

Fig. (1)

A, B, C, D = "Thigh Servo"

1, 2, 3, 4 = "Knee Servo"

A = pin2

B = pin8

C = pin4

D = pin6

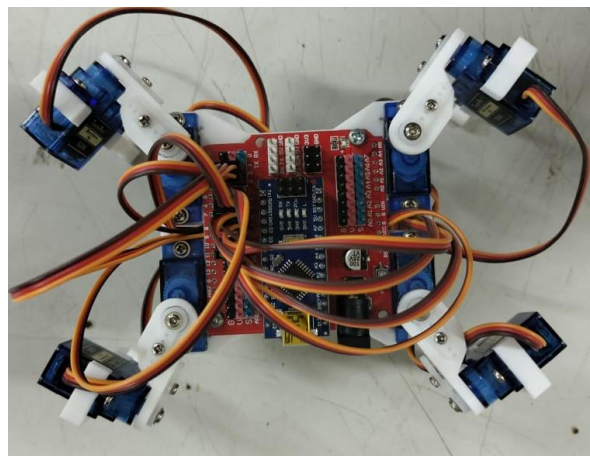
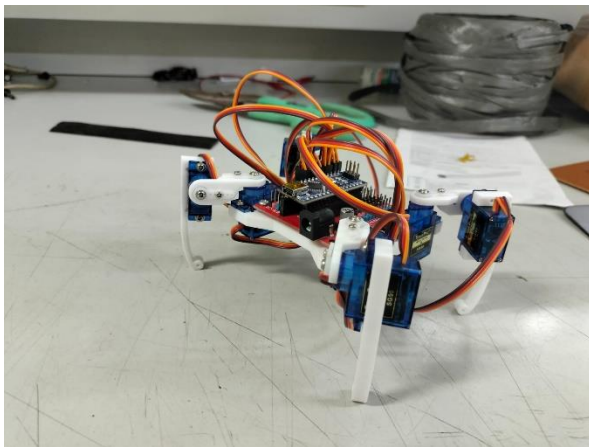
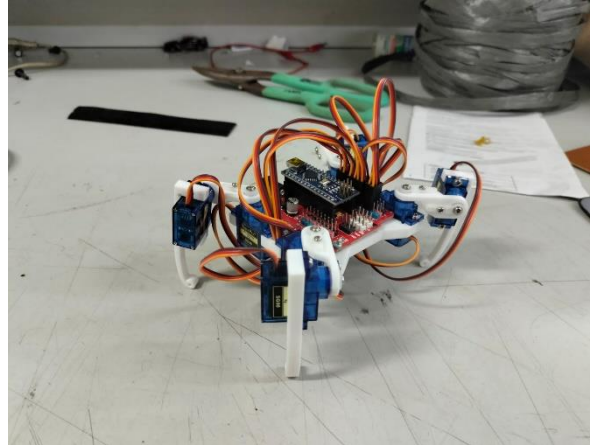
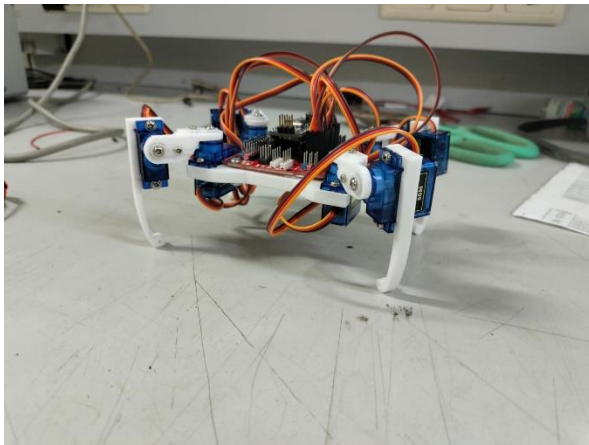
1 = pin3

2 = pin9

3 = pin5

4 = pin7

## Idle Position



Lihat fig. (2) – fig. (5) untuk referensi

Tabel sudut masing-masing servo

Servo	Lift	Down
1	0	90
2	90	0
3	90	0
4	0	90

Servo	Pivot (Max)	“Straight”
A	80	0
B	0	80
C	0	80
D	80	0

Posisi Servo 3 dalam kondisi “lift”:

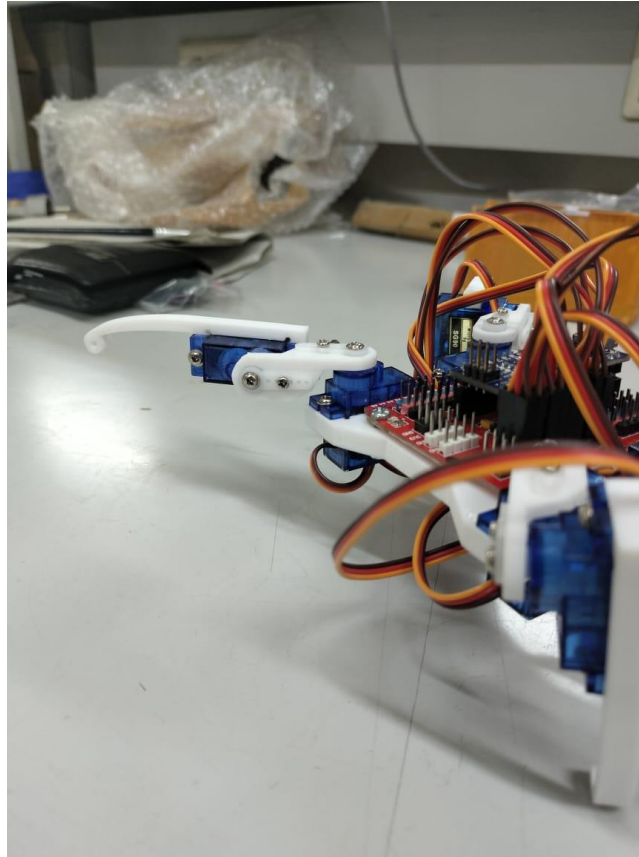


fig. (2)

Posisi Servo 1-4 dalam kondisi “down”:

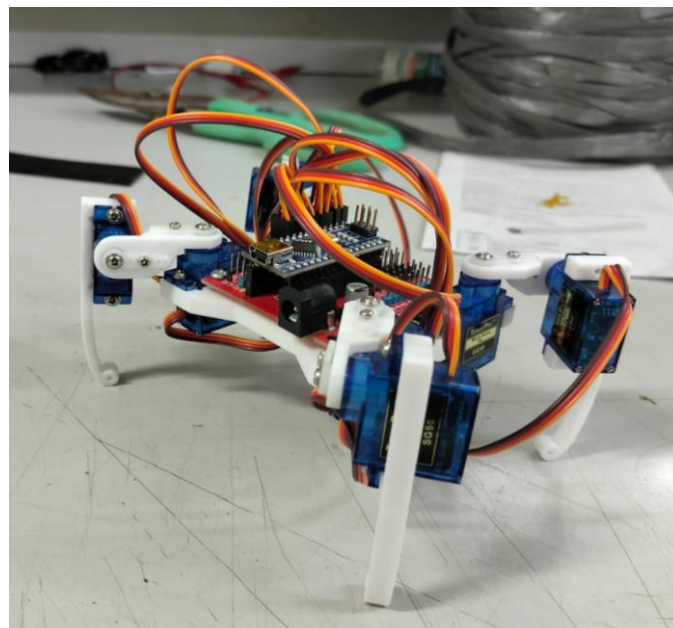


fig. (3)

Posisi Servo A-D dalam posisi “Pivot”:

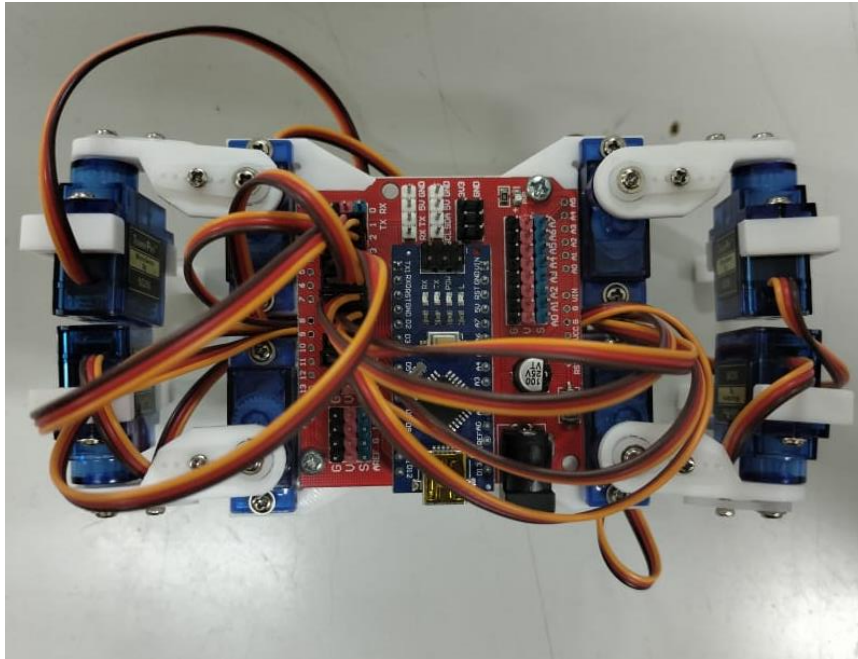


fig. (4)

Posisi Servo A-D dalam posisi “Straight”:

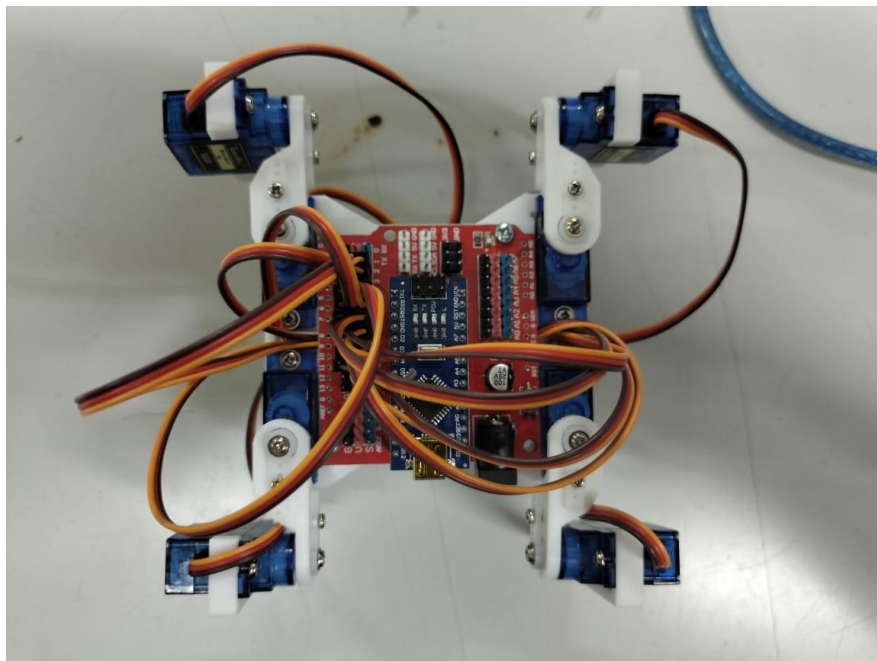


fig. (5)