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Modern Robotics - Northwestern Mechatronics Wiki

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Geometric algebra - Wikipedia

Because the product of any two basis vectors is plus or minus another basis vector, the set {±1, ±i, ±j, ±k} forms a group under multiplication. This non-Abelian Group is called the quaternion group and is denoted Q 8.The real group ring of Q 8 is a ring R[Q 8] which is also an eight-dimensional vector space over R.It has one basis vector for each element of Q 8.

Quaternion - Wikipedia

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DOCK. RETURN TO TABLE OF CONTENTS. 2.1. Overview. This section is intended as a reference manual for the features of the DOCK Suite of Programs. It is intended to give an overview of the ideas which form the basis of the DOCK suite of programs and to detail the available user parameters.

DOCK 6.9 User Manual - UCSF DOCK

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