

Fig. (1)

A, B, C, D = “Thigh Servo”

1, 2, 3, 4 = “Knee Servo”

A = pin2

B = pin8

C = pin4

D = pin6

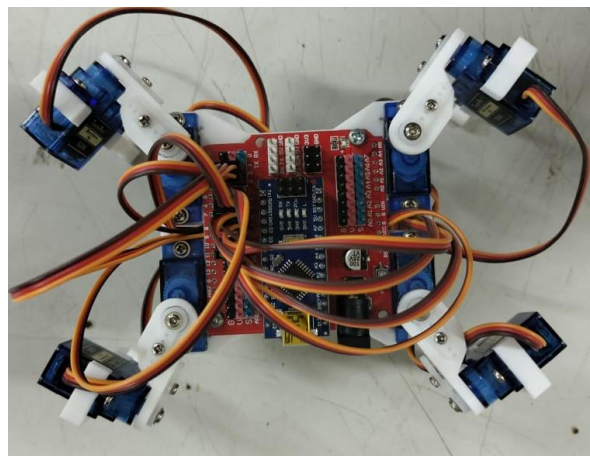
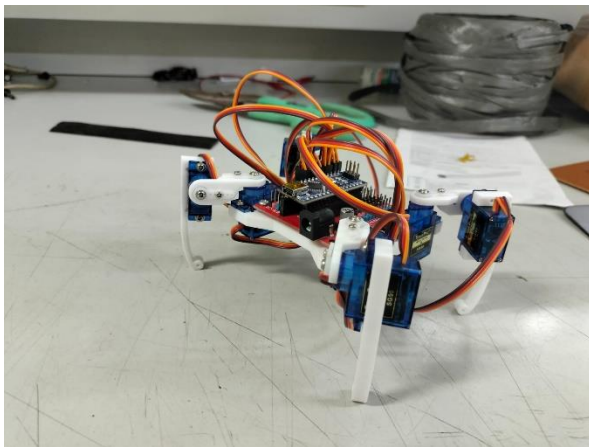
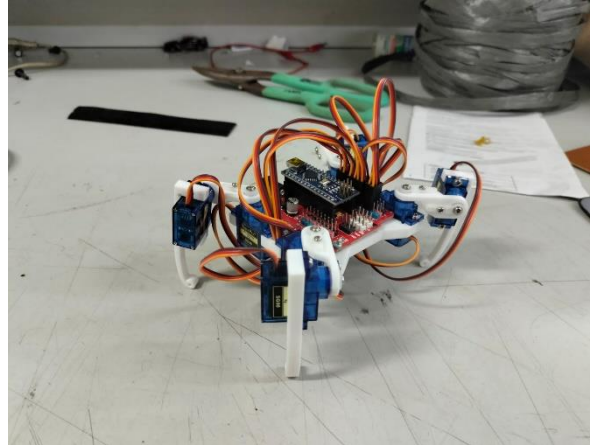
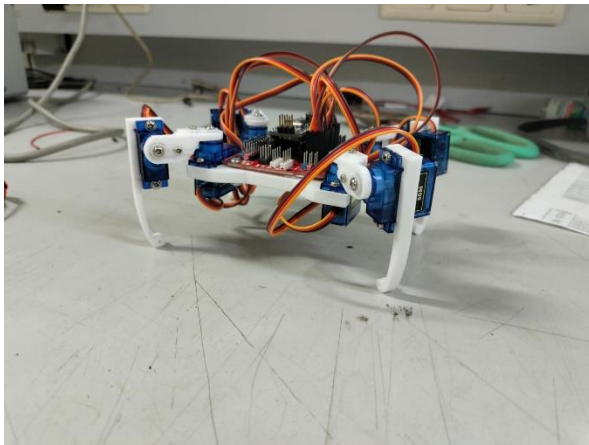
1 = pin3

2 = pin9

3 = pin5

4 = pin7

Idle Position



Look at fig. (2) – fig. (5) for reference.

Tabel of angles for each servo

Servo	Lift	Down
1	0	90
2	90	0
3	90	0
4	0	90

Servo	Pivot (Max)	“Straight”
A	80	0
B	0	80
C	0	80
D	80	0

Servo 3 in lift position:

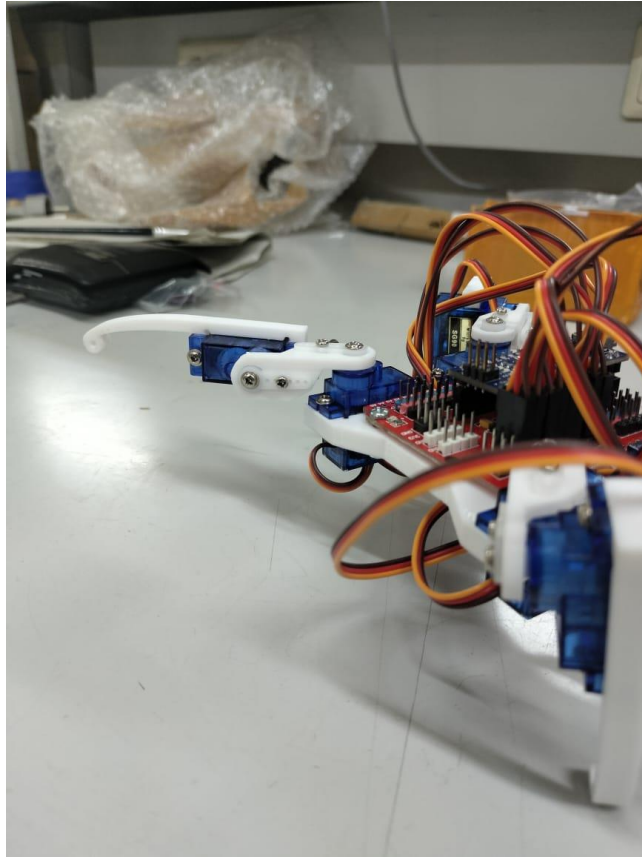


fig. (2)

Servos 1-4 in the down position:

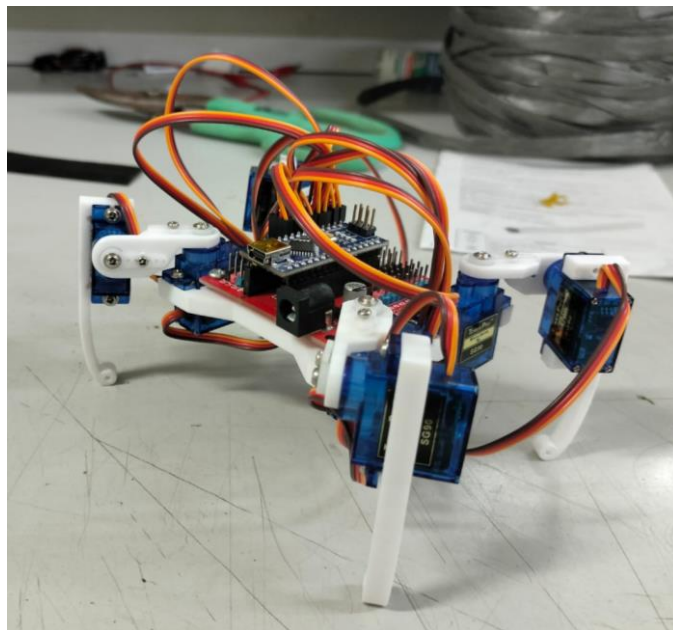


fig. (3)

Servos A-D in the pivot position:

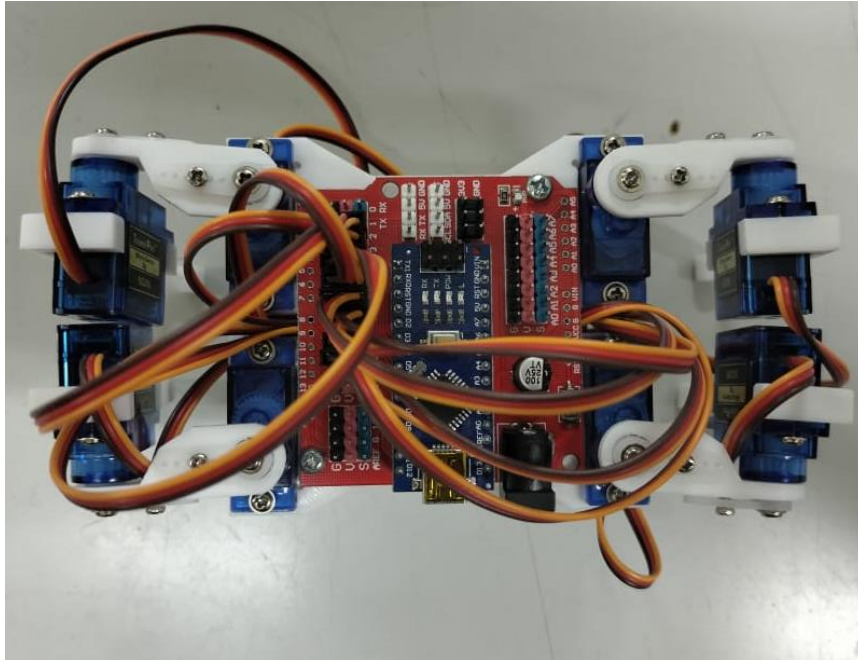


fig. (4)

Servos A-D in the Straight position:

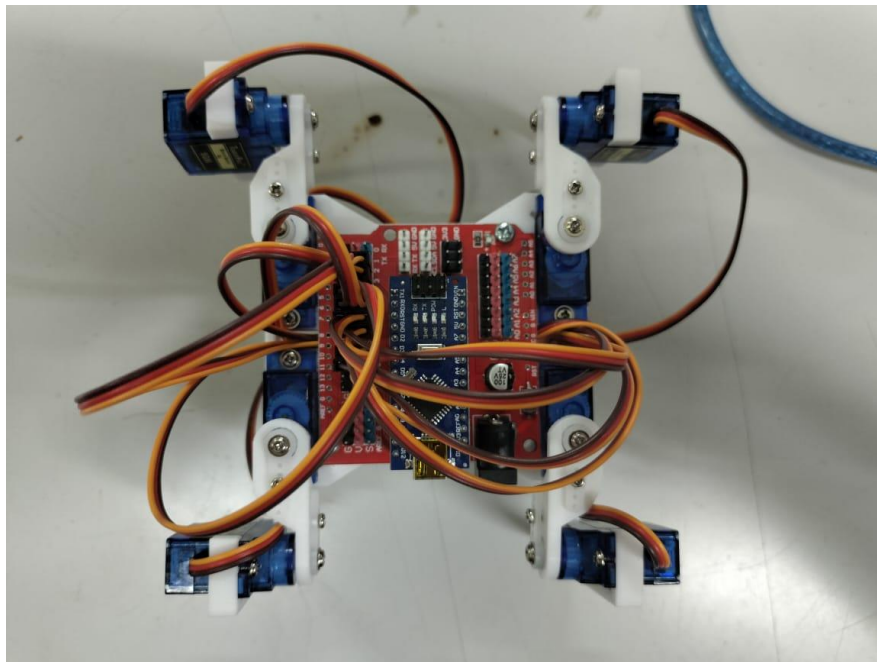


fig. (5)