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#### Question 1. What are the main messages you learned from this chapter?

- Autoencoder: an autoencoder is an unsupervised and nonlinear dimensionality reduction model and is widely used in many healthcare applications. Three different kinds of autoencoders are introduced in this chapter: stacked AE, sparse AE (sparse representation), and denoising AE (robustness representation).
- Sparse AE: this method adds a penalty term to the AE objective function to penalize \$\$\hat\rho\$\$ that deviates from the sparsity parameter \$\$rho\$\$.
- Stacked AE: each new AE layer receives its input from the output of the previous one.
- Denoising AE: adds noise to the original input x to obtain corrupted version \$\$\tilde{x}\$\$ and then train the AE on the corrupted version \$\$\tilde{x}\$\$.

# Question 2. What related resources (book, paper, blog, link) do you recommend your classmates to checkout?

Variational AE (similar to Denoising AE):
<a href="https://medium.com/@smallfishbigsea/varational-auto-encoder-448d7072e7e4">https://medium.com/@smallfishbigsea/varational-auto-encoder-448d7072e7e4</a>

#### Question 3. Which part do you want to improve in this chapter?

A clearer explanation of the layered AE would be helpful to me.

### Question 4. What are the main difference between autoencoder and principal component analysis?

In both the encoder and decoder, an autoencoder adds a nonlinear activation layer. In a PCA, the activation function is simply an identity function, which is a form of linear dimensionality reduction.

## Question 5. What is the main difference between autoencoder and denoising autoencoder?

A denoising autoencoder adds noises to the original input \$x\$ by adding noises and then attempts to recreate the input \$x\$ from  $$\tilde x$$  corrupted \$x\$. Different types of noise can be added, such as random Gaussian noise at all locations / some locations or modeled noises based on the input \$x\$.