

Mathematics and Statistics for Data Science Session 9

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The Gauss-Jordan Method for the solution of linear systems

We can:

- ▶ Interchange two equations
- ▶ Multiply all terms in an equation by a non-zero scalar
- ▶ Add in algebraic sense two equations

to obtain a "triangular system (matrix)" or diagonal system (matrix).

$$a_{11}x_1 + a_{12}x_2 = c_1$$

$$a_{21}x_1 + a_{22}x_2 = c_2$$

A possible idea is to obtain the following diagonal system (matrix):

$$ax_1 + 0x_2 = b$$

$$0x_1 + cx_2 = d$$

For some $a, b, c, d \in \mathbb{R}$

$$x_2 = \frac{d}{c}, \quad x_1 = \frac{b}{a}$$

Another possible idea is to obtain the following triangular system (matrix):

$$ex_1 + fx_2 = g$$

$$0x_1 + hx_2 = i$$

For some $e, f, g, h, i \in \mathbb{R}$

Example:

$$\begin{cases} x_1 + 3x_2 = 1 \\ x_1 + 2x_2 = 2 \end{cases}$$

$$\begin{cases} x_1 + 3x_2 = 1 \\ 0 + x_2 = -1 \end{cases} \rightarrow x_1 = 4$$

Injective linear transformation

Considering a linear transformation $T : V \rightarrow W$ then T is injective if whenever $T(x) = T(y) \rightarrow x = y$ with $x, y \in V$ (which is logically equivalent to the contrapositive, $x \neq y \rightarrow T(x) \neq T(y)$)

Theorem

$T : V \rightarrow W$ is a linear transformation, then T is injective iff the kernel of $T = 0$ $N(T) = K(T) = 0$ (trivial kernel).

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = 1, \quad T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = 1 \text{ non-injective}$$

$$T : (x, y) \rightarrow ax + by \quad a, b \in \mathbb{R}$$

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = 1, \quad T\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}\right) = 1 \text{ non-injective}$$

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = 1, \quad T\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}\right) = 1 \text{ non-injective}$$

$$\begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 1 \rightarrow a \cdot 1 + b \cdot 2 = 1 \rightarrow 1 - 2b \rightarrow \begin{bmatrix} 1 - 2b & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$\rightarrow K(T) = \begin{bmatrix} 1 \\ \frac{2b-1}{b} \end{bmatrix} x$$

$$\begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1, \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = 2 \rightarrow b = 1 \rightarrow a = -1 \rightarrow \begin{bmatrix} -1 & 1 \end{bmatrix}$$

$$\rightarrow N(A) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} x \rightarrow A \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} x = \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} x = -x + x = 0$$

$$\dim(K(T)) + \dim(T) = \dim(V)$$

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad T\left(\begin{bmatrix} 1 \\ 4 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad T\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\text{non-injective} \quad T : (x, y) \rightarrow (ax + by, cx + dy)$$

$$\begin{cases} a + 4b = 1 \\ c + 4d = 2 \\ a + 3b = 1 \\ c + 3d = 2 \end{cases} \rightarrow a = 1, b = 0, c = 2, d = 0$$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow N(A) = K(T) = \begin{bmatrix} 0 \\ * \end{bmatrix} y$$

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}^3, \quad T \rightarrow A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 1 & 4 \end{bmatrix} \rightarrow T : (x, y) = (x+2y, 3x+4y, x+4y)$$

$$A \cdot N(A) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} x + 2y = 0 \\ 3x + 4y = 0 \\ x + 4y = 0 \end{cases} \rightarrow y = 0, x = 0 \text{ (injective, 0 dimension)}$$

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}^3, \quad T \rightarrow A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \\ 1 & 2 \end{bmatrix} \rightarrow T : (x, y) = (x+2y, 3x+6y, x+2y)$$

two columns, which are dependent

$$A \cdot N(A) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 \\ 3 & 6 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} x + 2y = 0 \\ 3x + 6y = 0 \\ x + 2y = 0 \end{cases} \rightarrow y = 0, x = 0 \text{ (injective, 0 dimension)}$$

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad T \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 2, \quad T \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1$$

\Rightarrow not a transformation, not a function, does not work!

We can speak in the "same way" about Transformation, Matrices and linear systems. We say that there is an isomorphism between!

Example: Is the following transformation a injective one?

$$\begin{cases} x_1 + 2x_2 = 1 \\ 2x_1 + 4x_2 = 2 \end{cases}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

1. step:

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_{1H} \\ x_{2H} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow N(A) = \begin{bmatrix} -2 \\ 1 \end{bmatrix} x_{2H}$$

The linear system does not represent an injective transformation.

Example: Is the following transformation a injective one?

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad T \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 2, \quad T \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1$$

\Rightarrow not a transformation, not a function, doesnt work!

$$T : (x, y) \rightarrow ax + by \quad a, b \in \mathbb{R}$$

$$a + 2b = 2$$

$$a + 2b = 1$$

$$\Rightarrow 2 = 1 \rightarrow \text{Contradiction!}$$

Theorem

Suppose that $T : V \rightarrow W$ is an injective linear transformation and a set $v = \{v_1, v_2, \dots, v_t\}$ consists of the linear independent vector, then $R = \{T(v_1), T(v_2), \dots, T(v_t)\}$ is a set of linear independent vectors.

Please look at the following example:

$$T : (x, y) \mapsto (2x, 2x + y)$$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \rightarrow \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 2 \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

Theorem

Linear transformation and bases.

Suppose that $T : V \rightarrow W$ is a linear transformation and $B = \{v_1, v_2, \dots, v_m\}$ a basis of V , then T is injective iff $R = \{T(v_1), T(v_2), \dots, T(v_m)\}$ is an independent set of W .

Try to do the following example with the solution in the following slides:

$$T : (x, y) \rightarrow (ax + by, cx + dy) \quad T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$a + 2b = 1 \rightarrow b = \frac{1}{2}$$

$$c + 2d = 2 \rightarrow d = -1$$

$$a = 2$$

$$c = 4$$

$$\Rightarrow$$

$$A = \begin{bmatrix} 2 & -\frac{1}{2} \\ 4 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -\frac{1}{2} \\ 4 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$2x - \frac{y}{2} = 0 \rightarrow y = 4x$$

$$4x - y = 0 \rightarrow y = 4x$$

$$\Rightarrow N(A) = \begin{bmatrix} 1 \\ 4 \end{bmatrix} x \rightarrow \text{not injective}$$