the dynamical food-web reorganization and redirection of energy flow pathways under environmental changes (Tomczak et al., 2013). Nonetheless, these holistic conclusions relied on single values of ENA indices which were derived from a single input data matrix with no specified uncertainty. Moreover, the ecological interpretation of these single values mostly relies on non-statistical comparisons with values obtained for ecosystems of the same type. Given that data uncertainties may translate to uncertainties in model outputs (e.g. Niiranen et al., 2012), it is generally agreed that important scientific questions should be scrutinized with as many models as possible (Fulton, 2010; Gårdmark et al., 2012). One method of incorporating uncertainty into Ecopath model analysis is to use an ensemble parameterization technique, building several Ecopath models each representing a potential manifestation of a food web and falling within the uncertainty ranges of the observed data (Aydin et al., 2007; Kearney, 2012). This approach results in distributions of parameters rather than specific values, while still meeting basic thermodynamic requirements. Kearney et al. (2012) provided a suite of Matlab functions to construct such a distribution of parameters based on an Ecopath model and its data pedigree, i.e. a quantification of the parameter certainty tied to the parameter's origin. In this study, we extend the Kearney et al. (2012) code for generating this type of ensemble to feed into calculations of ENA indices. This work will allow parameter uncertainty to be incorporated into model-derived ENA indices, and will also improve interpretation of these indices by allowing statistical analyses. When overhauling the EwE source code between the release of EwE versions 5 and 6, the EwE developers chose not to continue support of the Ecoranger module, which had allowed users to explore parameter uncertainty ranges in a Bayesian context (Christensen et al., 2005). The code presented in this paper now offers an alternative method for analyzing this uncertainty.

The aim of this software development is to provide an easy-to-use routine to EwE users to generate a set of values for key ENA indices by explicitly taking into account uncertainty in model input data. To this end, two characteristics are identified as important: (i) a routine that can be called by a single line of Matlab code and can be run on all commonly used operating systems (recent Windows, Unix-based, and Mac platforms), independent of the EwE software versions used for the pre-existing ecosystem model construction

and (ii) a routine based on formulas of ENA indices currently in use in the last version of the EwE software. The present work is also the opportunity to harmonize ENA indices calculations derived from two main approaches for constructing ecological flow networks, i.e. EwE and linear inverse modelling (LIM; Vézina and Platt, 1988). Different formulas for the same index exist in the scientific literature and correspond to different interpretations of the same idea. We demonstrate the use of this tool by applying it to a pre-existing Ecopath model of the Bay of Biscay continental shelf (Lassalle et al., 2011) for which data quality is already categorized using Pedigree scores (Lassalle et al., 2014). ENA indices distributions derived from the ENAtool routine are compared with previous point estimate values obtained with this Ecopath model to test for robustness of ENA-derived ecological conclusions. Finally, we test sensitivity of ENA indices distributions to the number of balanced ensemble members underlying their calculation and to the level of uncertainty applied to specific Ecopath model parameters.

2. Materials and methods

2.1. The Ecopath concept and equations

The Ecopath with Ecosim (EwE) modelling software enables the building and analysis of food-web models (Polovina, 1984; Christensen and Walters, 2004; Christensen et al., 2008). The full software package includes several modules (e.g. Ecopath, Ecosim, Ecospace) to explore food webs across both space and time. However, for this study, we will focus only on the Ecopath component, which calculates a static mass-balanced snapshot of the biomass and energy fluxes between functional groups in a food web. In this context, a functional group refers to a species or group of species that occupy a particular niche in the food web, and can range in resolution from a broad grouping (e.g. pelagic fish) to specific life stage of a species (e.g. juvenile herring). The Ecopath model calculation is based on two "master" equations. The first equation decomposes the production term of each functional group:

Production = fishery catch + predation mortality + net migration + biomass accumulation + other mortality

"Other mortality" includes natural mortality factors such as mortality due to senescence and diseases.

The second equation describes the energy balance within each *functional* group:

Consumption = production + respiration + unassimilated food

More formally, the two equations can be written as follows for functional group i and its predator j:

$$B_{i} \times \left(\frac{P}{B}\right)_{i} = Y_{i} + \sum_{j} \left(B_{j} \times \left(\frac{Q}{B}\right)_{j} \times DC_{ij}\right) + Ex_{i} + Bacc_{i} + B_{i}(1 - EE_{i}) \times \left(\frac{P}{B}\right)_{i}$$

$$(1)$$

and

$$B_i \times \left(\frac{Q}{B}\right)_i = B_i \times \left(\frac{P}{B}\right)_i + R_i + U_i \tag{2}$$

where the main input parameters are biomass density (B, here in kg C km $^{-2}$), production rate (P/B, year $^{-1}$), consumption rate (Q/B, year $^{-1}$), proportion of i in the diet of j (DC_{ij} ; DC = diet composition), net migration rate (Ex, year $^{-1}$), biomass accumulation (Bacc, year $^{-1}$), total catch (Y; kg C km $^{-2}$ year $^{-1}$), respiration (R; kg C km $^{-2}$ year $^{-1}$), amount of consumed food that is unassimilated

(*U*; kg C km⁻² year⁻¹) and ecotrophic efficiency (*EE*; amount of species production used within the system).

2.2. The generalized intra-model ensemble routine: ENAtool

In keeping with our goal to provide a single user-friendly tool for ENA index ensemble generation, we have packaged together a master Matlab script (ENAtool.m) and two data input templates, all of which are available via the supplementary materials. The ENAtool.m script grew out of, and now incorporates several subfunctions from, the Matlab implementation of Ecopath (Kearney, 2015; doi:10.5281/zenodo.17837), with additional routines added to calculate ENA indices from the resulting model ensemble. The key calculations performed by this tool are as follows. All the Matlab functions called during the ENAtool routine operate only on Ecopath data.

2.2.1. Import of a EwE model into Matlab

ENAtool first imports data from EwE6 databases into Matlab, storing them in a variable format we will refer to as EwE input structures (Fig. 1). The original data import function, mdb2ewein, relies on the 'mdbtools' (http://mdbtools.sourceforge.net/) set of utilities to read data from the MS Access file format used by EwE. As an alternative for those unwilling or unable to compile C source code, we have provided a companion import function, excel2ewein. which relies on an Excel template to provide the necessary input data (Fig. 1). This function is based on a template (see Template A provided in supplementary material 1) that must be filled with key input parameters and other related information by first opening the pre-existing EwE model with a database program such as Microsoft Access or OpenOffice Base. The template was provided as an Excel file and can be completed using any spreadsheet program (e.g. Microsoft Excel, OpenOffice Calc, etc.) but must be in the end saved as an Excel file (.xlsx). Both functions import all necessary Ecopath data, including basic inputs, diet compositions, fleet catches and discards, and multi-stanza group parameters, to the EwE input structure.

2.2.2. Generation of a set of balanced ensemble members

This second step can be decomposed into two phases: first, the definition of uncertainty around input parameters and then the construction of an ensemble of balanced Ecopath models (Fig. 1). A probability distribution for all or certain input parameters (i.e. field biomasses (B), production over biomass ratios (P), consumption over biomass ratios (P) in the EwE input structure has to be defined. To do so, a level of uncertainty around each single value entered in the EwE input structure needs to be fixed. Uncertainty values were assigned as a percentage of the point estimate of each parameter. Minimum and maximum values of the parameter distribution can then be calculated as follows:

Limits = single value of the parameter
$$\pm$$
(percentage * single value of the parameter) (3)

In the present work, the *createpedigree* function was developed to ease this step, particularly in the case of pre-existing EwE models for which Pedigree scores were already estimated (Fig. 1 and Table 1). The Pedigree index (Funtowicz and Ravetz, 1990; Pauly et al., 2000) was designed to evaluate whether an EwE model was based on extensive field sampling performed within the boundaries of the system during specific dates. The Pedigree component in the EwE software allows marking/categorizing the data origin of each single input using pre-defined tables; the key criterion being that inputs from local data have the best confidence and the highest

Table 1

Uncertainty applied to input parameters of the pre-existing Ecopath model of the Bay of Biscay continental shelf by Lassalle et al. (2011) (i.e. term 'percentage' in Eq. (3)). Values were derived from pre-defined tables provided by Christensen et al. (2005) associating a Pedigree score to each given level of uncertainty for each basic input parameter. Blank cells correspond to parameters left to be estimated by the model, where the parameter did not apply (e.g. *Q/B* for primary producers), or where the EwE software did not allow setting Pedigree scores (e.g. *P/B* of primary producers). To run the ENAtool routine, blank cells were replaced by zeros.

	В	P/B	Q/B	DC
Pursuit divers seabirds	0.1	0.9	0.5	0.8
Surface feeders seabirds	0.1	0.9	0.5	0.8
Striped dolphins	0.1	0.8	0.5	0.3
Bottlenose dolphins	0.1	0.8	0.5	0.3
Common dolphins	0.1	0.8	0.5	0.3
Long-finned pilot whales	0.1	0.8	0.5	0.3
Harbour porpoises	0.1	0.8	0.5	0.3
Piscivorous demersal fish	0.1	0.5	0.5	0.4
Piscivorous and benthivorous demersal fish 0.1	0.5	0.5	0.4	
Suprabenthivorous demersal fish	0.1	0.5	0.5	0.4
Benthivorous demersal fish	0.1	0.5	0.5	0.4
Mackerel	0.6	0.5	0.5	0.3
Horse mackerel	0.6	0.5	0.5	0.3
Anchovy	0.1	0.5	0.5	0.3
Sardine	0.1	0.5	0.5	0.3
Sprat	0.1	0.5	0.5	0.3
Benthic cephalopods	0.8	0.8	0.5	
Pelagic cephalopods	0.8	0.8	0.5	
Carnivorous benthic invertebrates	0.4	0.5		0.3
Necrophageous benthic invertebrates	0.4	0.5		0.3
Sub-surface deposit feeders invertebrates	0.4	0.5		0.3
Surface suspension and deposit feeders inv.	0.4	0.5		0.3
Benthic meiofauna	0.4	0.5		0.3
Suprabenthic invertebrates	0.4	0.5		0.3
Macrozooplankton	0.1		0.8	0.3
Mesozooplankton	0.1		0.8	0.3
Microzooplankton	0.1		0.8	0.3
Bacteria	0.1	0.1		0.3
Large phytoplankton	0.1			
Small phytoplankton	0.1			
Discards				
Detritus				

level in the scale (Christensen et al., 2005). In the pre-defined tables, each Pedigree score is associated with a default level of uncertainty expressed as $\pm\%$. For example, a Pedigree score of 1 (e.g. for a local biomass value) indicates a 10% uncertainty value. The createpedigree function builds a table of uncertainties based on an Excel file which contains for each parameter and each functional group the level of uncertainty to be applied to the single value (see Template B in supplementary material 2). Again, this Excel file can be opened with any spreadsheet program but must be finally saved as an Excel file. This Excel file can be also an export of the Pedigree table from the EwE software. If the user has no estimate of the uncertainty surrounding the input parameters in the pre-existing EwE model, a level of uncertainty can be set and a matrix of the same dimension as the uncertainty table will be automatically generated. With no specification from the user, the default values will be 20% around single values (Richardson et al., 2006).

As inputs, the *createensemble* function requires the uncertainty table built using the *createpedigree* function and the model imported into Matlab using *mdb2ewein* or *excel2ewein* (Fig. 1). The *createensemble* function generates a defined number of ensemble members that all fall within the prescribed uncertainty ranges. Parameter values can be sampled from a uniform distribution within limits fixed by the uncertainty table or a lognormal distribution with the mean and standard deviation set according to the uncertainty table. Both Latin hypercube and Monte-Carlo sampling methods can be used for random sampling in this interval. In the present application case, parameter values were randomly sampled using a Monte Carlo method from a uniform distribution with bounds directly related to the level of uncertainty.

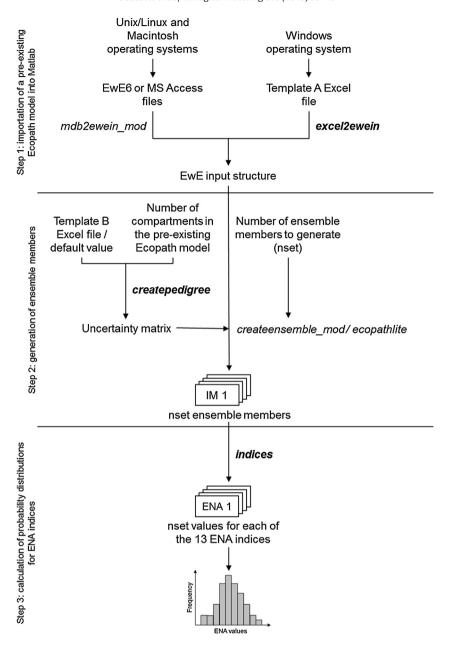


Fig. 1. Schematic representation of the different Matlab functions that compose the ENAtool routine. The functions that were previously developed by Kearney (2012) are given in italics. In agreement with the developer, some modifications were made to these functions to enhance their applicability to all operating systems and to all EwE model versions. These modifications were specified in the name of the function by "_mod". The functions that were specifically built for the present work were marked in bold. The origins of formulas used in the *indices* functions are listed in Table 2.

The ecopathlite function called by the createensemble function is the one that reproduces the main calculations performed by the Ecopath module of the EwE software (Fig. 1). This function is a 'stripped-down' version of the Ecopath algorithms allowing an estimation of missing parameters by solving the system of nequations with n unknowns (see Eqs. (1) and (2)). Users can also choose whether they want ensemble members that respect the biomass conservation hypothesis, i.e. here, that met the ecotrophic efficiency balance requirements (EE < 1). Combining createensemble and ecopathlite functions allows the user to compute a specific number (referred to henceforth as nset) of balanced ensemble members before calculating any ENA indices. For multi-stanza configurations, adjustments of parameters are made when calling subecopathens.m to calculate Ecopath values and check for balance. So the resulting ENA index values stemming from this code will incorporate the same multi-stanza relationships as in EwE.

2.2.3. Calculation of an ensemble of values for ENA indices

Finally, the *indices* function was developed in this present work to calculate a set of 13 ENA indices (Fig. 1; Table 2) for each ensemble member generated by the *createensemble* function. The mathematical formulas for these indices required a harmonization between the EwE and LIM ecosystem modelling communities. We compared the formulas in use in EwE with those currently in use by modellers working with linear inverse models (LIMs) in Matlab (Leguerrier et al., 2007; Johnson et al., 2009; Niquil et al., 2011; Saint-Béat et al., 2013) (Table 2). Most formulas were shared in common between both communities and were as such already available in Matlab. Ecological interpretations of ENA indices are summarized in Table 2. Full details regarding their links with ecosystem ecology theories can be found, for instance, in Ulanowicz (2004), Kones et al. (2009), and Saint-Béat et al. (2015).

Table 2 Formulas to calculate the 13 ENA indices in the *indices* function of the ENAtool routine. Formulas and their origins are presented for EwE software v.6 as well as for the linear inverse modelling approach. For each ENA index, its single value calculated using the EwE model of the Bay of Biscay continental shelf of Lassalle et al. (2011) was presented. TL_i is the trophic level of the *ith functional group*, Y_i the captures (i.e. landings and discards) for *functional group*, TST_C the sum of flows involved in cycles, T_{ij} the magnitude of the unidirectional flow from T_i to T_i the consumption of T_i the proportion of T_i in the diet of T_i and T_i and T_i in the omnivory index for T_i . The internal ascendency T_i and internal relative ascendency T_i are also calculated by only considering internal flows to the system and constitute indices 11, 12 and 13, respectively.

Indices	General interpretation	EwE software formula	References	Single value of ENA index	Linear inverse modelling formula	References
Mean trophic level of captures (MTL)/no units	Fishing down, up or through the food web	$\frac{\sum_{i} \pi_{i} \times Y_{i}}{\sum_{i} Y_{i}}$	Pauly et al. (1998)	3.753	~	
Total system throughput (TST)/kg C km ⁻² year ⁻¹	Global activity of the system	Sum of all flows, i.e. consumption, respiration, imports and exports	Ulanowicz (1986)	935,578	~	
Finn cycling index (FCI)/no units	Proportion of flows in a system that is recycled	$\frac{TSI_c}{TST} = \sum_j \frac{\sum_{ij} T_{ij} + \text{Imports}_j}{TST}$	Finn (1980)	34.61	~	
Comprehensive cycling index (CCI)/no units	Proportion of all flows in a system that is recycled	1.142 × FCI	Allesina and Ulanowicz (2004)	39.53	~	
Averaged path length (APL)/no units	Average number of functional groups that an atom of carbon passes through between its entry into the system and its exit	$\sum\nolimits_{i}^{TST} Exports + \sum\nolimits_{i}^{TST} Respiration$	Finn (1980)	4.857	$\frac{TST - \sum_{i} Imports}{\sum_{i} Imports}$	Kay et al. (1989) and Baird et al. (1991)
Ascendency (A)/flowbits	Quantification of the system activity in association with the degree of flows specialization	$\sum_{i} \sum_{j} T_{ij} \times \log \left[\frac{TST \times T_{ij}}{\sum_{j} T_{ij} \times \sum_{i} T_{ij}} \right]$	Ulanowicz (1986)	860,882	~	
Capacity (C)/flowbits	Maximum potential ascendency	$-\sum_{i}\sum_{j}T_{ij}\times\log\left[\frac{T_{ij}}{^{1\overline{\Sigma t}}}\right]$	Patricio et al. (2006)	3,808,206	$-TST \times \sum_{i} \frac{\sum_{j} T_{ij}}{TST} \times \log \left[\frac{T_{ij}}{TST} \right]^{i}$	Ulanowicz (1986)
Relative ascendency (A/C)/no units	Fraction of the system that is	A C	Ulanowicz (1986)	0.226	$\log \left\lfloor \frac{\sqrt{s}}{151} \right\rfloor$	
Overheads (O)/flowbits	organized Unorganized part of the system	C-A	Ulanowicz (1986)	2,947,325	~	
System Omnivory Index (SOI)/no units ^a	Omnivory	$\begin{cases} \sum_{i} \log \left[\frac{Q_{i}}{\min(Q)} \right] \times BQB_{i} \\ \sum_{i} \log \left[\frac{Q_{i}}{\min(Q)} \right] \times BQB_{i} \end{cases} \text{si } s > 0 \\ \text{with } s = \sum_{i} \log \left[\frac{Q_{i}}{\min(Q)} \right] \text{ and } \\ BQB_{i} = OI_{i} = \sum_{j} \left(TL_{j} - \left(\sum_{j} TL_{j} \times DC_{ji} \right) \right)^{2} \end{cases}$	Villy Christensen (pers. comm.)	0.195	$\frac{\sum_{i} O_i \times \log[Q_i]}{\sum_{i} \log[Q_i]}$	Christensen and Pauly (1993)

^a See http://sources.ecopath.org/trac/Ecopath/ticket/1348 for issues regarding calculation of OI when imports are set in the diet matrix in Ecopath with Ecosim v.6.

2.3. The ENAtool application

2.3.1. Description of the Bay of Biscay Ecopath model

A full description of the Bay of Biscay Ecopath parameterization can be found in Lassalle et al. (2011). The model considered for this zone was restricted to the central part of the shelf between the 30-m and 150-m isobaths with a surface area of 102,585 km² (Fig. 2). The model represented a typical year between 1994 and 2005, i.e. before the collapse of the European anchovy (Engraulis encrasicolus) and the subsequent five-year closure of the fishery for this species. Thirty-two functional groups were retained, including two seabirds, five marine mammals, nine fish, eight invertebrates, three zooplankton, two primary producers, one bacteria, discards from commercial fisheries, and pelagic detritus. Cephalopods were included in the form of two classes relating to their main oceanic domain (pelagic/benthic). The five main pelagic forage fish were given their own functional groups and demersal fish were divided into four multi-species functional groups on the basis of their diet regime. Marine mammals were included in the form of five monospecific functional groups representing the small-toothed cetaceans most frequently encountered in the area.

2.3.2. Summary of previous ENA-derived results

Some insights regarding the Bay of Biscay structure and function have been derived from ENA indices calculated with the EwE model of Lassalle et al. (2011) (see Table 2 for single estimates). In this previous work, single point estimates were interpreted by comparison to those obtained for ecosystems of the same type or for other Ecopath models of the same ecosystem. The high Finn's Cycling Index (FCI) value, which measures the relative importance of cycling to the total flow (Finn, 1980), highlighted the strategic position of detritus as a perennial reservoir of energy in the Bay of Biscay. The System Omnivory Index (SOI) was regarded as an index reflecting the complexity of the inner linkages within the ecosystem (Christensen and Pauly, 1992). It is correlated with system maturity, since the internal network organization is expected

to increase as the system matures (Odum, 1969). The relatively moderate value for this output suggested a "web-like" food chain with an intermediate level of internal flow complexity. The Bay of Biscay also appeared as relatively immature, as indicated by the Ascendency (A), and has a high resistance to external perturbations according to System Overhead (O). Ascendency (A) merges the quantification of the system activity and the degree of specialization of flows in the network (Ulanowicz, 1986; Ulanowicz and Wulff, 1991). During maturation, ecosystem structure evolves towards an increase in ascendency (Ulanowicz et al., 2006). System Overhead (O) represents the amount of development capacity that does not appear as organized structure or constraints (Ulanowicz, 1986) and as such it corresponds to the system reserves when facing perturbations (Heymans and Baird, 2000).

2.3.3. The Bay of Biscay Ecopath ensemble and ENA ensemble

The ENAtool routine was used to generate 1000 balanced ensemble members based on the uncertainty values assigned to each input parameter according to Pedigree scores (Table 1) (Lassalle et al., 2014); for this particular food web, the search for 1000 balanced ensemble members took between three and five days to run on a single-processor machine. For each ENA index listed in Table 2, the single value obtained with the EwE software was graphically compared to the 1000 values derived from the ENA-tool routine as to whether it falls between the boxplot whiskers. Then, the coefficient of variation between the mean value and the single Ecopath estimate was calculated.

The 'balance' constraint can move the parameter distribution of the balanced ensemble members away from the initial sampling distribution. It could make a crucial difference as to whether the ensemble experiment applied to the Bay of Biscay is simply adding error bars onto the input to the ENA index equations, or if it is adding error bars and shifting the mean/median value of the inputs variables. As such, an additional 1000-member ensemble based on the Bay of Biscay input dataset and Pedigree scores was generated, with keeping both balanced and unbalanced members. Then, the

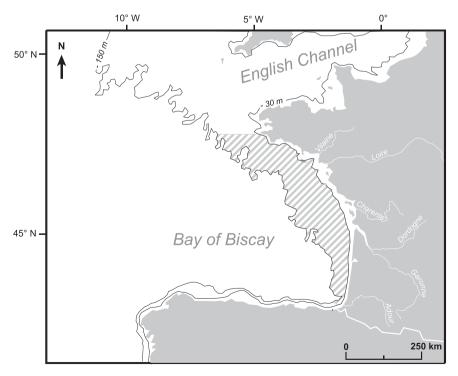


Fig. 2. Study area of the Bay of Biscay continental shelf and locations of the main rivers flowing into it. The shaded area corresponds to the French part of the continental shelf between 30 and 150 m depth, and represents the spatial extent of the Ecopath model.

Table 3Summary of results from the application of the ENAtool routine to the Bay of Biscay continental shelf ecosystem model and of results from the preliminary sensitivity analyses. 'Global' means that all input parameters were simultaneously changed according to the level of uncertainty and 'Local' that B, P/B, Q/B and DC were alternatively modified.

Application of the ENAtool routine (<i>nset</i> of 1000 and levels of uncertainty based on pedigrees)	Preliminary sensitivity analyses			
	Global/all combinations of <i>nset</i> (10, 100, 1000) and levels of uncertainty (20, 40, 60%)	Local/ <i>nset</i> of 1000 and level of uncertainty of 20%		
The single ENA indices values obtained from the pre-existing Ecopath model using the EwE software all felt within the boxplot whisker intervals.	• No influence of <i>nset</i> on the variance of ENA indices distributions.	The variance of ENA indices distributions changed the most when variations were applied to B and DC.		
The coefficients of variation between the single ENA indices values obtained from the pre-existing Ecopath model using the EWE software and the mean distribution values were comprised between 0.08 (MTL) and 11.45% (G)	• The variance of ENA indices distributions systematically increased with the level of uncertainty.			

ensemble mean parameter values of these two ensembles were statistically compared using two-sample Kolmogorov–Smirnov goodness-of-fit tests (alpha = 0.05).

2.3.4. The preliminary sensitivity study

The ENAtool routine requires as main input arguments the number of ensemble members to generate and the level of uncertainty to be applied on B, P/B, Q/B, and DC. Therefore, it was important to study the influence of these arguments on the output variables, namely ENA indices. 1. A first exercise was performed to assess in which proportions ENA indices distributions were impacted by the number of ensemble members to generate and by the uncertainty set around input parameters in the ENAtool routine. Values for nset of 1000, 100 and 10 were tested. The point value of each parameter was changed by 20/40/60% up or down following Eq. (3). All combinations of nset and levels of uncertainty were run for the preexisting Ecopath model of the Bay of Biscay continental shelf. 2. A second exercise tested which type of input parameter (i.e. B, P/B, Q/B, and DC) influenced the ENA index distributions most strongly. To do so, the ENAtool routine was run with a nset of 1000 and a level of uncertainty of 20% alternatively applied to each input parameter type of the pre-existing Ecopath model of the Bay of Biscay continental shelf (Richardson et al., 2006).

In both exercises, the variance of ENA indices distributions (i.e. standard deviation squared) was the metric used to analyze the sensitivity results through graphical representations.

3. Results

First, based on the exploratory statistical comparisons of the parameter distributions between the balanced ensemble and the mixed ensemble (i.e. balanced and unbalanced), 52 of the basic estimates parameters shifted mean and 169 of the non-zero diet components shifted too.

For the pre-existing Ecopath model of the Bay of Biscay continental shelf, the value derived from the EwE software for each ENA index was compared to the range of values obtained following the application of the ENAtool routine to this model with a nset of 1000 and levels of uncertainty in accordance with Pedigree scores (Table 3). For A, A_i/C_i , and MTL, the EwE single estimates fell within the range defined by the 1st (25%) and the 3rd (75%) quartile of ENA values (Fig. 3; Table 2 for the list of ENA indices with their abbreviations). For 9 of the 10 remaining ENA indices, the EwE single estimates fell in the upper boxplot whiskers calculated as 1.5 times the interquartile range. Regarding more specifically at the ENA indices used by Lassalle et al. (2011) in their assessment of the Bay of Biscay functioning, we calculated an FCI value with a mean of 33.09% across ensembles, compared to the single value of 34.61% obtained by Lassalle et al. (2011) (Fig. 3). The System Omnivory Index (SOI) presented the broader difference between the Ecopath single estimate and the mean value, i.e. 0.195 versus 0.179, respectively (Fig. 3); the Ecopath SOI estimate being at the upper end of the distribution. The mean Ascendency (A) was of 846,015 versus 860,882 flowbits for the pre-existing Ecopath model. The mean Overhead (O) and the single Overhead estimate were of 2,639,671 and 2,947,325 flowbits, respectively. The coefficients of variation between the mean values and the single Ecopath estimates for those four indices were no greater than 10% (Table 3).

The first sensitivity exercise performed on the outputs of the ENAtool routine showed that the number of ensemble members generated induced no trend on the variance of ENA indices calculated as the standard deviation squared (Fig. 4 and Table 3). Indeed, for all of the three levels of uncertainty applied in the routine, i.e. 20, 40 and 60% on all parameters, and for all ENA indices, the variance of the distribution did not systematically increase with the number of ensemble members generated as first suspected (Fig. 4). On the contrary, when looking at a given number of ensemble members to generate, i.e. at a specific shade of grey, the variance of the distribution systematically increased with the level of uncertainty applied to the input parameters (Table 3). This trend was particularly marked for the Total System Throughputs (TST) with variances that almost doubled when the level of uncertainty was changed from 40 to 60% (Fig. 4). These results were in line with the method, as parameters for the ensemble members were here randomly sampled from a uniform distribution with bounds directly related to the level of uncertainty; every value in the interval having the same probability of being picked.

In the second sensitivity exercise, two input parameters appeared to be the most influential on ENA indices (Fig. 5). On the one hand, the Comprehensive Cycling Index (CCI), the Finn Cycling Index (FCI), the Mean Trophic Level of captures (MTL) and the System Omnivory Index (SOI) were the most sensitive to less constrained diet compositions (DC) (Fig. 5). On the other hand, the relative Ascendency (A/C), the Ascendency (A), the Capacity (C), the Averaged Path Length (APL), the Overheads (O) and the Total System Throughput (TST) were the most sensitive to uncertainty in the Biomass (B) parameter (Fig. 5).

4. Discussion

The present work provides EWE modellers, and more broadly ecosystem ecologists, with a routine that generates distributions of values for a set of well-known indices synthesizing structural and functional properties of ecosystems by taking into account uncertainty in model input parameters. In the first place, reanalyzing the Bay of Biscay continental shelf food web in the light of the most probable estimates of uncertainty around input parameters for this ecosystem supported the main ENA-derived ecological conclusions. Indeed, ENA index distributions all encompassed the single ENA values derived from the EWE software with mean values

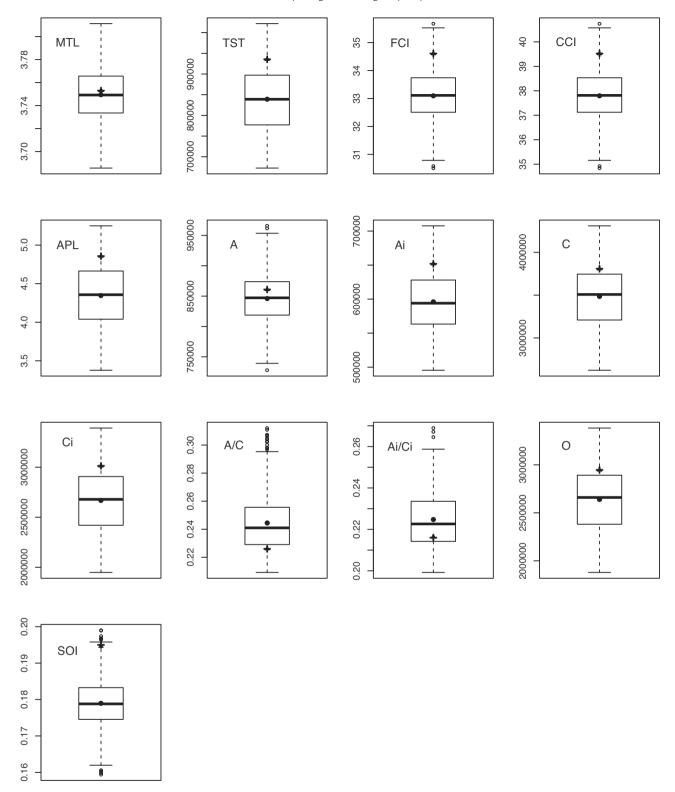


Fig. 3. Boxplot of ENA indices values obtained from the ENAtool routine, run with a *nset* of 1000 and a level of uncertainty specific to each input parameter according to Pedigree scores for the pre-existing Ecopath model of the Bay of Biscay continental shelf of Lassalle et al. (2011). A black circle corresponds to the mean of the 1000 ENA indices values. A black cross represents the single ENA indices values obtained from the pre-existing Ecopath model using the EwE software. A black triangle is used for the ENA indices values calculated after the importation of the pre-existing Ecopath model to Matlab with no change on the input parameters. Results are depicted for the 13 ENA indices. Graphics are organized following the order of Table 2.

in the same range as the initial Ecopath estimates (Table 3). The Bay of Biscay ensemble approach as such supported and strengthened the main conclusion of a detritus-based, and relatively mature ecosystem (Lassalle et al., 2011). In addition, when interpreting

and using ENA distributions, it should be kept in mind that those values are derived from the propagation of parameter uncertainty forward but also, to some point, to the interplay in parameters required to keep the models balanced when any changes are made.

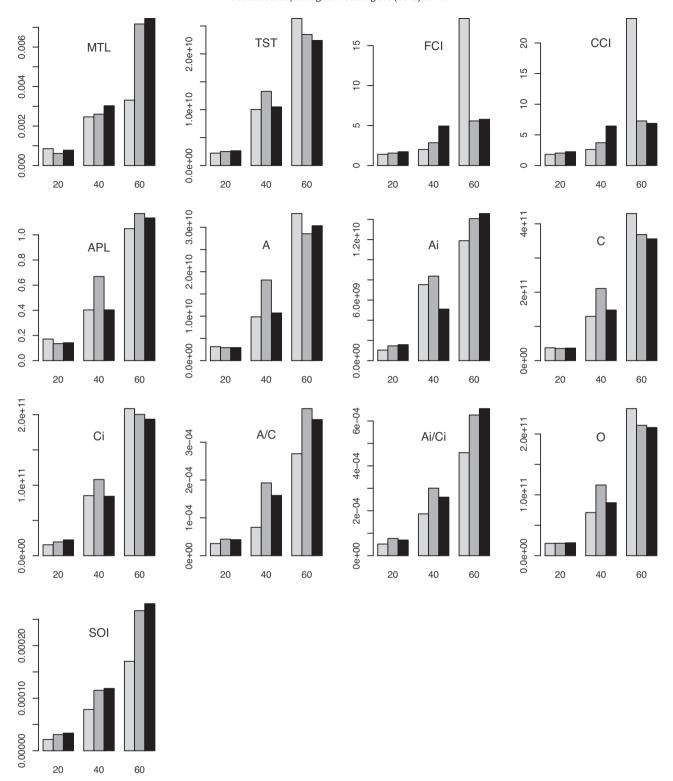


Fig. 4. Variance of ENA indices values obtained from the ENAtool routine run with every combinations of *nset* equal to 10 (light-grey bars), 100 (medium-grey bars) and 1000 (dark-grey bars) and levels of uncertainty of 20, 40 and 60% on the pre-existing Ecopath model of the Bay of Biscay continental shelf of Lassalle et al. (2011). Results are depicted for the 13 ENA indices. Graphics are organized following the order of Table 2.

The ENAtool routine was developed with the primary goal of strengthening ecological conclusions derived from comparative studies and before/after impact evaluations. Interpretation will no longer rely only on single value comparisons. The routine will permit one to test differences between ENA indices through statistical tests as performed in Saint-Béat et al. (2013) with LIM models.

The LIM models have evolved in the last decade from a single-solution method (Vézina and Platt, 1988) to statistical approaches with outputs composed of uncertainty intervals (density probability functions) of the flows and allowing the definition of uncertainty intervals of ENA indices. These methods first based on Monte Carlo approaches (Kones et al., 2006) are now used with a Monte Carlo

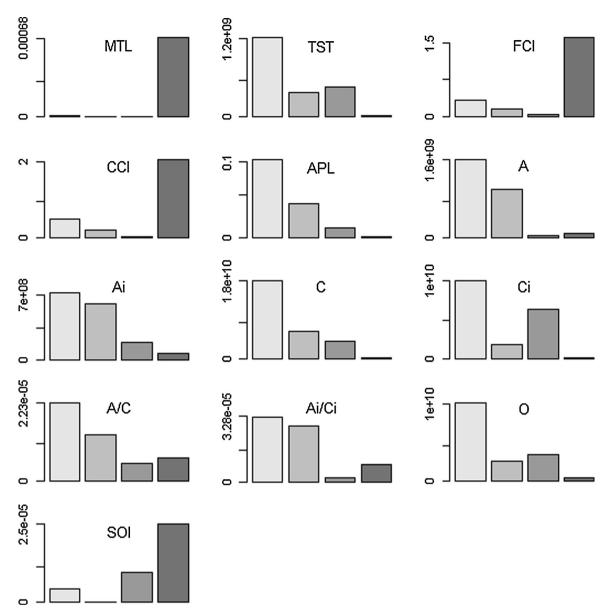


Fig. 5. Variance of ENA indices values obtained from the ENAtool routine run with a *nset* equal to 1000 and a level of uncertainty of 20% alternatively applied on each key input parameter. The application case is the pre-existing Ecopath model of the Bay of Biscay continental shelf of Lassalle et al. (2011). For each histogram, from the left to the right, the field biomasses are modified by $\pm 20\%$, then production to biomass ratios, consumption to biomass ratios, and finally diet compositions. Results are depicted for the 13 ENA indices. Graphics are organized following the order of Table 2.

Markov Chain routine (Kones et al., 2009). Several meta-analyses, based on a selection of EwE models, have been done, focusing either on theoretical ecology and ecological concepts, or on ecosystems and species of particular interest (see details in Colléter et al., 2013b), a growing proportion being based on ENA indices (e.g. Christensen, 1995; Pérez-España and Arreguin-Sánchez, 2001; Lobry et al., 2008; Coll and Libralato, 2012; Selleslagh et al., 2012). In the present work, complementary analyses were performed on the ENAtool routine to determine how much the ENA indices distributions were sensitive to the main routine arguments, namely the number of ensemble members to be generated (nset) and the level of uncertainty to apply on the EwE input parameters (Pedigree). The first induced no remarkable trend on the distributions whereas the latter was found positively related to the variance of the distributions (Table 3). As such, in future applications of the ENAtool routine, we recommend keeping the levels of uncertainty within a range compatible with known uncertainties on parameters. If no Pedigree scores were filled for the EwE model, model builders

or experts of the study area should be interviewed regarding the quality of data used during model construction. This was even more strongly suggested for field biomasses (B) and diet compositions (DC) that appeared as the most influential input parameters (Table 3). This last result can be also interpreted as an uncertainty analysis, showing that less constrained biomasses and diet compositions in input matrices both had a marked influence on ecosystem-level EwE model outputs such as ENA indices. This reinforces the well-known need for extra care to be used when setting these two parameters in EwE models, and more importantly for better information to be collected on these key characteristics of biological taxa. In the particular case of the Bay of Biscay, biomasses and diet compositions were both associated with low levels of uncertainty in the pre-existing Ecopath model, meaning they were already relatively well constrained by data. Within the four ENA indices that were strongly influenced by variations in diet compositions, the Mean Trophic Level (MTL) and the System Omnivory Index (SOI) were directly linked to trophic levels of functional groups

compared to the Finn Cycling Index (FCI) and the Comprehensive Cycling Index (CCI) for which interpretation of diet compositions influence was less intuitive. Nonetheless, FCI and CCI were both calculated from a matrix of internal exchanges that portrays the diet compositions of predators (Allesina and Ulanowicz, 2004). Indeed, both of these indices include the term T_{ij} (i.e. flow between functional groups i and j) in their definition, which is the same as Q_{ij} in Ecopath, with $Q_{ij} = B_i \times DC_{ij}$. FCI, CCI and SOI were commonly used to assess key ecosystem structural and functional features such as system maturity (Christensen, 1995), complexity, and stability (Libralato, 2008). From an applied perspective, in a comparative study by Selleslagh et al. (2012), the SOI was also demonstrated to be positively correlated with the degree of anthropogenic perturbations in estuaries. In the context of the European Water Framework Directive, the development of more functional indicators based on fluxes of matters and energy, and trophic networks at the scale of the ecosystem was recently listed as a critical way to improve the implementation of European policies (Reyjol et al., 2014). In this scope, by using the ENAtool routine and by applying variations more specifically to the diet compositions, the robustness of this relationship 'SOI/anthropogenic impacts' is planned to be statistically tested in an upcoming comparative study before presentation as a potential indicator of "Good Environmental Status". Attention will have to be paid to the topology and the degree of aggregation among functional groups in the compared models as these two factors were demonstrated to influence ENA values (Johnson et al.,

Application of the ENAtool routine is not strictly limited to the generation of ENA indices distributions for comparative studies; it can be also used to performed conventional uncertainty analyses. There is a need to assess parameter uncertainty of EwE outputs for decision making processes. In this scope, all balanced ensemble members derived from the resampling procedure in the ENAtool routine can be stored. And then, the various graphical representations proposed in the present work and more sophisticated statistical analyses can be performed to assess the influence of less constrained parameters on model estimates. Parameter uncertainty testing is also under development by the CEFAS (UK) where alternate balanced EwE models are generated to assess the impact of parameter uncertainty on fishing policies. A new R package, called 'Rpath', is currently under development and will address uncertainty in input parameters allowing for a creditable interval around model outputs (Lucey et al., 2014).

5. Conclusion

ENA indices are increasingly considered as potential indicators of ecosystem status. They express, alone or in combinations, key structural and functional aspects of a given system. The ENAtool routine will help to go a step further in ecosystem-based fisheries management (EBFM) by communicating to natural resources managers the distribution and mean values of ecosystem-level indices surrounded by confidence intervals. Statistical comparison of ENA index distributions, either between neighbouring ecosystems or under various management scenarios within a single ecosystem (i.e. before/after management action evaluations) can be performed using this tool, improving ecological diagnosis for a given system. Because the ENAtool routine is based on an ensemble parameterization technique, it will also contribute to the effort of the EwE community for parameter uncertainty testing.

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Appendix A. Supplementary data

Supplementary data associated with this article can be found, in the online version, at http://dx.doi.org/10.1016/j.ecolmodel.2015.05.036

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