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Phase 3: Implementation of Project

Title: Traffic Flow Optimization

Objective

The goal of Phase 3 is to implement the core components of the Traffic Flow Optimization system based on the strategies and innovative solutions developed during Phase 2. This includes the development of the traffic prediction model, the real-time monitoring dashboard, initial sensor integration, and the implementation of data privacy measures.

1. Al Model Development

Overview

The primary feature of the Traffic Flow Optimization system is its ability to analyze traffic patterns and suggest optimal traffic control strategies. In Phase 3, the AI model will be trained and implemented to predict congestion and optimize signal timings.

Implementation

• Machine Learning Model: The system uses machine learning to forecast traffic conditions based on historical and real-time data. During this phase, the AI is developed to analyze traffic density, speed, and flow using training data from road sensors and traffic cameras.

• Data Source: The model is based on traffic datasets including vehicle counts, congestion levels, and signal timing logs. Real-time data will be partially integrated in this phase, with full integration planned for future versions.

Outcome

By the end of this phase, the AI model is expected to predict traffic congestion levels and suggest optimized traffic signal schedules to reduce bottlenecks and improve flow in urban areas.

2. Dashboard Development

Overview

The system will be made accessible through a dashboard interface that allows traffic operators to view and interact with real-time traffic data.

Implementation

- User Interaction: Traffic control personnel will use the dashboard to view predictions, congestion heatmaps, and system recommendations.
- Visualization: The dashboard will display live feeds, historical trends, and suggested interventions for congested intersections.

Outcome

At the end of Phase 3, the dashboard will be functional, allowing users to monitor traffic and implement recommended optimizations.

3. Sensor Integration (Optional)

Overview

While extensive sensor integration is optional for this phase, we aim to establish basic connections between the optimization system and existing traffic sensors or cameras.

Implementation

- Traffic Data: Sensors such as inductive loops, infrared counters, or surveillance cameras will be used to feed live data into the system.
- API Use: APIs from municipal traffic systems will be leveraged to access sensor data and vehicle counts.

Outcome

By the end of Phase 3, the system should be able to collect basic traffic data from selected sensors and use it to refine its predictions and recommendations.

4. Data Privacy Implementation

Overview

is Given the use of public surveillance and location data, it important to implement strong data privacy safeguards.

Implementation

• Anonymization: All vehicle or user data collected will be anonymized to prevent identification of individuals.

• Secure Storage: Data will be stored in a secure server with restricted access, complying with urban data governance standards.

Outcome

At the end of Phase 3, the system will securely handle all traffic data with essential encryption and privacy protections in place.

5. Testing and Feedback Collection

Overview

Initial testing of the Traffic Flow Optimization system will be conducted to evaluate prediction accuracy and interface usability.

Implementation

- Test Zones: Selected intersections or road segments will be monitored using the system. Results will be compared against actual conditions.
- Feedback Loop: Feedback from traffic operators and pilot users will be collected on system accuracy and usability.

Outcome

The feedback collected during Phase 3 will guide improvements for Phase 4, particularly in refining the AI model and enhancing dashboard functionality.

Challenges and Solutions

1. Model Accuracy

- Challenge: The AI may produce less accurate predictions due to limited real-time input.
- Solution: Ongoing updates and feedback integration will help tune the model.

2. Data Integration

- Challenge: Inconsistent data from various sources may affect reliability.
- Solution: Data preprocessing and API standardization will be applied.
- 3. Sensor Availability
- Challenge: Some areas may lack the required sensors or cameras.
- Solution: Simulated data and mobile sensors will be used to systemfunctionality.

```
import networkx as nx
   import matplotlib.pyplot as plt
 3
   import heapq
 5 - class TrafficNetwork:
        def _init_(self):
 7
            self.graph = nx.DiGraph()
 8
 9 -
        def add_road(self, from_node, to_node, base_time, traffic_factor=1.0
            ):
            travel_time = base_time * traffic_factor
10
11
            self.graph.add_edge(from_node, to_node, weight=travel_time)
12
13
        def dijkstra(self, start):
            distances = {node: float('inf') for node in self.graph.nodes}
14
            distances[start] =
16
            queue = [(0, start)]
17
            while queue:
18
                current_dist, current_node = heapq.heappop(queue)
19
20
                for neighbor in self.graph.neighbors(current_node):
21
                    weight = self.graph[current_node][neighbor]['weight']
22
                    distance = current_dist + weight
                    if distance < distances[neighbor]:</pre>
24
25
                        distances[neighbor] = distance
26
                        heapq.heappush(queue, (distance, neighbor))
```

```
return distances
29
        def draw_network(self):
30
           pos = nx.spring_layout(self.graph)
            edge_labels = nx.get_edge_attributes(self.graph, 'weight')
           nx.draw(self.graph, pos, with_labels=True, node_color
               ='lightblue', node_size=1000, font_size=12)
34
           nx.draw_networkx_edge_labels(self.graph, pos, edge_labels
               =edge_labels)
           plt.title("Traffic Network with Travel Times")
36
           plt.show()
38
39 # Example usage
40 network = TrafficNetwork()
41 network.add_road('A', 'B', base_time=4, traffic_factor=1.0)
42 network.add_road('A', 'C', base_time=2, traffic_factor=1.2) # Slight
   network.add_road('B', 'C', base_time=5, traffic_factor=1.5) # Heavy
44 network.add_road('B', 'D', base_time=10, traffic_factor=0.9) # Light
45 network.add_road('C', 'D', base_time=3, traffic_factor=1.1)
48 shortest_paths = network.dijkstra('A')
49 print("Shortest travel times from A:", shortest_paths)
```

