## Week-1

#### Rajesh Kalakoti

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- Packages
  - devtools
  - tidyverse
  - here

```
# Include the script from the R directory
project_path <- here()
source(here("R", "utils.R"))
source(here("R", "distance_functions.R"))</pre>
```

#### Clustering

Given a clustering  $C = \{C_1, C_2, \dots, C_k\}$ , we need some scoring function that evaluates its quality or goodness. This sum of squared errors scoring function is defined as:

$$W(C) = \frac{1}{2} \sum_{k=1}^K \sum_{i:C(i)=k} \|x_i - \bar{x}_k\|^2$$

The goal is to find the clustering that minimizes:

$$C^* = \arg\min_{C} \{W(c)\}$$

K-means employs a greedy iterative approach to find a clustering that minimizes loss function.

Note that the echo = FALSE parameter was added to the code chunk to prevent printing of the R code that generated the plot.

```
euclidean_dist <- function(point1, point2) {
    squared_diff <- (point1 - point2)^2
    sqrt(sum(squared_diff))
}

x <- y <- seq(-1, 1, length = 20)
grid <- expand.grid(x = x, y = y) # Create a grid of points
z <- matrix(0, nrow = length(x), ncol = length(y)) # Initialize the z matrix

for (i in 1:length(x)) {
    for (j in 1:length(y)) {</pre>
```

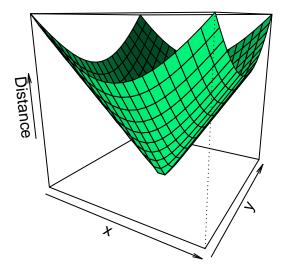
#### Algorithm 1: K-means Algorithm

```
\overline{\mathbf{Data:}\ D, k, \varepsilon}
 1 K-means(D, k, \varepsilon):
 2 t \leftarrow 0;
 3 Randomly initialize k centroids: \mu_1^t, \mu_2^t, \dots, \mu_n^t \in \mathbb{R}^d;
 4 repeat
          t \leftarrow t + 1;
 5
          C_i \leftarrow \emptyset for all i=1,\dots,k
 7
           /* Cluster assignment step */
          \mathbf{for}\ x_j \in D\ \mathbf{do}
 8
                i^* \overset{-}{\leftarrow} \operatorname{argmin}_i\{||x_j - \mu_i^{t-1}||^2\};
  9
               /* assign x_i to closest centroid */
10
              C_{i^*} \leftarrow C_{i^*} \stackrel{\circ}{\cup} \{x_j\};
11
           end
12
           for i = 1,..,k do
13
           16 until \sum_{i=1}^{k} ||\mu_i^t - \mu_i^{t-1}||^2 \le \varepsilon;
```

```
z[i, j] <- euclidean_dist(c(x[i], y[j]), c(0, 0))
}

persp(x, y, z,
    main = "3D Plot of Euclidean Distance",
    zlab = "Distance",
    theta = 30, phi = 15,
    col = "springgreen", shade = 0.5)</pre>
```

## 3D Plot of Euclidean Distance

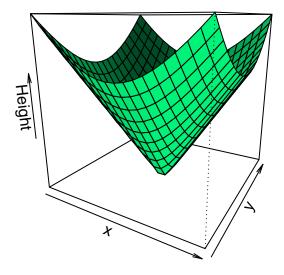


```
cone1 <- function(x, y){
sqrt(x^2+y^2)
}

x <- y <- seq(-1, 1, length= 20)
z <- outer(x, y, cone1)

persp(x, y, z,
main="Perspective Plot of a Cone",
zlab = "Height",
theta = 30, phi = 15,
col = "springgreen", shade = 0.5)</pre>
```

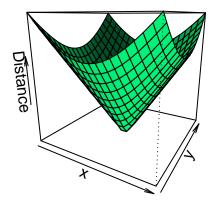
# Perspective Plot of a Cone

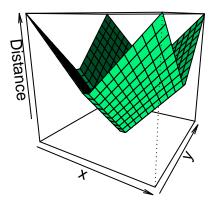


```
euclidean_dist <- function(point1, point2) {</pre>
  squared_diff <- (point1 - point2)^2</pre>
  sqrt(sum(squared_diff))
manhattan_distance <- function(point1, point2) {</pre>
  if (length(point1) != length(point2)) {
    stop("Both points should have the same number of dimensions.")
  abs_diff <- abs(point1 - point2)</pre>
  distance <- sum(abs_diff)</pre>
  return(distance)
}
x \leftarrow y \leftarrow seq(-1, 1, length = 20)
grid <- expand.grid(x = x, y = y) # Create a grid of points</pre>
z_euclidean <- matrix(0, nrow = length(x), ncol = length(y)) # Initialize the z matrix for Euclidean d</pre>
z_manhattan <- matrix(0, nrow = length(x), ncol = length(y)) # Initialize the z matrix for Manhattan
for (i in 1:length(x)) {
  for (j in 1:length(y)) {
    z_euclidean[i, j] <- euclidean_dist(c(x[i], y[j]), c(0, 0))</pre>
    z_manhattan[i, j] <- manhattan_distance(c(x[i], y[j]), c(0, 0))</pre>
  }
}
```

```
{\it \# Create \ a \ layout \ of \ subplots \ to \ show \ both \ Euclidean \ and \ Manhattan \ distances}
par(mfrow = c(1, 2))
# Plot for Euclidean distance
persp(x, y, z_euclidean,
      main = "3D Plot of Euclidean Distance",
      zlab = "Distance",
      theta = 30, phi = 15,
      col = "springgreen", shade = 0.5)
# Plot for Manhattan distance
persp(x, y, z_manhattan,
      main = "3D Plot of Manhattan Distance",
      zlab = "Distance",
      theta = 30, phi = 15,
      col = "springgreen", shade = 0.5)
```

### 3D Plot of Euclidean Distance 3D Plot of Manhattan Distance

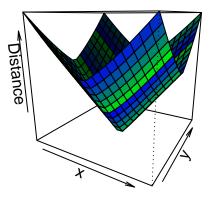




```
# Reset the layout
par(mfrow = c(1, 1))
euclidean_dist <- function(point1, point2) {</pre>
  squared_diff <- (point1 - point2)^2</pre>
  sqrt(sum(squared_diff))
}
```

```
manhattan_distance <- function(point1, point2) {</pre>
  if (length(point1) != length(point2)) {
    stop("Both points should have the same number of dimensions.")
  }
  abs_diff <- abs(point1 - point2)</pre>
  distance <- sum(abs_diff)</pre>
 return(distance)
}
x \leftarrow y \leftarrow seq(-5, 5, length = 20)
grid <- expand.grid(x = x, y = y) # Create a grid of points</pre>
z_euclidean <- matrix(0, nrow = length(x), ncol = length(y)) # Initialize the z matrix for Euclidean d
z_manhattan <- matrix(0, nrow = length(x), ncol = length(y)) # Initialize the z matrix for Manhattan
for (i in 1:length(x)) {
  for (j in 1:length(y)) {
    z_euclidean[i, j] <- euclidean_dist(c(x[i], y[j]), c(0, 0))</pre>
    z_manhattan[i, j] <- manhattan_distance(c(x[i], y[j]), c(0, 0))</pre>
 }
}
# Combine the distances and choose different colors for each
combined_distances <- z_euclidean + z_manhattan</pre>
color_palette <- colorRampPalette(c("blue", "green"))(100) # Choose colors for mapping distances</pre>
# Create a layout of subplots
layout(matrix(c(1, 2), nrow = 1))
# Plot both distances on the same 3D plane with different colors
persp(x, y, combined_distances,
      main = "3D Plot of Combined Distances",
      zlab = "Distance",
      theta = 30, phi = 15,
      col = color_palette, shade = 0.5)
# Reset the layout
layout(1)
```

## **3D Plot of Combined Distances**



```
# Include the script from the R directory
project_path <- here()</pre>
source(here("R", "utils.R"))
?entropy
## No documentation for 'entropy' in specified packages and libraries:
## you could try '??entropy'
library("car")
## Loading required package: carData
## Attaching package: 'car'
## The following object is masked from 'package:dplyr':
##
##
       recode
## The following object is masked from 'package:purrr':
##
##
       some
```

```
library("rgl")
## This build of rgl does not include OpenGL functions. Use
## rglwidget() to display results, e.g. via options(rgl.printRglwidget = TRUE).
data(iris)
head(iris)
     Sepal.Length Sepal.Width Petal.Length Petal.Width Species
## 1
              5.1
                                        1.4
                          3.5
                                                    0.2 setosa
## 2
              4.9
                          3.0
                                        1.4
                                                    0.2 setosa
## 3
              4.7
                          3.2
                                        1.3
                                                   0.2 setosa
## 4
              4.6
                         3.1
                                        1.5
                                                   0.2 setosa
                                                    0.2 setosa
## 5
              5.0
                          3.6
                                        1.4
## 6
              5.4
                          3.9
                                        1.7
                                                    0.4 setosa
sep.l <- iris$Sepal.Length</pre>
sep.w <- iris$Sepal.Width</pre>
pet.l <- iris$Petal.Length</pre>
library("car")
library("rgl")
data(iris)
sep.l <- iris$Sepal.Length</pre>
sep.w <- iris$Sepal.Width</pre>
pet.l <- iris$Petal.Length</pre>
save <- getOption("rgl.useNULL")</pre>
options(rgl.useNULL = TRUE)
scatter3d(x = sep.1, y = pet.1, z = sep.w, groups = iris$Species,
          surface = FALSE, ellipsoid = TRUE)
## Loading required namespace: mgcv
## Loading required namespace: MASS
widget <- rglwidget()</pre>
## Warning in snapshot3d(scene = x, width = width, height = height): webshot =
## TRUE requires the webshot2 package and Chrome browser; using rgl.snapshot()
## instead
## Warning in rgl.snapshot(filename, fmt, top): this build of rgl does not support
## snapshots
# Explicitly set the elementId property
widget$elementId <- "my-rgl-plot"</pre>
```

```
widget
```

```
## [[1]]
## [1] "../../../tmp/Rtmpo8qGEg/file699161ea2a45.png"
##
## $elementId
## [1] "my-rgl-plot"
##
```