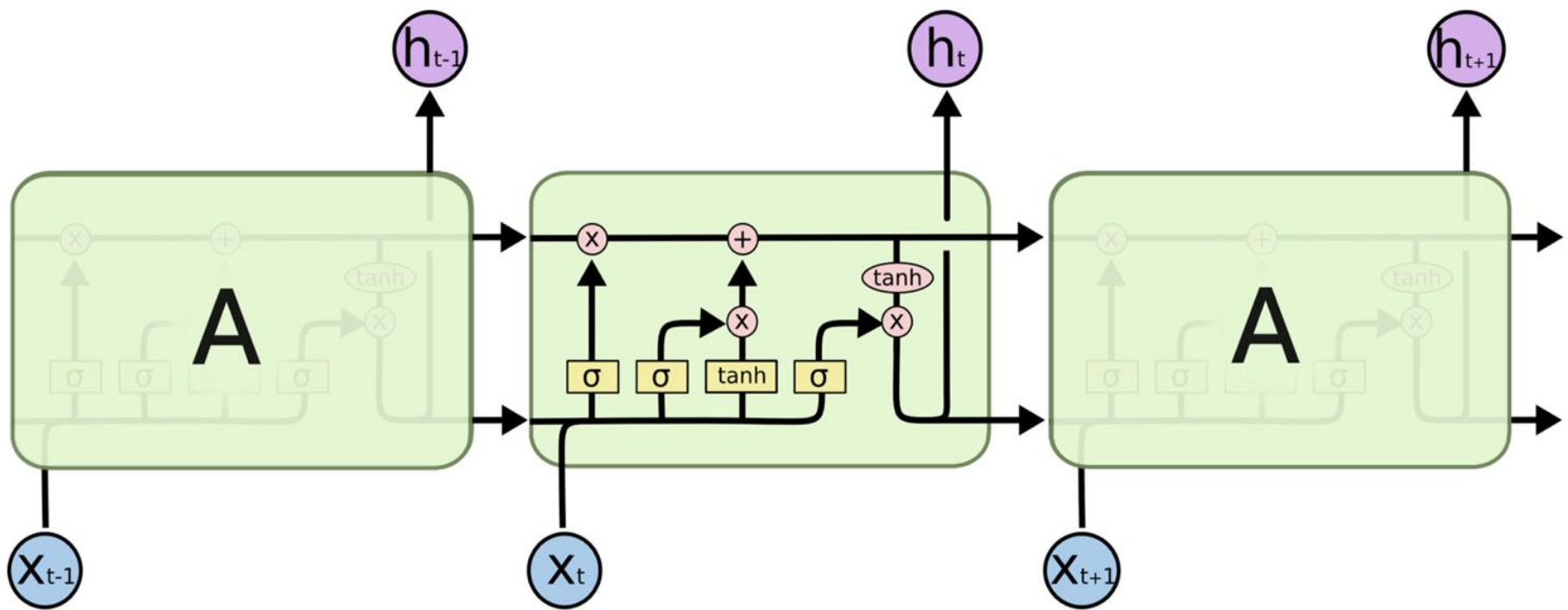


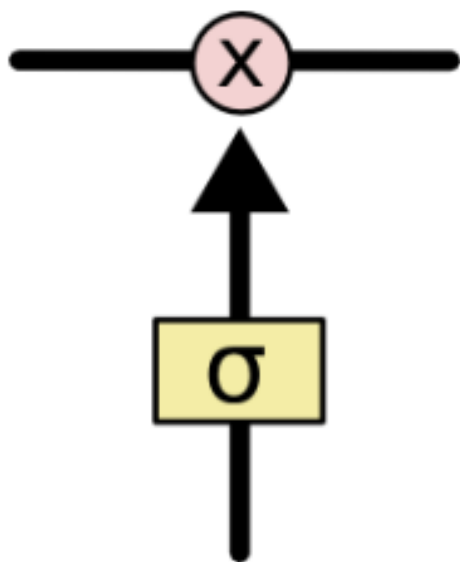
# LSTM

Long-short term memory Unit

# LSTM

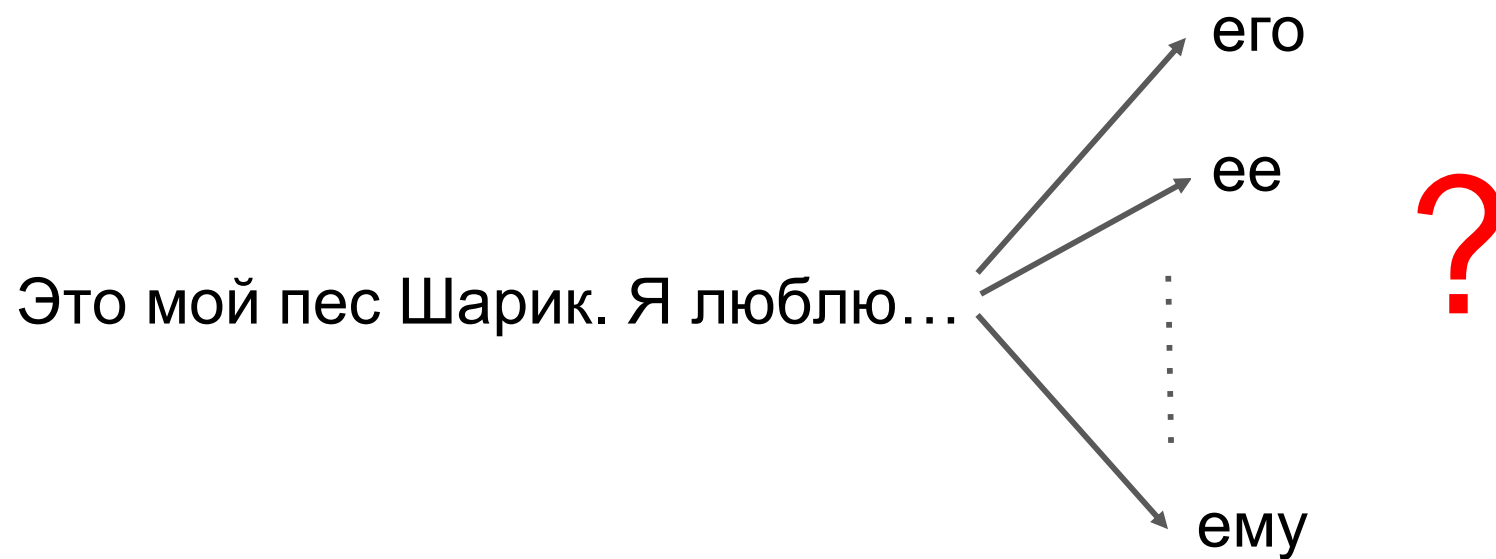


# LSTM Gates

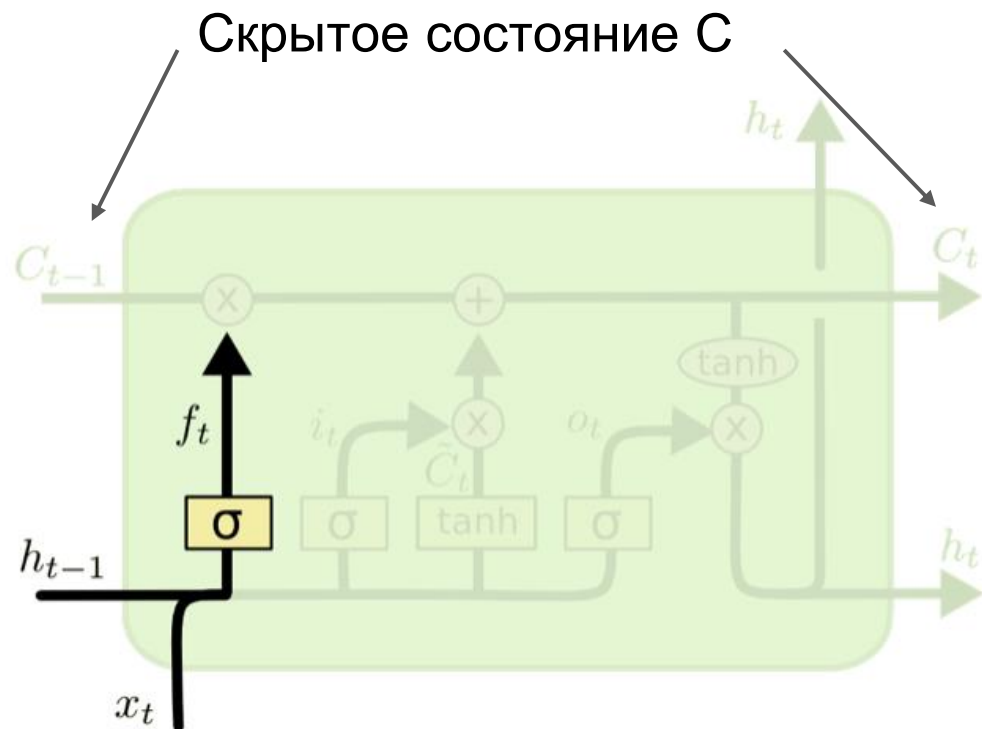


$$f_t = \sigma(\mathbf{W}_f \cdot [h_{t-1}, x_t] + \mathbf{b}_f)$$

# LSTM Gates

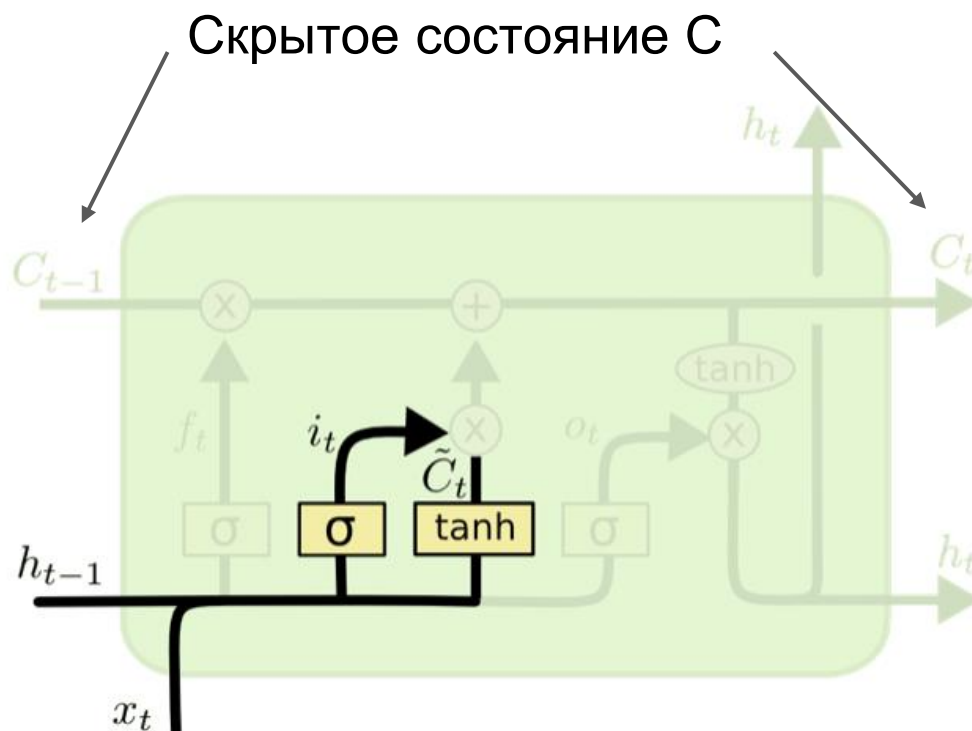


# LSTM Forget gate



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

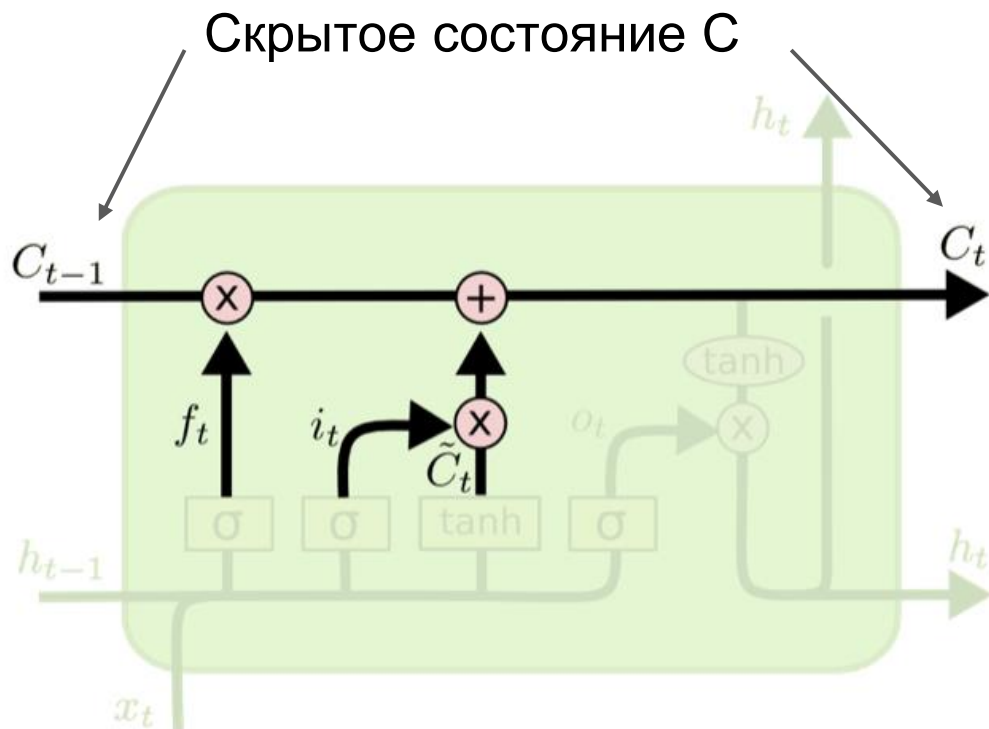
# LSTM Update gate



update gate: 
$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

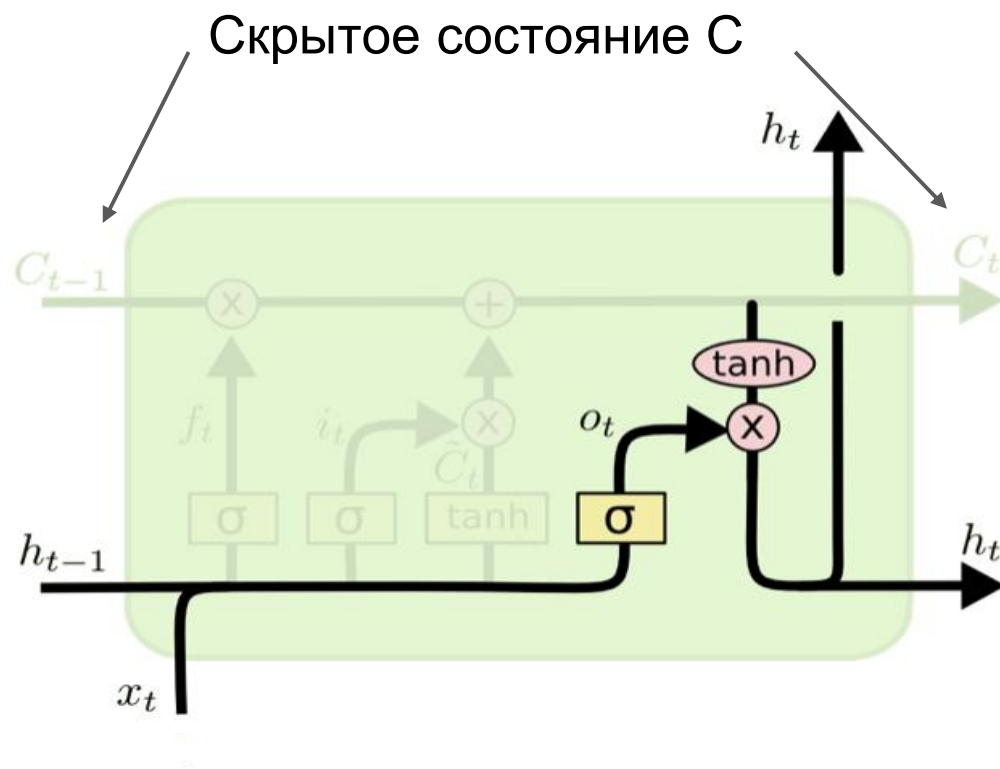
new information: 
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

# LSTM Hidden state



$$C_t = f_t \cdot C_{t-1} + i_t \cdot \tilde{C}_t$$

# LSTM Output

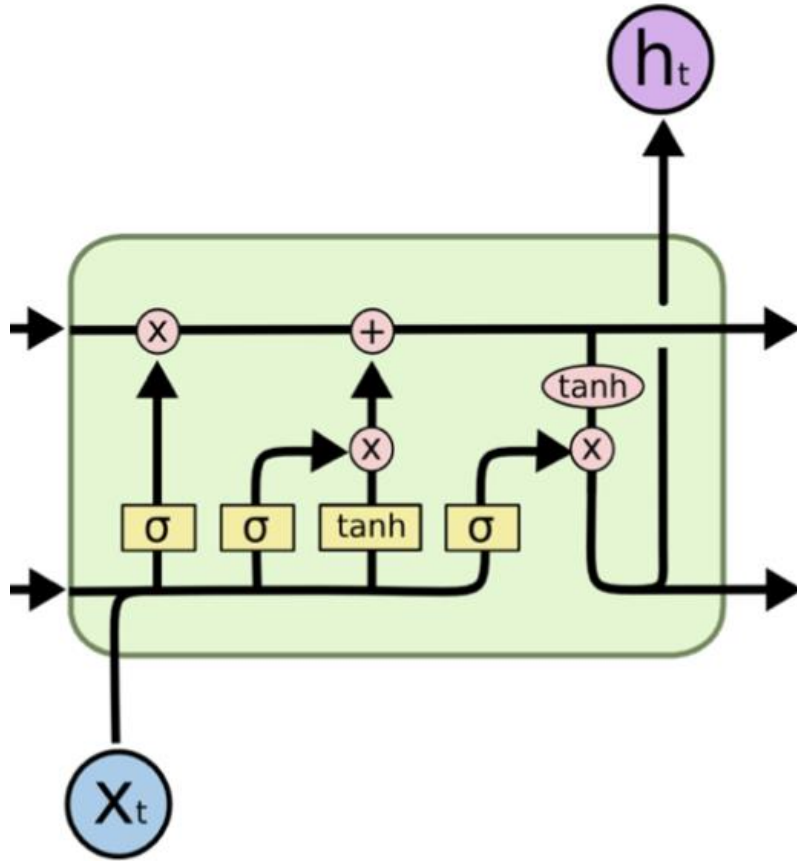


$$o_t = \sigma(W_o \cdot [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t \cdot \tanh(C_t)$$



# LSTM



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

$$C_t = f_t \cdot C_{t-1} + i_t \cdot \tilde{C}_t$$

$$o_t = \sigma(W_o \cdot [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t \cdot \tanh(C_t)$$