Analysis of Algorithms 1 (Fall 2013) Istanbul Technical University Computer Eng. Dept.



Chapter 10
Elementary Data Structures

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Purpose

- Define dynamic sets and why they are needed, define dynamic set operations
- Review the elementary data structures to represent dynamic sets.
 - stacks
 - queues
 - linked lists
 - rooted trees

Outline

- dynamic sets
- dynamic set operations
- stacks
- queues
- linked lists
- array representation of linked lists
- array representation of rooted trees

Abstract Data Types (ADTs)

- ADT is a mathematically specified entity that defines a set of its instances, with:
 - a specific *interface* a collection of signatures of methods that can be invoked on an instance,
 - a set of axioms that define the semantics of the methods (i.e., what the methods do to instances of the ADT, but not how)

Dynamic Sets

- We will deal with ADTs, instances of which are sets of some type of elements.
 - The methods are provided that change the set
- We call such class of ADTs dynamic sets

Dynamic Set

- Set in mathematics
 - $-\{1, 2, 5, 4, 3, 6\}$
- Set in algorithms
 - Allow repetition in set elements: {1, 5, 4, 3, 6, 4}
 - Dynamic: can grow, shrink, or change over time
 - Set operations: insert, delete, test membership

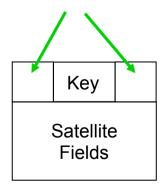
Elements of A Dynamic Set

- Each element is represented by an object (or record)
 - An object may consists of many fields
 - Need a pointer to an object to examine and manipulate its fields
 - Key field for identifying objects and for the set manipulation
 - Keys are usually drawn from a totally ordered set
 - Satellite fields: all the fields irrelevant for the set manipulation

```
Type Record patron {
  integer patron_ID;
  char[20] name;
  integer age;
  char[10] department;
  ...
}

Type patron p1, p2, p3, p4;
```

Other information relevant for set manipulation

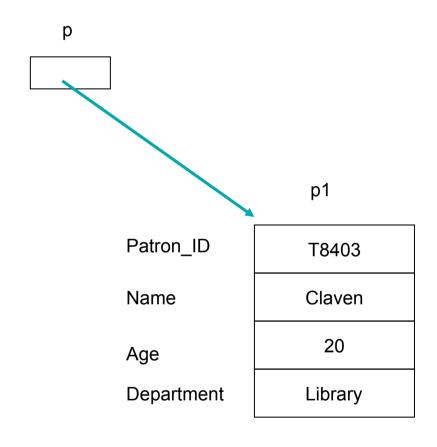


Record(Object) and Pointer

```
Type Record patron {
  integer patron_ID;
  char[20] name;
  integer age;
  char[10] department;
  ...
}
```

Type patron p1, p2, p3, p4;

Type patron *p;



Operations on Dynamic Sets

Query operations: return information about a set

- SEARCH(S, k): given a set S and key value k, returns a
 pointer x to an element in S such that key[x] = k, or NIL
 if no such element belongs to S
- MINIMUM(S): returns a pointer to the element of S with the smallest key
- MAXIMUM(S): returns a pointer to the element of S with the largest key
- SUCCESSOR(S, x): returns a pointer to the next larger element in S, or NIL if x is the maximum element
- PREDECESSOR(S, x): returns a pointer to the next smaller element in S, or NIL if x is the minimum element

Operations on Dynamic Sets (Cont.)

- Modifying operations: change a set
 - INSERT(S, x): augments the set S with the element pointed to by x. We usually assume that any fields in element x needed by the set implementation have already initialized.
 - DELETE(S, x): given a pointer x to an element in the set S, removes x from S.

Overview of Part III of CLRS Book

- Heap Chapter 6
- Elementary data structures Chapter 10
 - Stacks, queues, linked lists, root trees
- Hash tables Chapter 11
- Binary search trees Chapter 12
- Red-Black trees Chapter 13
- Augmenting Data Structures Chapter 14
- B-Trees Chapter 18

10.1. Stacks and Queues

STACK

- Stack
 - The element deleted from the set is the one most recently inserted
 - Last-in, First-out (LIFO)
- Stack operations
 - PUSH: Insert
 - DELETE: Delete
 - TOP: return the key value of the most recently inserted element
 - STACK-EMPTY: check if the stack is empty
 - STACK-FULL: check if the stack is full

Represent Stack by Array

- A stack of at most n elements can be implemented by an array S[1..n]
 - top[S]: a pointer to the most recently inserted element
 - A stack consists of elements S[1..top[S]]
 - S[1]: the element at the bottom of the stack
 - S[top[S]]: the element at the top

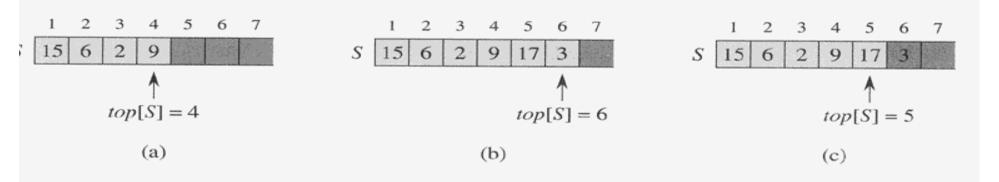


Figure 10.1 An array implementation of a stack S. Stack elements appear only in the lightly shaded positions. (a) Stack S has 4 elements. The top element is 9. (b) Stack S after the calls PUSH(S, 17) and PUSH(S, 3). (c) Stack S after the call POP(S) has returned the element 3, which is the one most recently pushed. Although element 3 still appears in the array, it is no longer in the stack; the top is element 17.

Stack Operations

```
STACK-EMPTY(S)

1 if top[S] = 0

2 then return TRUE

3 else return FALSE
```

```
Pop(S)

1 if STACK-EMPTY(S)

2 then error "underflow"

3 else top[S] \leftarrow top[S] - 1

4 return S[top[S] + 1]
```

```
PUSH(S, x)
1 \quad top[S] \leftarrow top[S] + 1
2 \quad S[top[S]] \leftarrow x
```

How to implement TOP(S), STACK-FULL(S)?

Stack Operations

STACK-EMPTY(S) 1 if top[S] = 0

- 2 then return TRUE
- 3 **else return** FALSE

```
PUSH(S, x)
1 \quad top[S] \leftarrow top[S] + 1
2 \quad S[top[S]] \leftarrow x
```

```
Pop(S)

1 if STACK-EMPTY(S)

2 then error "underflow"

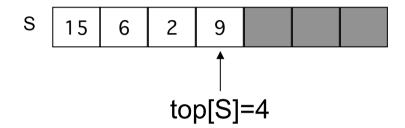
3 else top[S] \leftarrow top[S] - 1

4 return S[top[S] + 1]
```

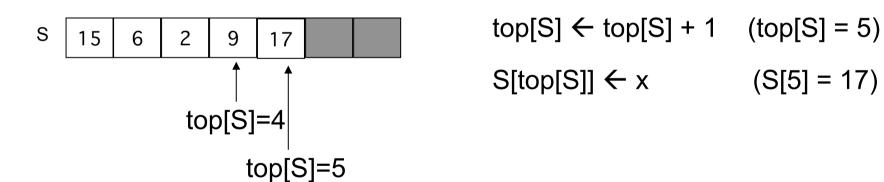
```
TOP(S)
if STACK-EMPTY(S)
   then return Error
   else return S[top[S]]

STACK-FULL(S)
if top[S] = n then
   then return TRUE
   else return FALSE
```

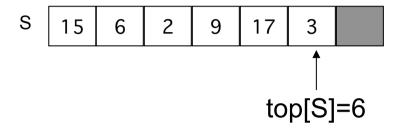
PUSH



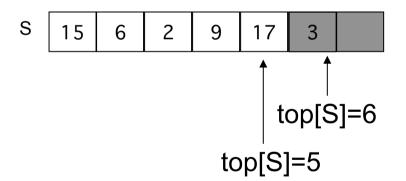
PUSH(S, 17)



POP



POP(S)



$$top[S] \leftarrow top[S] - 1 \quad (top[S] = 5)$$

QUEUE

- Queue
 - The element deleted is always the one that has been in the set for the longest time
 - First-in, First-out (FIFO)
- Queue operations
 - ENQUEUE: Insert
 - DEQUEUE: Delete
 - HEAD: return the key value of the element that has been in the set for the longest time
 - TAIL: return the key value of the element that has been in the set for the shortest time
 - QUEUE-EMPTY: check if the stack is empty
 - QUEUE-FULL: check if the stack is full

Represent Queue by Array

- A queue of at most n-1 elements can be implemented by an array S[1..n]
 - head[S]: a pointer to the element that has been in the set for the longest time
 - tail[S]: a pointer to the next location at which a newly arriving element will be inserted into the queue
 - The elements in the queue are in locations head[Q], head[Q]+1,
 ..., tail[Q]-1
 - The array is circular
 - Empty queue: head[Q] = tail[Q]
 - Initially we have head[Q] = tail[Q] = 1
 - Full queue: head[Q] = tail[Q] + 1 (in circular (modular) sense)

Illustration of A Queue

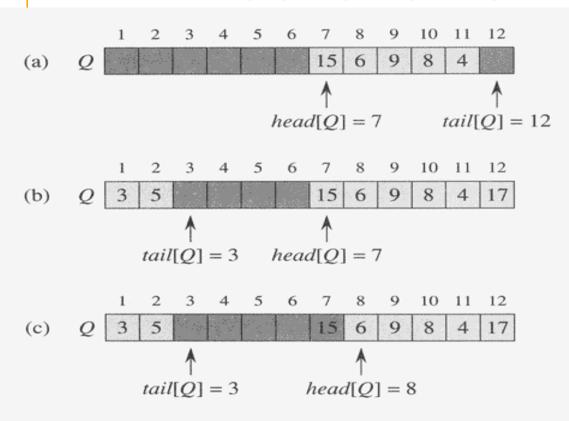


Figure 10.2 A queue implemented using an array Q[1..12]. Queue elements appear only in the lightly shaded positions. (a) The queue has 5 elements, in locations Q[7..11]. (b) The configuration of the queue after the calls $\mathsf{ENQUEUE}(Q, 17)$, $\mathsf{ENQUEUE}(Q, 3)$, and $\mathsf{ENQUEUE}(Q, 5)$. (c) The configuration of the queue after the call $\mathsf{DEQUEUE}(Q)$ returns the key value 15 formerly at the head of the queue. The new head has key 6.

Queue Operations

```
ENQUEUE(Q, x)

1 Q[tail[Q]] \leftarrow x

2 if tail[Q] = length[Q]

3 then tail[Q] \leftarrow 1

4 else tail[Q] \leftarrow tail[Q] + 1
```

```
DEQUEUE(Q)

1 x \leftarrow Q[head[Q]]

2 if head[Q] = length[Q]

3 then head[Q] \leftarrow 1

4 else head[Q] \leftarrow head[Q] + 1

5 return x
```

0(1)

10.2. Linked Lists

- A linked list is a data structure in which the objects are arranged in linear order
 - The order in a linked list is determined by pointers in each object
- Doubly linked list
 - Each element is an object with a key field and two other pointer fields: next and prev, among other satellite fields.
 Given an element x
 - next[x] points to its successor
 - if x is the last element (called tail), next[x] = NIL
 - prev[x] points to its predecessor
 - if x is the first element (called head), prev[x] = NIL
 - An attribute head[L] points to the first element of the list
 - if head[L] = NIL, the list is empty

Linked Lists (Contd)

- Singly linked list: omit the prev pointer in each element
- Sorted linked list: the linear order of the list corresponds to the linear order of keys stored in elements of the list
 - The minimum element is the head
 - The maximum element is the tail
- Circular linked list: the prev pointer of the head points to the tail, and the next pointer of the tail points to the head

Illustration of A Doubly Linked List

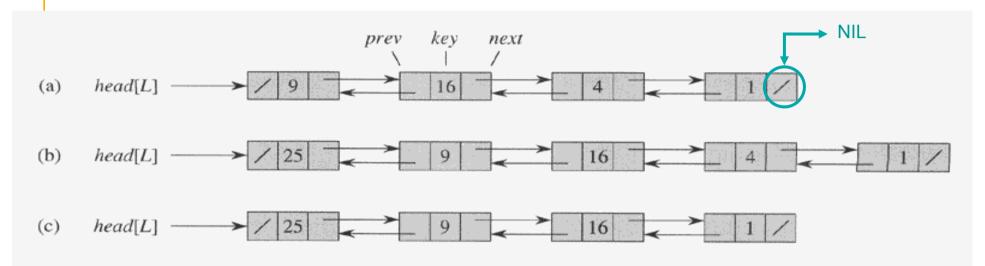
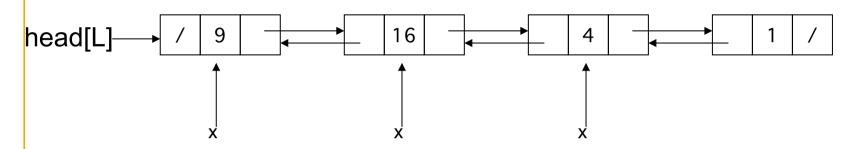


Figure 10.3 (a) A doubly linked list L representing the dynamic set $\{1, 4, 9, 16\}$. Each element in the list is an object with fields for the key and pointers (shown by arrows) to the next and previous objects. The *next* field of the tail and the *prev* field of the head are NIL, indicated by a diagonal slash. The attribute head[L] points to the head. (b) Following the execution of LIST-INSERT(L, x), where key[x] = 25, the linked list has a new object with key 25 as the new head. This new object points to the old head with key 9. (c) The result of the subsequent call LIST-DELETE(L, x), where x points to the object with key 4.

Searching A Linked List

- LIST-SEARCH(L, k): finds the first element with key k in list L by a simple linear search, returning a pointer to this element
 - If no object with key k appears in the list, then NIL is returned
- LIST-SEARCH(L, k)
- 1 x ← head[L]
- 2 while x ≠ NIL and key[x] ≠ k
- $3 \text{ do } x \leftarrow \text{next}[x]$
- 4 return x

LIST-SEARCH



LIST-SEARCH(L, 4)

How about LIST-SEARCH(L, 7)?

```
LIST-SEARCH(L, k)

1 x \leftarrow head[L]

2 while x \neq NIL and key[x] \neq k

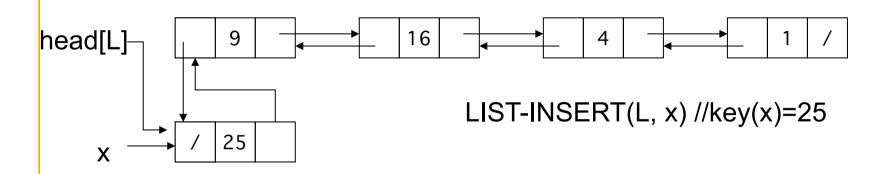
3 do x \leftarrow next[x]

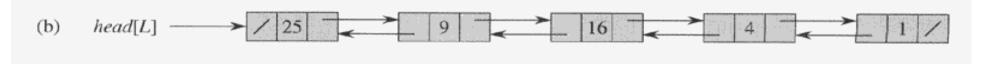
4 return x
```

Inserting Into A Linked List

- LIST-INSERT(L, x): given an element pointed by x, splice x onto the front of the linked list
- LIST-INSERT(L, x)
- 1 next[x] ← head[L]
- 2 if head[L] ≠ NIL
- 3 then prev[head[L]] ← x
- 4 head[L] ← x
- 5 prev[x] ← NIL

Illustration of LIST-INSERT





```
LIST-INSERT (L, x)

1 next[x] \leftarrow head[L]

2 if head[L] \neq NIL

3 then prev[head[L]] \leftarrow x

4 head[L] \leftarrow x

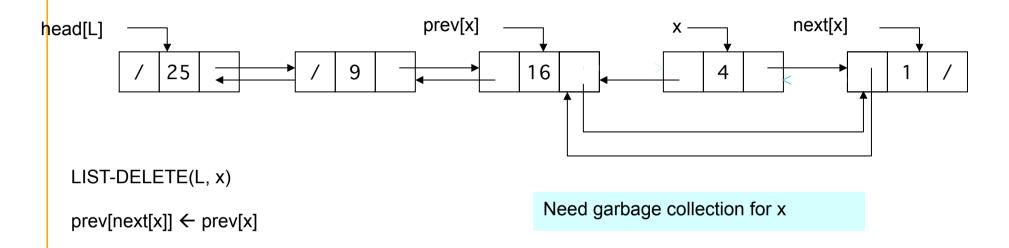
5 prev[x] \leftarrow NIL
```

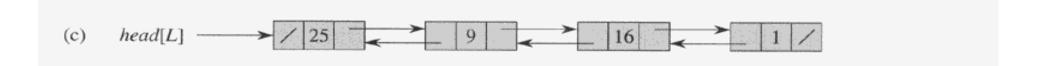
Week 6: Elementary Data Structures

Deleting From A Linked List

- LIST-DELETE(L, x): given an element pointed by x, remove x from the linked list
- LIST-DELETE(L, x)
- 1 if prev[x] ≠ NIL
- 2 then next[prev[x]] ← next[x]
- 3 else head[L] ← next[x]
- 4 if next[x] ≠ NIL
- 5 then prev[next[x]] ← prev[x]

Illustration of LIST-DELETE





Sentinel

A sentinel is a dummy object that allows us to simplify boundary conditions.

Simpler LIST-DELETE if we could ignore the boundary conditions at the head and tail of the list:

```
LIST-DELET' (L, x)

1 next[prev[x]] \leftarrow next[x]

2 prev[next[x]] \leftarrow prev[x]
```

suppose that we provide with list L an object nil[L] that represents NIL but has all the fields of the other list elements. Wherever we have a reference to NIL in list code, we replace it by a reference to the sentinel nil[L].

Week 6: Elementary Data Structures

10.3. Implementing Pointers and Objects

- Some languages allow use of pointers (C, C++)
- Some don't: fortran.
- How to implement pointers in such languages?

A Multiple-Array Representation of Objects

- We can represent a collection of objects that have the same fields by using an array for each field.
 - Figure 10.3 (a) and Figure 10.5
 - For a given array index x, key[x], next[x], and prev[x] represent an object in the linked list
 - A pointer x is simply a common index on the the key, next, and prev arrays
 - NIL can be represented by an integer that cannot possibly represent an actual index into the array

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A Multiple-Array Representation of Objects Example

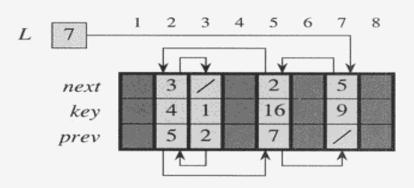
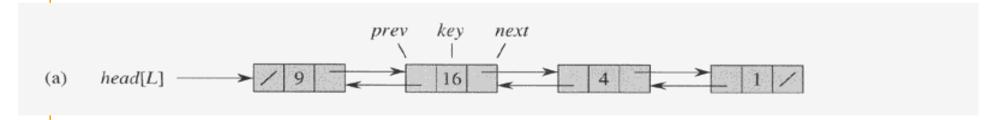
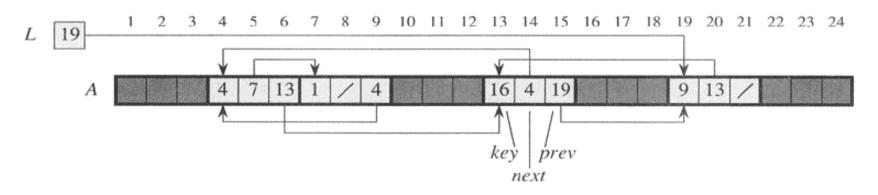


Figure 10.5 The linked list of Figure 10.3(a) represented by the arrays key, next, and prev. Each vertical slice of the arrays represents a single object. Stored pointers correspond to the array indices shown at the top; the arrows show how to interpret them. Lightly shaded object positions contain list elements. The variable L keeps the index of the head.



A Single-Array Representation of Objects

- An object occupies a contiguous set of locations in a single array → A[j..k]
 - A pointer is simply the address of the first memory location of the object → A[j]
 - Other memory locations within the object can bed indexed by adding an offset to the pointer → 0 ~ k-j
 - Flexible but more difficult to manage



Allocating and Freeing Objects

- To insert a key into a dynamic set represented by a linked list, we must allocate a pointer to a currently unused object in the linked-list representation
 - It is useful to manage the storage of objects not currently used in the linked-list representation so that one can be allocated
- Allocate and free homogeneous objects using the example of a doubly linked list represented by multiple arrays
 - The arrays in the multiple-array representation have length
 m
 - At some moment the dynamic set contains n ≤ m elements
 - The remaining m-n objects are free → can be used to represent elements inserted into the dynamic set in the future

Free List

- A singly linked list to keep the free objects
 - Initially it contains all n unallocated objects
- The free list is a stack
 - Allocate an object from the free list → POP
 - De-allocate (free) an object → PUSH
 - The next object allocated the last one freed
- Use only the next array to implement the free list
- A variable free pointers to the first element in the free list
- Each object is either in list L or in the free list, but not in both

Free List Example

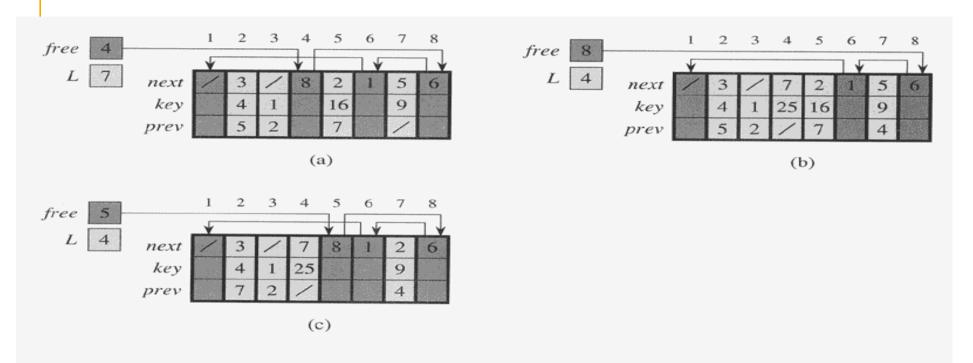


Figure 10.7 The effect of the ALLOCATE-OBJECT and FREE-OBJECT procedures. (a) The list of Figure 10.5 (lightly shaded) and a free list (heavily shaded). Arrows show the free-list structure. (b) The result of calling ALLOCATE-OBJECT() (which returns index 4), setting key[4] to 25, and calling LIST-INSERT(L, 4). The new free-list head is object 8, which had been next[4] on the free list. (c) After executing LIST-DELETE(L, 5), we call FREE-OBJECT(5). Object 5 becomes the new free-list head, with object 8 following it on the free list.

Allocate And Free An Object

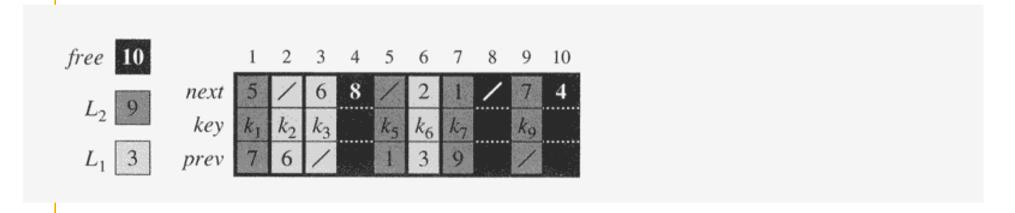
```
ALLOCATE-OBJECT()
```

- 1 if free = NIL
- 2 then error "out of space"
- 3 else $x \leftarrow$ free
- 4 free \leftarrow next[x]
- 5 return x

FREE-OBJECT(x)

- $1 \text{ next}[x] \leftarrow \text{free}$
- 2 free \leftarrow x

A Free List for Multiple Lists



Two linked lists, L1 (lightly shaded) and L2 (heavily shaded), and a free list (darkened) intertwined.

10.4.Representing Rooted Trees

- The methods for representing lists given in the previous section extend to any homogeneous data structure.
- In this section, we look specifically at the problem of representing rooted trees by linked data structures.

Binary Tree

- Use linked data structures to represent a rooted tree
 - Each node of a tree is represented by an object
 - Each node contains a key field and maybe other satellite fields
 - Each node also contains pointers to other nodes
- For binary tree...
 - Three pointer fields
 - p: pointer to the parent → NIL for root
 - left: pointer to the left child → NIL if no left child
 - right: pointer to the right child → NIL if no right child
 - root[T] pointer to the root of the tree
 - NIL for empty tree

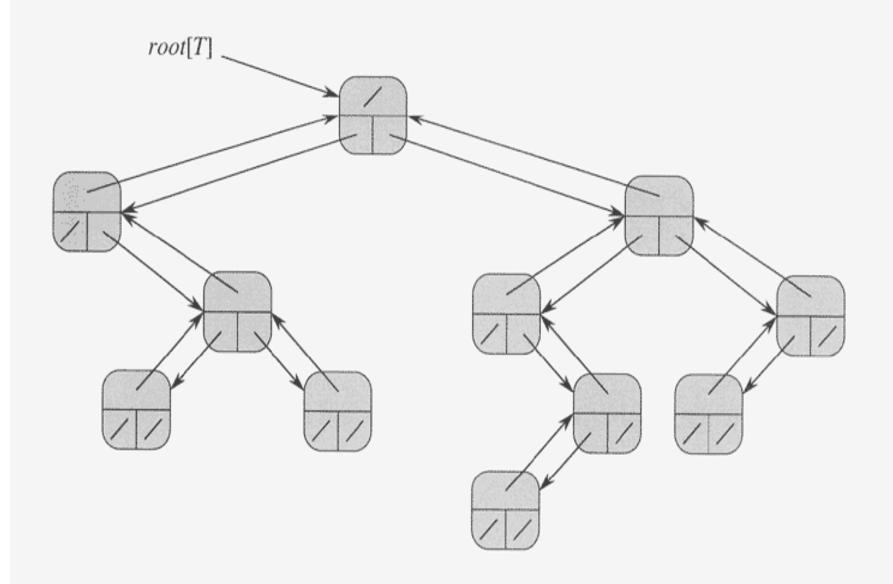
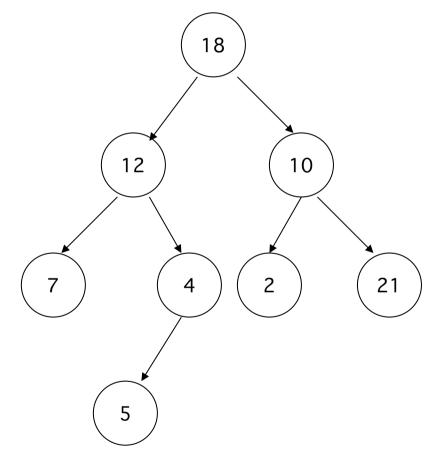


Figure 10.9 The representation of a binary tree T. Each node x has the fields p[x] (top), left[x] (lower left), and right[x] (lower right). The key fields are not shown.

Draw the Binary Tree Rooted At Index 6

Index	Key	Left	Right
1	12	7	3
2	15	8	NIL
3	4	10	NIL
4	10	5	9
5	2	NIL	NIL
6	18	1	4
7	7	NIL	NIL
8	14	6	2
9	21	NIL	NIL
10	5	NIL	NIL



Rooted Trees With Unbounded Branches

- The representation for binary trees can be extended to a tree in which no. of children of each node is at most k
 - left, right → child₁, child₂, ..., child_k
- If no. of children of a node can be unbounded, or k is large but most nodes have small numbers of children...
 - Left-child, right sibling representation
 - Three pointer fields
 - -p: pointer to the parent
 - left-child: pointer to the leftmost child
 - right-sibling: pointer to the sibling immediately to the right
 - root[T] pointer to the root of the tree
 - O(N) space for any n-node rooted tree

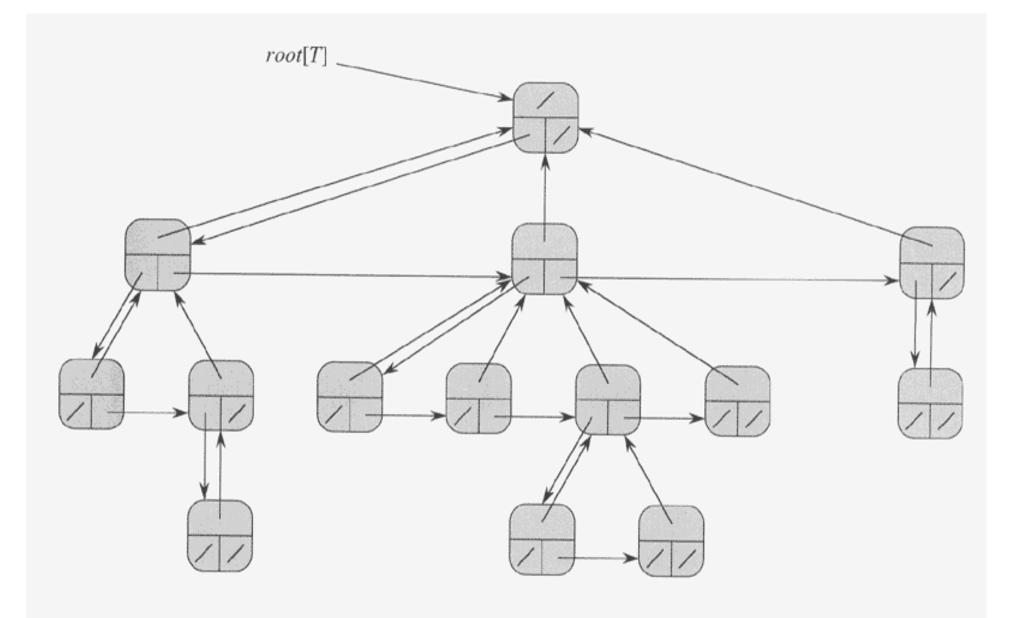


Figure 10.10 The left-child, right-sibling representation of a tree T. Each node x has fields p[x] (top), left-child[x] (lower left), and right-sibling[x] (lower right). Keys are not shown.

Summary

- dynamic sets
- dynamic set operations
- stacks
- queues
- linked lists
- array representation of linked lists
- array representation of rooted trees