

Scene Understanding

INTERNSHIP REPORT

*Submitted in partial fulfillment of the
Requirement for the award of the
Degree of*

**BACHELOR OF ENGINEERING
IN
COMPUTER SCIENCE ENGINEERING**

By

**KOMPALLY AKSHATHA
(2451-21-733-001)
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Under the guidance of
Dr. Sudha Pelluri
Head of the Department of CSE,
College of Engineering, Osmania University



Maturi Venkata Subba Rao Engineering College
Nadergul, Saroornagar Mandal, Hyderabad, Telangana-501510

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This is to certify that Summer Training entitled “**Scene Understanding**” is a bonafide work carried out by **Kompally Akshatha (2451-21-733-001)** in partial fulfillment of the requirements for the award of degree of **Bachelor of Engineering in Computer Science and Engineering** from **Maturi Venkata Subba Rao(MVSR) Engineering College**, affiliated to Osmania University, Hyderabad during the Academic Year 2023-2024, under my guidance and supervision.

The results embodied in this report have not been submitted to any other university or institute for the award of any degree or diploma.

Head of the Department Dr.Sudha
Pelluri Professor & Head
Department of CSE College of
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DECLARATION

This is to certify that the work reported in the present project entitled “**Scene Understanding**” is a record of bonafide work done by us in the Department of Computer Science and Engineering, MVSR Engineering College, Osmania University. The reports are based on the work done entirely by us and not copied from any other source.

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Student
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(2451-21-733-001)

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Student
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SUBMITTED BY
KOMPALLY AKSHATHA
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ABSTRACT

This project introduces a Flask-based scene understanding application that seamlessly integrates cutting-edge object detection and image captioning models for an in-depth scene analysis. Leveraging the VisionEncoderDecoderModel from the Transformers library for generating detailed image captions and the YOLOv8 model for accurate object detection, this application provides both comprehensive textual descriptions and a list of detected objects, delivering a thorough understanding of each scene.

A standout feature of this application is its advanced image preprocessing pipeline, which includes techniques such as contrast enhancement and edge sharpening—approaches that are not commonly implemented in existing models. This preprocessing step significantly improves image quality, leading to more precise detection and captioning results.

Designed for versatility, the application can handle images of any size and resolution, including those from smart phones, without the need for resizing. This flexibility ensures that the models process the highest quality data, enhancing compatibility across a range of devices and scenarios.

Moreover, the application prioritizes accessibility by converting textual captions into spoken words using speech synthesis. This feature makes the information accessible to users with visual impairments, extending the application's usability and inclusivity.

In summary, this scene understanding application is distinguished by its integrated approach to object detection and captioning, advanced image preprocessing, ability to handle diverse image inputs, and commitment to accessibility. These attributes collectively enhance the application's effectiveness and broaden its reach, setting it apart from existing models in the field.

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1. INTRODUCTION

1.1 PROBLEM STATEMENT

Existing scene understanding systems often face limitations in providing a comprehensive analysis of images. Many rely on basic object detection and image captioning techniques that lack integration and fail to process images of varying sizes and resolutions effectively. These systems frequently overlook accessibility features, leaving users with visual impairments under served.

Current solutions may not include advanced preprocessing steps that could enhance image quality before analysis, and they often require images to be resized, potentially leading to a loss of detail and accuracy. There is a clear need for a more robust and inclusive solution that integrates detailed object detection, advanced image captioning, flexible image handling, and accessibility features to offer a complete and user-friendly scene understanding experience.

1.2 OBJECTIVES

- **Integrate Advanced Models** : Combine the VisionEncoderDecoderModel for detailed image captioning with YOLOv8 for precise object detection to provide a thorough analysis of scenes.
- **Enhance Image Quality** : Implement a sophisticated image preprocessing pipeline that includes contrast enhancement and edge sharpening to improve the quality of images before processing.
- **Support Flexible Image Handling** : Design the system to handle images of any size and resolution, including those captured from smart phones, without requiring resizing.
- **Improve Accessibility** : Incorporate text-to-speech synthesis to convert generated captions into spoken words, making the content accessible to users with visual impairments.
- **Deliver Comprehensive Results** : Provide both textual descriptions and a list of detected objects in the scene, ensuring a complete understanding of the image content.
- **Ensure Robustness and Usability** : Develop a user-friendly Flask-based web application that allows for seamless image uploads and captures, with reliable error handling and intuitive interfaces.

1.3 MOTIVATIONS

- **Enhanced Scene Understanding**: Traditional models often focus on either object detection or image captioning separately, limiting the depth of scene analysis. Integrating the VisionEncoderDecoderModel with YOLOv8 addresses this gap by providing both detailed captions and a list of detected objects, offering a more comprehensive understanding of visual content.

- **Improved Image Quality:** Many existing models do not address image preprocessing, which can affect detection and captioning accuracy. This project incorporates advanced preprocessing techniques to enhance image contrast and sharpness, improving the quality of inputs and potentially leading to more precise results.
- **Versatility and Adaptability:** With the increasing use of smart phones and various image sources, handling images of any size and resolution is crucial. This project's ability to process images from diverse devices without resizing ensures adaptability and usability across different contexts.
- **Accessibility:** There is a significant need for technology that supports users with visual impairments. By integrating text-to-speech functionality, this project ensures that image captions are accessible to a broader audience, promoting inclusivity and making advanced scene understanding technology available to those who might otherwise be excluded.
- **User-Centric Approach:** The project's design considers real-world applications and user needs, focusing on both technical improvements and accessibility features. This User-Centric approach aims to enhance the overall user experience and extend the application's impact.

1.4 SCOPE

The scope of the scene understanding in the provided Flask application encompasses several key functionalities designed to enhance image analysis through advanced AI techniques. The application integrates VisionEncoderDecoderModel for generating descriptive captions and YOLOv8 for object detection, providing a comprehensive understanding of the scene captured or uploaded by the user. By preprocessing images to enhance contrast and sharpen edges, the application ensures that the visual inputs are optimized for accurate analysis.

The image captioning model generates detailed captions by analyzing visual features, while the YOLO model identifies and labels objects within the scene. The combination of these technologies allows for a dual output: a textual description of the scene and a list of detected objects, which are then merged into a single, cohesive caption. This dual approach not only aids in providing a more nuanced understanding of the scene but also enhances accessibility by generating speech output via gTTS, catering to users with visual impairments.

Moreover, the application supports image inputs of various sizes and resolutions, ensuring flexibility in usage across different devices. The processed images, along with their corresponding captions and detected objects, are displayed on a result page, offering a user-friendly interface for interacting with the analyzed data. This makes the application highly versatile, applicable in domains such as automated image annotation, accessibility tools for the visually impaired, and intelligent content management systems.

2. SYSTEM REQUIREMENT SPECIFICATIONS

2.1 SOFTWARE REQUIREMENTS

Web Development Framework

Flask : A Python-based micro web framework ideal for building web applications. It provides simplicity and flexibility for developing APIs and serving user interfaces.

Scene Understanding

- **Vision Transformer (ViT)** : A transformer-based model designed for image classification by treating images as sequences of patches. Utilized for extracting features from images before feeding them into language models for caption generation.
- **YOLOv8 (You Only Look Once, Version 8)** : An advanced object detection model for real-time detection of objects within images. YOLOv8 provides high accuracy and efficiency in detecting and classifying objects.
- **GPT-2** : A large-scale language model capable of generating human-like text. When combined with ViT, GPT-2 processes extracted image features to generate descriptive captions.
- **gTTS (Google Text-to-Speech)** : A library for converting text generated by GPT-2 into spoken audio, enhancing accessibility and providing auditory feedback.

Supporting Libraries

- **PyTorch** : A deep learning library used for training and deploying neural networks, including implementations of ViT and YOLOv8 models. It supports GPU acceleration and is integral for model inference and fine-tuning.
- **Transformers (Hugging Face)** : A library for working with transformer-based models like GPT-2. It provides pre-trained models, utilities for fine-tuning, and tools for efficient model inference.
- **OpenCV** : A library for advanced image processing tasks within the Flask application. It is used for operations such as image resizing, manipulation, and preparation for object detection.
- **Pillow (PIL)** : A library for basic image processing tasks such as loading, transforming, and saving images. It prepares images before they are processed by ViT and YOLOv8.

- **NumPy** : A library for numerical operations in Python. It supports various data manipulations and is essential for handling image data arrays.
- **Ultralytics** : The ultralytics package is a Python library that provides tools and functionalities for implementing the YOLO (You Only Look Once) family of models, which are popular for real-time object detection

Development Tools

IDE/Code Editor : Integrated Development Environments (IDEs) or code editors like VSCode, PyCharm, or similar tools for writing and managing code.

2.2 HARDWARE COMPONENTS

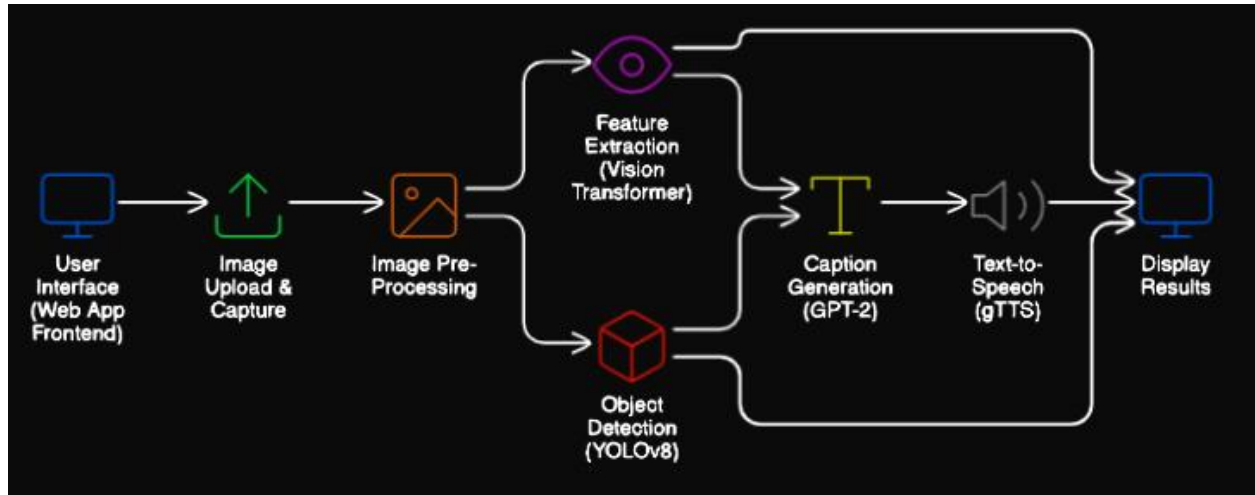
- **CPU**: Multi-core processor (e.g., Intel Core i7 or AMD Ryzen 7) to efficiently handle image processing, object detection, and web server tasks
- **RAM**: Minimum 16 GB to support smooth operation of machine learning models and handle concurrent user requests. More RAM (32 GB) may be needed for larger datasets and more intensive tasks.
- **Storage**: SSD (Solid State Drive) for fast read/write speeds and improved performance, crucial for managing large image datasets and model files.
- **GPU**: High-performance GPU with CUDA support (e.g., NVIDIA RTX 3060 or higher) for accelerated deep learning model training and inference. For large-scale deployments, consider GPUs like NVIDIA RTX 4090 or A100 for enhanced processing power.
- **Network**: Reliable and high-speed internet connection to support web application hosting and efficient handling of user interactions, especially for cloud-based or remote server deployments.

These components will provide the necessary infrastructure to effectively run and scale your scene understanding application with object detection and image captioning. They ensure efficient processing, fast data access, and responsiveness to user interactions, allowing for smooth operation and scalability of the web application and machine learning models.



3.SYSTEM DESIGN

3.1 SYSTEM ARCHITECTURE / BLOCK DIAGRAM



The diagram illustrates the architecture of a scene understanding application that integrates image captioning and object detection. It begins with the **User Interface (Web App)**, where users upload or capture images. This interface communicates with the **Flask Server**, which manages requests and orchestrates the processing workflow.

Uploaded images are first handled by the **Image Upload & Capture Service**, which prepares the images for further processing. The preprocessed images are then sent to the **Image PreProcessing Service** for tasks such as resizing and normalization.

Next, the images are analyzed by the **Feature Extraction and Object Detection Service**. Here, models like Vision Transformer (ViT) and YOLOv8 are employed to extract features and detect objects within the images. These detected objects and features are used by the **Caption Generation Service**, which leverages the GPT-2 model to generate descriptive captions based on the image content.

The generated captions are then converted into spoken audio by the **Text-to-Speech (TTS) Service** using gTTS (Google Text-to-Speech). Finally, the audio file is returned to the user through the **Flask Server**, which completes the process by delivering the audio back to the Web App.

This architecture efficiently integrates image processing, object detection, and speech synthesis to provide users with detailed, spoken descriptions of their images. The seamless flow from image upload to audio output demonstrates a robust and user-friendly solution for automated scene understanding.

4.IMPLEMENTATION

4.1 ENVIRONMENTAL SETUP

- **Frameworks:** Flask is a suitable choice for developing the backend of scene understanding applications due to its lightweight and flexible nature. It allows for efficient API development and web server management.
- **Programming Languages:** Python is preferred for its extensive support for machine learning and computer vision libraries. It enables seamless integration of image captioning, object detection, and speech synthesis functionalities.
- **Version Control:** Git is crucial for managing source code and collaboration among team members. Platforms like GitHub or GitLab help in version control, code reviews, and collaborative development.
- **Development Environment:** Integrated Development Environments (IDEs) such as PyCharm or Visual Studio Code offer powerful tools for coding, debugging, and managing dependencies. They streamline development processes and improve productivity.
- **Python Libraries:** Essential libraries include:
 - ◆ **PyTorch** for deep learning model training and inference.
 - ◆ **Transformers** for leveraging pre-trained models like Vision Transformer (ViT) and GPT-2.
 - ◆ **OpenCV** for image processing and manipulation tasks.
 - ◆ **Pillow (PIL)** for image loading and transformations.
 - ◆ **gTTS** for converting text captions into speech.

This setup ensures a robust and efficient development environment for building and deploying a scene understanding application, integrating image captioning and object detection features.

4.2 Model Architecture

Vision Transformer (ViT)

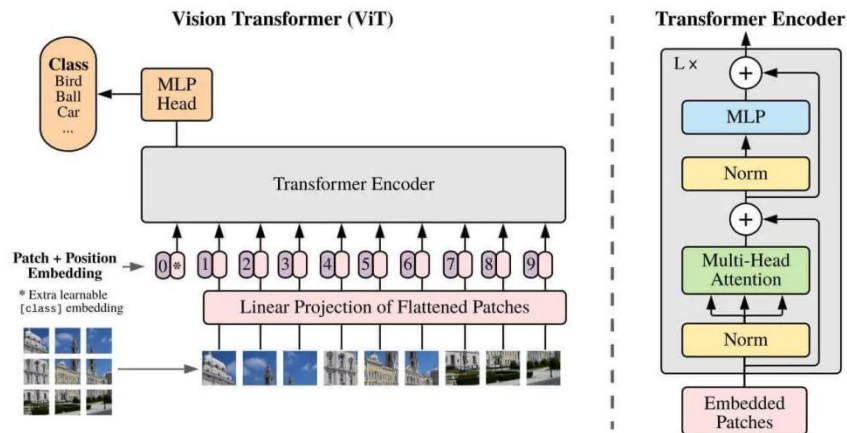


Fig: The Vision Transformer (ViT) architecture

The Vision Transformer (ViT) is a transformer-based model originally designed for image classification tasks, but it can also be adapted for tasks like image captioning. Here's a brief overview of the ViT architecture and its adaptation for image captioning:

Transformer Architecture: ViT applies the transformer architecture, which is widely used in natural language processing (NLP) tasks, to images. It consists of transformer blocks that process both spatial and positional information of image patches.

Input Representation: Unlike traditional convolutional neural networks (CNNs) that process images as grids of pixels, ViT splits the image into fixed-size patches and flattens each patch into a vector. These patch embeddings are then linearly embedded to form the input tokens for the transformer.

Positional Encoding: Since transformers do not inherently encode spatial information, ViT uses learned positional embeddings to inject spatial information about the patches' positions into the input tokens.

Transformer Encoder: The core of ViT consists of multiple transformer encoder blocks. Each block includes self-attention mechanisms to capture dependencies between different patches and feedforward neural networks for processing.

CLS Token: ViT uses a special learnable token called the "CLS" token, similar to its use in NLP transformers like BERT. This token aggregates information from the entire image and is used for classification tasks.

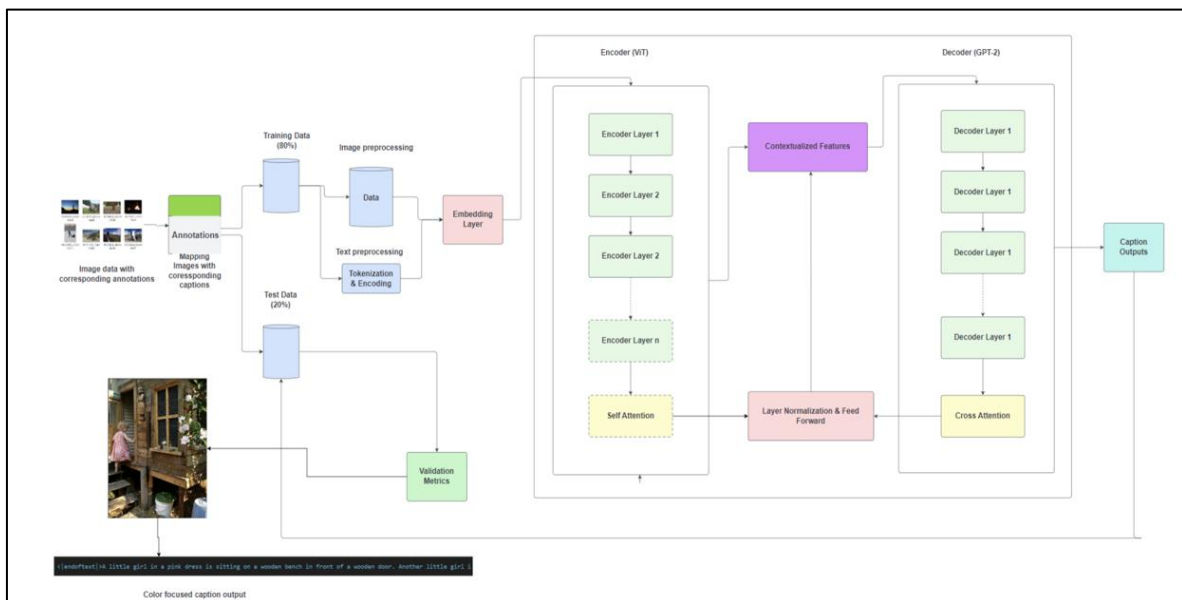
Adaptation for Image Captioning:

- **Encoding Images:** ViT can be adapted for image captioning by using the final hidden state of the CLS token or other tokens for context aggregation across patches.
- **Generating Captions:** Post-encoding, a decoder component can be added to generate captions. This decoder typically involves additional transformer layers or recurrent neural networks (RNNs) to produce sequences of words that describe the image content.

Training: ViT for image captioning requires pre-training on large-scale image datasets (e.g., ImageNet) followed by fine-tuning on captioning-specific datasets (e.g., COCO) to optimize performance for generating accurate and relevant captions.

Advantages: ViT offers several advantages such as scalability to larger image sizes, ability to capture long-range dependencies, and flexibility in handling various image-related tasks beyond classification, including captioning.

Adopting ViT for image captioning involves integrating its encoder with a suitable decoder architecture to handle the sequence generation aspect effectively, ensuring coherence and relevance in generated captions.



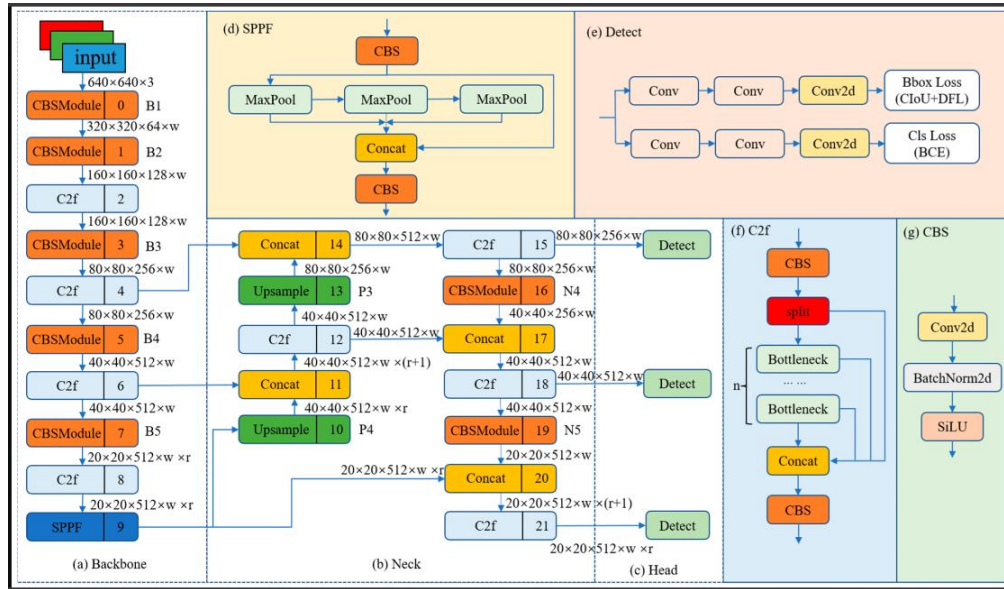
YOLOv8

What is Architecture of YOLOv8?

- The architecture of YOLOv8, or You Only Look Once version 8, is a state-of-the-art object detection model that builds upon the success of its predecessors. YOLOv8 is

known for its efficiency and accuracy in real-time object detection tasks, making it widely adopted in various computer vision applications.

- The architecture is designed to address the limitations of previous YOLO versions while maintaining a balance between speed and precision.
- One notable improvement in YOLOv8 is its modular and scalable design. The model is divided into three main components: the backbone, neck, and head. The backbone is responsible for extracting features from the input image, and YOLOv8 employs a variety of backbones, including CSPDarknet53 and EfficientDet.
- The neck connects the backbone to the head and is crucial for feature fusion. The head is responsible for predicting bounding boxes, object classes, and confidence scores.
- Another key aspect of YOLOv8's architecture is its focus on model scaling. YOLOv8 offers different variants, such as YOLOv8-tiny and YOLOv8x, which vary in size and computational complexity. This allows users to choose a model that fits their specific requirements, whether it be for resource-constrained environments or high-performance applications.
- YOLOv8 also introduces advancements in training strategies, incorporating techniques like Rectified Adam (RAdam) optimization and the use of anchor-based or anchor-free object detection. These improvements contribute to faster convergence during training and enhanced performance in object detection tasks.
- Moreover, YOLOv8 has a flexible configuration system that allows users to easily customize various parameters, such as input size, anchor boxes, and model complexity. This flexibility makes YOLOv8 adaptable to diverse datasets and application scenarios.
- The architecture of YOLOv8 is characterized by its modular design, scalable variants, improved backbones, and advanced training strategies. These features collectively contribute to its success in real-time object detection, making it a popular choice for researchers and practitioners in the field of computer vision.



Key Features of YOLOv8 Architecture

YOLOv8, or You Only Look Once version 8, is an object detection model that builds upon its predecessors to improve accuracy and efficiency. Here are some key features of the YOLOv8 architecture:

● Backbone Network

- YOLOv8 employs a feature-rich backbone network as its foundation. The network serves to extract hierarchical features from the input image, providing a comprehensive representation of the visual information.
- YOLOv8 utilizes CSPDarknet53, a modified version of the Darknet architecture, as its backbone. This modification incorporates Cross Stage Partial networks, enhancing the learning capacity and efficiency.

● Neck Architecture

- The architecture includes a novel neck structure, which is responsible for feature fusion. This is crucial for combining multi-scale information and improving the model's ability to detect objects of varying sizes.
- YOLOv8 introduces PANet (Path Aggregation Network), a feature pyramid network that facilitates information flow across different scales. PANet enhances the model's ability to handle objects with diverse scales in a more effective manner.

- YOLO Head

- YOLOv8 retains the characteristic feature of the YOLO series – the YOLO head. This component generates predictions based on the features extracted by the backbone network and the neck architecture.
- The YOLO head predicts bounding box coordinates, objectness scores, and class probabilities for each anchor box associated with a grid cell. The architecture uses anchor boxes to efficiently predict objects of different shapes and sizes.

- Training Techniques

- YOLOv8 leverages advancements in training strategies to improve convergence speed and model performance. MixUp, a data augmentation technique, is employed to create linear interpolations of images, enhancing the model's generalization capabilities.
- Additionally, YOLOv8 utilizes a cosine annealing scheduler for learning rate adjustments during training, contributing to more stable convergence.

- Model Variants

- YOLOv8 is available in different variants, each designed for specific use cases. YOLOv8-CSP, for instance, focuses on striking a balance between accuracy and speed.
- YOLOv8x-Mish, another variant, employs the Mish activation function for improved non-linearity, leading to better generalization and performance.

- YOLOv8 Performance

- YOLOv8 has demonstrated remarkable improvements in terms of accuracy and speed compared to its predecessors. With superior real-time object detection capabilities, YOLOv8 has become a popular choice in various applications, including robotics, surveillance, and augmented reality.
- These features collectively contribute to making YOLOv8 a versatile and efficient object detection model for various applications, from real-time systems to high-accuracy scenarios.



Adaptation for Image Captioning

- **Object Detection**
YOLOv8: Detects and localizes objects in the image, providing bounding boxes and class labels.
- **Feature Integration**
Feature Encoding: Converts detected object features into a format suitable for captioning.
- **Caption Generation**
Language Model: Uses a transformer-based model (e.g., GPT-2) to generate descriptive captions based on detected objects and their context.
- **Post-Processing**
Refinement: Enhances and formats captions for accuracy and coherence.

Advantages

- **Accuracy:** YOLOv8's precise object detection improves caption quality.
- **Real-Time:** Fast inference for timely caption generation.
- **Contextual Descriptions:** Generates detailed captions that include object interactions and scene context.
- **Scalability:** Efficient for handling large image datasets.
- **User Experience:** Provides informative and contextually relevant descriptions.
- **Versatility:** Adaptable to various domains and applications.

4.2.1 Frontend Development

Home Page (home.html):

Purpose: This is the landing page of the web application, offering two primary Functionalities which are uploading an image or capturing an image using the webcam.

Design:

- The page features a visually appealing design with a linear gradient background.
- It contains a central container with two buttons: "Upload Image" and "Capture Image".
- The container has hover effects for interactivity, enhancing user

Upload Image Page (index.html):

Purpose: This page allows users to upload an image from their local device for captioning.

Design:

- A clean, responsive design with a linear gradient background.
- The page includes an upload form where users can select an image file and submit it.
- It has an animated container for the upload form, providing a smooth user experience.
- Additional UI elements like animated background and hover effects on the image and buttons.

Capture Image Page (index1.html):

Purpose: This page allows users to capture an image using their webcam for captioning.

Design:

- Similar visual style to the upload page, with a focus on webcam integration.
- Includes a video element displaying the webcam feed and a "Capture" button to take a snapshot.
- Captured images are automatically submitted for processing.

Result Page (result.html):

Purpose: This page displays the results of the image captioning process, featuring both the uploaded or captured image and its generated caption with synthesized speech.

Design:

- **Image Display:** Shows the original uploaded or captured image and the processed image with any detected objects.

- **Caption:** Provides the generated caption text below the images.
- **Audio Player:** Includes a player for the synthesized speech of the caption.
- **Navigation Button:** A "Upload Another Image" button for users to return to the home page and restart the image processing.
- **Visual Style:** Utilizes a dynamic background and a central container with a clear and visually appealing layout to ensure a cohesive user experience.

4.1.2 Backend Development

Framework :

- **Flask:** A lightweight Python web framework for handling web requests and serving pages.

Image Upload and Processing :

- **File Handling:** Saves uploaded and captured images to specified directories.
- **Preprocessing:** Enhances images by converting to RGB, applying contrast adjustment, and sharpening edges.

Image Captioning :

- **Model:** Uses VisionEncoderDecoderModel (ViT-GPT2) from the transformers library for generating captions.
- **Feature Extraction:** Utilizes ViTFeatureExtractor to extract image features.
- **Tokenization:** Decodes generated captions with AutoTokenizer.
- **Device Management:** Loads the model on GPU if available, otherwise defaults to CPU.

Object Detection :

- **YOLO Model:** Uses YOLO for detecting objects in images.
- **Detection:** Identifies and lists objects in the image, saves processed images with object annotations.

Caption and Object Detection Integration :

- **Predict Step:** Processes images to generate captions and detect objects. Combines captions with detected objects for final output.

Speech Synthesis :

- **Text-to-Speech:** Converts captions to speech using gTTS (Google Text-to-Speech) and saves as an MP3 file.

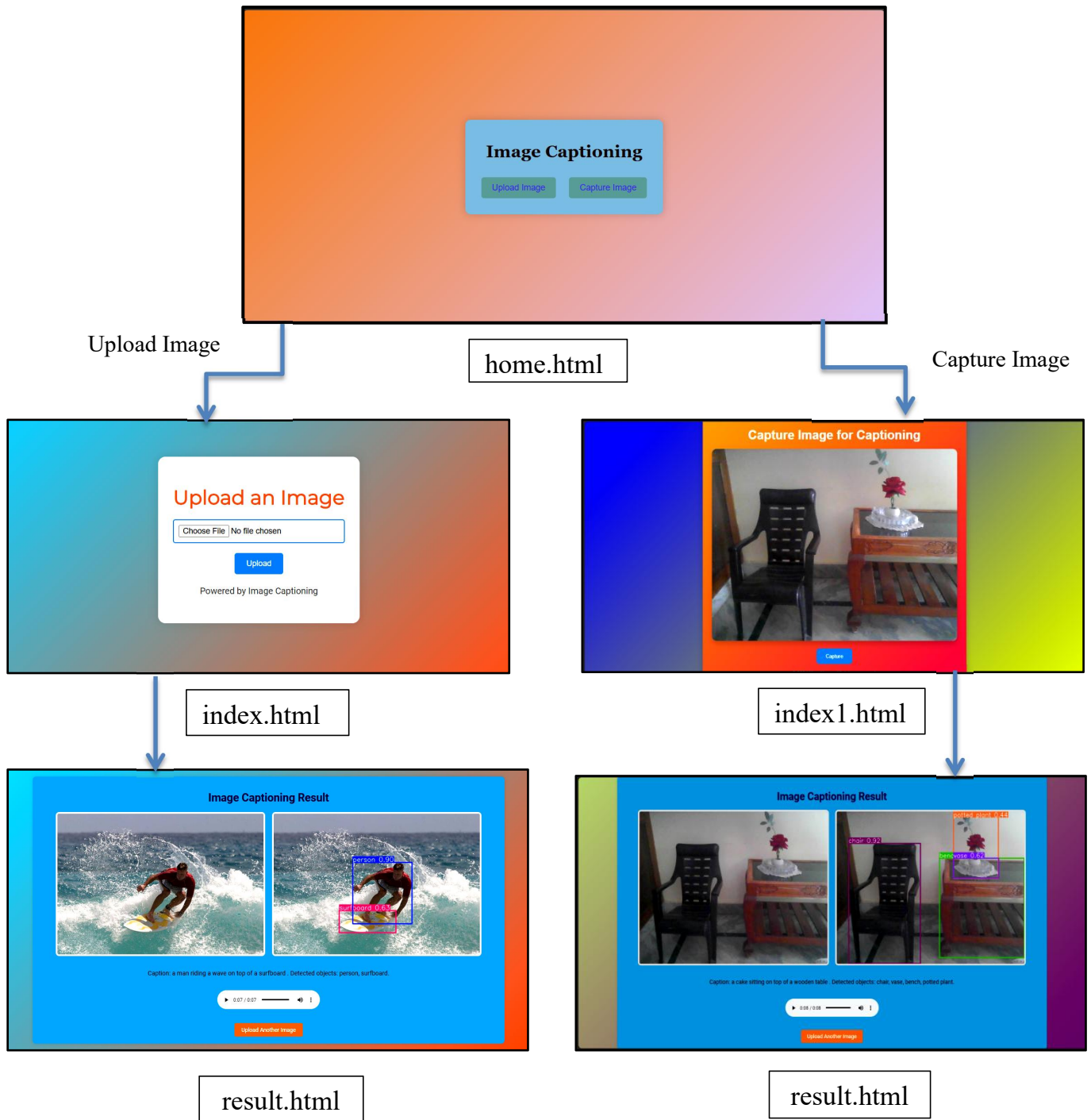
Routes and Handlers:

- **Home Route:** Displays the home page.
- **Upload Image Route:** Renders the image upload page.
- **Capture Image Route:** Renders the image capture page.
- **Upload Handler:** Processes uploaded images, generates captions, and redirects to the result page.
- **Capture Handler:** Processes captured images, generates captions, and redirects to the result page.

Result Presentation :

- **Dynamic Rendering:** Shows uploaded/captured image, processed image with detected objects, generated caption, and provides playback for synthesized speech.
- **URL Management:** Ensures proper linking and retrieval of image and audio files.

5.RESULTS



7. CONCLUSION

The Flask-based web application for image captioning and object detection exemplifies a robust integration of advanced AI technologies with practical web development. By leveraging the VisionEncoderDecoderModel (ViT-GPT2) for generating detailed captions and YOLO for object detection, the application provides a sophisticated solution for comprehensive image analysis.

Key Advantages:

- **Enhanced Accuracy and Detail:** The application employs ViT-GPT2 to produce contextually rich and accurate captions for images. When combined with YOLO's object detection capabilities, it identifies and labels objects within images, delivering a detailed understanding of the visual content.
- **Image Quality Improvement:** The preprocessing step enhances image clarity through contrast adjustment and edge sharpening. This ensures that the images processed by the AI models are of high quality, leading to more precise and reliable results in both captioning and object detection.
- **User-Friendly Interface:** Designed with accessibility in mind, the web interface allows users to easily upload or capture images. This intuitive design caters to users with various levels of technical expertise, making the application straightforward and user-friendly.
- **Comprehensive Output:** The application's result page displays both the original and processed images along with generated captions and detected objects. The incorporation of text-to-speech functionality (gTTS) provides an auditory output of the captions, enhancing accessibility for visually impaired users.
- **Versatile Functionality:** Supporting both image uploads and real-time captures via webcam, the application adapts to different user needs. Its efficient handling of file processing and real-time image analysis ensures a smooth and effective user experience.

In essence, this application successfully integrates cutting-edge machine learning models with a User-Centric design, offering a powerful tool for image analysis. Its accurate captioning, object detection, and accessible interface make it a valuable resource for various applications, from casual use to more specialized needs.

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9. APPENDIX

SOURCE CODE:

Refer to the source code at: [Scene-understanding](#) (GitHub)