Robotics and Navigation in Medicine

Summer term 2015

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Robotics & Navigation in Medicine

Robotics

Navigation

Clinical Examples

basic principles

calibration

serial kinematics

kinematics

localization

parallel kinematics

paths & trajectories

image guidance

special robots

Robotics and Navigation in Medicine

IMAGE GUIDANCE



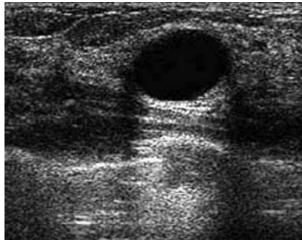
- So far we have considered tracking artificial markers
- Images of the patient (anatomy) can serve as a means for localization and visualization
 - Identify the target region (radiology, tumors, vessels, ...)
 - Identify natural landmarks (bones, skull, vertebrae, ...)
 - Measure motion and deformation



- A patient is no rigid object with a natural coordinate frame
- While we can easily scan / sense the outer perimeter of a patient, the true regions of interest are often inside
- We need to relate the robot to images of the patient
- Motion and deformation of the patient and the organs is still a challenge!



- Image modalities
 - Ultrasound (US): well established, realtime,
 2D(+3D), non-ionizing, medium to high resolution
 - 3D by motorized transducer, 2D array, or tracking





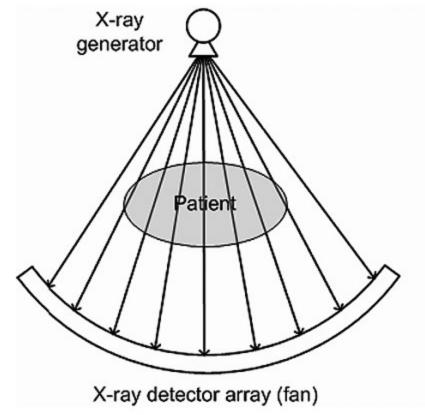


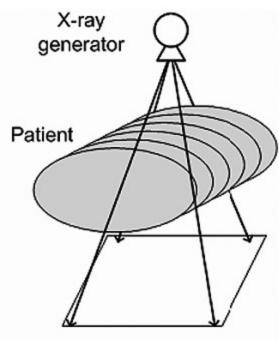
- Image modalities
 - X-ray: well established,
 realtime, 2D, ionizing,
 medium to high resolution,
 available in (almost) every
 OR





- Image modalities
 - Computed Tomography (CT): not-realtime, 3D, ionizing, medium to high resolution, typically available before treatment, sometimes in OR





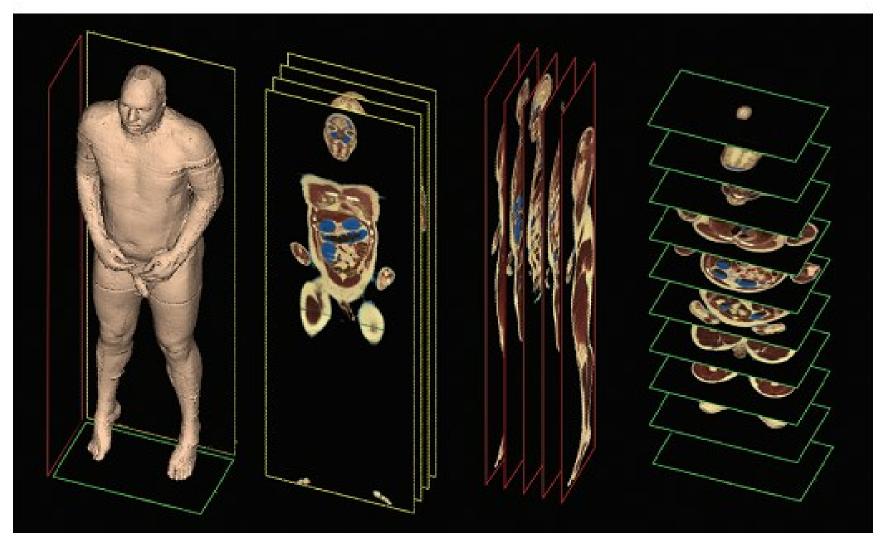
X-ray detector array (panel)



- Image modalities
 - Magnetic resonance imaging (MRI): limitedrealtime, 3D, nonionizing, medium to high resolution, typically available before treatment, sometimes in OR







Coronal

Sagittal

Transverse



Fiducial Localization Error (FLE)

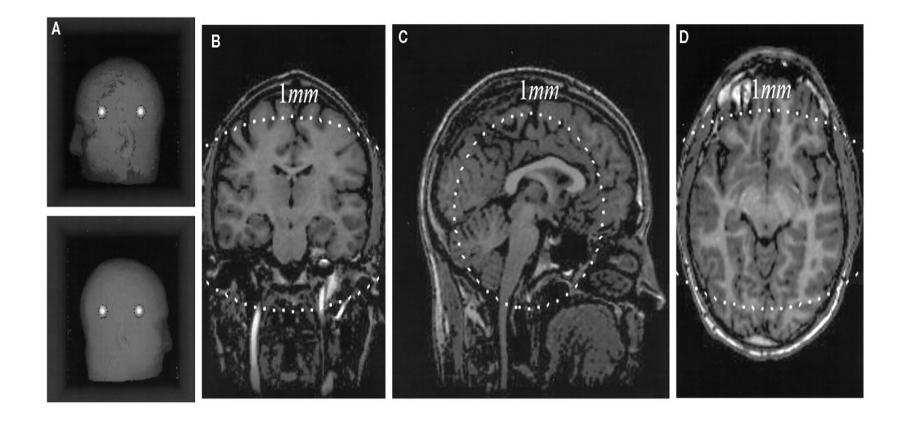


Fiducial Registration Error (FRE)

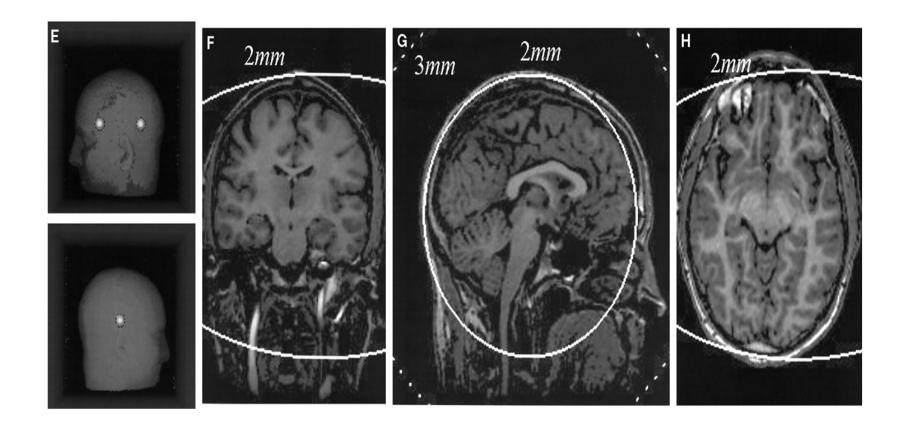


Target Registration Error (TRE)

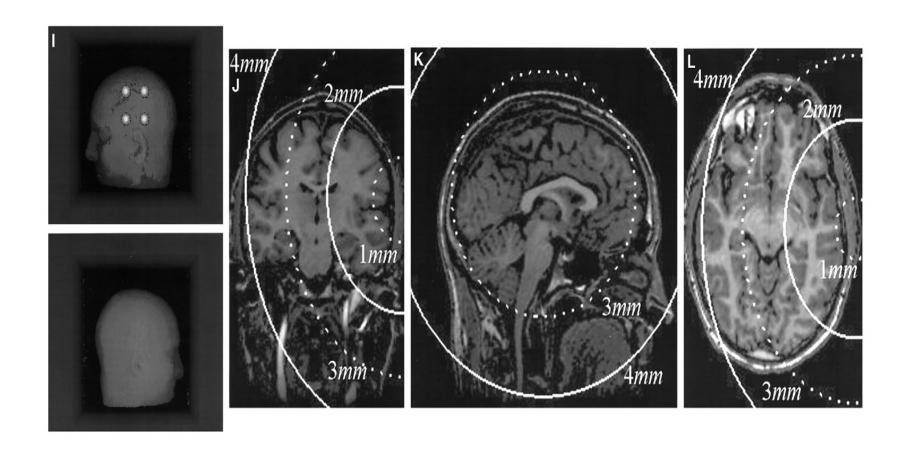




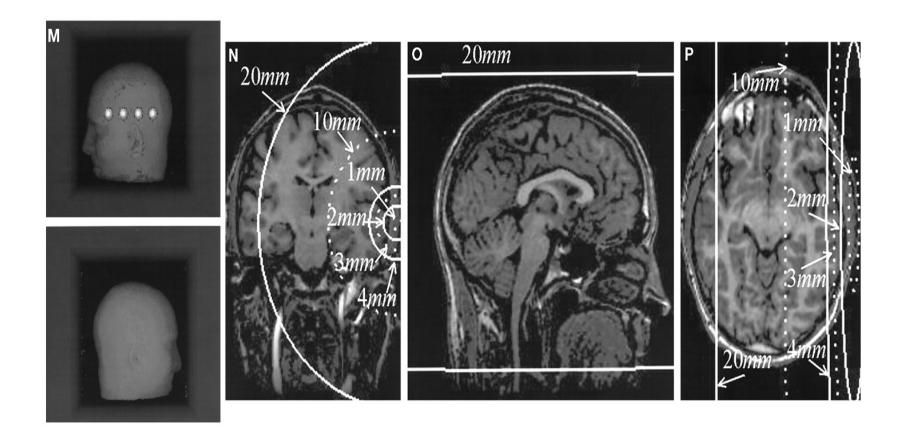


















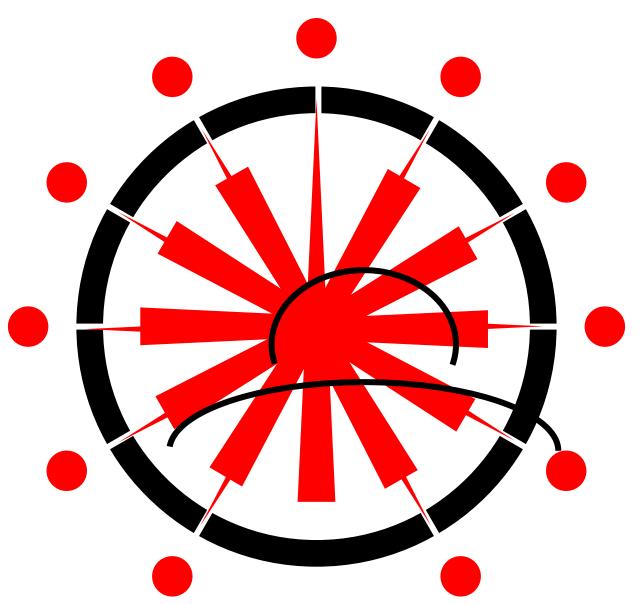


Non-invasive radiation

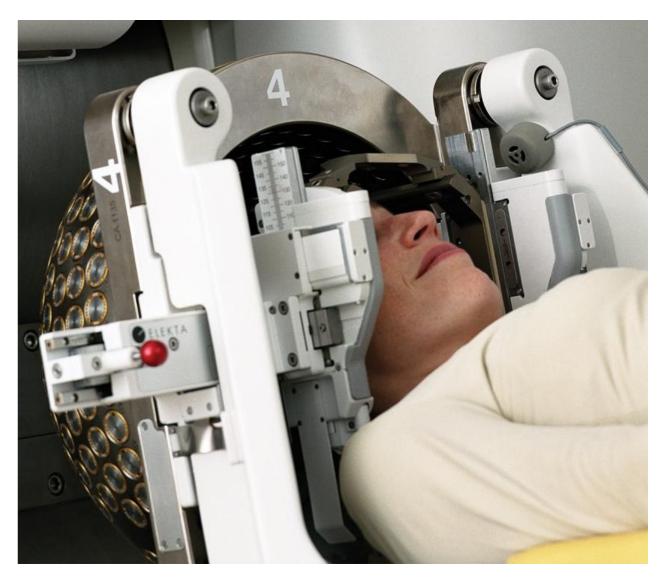
Fixation with stereotactic frame











http://images.elektagallery.com



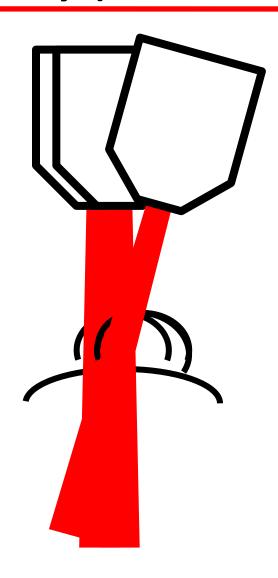


T. Viulet, F. Ernst, A.Schweikard, Accuray Inc.

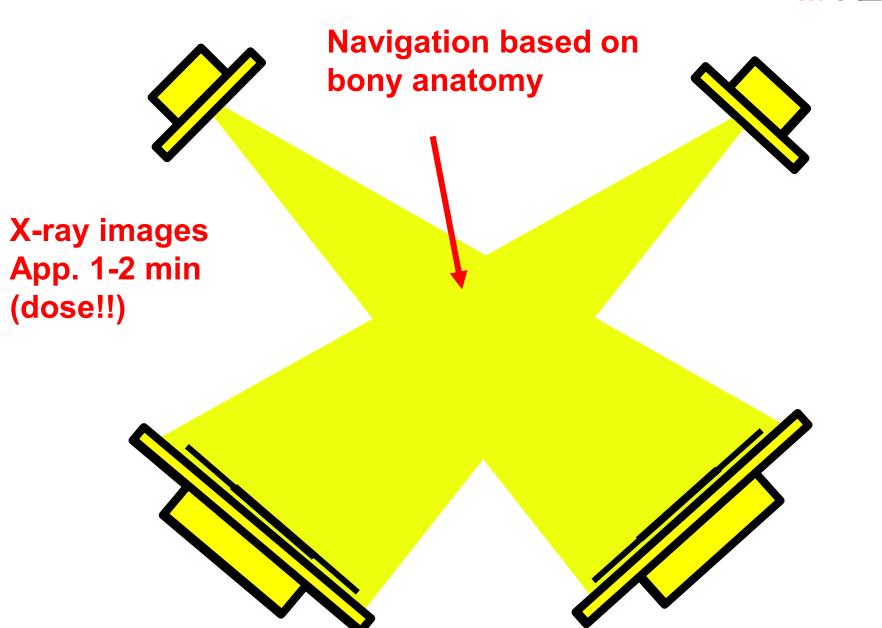




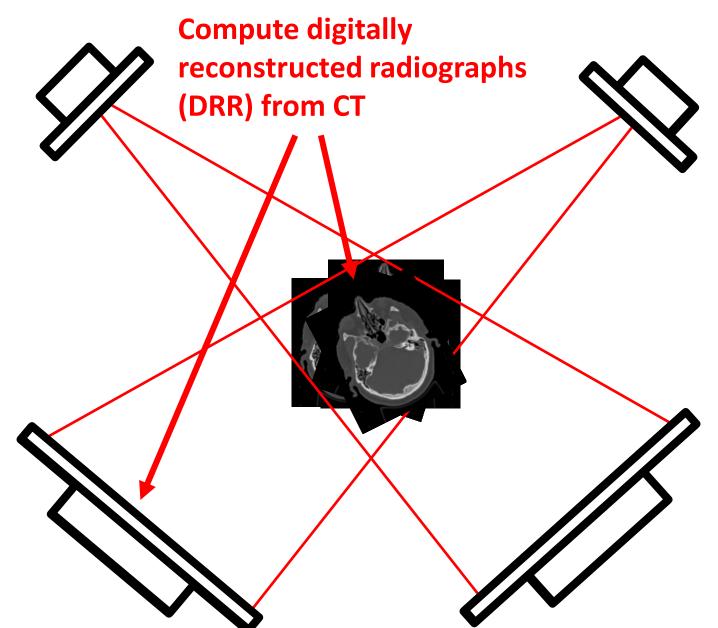




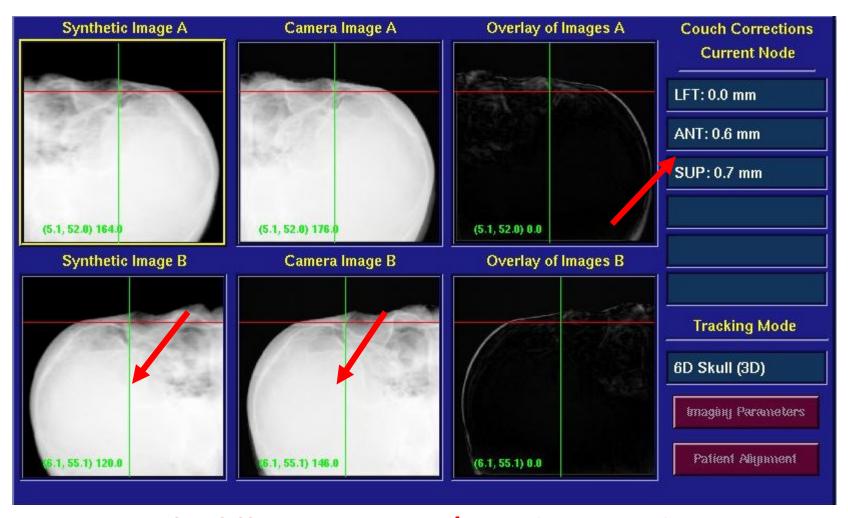












Compare DRRs for fifferent rotation / translation with actuaX-ray images: best fitting DRR yields offset angle / vector

Wikipedia

- Intro
 - X-ray
 - CT
 - MRI
 - US
 - -OCT
- Patient models
 - Voxels
 - Surfaces
 - Splines (NURBS)