

Day 2 - 1/18/2024

Unit Vectors

Vectors $\vec{i} = \langle 1, 0 \rangle$ and $\vec{j} = \langle 0, 1 \rangle$ both have the same length of $\|\vec{i}\| = \|\vec{j}\| = 1$

Finding the Unit Vector of \vec{v}

We can find the unit vector in the direction of \vec{v} by dividing \vec{v} by its magnitude.

Example:

$\vec{v} = \langle 3, 4 \rangle$, Unit vector of \vec{v} is:

$$\begin{aligned}\|\vec{v}\| &= \sqrt{3^2 + 4^2} = 5 \\ \frac{\vec{v}}{\|\vec{v}\|} &= \frac{\langle 3, 4 \rangle}{5} = \underline{\left\langle \frac{3}{5}, \frac{4}{5} \right\rangle}\end{aligned}$$

Vector from Angle α

Given an angle $\alpha = \frac{\pi}{3}$ and a length of the vector \vec{v} , $\|\vec{v}\| = 3$, we can use trigonometric identities to determine \vec{v} .

The unit vector of \vec{v} will necessarily be defined as $\langle \cos(\alpha), \sin(\alpha) \rangle$, we can then define the vector from before to be

$\vec{v} = \langle \|\vec{v}\| \cos(\alpha), \|\vec{v}\| \sin(\alpha) \rangle$. We can solve this to find \vec{v} :

$$\vec{v} = \left\langle 3 \cos\left(\frac{\pi}{3}\right), 3 \sin\left(\frac{\pi}{3}\right) \right\rangle = \underline{\left\langle \frac{3}{2}, \frac{3\sqrt{3}}{2} \right\rangle}$$

Examples of Vector-Valued Quantities

- Newtons ($N = \text{kg} \cdot \frac{m}{s^2}$)
- Velocity ($\frac{m}{s}$)
- Acceleration ($\frac{m}{s^2}$)
- Position (m)

3-Dimensional Vectors

3-Dimensional vectors contain an extra z component, making them defined as $\langle x, y, z \rangle$.

xy Planes

An important concept is the xy plane, a 2-dimensional slice along the z axis in a 3-dimensional space.

For any given plane will have the plane $P(x, y, z)$:

$$yz \text{ plane} \Leftrightarrow x = 0$$

$$xy \Leftrightarrow z = 0$$

$$zx \Leftrightarrow y = 0$$

For any given 3 points there is a plane. For example:

The three points $(1, 2, 3)$, $(-4, 4, 3)$, and $(-5, 3, 3)$:

Note that all points have $z = 3$, $\therefore z = 3$

$z = 3$ is the equation for a plane that contains these points

Length

The length of a 3-dimensional vector \overrightarrow{PQ} is defined as:

$$\sqrt{(P_x - Q_x)^2 + (P_y - Q_y)^2 + (P_z - Q_z)^2}$$

Midpoints

The midpoint of a *vector* \vec{v} is defined as:

$$\frac{\vec{v}}{2}$$

The midpoint of any segment PQ is defined as:

$$\left(\frac{P_x + Q_x}{2}, \frac{P_y + Q_y}{2}, \frac{P_z + Q_z}{2} \right)$$