

8. CONCLUSION & FUTURE WORK

In the existing system in the warehouse picking there are robots that can pick the items in the warehouse but there is no proper way to find out an optimal and minimal path to follow in picking those items.

Our warehouse picking system provides an optimal path by using the genetic algorithm and thereby providing an optimal path. It uses the distances between the items to provide a path. But we know if there are more number of items then it will be difficult for the fitness functions to process and it will take more time to provide a result. So the future work to be done is to work.