

# Time-Varying Graph Learning Under Structured Temporal Priors

Xiang Zhang<sup>1</sup>   Qiao Wang<sup>1</sup>

<sup>1</sup>School of Information Science and Engineering  
Southeast University

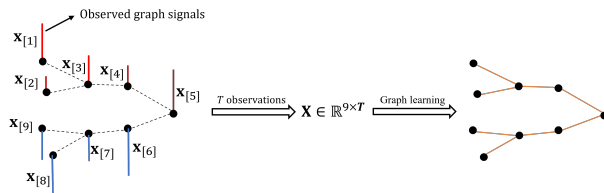
August 30, 2022



- 1 Motivations
- 2 Proposed Model and Algorithm
- 3 Experiments
- 4 Conclusions

- 1 Motivations
- 2 Proposed Model and Algorithm
- 3 Experiments
- 4 Conclusions

- Graph learning



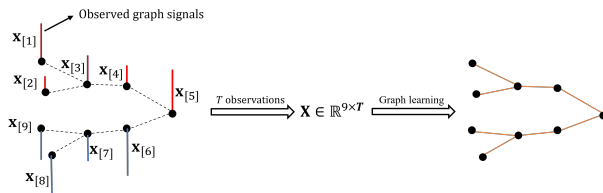
- Classic Formulation [Kal16]

$$\begin{aligned} \min_{\mathbf{L} \in \mathcal{L}} \quad & \text{Tr}(\mathbf{X}^\top \mathbf{L} \mathbf{X}) - \alpha \mathbf{1}^\top \log(\text{diag}(\mathbf{L})) + \frac{\beta}{2} \|\text{diag}(\mathbf{L})\|_F^2, \\ = \min_{\mathbf{w} \geq 0} \quad & 2\mathbf{r}^\top \mathbf{w} - \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}) + \beta \|\mathbf{w}\|_2^2 = \min_{\mathbf{w} \geq 0} f(\mathbf{w}) \end{aligned}$$

- Limitation

Not suitable for time-varying graphs

- Graph learning



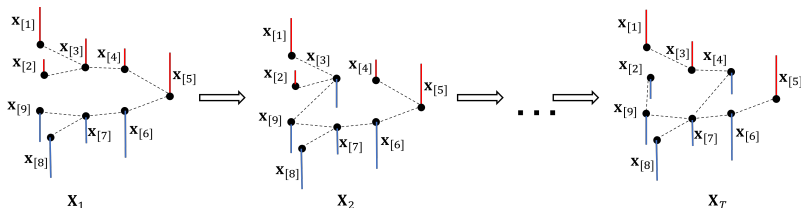
- Classic Formulation [Kal16]

$$\begin{aligned} \min_{\mathbf{L} \in \mathcal{L}} & \text{Tr}(\mathbf{X}^\top \mathbf{L} \mathbf{X}) - \alpha \mathbf{1}^\top \log(\text{diag}(\mathbf{L})) + \frac{\beta}{2} \|\text{diag}_0(\mathbf{L})\|_F^2, \\ = & \min_{\mathbf{w} \geq 0} 2\mathbf{r}^\top \mathbf{w} - \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}) + \beta \|\mathbf{w}\|_2^2 = \min_{\mathbf{w} \geq 0} f(\mathbf{w}) \end{aligned}$$

- Limitation

Not suitable for time-varying graphs

- Time-varying graphs

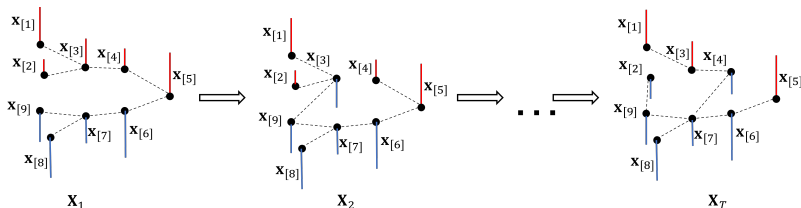


Given  $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_T$  collected during  $T$  time periods, time-varying graph learning aims to infer the topology of the  $T$  graphs jointly.

- Temporal homogeneity [YTO19]

$$\begin{aligned}
 & \min_{\mathbf{w}_t \geq 0} \sum_{t=1}^T f_t(\mathbf{w}_t) + \eta \sum_{t=2}^T \|\mathbf{w}_t - \mathbf{w}_{t-1}\|_1 \\
 & = \min_{\mathbf{w}_t \geq 0} \sum_{t=1}^T 2\mathbf{r}_t^\top \mathbf{w}_t - \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}_t) + \beta \|\mathbf{w}_t\|_2^2 + \eta \sum_{t=2}^T \|\mathbf{w}_t - \mathbf{w}_{t-1}\|_1
 \end{aligned}$$

- Time-varying graphs



Given  $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_T$  collected during  $T$  time periods, time-varying graph learning aims to infer the topology of the  $T$  graphs jointly.

- Temporal homogeneity [YTO19]

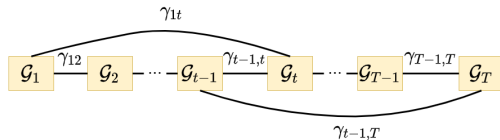
$$\begin{aligned}
 & \min_{\mathbf{w}_t \geq 0} \sum_{t=1}^T f_t(\mathbf{w}_t) + \eta \sum_{t=2}^T \|\mathbf{w}_t - \mathbf{w}_{t-1}\|_1 \\
 & = \min_{\mathbf{w}_t \geq 0} \sum_{t=1}^T 2\mathbf{r}_t^\top \mathbf{w}_t - \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}_t) + \beta \|\mathbf{w}_t\|_2^2 + \eta \sum_{t=2}^T \|\mathbf{w}_t - \mathbf{w}_{t-1}\|_1
 \end{aligned}$$

- 1 Motivations
- 2 Proposed Model and Algorithm
- 3 Experiments
- 4 Conclusions



# Proposed Model and Algorithm

- Temporal graph

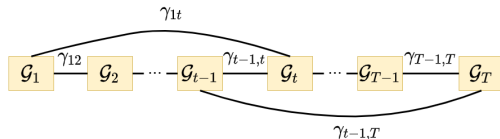


- Our formulation

$$\begin{aligned} & \min_{\mathbf{w}_t \geq 0} \sum_{t \in \mathcal{V}_N} f_t(\mathbf{w}_t) + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{w}_i - \mathbf{w}_j\|_1 \\ &= \min_{\mathbf{w}_t \geq 0} \sum_{t=1}^T 2\mathbf{r}_t^\top \mathbf{w}_t - \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}_t) + \beta \|\mathbf{w}_t\|_2^2 + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{w}_i - \mathbf{w}_j\|_1 \end{aligned}$$

# Proposed Model and Algorithm

- Temporal graph



- Our formulation

$$\begin{aligned} & \min_{\mathbf{w}_t \geq 0} \sum_{t \in \mathcal{V}_N} f_t(\mathbf{w}_t) + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{w}_i - \mathbf{w}_j\|_1 \\ & = \min_{\mathbf{w}_t \geq 0} \sum_{t=1}^T 2\mathbf{r}_t^\top \mathbf{w}_t - \alpha \mathbf{1}^\top \log(\mathbf{S}\mathbf{w}_t) + \beta \|\mathbf{w}_t\|_2^2 + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{w}_i - \mathbf{w}_j\|_1 \end{aligned}$$

- ADMM based algorithm [BBV04]

The original problem is equivalent to

$$\begin{aligned} \min_{\mathbf{w}_t \geq 0} \quad & \sum_{t \in \mathcal{V}_N} f_t(\mathbf{w}_t) + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 \\ \text{s.t. } \quad & \mathbf{w}_i = \mathbf{z}_{ij}, \text{ for } i = 1, \dots, T \text{ and } j \in \mathcal{M}(i) \end{aligned}$$

Scaled augmented Lagrangian:

$$\begin{aligned} & L_\rho(\mathbf{W}, \mathbf{Z}, \mathbf{U}) \\ = & \sum_{t \in \mathcal{V}_N} f_t(\mathbf{w}_t) + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 + \sum_{(i,j) \in \mathcal{E}_N} \left( \frac{\rho}{2} (\|\mathbf{u}_{ij}\|_2^2 + \|\mathbf{u}_{ji}\|_2^2) \right. \\ & \left. + \frac{\rho}{2} (\|\mathbf{w}_i - \mathbf{z}_{ij} + \mathbf{u}_{ij}\|_2^2 + \|\mathbf{w}_j - \mathbf{z}_{ji} + \mathbf{u}_{ji}\|_2^2) \right), \end{aligned}$$

- ADMM based algorithm [BBV04]

The original problem is equivalent to

$$\begin{aligned} \min_{\mathbf{w}_t \geq 0} \quad & \sum_{t \in \mathcal{V}_N} f_t(\mathbf{w}_t) + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 \\ \text{s.t. } \quad & \mathbf{w}_i = \mathbf{z}_{ij}, \text{ for } i = 1, \dots, T \text{ and } j \in \mathcal{M}(i) \end{aligned}$$

Scaled augmented Lagrangian:

$$\begin{aligned} & L_\rho(\mathbf{W}, \mathbf{Z}, \mathbf{U}) \\ = & \sum_{t \in \mathcal{V}_N} f_t(\mathbf{w}_t) + \eta \sum_{(i,j) \in \mathcal{E}_N} \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 + \sum_{(i,j) \in \mathcal{E}_N} \left( \frac{\rho}{2} (\|\mathbf{u}_{ij}\|_2^2 + \|\mathbf{u}_{ji}\|_2^2) \right. \\ & \left. + \frac{\rho}{2} (\|\mathbf{w}_i - \mathbf{z}_{ij} + \mathbf{u}_{ij}\|_2^2 + \|\mathbf{w}_j - \mathbf{z}_{ji} + \mathbf{u}_{ji}\|_2^2) \right), \end{aligned}$$

# Proposed Model and Algorithm

- ADMM based algorithm

Update of  $\mathbf{W}$  :

$$\mathbf{w}_t^{k+1} = \underset{\mathbf{w}_t \geq 0}{\operatorname{argmin}} f_t(\mathbf{w}_t) + \frac{\rho}{2} \sum_{j \in \mathcal{M}(t)} \|\mathbf{w}_t - \mathbf{z}_{tj}^k + \mathbf{u}_{tj}^k\|_2^2$$

Update of  $\mathbf{Z}$  :

$$\begin{aligned} & \mathbf{z}_{ij}^{k+1}, \mathbf{z}_{ji}^{k+1} \\ &= \underset{\mathbf{z}_{ij}, \mathbf{z}_{ji}}{\operatorname{argmin}} \eta \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 + \frac{\rho}{2} \left( \left\| \mathbf{w}_i^{k+1} - \mathbf{z}_{ij} + \mathbf{u}_{ij}^k \right\|_2^2 + \left\| \mathbf{w}_j^{k+1} - \mathbf{z}_{ji} + \mathbf{u}_{ji}^k \right\|_2^2 \right) \\ & \Rightarrow \begin{bmatrix} \mathbf{z}_{ij}^{k+1} \\ \mathbf{z}_{ji}^{k+1} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} \mathbf{e}_i^k + \mathbf{e}_j^k \\ \mathbf{e}_i^k + \mathbf{e}_j^k \end{bmatrix} + \frac{1}{2} \begin{bmatrix} -\operatorname{prox}_{\frac{2\eta\gamma_{ij}}{\rho} \|\cdot\|_1} (\mathbf{e}_j^k - \mathbf{e}_i^k) \\ \operatorname{prox}_{\frac{2\eta\gamma_{ji}}{\rho} \|\cdot\|_1} (\mathbf{e}_j^k - \mathbf{e}_i^k) \end{bmatrix}, \\ & \text{where } \mathbf{e}_i = \mathbf{u}_{ij}^k + \mathbf{w}_i^{k+1} \end{aligned}$$

Update of  $\mathbf{U}$  :

$$\begin{aligned} \mathbf{u}_{ij}^{k+1} &= \mathbf{u}_{ij}^k + \mathbf{w}_i^{k+1} - \mathbf{z}_{ij}^{k+1} \\ \mathbf{u}_{ji}^{k+1} &= \mathbf{u}_{ji}^k + \mathbf{w}_j^{k+1} - \mathbf{z}_{ji}^{k+1} \end{aligned}$$

# Proposed Model and Algorithm

- ADMM based algorithm

Update of  $\mathbf{W}$  :

$$\mathbf{w}_t^{k+1} = \underset{\mathbf{w}_t \geq 0}{\operatorname{argmin}} f_t(\mathbf{w}_t) + \frac{\rho}{2} \sum_{j \in \mathcal{M}(t)} \|\mathbf{w}_t - \mathbf{z}_{tj}^k + \mathbf{u}_{tj}^k\|_2^2$$

Update of  $\mathbf{Z}$  :

$$\begin{aligned} & \mathbf{z}_{ij}^{k+1}, \mathbf{z}_{ji}^{k+1} \\ &= \underset{\mathbf{z}_{ij}, \mathbf{z}_{ji}}{\operatorname{argmin}} \eta \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 + \frac{\rho}{2} \left( \left\| \mathbf{w}_i^{k+1} - \mathbf{z}_{ij} + \mathbf{u}_{ij}^k \right\|_2^2 + \left\| \mathbf{w}_j^{k+1} - \mathbf{z}_{ji} + \mathbf{u}_{ji}^k \right\|_2^2 \right) \\ \Rightarrow & \begin{bmatrix} \mathbf{z}_{ij}^{k+1} \\ \mathbf{z}_{ji}^{k+1} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} \mathbf{e}_i^k + \mathbf{e}_j^k \\ \mathbf{e}_i^k + \mathbf{e}_j^k \end{bmatrix} + \frac{1}{2} \begin{bmatrix} -\operatorname{prox}_{\frac{2\eta\gamma_{ij}}{\rho} \|\cdot\|_1} (\mathbf{e}_j^k - \mathbf{e}_i^k) \\ \operatorname{prox}_{\frac{2\eta\gamma_{ji}}{\rho} \|\cdot\|_1} (\mathbf{e}_j^k - \mathbf{e}_i^k) \end{bmatrix}, \\ & \text{where } \mathbf{e}_i = \mathbf{u}_{ij}^k + \mathbf{w}_i^{k+1} \end{aligned}$$

Update of  $\mathbf{U}$  :

$$\begin{aligned} \mathbf{u}_{ij}^{k+1} &= \mathbf{u}_{ij}^k + \mathbf{w}_i^{k+1} - \mathbf{z}_{ij}^{k+1} \\ \mathbf{u}_{ji}^{k+1} &= \mathbf{u}_{ji}^k + \mathbf{w}_j^{k+1} - \mathbf{z}_{ji}^{k+1} \end{aligned}$$

# Proposed Model and Algorithm

- ADMM based algorithm

Update of  $\mathbf{W}$  :

$$\mathbf{w}_t^{k+1} = \underset{\mathbf{w}_t \geq 0}{\operatorname{argmin}} f_t(\mathbf{w}_t) + \frac{\rho}{2} \sum_{j \in \mathcal{M}(t)} \|\mathbf{w}_t - \mathbf{z}_{tj}^k + \mathbf{u}_{tj}^k\|_2^2$$

Update of  $\mathbf{Z}$  :

$$\begin{aligned} & \mathbf{z}_{ij}^{k+1}, \mathbf{z}_{ji}^{k+1} \\ &= \underset{\mathbf{z}_{ij}, \mathbf{z}_{ji}}{\operatorname{argmin}} \eta \gamma_{ij} \|\mathbf{z}_{ij} - \mathbf{z}_{ji}\|_1 + \frac{\rho}{2} \left( \left\| \mathbf{w}_i^{k+1} - \mathbf{z}_{ij} + \mathbf{u}_{ij}^k \right\|_2^2 + \left\| \mathbf{w}_j^{k+1} - \mathbf{z}_{ji} + \mathbf{u}_{ji}^k \right\|_2^2 \right) \\ & \Rightarrow \begin{bmatrix} \mathbf{z}_{ij}^{k+1} \\ \mathbf{z}_{ji}^{k+1} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} \mathbf{e}_i^k + \mathbf{e}_j^k \\ \mathbf{e}_i^k + \mathbf{e}_j^k \end{bmatrix} + \frac{1}{2} \begin{bmatrix} -\operatorname{prox}_{\frac{2\eta\gamma_{ij}}{\rho} \|\cdot\|_1} (\mathbf{e}_j^k - \mathbf{e}_i^k) \\ \operatorname{prox}_{\frac{2\eta\gamma_{ji}}{\rho} \|\cdot\|_1} (\mathbf{e}_j^k - \mathbf{e}_i^k) \end{bmatrix}, \\ & \text{where } \mathbf{e}_i = \mathbf{u}_{ij}^k + \mathbf{w}_i^{k+1} \end{aligned}$$

Update of  $\mathbf{U}$  :

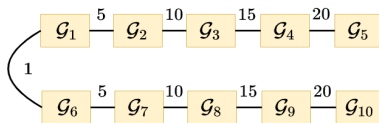
$$\begin{aligned} \mathbf{u}_{ij}^{k+1} &= \mathbf{u}_{ij}^k + \mathbf{w}_i^{k+1} - \mathbf{z}_{ij}^{k+1} \\ \mathbf{u}_{ji}^{k+1} &= \mathbf{u}_{ji}^k + \mathbf{w}_j^{k+1} - \mathbf{z}_{ji}^{k+1} \end{aligned}$$

- 1 Motivations
- 2 Proposed Model and Algorithm
- 3 Experiments**
- 4 Conclusions



# Experiments

- Main settings
  - Graph generation



- Graph signal generation [DTFV16]

$$\mathbf{x} \sim \text{Gauss} \left( 0, (\mathbf{L}_t + \sigma_w^2 \mathbf{I})^\dagger \right)$$

- Evaluation metrics

$$\text{MCC} = \frac{\text{TP} \cdot \text{TN} - \text{FP} \cdot \text{FN}}{\sqrt{(\text{TP} + \text{FP})(\text{TP} + \text{FN})(\text{TN} + \text{FP})(\text{TN} + \text{FN})}}$$

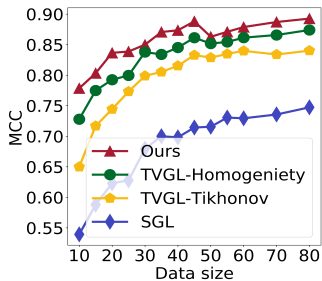
$$\text{Relative error} = \frac{\|\mathbf{A}^* - \mathbf{A}_{\text{gt}}\|_{\text{F}}}{\|\mathbf{A}_{\text{gt}}\|_{\text{F}}}$$

- Baselines

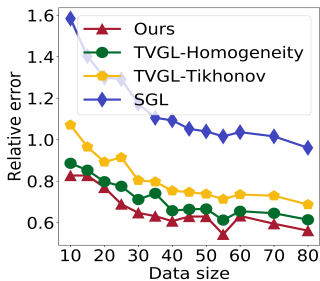
(1) SGL [Kal16], (2) TVGL-Homogeniety [YTO19] (3)TVGL-Tikhonov [KLTF17]

# Experiments

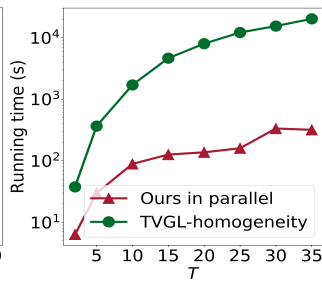
- Synthetic data



(a)



(b)



(c)

Figure: (a)-(b) Performance of different sample sizes; (c) Performance of running time

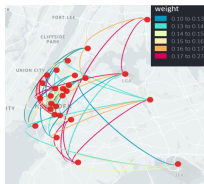
- Data source: Yellow Taxi Trip data of New York city <sup>1</sup>
- Task: Learn time-varying travel relationships between different taxi zones.
- Data selection: Data from 0 a.m. to 12 a.m. of 20 workdays in September

---

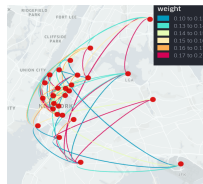
<sup>1</sup><https://data.cityofnewyork.us/Transportation/2018-Yellow-Taxi-Trip-Data>

# Experiments

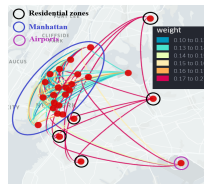
- Real data



(a) 2 a.m. - 3 a.m.



(b) 4 a.m. - 5 a.m.



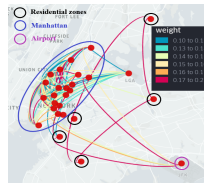
(c) 8 a.m. - 9 a.m.



(d) 2 a.m. - 3 a.m.



(e) 4 a.m. - 5 a.m.



(f) 8 a.m. - 9 a.m.

**Figure:** The learned graphs of taxi zones of New York. The upper row (a)-(c) shows results of our model and the lower row (d)-(e) shows the results of TV-Homogeneity model.

- 1 Motivations
- 2 Proposed Model and Algorithm
- 3 Experiments
- 4 Conclusions**

- Our proposed model can describe intricate temporal relationships effectively
- The ADMM based algorithm can solve the induced optimization problem in a parallel manner efficiently.
- Experimental results of both synthetic and real data illustrate the superiority of our model and algorithm.

# The End

- [BBV04] Stephen Boyd, Stephen P Boyd, and Lieven Vandenberghe, *Convex optimization*, Cambridge university press, 2004.
- [DTFV16] Xiaowen Dong, Dorina Thanou, Pascal Frossard, and Pierre Vandergheynst, *Learning laplacian matrix in smooth graph signal representations*, IEEE Transactions on Signal Processing **64** (2016), no. 23, 6160–6173.
- [Kal16] Vassilis Kalofolias, *How to learn a graph from smooth signals*, Artificial Intelligence and Statistics, PMLR, 2016, pp. 920–929.
- [KLTF17] Vassilis Kalofolias, Andreas Loukas, Dorina Thanou, and Pascal Frossard, *Learning time varying graphs*, 2017 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), Ieee, 2017, pp. 2826–2830.
- [YTO19] Koki Yamada, Yuichi Tanaka, and Antonio Ortega, *Time-varying graph learning based on sparseness of temporal variation*, ICASSP 2019-2019 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), IEEE, 2019, pp. 5411–5415.