#### Workshop: Projectile Motion

An introduction to computing trajectories

Jonas van den Brink j.v.brink@fys.uio.no

Simula Research Laboratory Oslo, Norway

January 29, 2015

## This workshop focuses on introducing computations to introductory physics

Introducing computations should lead to a sense of empowerment

# This workshop focuses on introducing computations to introductory physics

Introducing computations should lead to a sense of empowerment

For this to be possible, the computations must

- 1. Relate to well-known problems
- 2. Must be shown to be a powerful tool
- 3. Understable. Students should write their own code





Equations of motion

$$\frac{\mathrm{d}\vec{r}}{\mathrm{d}t} = \vec{v}(t), \qquad \frac{\mathrm{d}\vec{v}}{\mathrm{d}t} = \vec{a}(t)$$

Newtons 2. law of motion

$$\vec{F} = m\vec{a}$$

Newtons 2. law of motion

$$\vec{F} = m\vec{a}$$



Newtons 2. law of motion

$$\vec{F} = m\vec{a}$$



$$\vec{F}(r, v, t) = m\vec{a}(r, v, t).$$

Our algorithm is now as follows

- 1. Find the physical forces of the system.
- 2. Use Newtons 2. law to find the acceleration
- 3. Calculate  $\vec{v}(t)$  and  $\vec{r}(t)$  by solving the equations of motion

Our algorithm is now as follows

- 1. Find the physical forces of the system.
- 2. Use Newtons 2. law to find the acceleration
- 3. Calculate  $\vec{v}(t)$  and  $\vec{r}(t)$  by solving the equations of motion

In this workshop, we will solve step number 3 numerically, using the Euler method.

### The Euler Method

A method for solving ordinary differential equations (ODEs)

From the definition of the derivative

$$\frac{\mathrm{d}v}{\mathrm{d}t} = \lim_{\Delta t \to 0} \frac{v(t + \Delta t) - v(t)}{\Delta t} = a(t)$$

From the definition of the derivative

$$\frac{\mathrm{d}v}{\mathrm{d}t} = \lim_{\Delta t \to 0} \frac{v(t + \Delta t) - v(t)}{\Delta t} = a(t)$$

We now remove the limit, making  $\Delta t$  a very small constant

$$\frac{v(t+\Delta t)-v(t)}{\Delta t}\approx a(t)$$

From the definition of the derivative

$$rac{\mathrm{d} v}{\mathrm{d} t} = \lim_{\Delta t o 0} rac{v(t + \Delta t) - v(t)}{\Delta t} = a(t)$$

We now remove the limit, making  $\Delta t$  a very small constant

$$rac{v(t+\Delta t)-v(t)}{\Delta t}pprox a(t)$$

Solving for  $v(t+\Delta t)$  gives

$$v(t + \Delta t) \approx v(t) + a(t) \cdot \Delta t$$

We can solve the equations of motion by stepping forward in time

$$v(t + \Delta t) = v(t) + a(t) \cdot \Delta t$$

We can solve the equations of motion by stepping forward in time

$$v(t + \Delta t) = v(t) + a(t) \cdot \Delta t$$

If a(t) and v(t) are known, we can calculate  $v(t+\Delta t)$ 

We can solve the equations of motion by stepping forward in time

$$v(t+\Delta t)=v(t)+a(t)\cdot \Delta t$$
 If  $a(t)$  and  $v(t)$  are known, we can calculate  $v(t+\Delta t)$  
$$v(t)$$
 
$$v(t+\Delta t)$$

We only focus on multiples of our time-step

```
t \in \{0, \Delta t, 2\Delta t, 3\Delta t, \ldots\}
t_i \equiv i \cdot \Delta t
```

We only focus on multiples of our time-step

$$t \in \{0, \Delta t, 2\Delta t, 3\Delta t, \ldots\}$$
  
 $t_i \equiv i \cdot \Delta t$ 

Introduce the shorthand

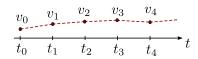
$$v(t_i) \equiv v_i$$
  
 $r(t_i) \equiv r_i$ 

We only focus on multiples of our time-step

$$t \in \{0, \Delta t, 2\Delta t, 3\Delta t, \ldots\}$$
  
 $t_i \equiv i \cdot \Delta t$ 

Introduce the shorthand

$$v(t_i) \equiv v_i$$
  
 $r(t_i) \equiv r_i$ 



$$v_{i+1} = v_i + a_i \cdot \Delta t$$

$$v_{i+1} = v_i + a_i \cdot \Delta t$$

$$r_{i+1} = r_i + v_i \cdot \Delta t$$

$$v_{i+1} = v_i + a_i \cdot \Delta t$$
  
 $r_{i+1} = r_i + v_i \cdot \Delta t$ 

For each time step, we must calculate the acceleration

$$a_i = a(r_i, v_i, t_i).$$

$$v_{i+1} = v_i + a_i \cdot \Delta t$$

$$r_{i+1} = r_i + v_i \cdot \Delta t$$

For each time step, we must calculate the acceleration

$$a_i = a(r_i, v_i, t_i).$$

We repeat these steps, starting at our initial conditions  $v_0$  and  $r_0$ , until we have reached our end-time  $t_N$ 

$$i = 0, 1, 2, 3, \ldots, N$$
.

### Algorithm for the Euler method

for  $i = 0, 1, 2, 3, \dots, N-1$ :

- 1. Use the previous results  $x_i$  and  $v_i$  to compute the acceleration:  $a_i = F(x_i, v_i, t_i)/m$ .
- 2. Compute the new velocity:  $v_{i+1} = v_i + a_i \Delta t$ .
- 3. Compute the new position:  $r_{i+1} = r_i + v_i \Delta t$ .

### Implementation

Moving from physics and math to actual computer code

- 1. Use the previous results  $x_i$  and  $v_i$  to compute the
- 1. Use the previous results  $x_i$  and  $v_i$  to compute the acceleration:  $a_i = F(x_i, v_i, t_i)/m$ .
- 2. Compute the new velocity:  $v_{i+1} = v_i + a_i \Delta t$ .

for  $i = 0, 1, 2, 3, \dots, N-1$ :

3. Compute the new position:  $r_{i+1} = r_i + v_i \Delta t$ .

- for  $i = 0, 1, 2, 3, \dots, N-1$ :
  - 1. Use the previous results  $x_i$  and  $v_i$  to compute the acceleration:  $a_i = F(x_i, v_i, t_i)/m$ .
  - 2. Compute the new velocity:  $v_{i+1} = v_i + a_i \Delta t$ .
  - 3. Compute the new position:  $r_{i+1} = r_i + v_i \Delta t$ .



```
for i in range(N):
    a[i] = F(r[i], v[i], t[i])/m
    v[i+1] = v[i] + a[i]*dt
    r[i+1] = r[i] + v[i]*dt
```

for i = 0, 1, 2, 3, ..., N - 1:

- 1. Use the previous results  $x_i$  and  $v_i$  to compute the acceleration:  $a_i = F(x_i, v_i, t_i)/m$ .
- 2. Compute the new velocity:  $v_{i+1} = v_i + a_i \Delta t$ .
- 3. Compute the new position:  $r_{i+1} = r_i + v_i \Delta t$ .



```
for i in range(N):
    a[i] = F(r[i], v[i], t[i])/m
    v[i+1] = v[i] + a[i]*dt
    r[i+1] = r[i] + v[i]*dt
```

We want the code to look as much as possible like the physics and math we write on paper

$$t_i \Rightarrow t[i]$$
  $v_i \Rightarrow v[i]$   $r_i \Rightarrow r[i]$ 

#### We also need various bookeeping code

Here we define the arrays we will be using

```
# Import various functions meant for numerical science
import numpy as np
t_0 = 0 \# Start time, s
t_{end} = 10 \# End time, s
N = 1000 \# Number of time steps
# Create a uniformly spaced time-array
t = np.linspace(t_0, t_end, N+1)
# Calculate the size of a time step
dt = t[1] - t[0]
# Create empty acceleration, velocity and position arrays
a = np.zeros((2, N+1))
v = np.zeros((2, N+1))
r = np.zeros((2, N+1))
# Set initial conditions
v[0] = (100*cos(pi/6), 100*sin(pi/6)) # inital velocity, m/s
r[0] = (0,1) # initial position, m
```

#### We also need various bookeeping code

Here we define physical constants for our system and define the function that describes the forces

```
m = 5.5 # mass, kg
g = 9.81 # acceleration of gravity, m/s^2
rho = 1.3 # air density, kg/m^3
C_D = 0.45 # drag coefficient
d = 0.11 # diameter of cannonball, m
A = pi*d**2 # cross-sectional area, m^2

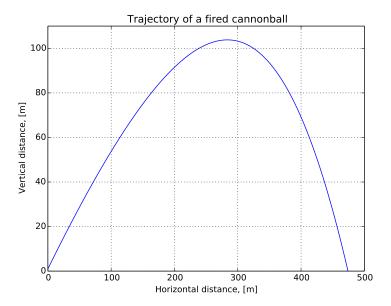
def F(r, v, t):
    return (0, -m*g) - 0.5*rho*C_D*A*abs(v)*v
```

This example show the forces acting on the cannonball as it sails through the air

$$F(x, v, t) = F_g + F_d(\vec{v}) = -mg\vec{k} - \frac{1}{2}\rho C_D A |\vec{v}|\vec{v}$$

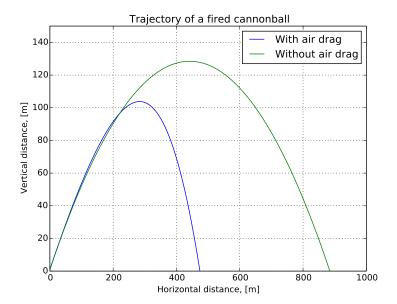
# As soon as we have solved the equations of motion, we can plot the result

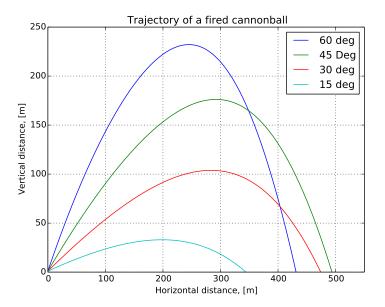
```
# Extract x and v coordinates
x = r[:,0]
y = r[:,1]
# Import functionality for plotting
from matplotlib.pyplot import plt
# Plot figure
plt.plot(x,y)
# Prettify the plot
plt.xlabel('Horizontal distance, [m]')
plt.ylabel('Vertical distance, [m]')
plt.title('Trajectory of a fired cannonball')
plt.grid()
plt.axis([0, 900, 0, 250])
# Makes the plot appear on the screen
plt.show()
```



Numerical Experimentation

Altering parameters let's us immediately see the consequences





# Students can use numerical experimentation to build intuition and knowledge

- Numerical results can be compared to known analytical solutions. Are numerical results trustworthy?
- Can study how results are directly changed by parameter choice. Are the parameters chosen reasonable?
- Can look at systems with and without certain contributions, such as air drag.
   What is important, and what can be ignored?

### Examples of possible projects

You will have a chance to look at some of these today

### Catapults and cannons and sports such as baseball



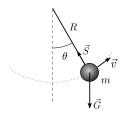
- Easy to compare with experimental data, either before or after simulation.
- Can look into studies of air drag, Reynolds number etc.

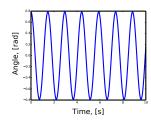
### Skydiving and bungeejumping



- Great study on free fall and terminal velocity
- Can study how parameters such as cross-sectional area and drag coefficient change as the parachute is opened
- Can plot the *g*-forces affecting the jumper. Which sport is more "extreme"?

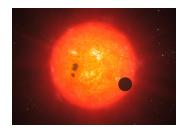
#### Pendulum and angular motion





- Can solve pendulum also for large angles!
- Energy can be plotted as functions of time
- Can also simulate double pendulum and chaotic systems

#### Modelling the solar system



- Students can gather real data of planetary orbits from NASA webpages
- Can combine numerical simulation with better graphics