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Because the product of any two basis vectors is plus or minus another basis vector, the set $\{\pm 1, \pm i, \pm j, \pm k\}$ forms a group under multiplication. This non-Abelian Group is called the quaternion group and is denoted Q_8 . The real group ring of Q_8 is a ring $R[Q_8]$ which is also an eight-dimensional vector space over R . It has one basis vector for each element of Q_8 .

Quaternion - Wikipedia

A centripetal force (from Latin centrum, "center" and petere, "to seek") is a force that makes a body follow a curved path. Its direction is always orthogonal to the motion of the body and towards the fixed point of the instantaneous center of curvature of the path. Isaac Newton described it as "a force by which bodies are drawn or impelled, or in any way tend, towards a point as to a centre".

Centripetal force - Wikipedia

The quaternions are members of a noncommutative division algebra first invented by William Rowan Hamilton. The idea for quaternions occurred to him while he was walking along the Royal Canal on his way to a meeting of the Irish Academy, and Hamilton was so pleased with his discovery that he scratched the fundamental formula of quaternion algebra, $i^2=j^2=k^2=ijk=-1$, (1) into the stone of the ...

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