Zhubo Zhou

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Education

M.S. in Computer Science, University of Southern California

Expected May 2024

Analysis of Algorithms, Intro to Programming Systems Design

B.S. in Mechanical Engineering (Highest Honor), Georgia Institute of Technology

Sept 2016-Dec 2020

Minor in Robotics (minor GPA: 4.0)

GPA: 3.7/4.0

- President's Undergraduate Research Award
- Object-Oriented Programming, Computing for Engineers, Machine Learning, Robotics, Control of Dynamic Systems

Skills

Programming Language: Java, C++, C, Python, MATLAB, Simulink

Other Skills & Software: Mechatronics (Arduino, MSP432), Linux, LabView, SolidWorks, ANSYS, Siemens NX, fast prototyping

Work & Research Experience

New Product Development Engineer | Signify (Philips Lighting), Atlanta, GA

Feb 2021-Dec 2021

- Led development of next-gen LED modules to meet functional & space requirements, project deadline, and tooling budget
- · Performed CAD review, mechanical analysis & prelim testing, created test plan, coordinated with internal & external team

Research Assistant | Adaptive Robotic Manipulation Lab, Atlanta, GA

May 2019-Dec 2020

- Multiscale Haptic Simulation: Created CHAI3D (a haptic framework written in C++) and CoppeliaSim (a robot simulator) simulations to validate the framework for controlling 2 programs simultaneously using a haptic device
- Synchronous Position Control of the Haptic Paddle Suite: Prototyped an Arduino-based teleoperation suite (two force-feedback joysticks main & sub), achieved robust real-time position control utilizing a PID controller & signal processing

R&D Engineering Co-op | Medshape, Atlanta, GA

Jan 2019-Dec 2019

- Supported R&D department in design, analysis, testing, and manufacturing of next-gen orthopedic implants
- Designed & prototyped test fixtures & assembly fixtures; Optimized & validated new implant designs with FEA simulations

Shell Tutor for Computing Techniques | Georgia Institute of Technology, Atlanta, GA

May 2018-Dec 2018

Held weekly office hours to help students understand numerical methods and how to implement them using MATLAB

Projects

Automated Leak Sensor Assembling System for Rheem's Smart Water Heater Pan [Capstone]

Fall 2020

- Developed a fully automated system to replace the original manual installation process, cut assembly time by 70%
- Responsible for control system design & implementation (C++), actuator selection, and structural analysis

Instrument Identification for Real-world Music Pieces [CS4641 Machine Learning]

Summer 2020

- Applied supervised learning to identify instruments in the music, achieved a >90% accuracy for test music pieces
- Written in Python, extracted feature vectors using MFCC, and performed classification using SVM

Indoor Obstacle Avoidance Patrolling Vehicle [ME4405 Mechatronics]

Spring 2020

Built & programmed a smart robot car capable of avoiding obstacles autonomously via an MSP432 microcontroller (C++)

EcoCAR Mobility Challenge: Transform a Chevrolet Blazer into a Hybrid Vehicle

Aug 2018-Dec 2019

Propulsion System Integration team & Propulsion Controls and Modeling team

- Implemented safety requirements (e.g., fault detection) for the supervisory controller via Simulink
- Ran FEA to validate modifications to the vehicle using Siemens NX; Simulated performance of radiators using an EES script

Robot Design Challenge [ME 2110 Creative Decisions and Design]

Summer 2018

- Designed, built, and refined a robotic system capable of grasping and moving objects with 3 teammates
- Responsible for programming all the actuators and sensors using LabVIEW via an NI MyRIO microcontroller

Publication

Zhou Z, Zhang Y, Chen P, et al. "Graphene oxide-modified zinc anode for rechargeable aqueous batteries" (Chemical Engineering Science (2019) 142-147)