# Dimensionality Reduction Part 1: PCA and KPCA

Ng Yen Kaow

### **Dimensionality Reduction**

- Linear methods
  - **PCA** (Principal Component Analysis)
  - CMDS (Classical Multidimensional Scaling)
- Non-linear methods
  - **KPCA** (Kernel PCA)
  - mMDS (Metric MDS)
  - Isomap
  - LLE (Locally Linear Embedding)
  - Laplacian Eigenmap
  - t-SNE (t-distributed Stochastic Neighbor Embedding)
  - UMAP (Uniform Manifold Approximation and Projection)

- □ Let X be an  $n \times m$  matrix where each row represents a datapoint in an m-D space
  - X is like a spreadsheet with features in column and data cases in the rows
- We want to identify some form of "principal directions" of X, where ideally
  - 1. The directions should form a basis
  - 2. The directions should be orthogonal
  - 3. The first direction should account for the most variation, the second direction accounts for the most variation after removing the first, and so on

- Assume datapoints in X are generated by a random vector  $X = [v_1, ..., v_m]$ , where each  $v_i$  is a random variable
  - Covariance  $cov(\boldsymbol{v}_i, \boldsymbol{v}_j) = \mathbb{E}[(\boldsymbol{v}_i \mu_i)(\boldsymbol{v}_j \mu_j)]$
  - Define covariance matrix  $M = (m_{ij})$  of X where  $m_{ij} = \text{cov}(\boldsymbol{v}_i, \boldsymbol{v}_j)$  (M can be estimated from  $X = (x_{ij})$  as the outer product  $X^{c^{\mathsf{T}}}X^c/n$  of a centered matrix  $X^c = (x_{ij}^c)$  where  $x_{ij}^c = x_{ij} \mu_i$ )
- For the first principal direction, we want to find unit vector  $u \in \mathbb{R}^m$  such that variance  $var(u^T X)$  is maximized

The eigenvector u of the covariance matrix M of X with the largest eigenvalue maximizes var(u<sup>T</sup>X)

Let  $X \in \mathbb{R}^m$  be a random vector with

- mean vector  $\mu \in \mathbb{R}^m$  and
- covariance matrix  $M = \mathbb{E}[(X \mu)(X \mu)^{\top}]$

For any  $u \in \mathbb{R}^n$ , the projection of  $u^T X$  has

- $\blacksquare$   $\mathbb{E}[u^{\mathsf{T}}X] = u^{\mathsf{T}}\mu$  and
- $var(u^{\mathsf{T}}X) = \mathbb{E}[(u^{\mathsf{T}}X u^{\mathsf{T}}\mu)^{2}]$  $= \mathbb{E}[u^{\mathsf{T}}(X \mu)(X \mu)^{\mathsf{T}}u] = u^{\mathsf{T}}Mu$

From min-max theorem,  $u^TMu$  is maximized when u is the eigenvector of M with the largest eigenvalue

Gives a matrix since X and  $\mu$  are column vectors

- $\square$  Extend to k principal directions, we want
  - k-D subspace of X that is defined by orthogonal basis  $p_1, \dots, p_k \in \mathbb{R}^m$  and displacement  $p_0 \in \mathbb{R}^m$
  - Distance from X to this subspace is minimized
  - Projection of X onto subspace is  $P^TX + p_0$ , where P is matrix whose rows are  $p_1, \dots, p_k$
  - Squared distance to subspace is  $\mathbb{E}||X (P^TX + p_0)||^2$
  - By calculus,  $\mathbf{p_0} = \mathbb{E}||\mathbf{X} P^{\mathsf{T}}\mathbf{X}|| = (1 P^{\mathsf{T}})\mu$ , hence  $\mathbb{E}||\mathbf{X} (P^{\mathsf{T}}\mathbf{X} + p_{\mathbf{0}})||^2 = \mathbb{E}||\mathbf{X} \mu||^2 \mathbb{E}||P^{\mathsf{T}}(\mathbf{X} \mu)||^2$
  - To maximize that, need to maximize  $\mathbb{E}\|P^{\mathsf{T}}(X-\mu)\|^2 = \text{var}(P^{\mathsf{T}}X)$
  - Finally, same as in previous slide,  $p_1, ..., p_k$  are eigenvectors of M

As mentioned, given a centered matrix  $X^c = (x_{ij}^c)$  where  $x_{ij}^c = x_{ij} - \mu_i$ , an unbiased estimator of M can be obtained as

$$M = \frac{1}{n} X^{c \top} X^{c} \quad \text{(or } M = \frac{1}{n} \sum_{i} x_{i}^{c \top} x_{i}^{c} \text{)}$$

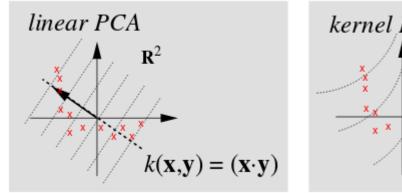
- This implies that M is positive semi-definite
- $\square$  Since SVD of *X* eigendecomposes  $X^{c^{\mathsf{T}}}X^{c}$ 
  - We can solve PCA through either
    - 1. Eigendecompose M, or
    - 2. Solve SVD for  $X^c$

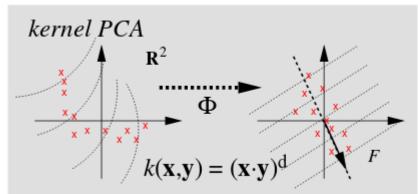
### Advantages of PCA with SVD

- □ SVD of matrix  $X^c$  performs a eigendecomposition of  $X^{c^T}X^c$ 
  - No need to compute  $X^{c^{T}}X^{c}$
  - Given SVD of  $X^c = USV^T$ ,
    - $\square$  *V* is the eigenvectors of  $X^{c^{\top}}X^{c}$
    - $\Box$   $S^2$  is the eigenvalues of  $X^{c^T}X^c$
    - $\Box$  Since  $X^cV = USV^TV = US$ 
      - $\Rightarrow$  US gives the projection of  $X^c$  on the principal directions V (called principal component scores)

#### Kernel PCA motivation

 $\hfill \square$  Datapoints that do not lie on a linear manifold in the coordinate space may lie on one after some non-linear feature map  $\phi$  to a high dimensional space





Scholkopf, Smola, and Muller. Kernel Principal Component Analysis, 1999

 $\Box$  Principal components in the  $\phi$ -mapped feature space may be more meaningful

#### Kernel PCA idea

- □ Steps to get the principal components in a  $\phi$ -mapped feature space:
  - 1.  $x' = \phi(x)$  and  $X' = [x_1' \quad ... \quad x_n']^{\top}$
  - 2. Center X' (deduct column mean)
  - 3. Find covariance matrix,  $M' = \frac{1}{n} \sum_{i} x_{i}'^{\mathsf{T}} x_{i}'$
  - 4. Eigendecompose M'
- □ Difficult since dimension of x', dim(x') will be large (or even  $\infty$ )
  - $\Rightarrow M'$  has large (or even  $\infty$ ) dimensions
  - ⇒ Eigendecomposition of M' gives large (or infinite) number of eigenvectors, each of large (or infinite) dimensions

#### Kernel PCA idea

#### Problem 1: Large number of eigenvectors

- How many eigenvectors are there actually
  - rank(M'), bounded by the number of datapoints
    - Recall that eigenvectors can be expressed as a linear combination of the datapoints by solving the equations  $x_i' = \sum_i \langle x_i', u_j \rangle u_j$ 
      - j is bounded by  $rank(M') \Rightarrow may$  be manageable
      - However, working with the system of equations is hard because  $x_i$  and  $u_i$  are of...

Problem 2: Large (or ∞) dimensions

#### Kernel method

- □ Do not compute  $\phi(x_1), ..., \phi(x_n)$  or eigenvectors of M'
  - Allow only comparisons between datapoints in mapped space through inner product  $\langle x_i', x_i' \rangle$ 
    - Sufficient for writing eigenvector u of M' in terms of  $\phi(x_1), ..., \phi(x_n)$  (i.e. project u onto  $\phi(x_1), ..., \phi(x_n)$ )
    - $\square$  Sufficient for finding the eigenvalues of M'
    - Given point x, sufficient for finding the projection of  $\phi(x)$  on the eigenvectors of M'
  - Use a function  $K(x_i, x_j)$  (called a kernel function) that does not require computing  $\phi$  to compute  $\langle x_i', x_i' \rangle$ 
    - Conditions for such a function given in later slides

## Project eigenvector to $x'_1, ..., x'_n$

- Relate eigenvectors of M' with  $x'_1, ..., x'_n$  using a computation that involves only  $\langle x'_i, x'_i \rangle$
- □ Start with the definition of  $M' = \frac{1}{n} \left( \sum_{i=1}^{n} x_i'^{\mathsf{T}} x_i' \right)$ 
  - Solving  $M'u = \lambda u$  means  $(\sum_i x_i'^{\mathsf{T}} x_i')u = n\lambda u$
  - This implies  $u = \frac{1}{n\lambda} \sum_{i} x_{i}'^{\mathsf{T}} x_{i}' u$ . Since

$$x^{\mathsf{T}}xu = xux^{\mathsf{T}}, \ u = \frac{1}{n\lambda}\sum_{i} x_{i}'ux_{i}'^{\mathsf{T}}$$

Hence can let  $u = \sum_{i=1}^{n} \alpha_i x_i^{\prime \top}$  for  $\alpha_i \in \mathbb{R}$ 

- $\alpha_1, \ldots, \alpha_n$  project eigenvector u to  $x'_1, \ldots, x'_n$
- $\square \quad \text{Place } u^{(r)} = \sum_{i} \alpha_{i}^{(r)} x_{i}^{\prime \top} \text{ back in } (\sum_{i} x_{i}^{\prime \top} x_{i}^{\prime}) u = n \lambda u$ 
  - Use superscript r to associate  $\alpha$  with its corresponding u and  $\lambda$

(Terms in bold cannot be reordered)

Solving  $\alpha_1, \dots, \alpha_n$ 

System of dim(u) equations

$$\left(\sum_{i=1}^{n} {\boldsymbol{x}_{i}^{\prime}}^{\mathsf{T}} {\boldsymbol{x}_{i}^{\prime}}\right) \boldsymbol{u}^{(r)} = n \lambda^{(r)} \boldsymbol{u}^{(r)}$$

Replace  $u^{(r)}$  with  $\sum_{j} \alpha_{j}^{(r)} x_{j}^{\prime \top}$ 

$$\left(\sum_{i=1}^{n} x_{i}^{'\top} x_{i}^{'}\right) \sum_{j=1}^{n} \alpha_{j}^{(r)} x_{j}^{'\top} = n \lambda^{(r)} \sum_{k=1}^{n} \alpha_{k}^{(r)} x_{k}^{'\top}$$

Reorder

$$\left(\sum_{i} \mathbf{x}_{i}^{\prime\top}\right) \sum_{j} \mathbf{x}_{i}^{\prime} \mathbf{x}_{j}^{\prime\top} \alpha_{j}^{(r)} = n \lambda^{(r)} \sum_{k} \mathbf{x}_{k}^{\prime\top} \alpha_{k}^{(r)}$$

Multiply from the left with  $x'_l$  (equation holds for each l)

 $\left(\sum_{i} x_{i}' x_{i}'^{\mathsf{T}}\right) \sum_{j} x_{i}' x_{j}'^{\mathsf{T}} \alpha_{j}^{(r)} = n \lambda^{(r)} \sum_{k} x_{i}' x_{k}'^{\mathsf{T}} \alpha_{k}^{(r)}$ scalar

Replace  $x_i'x_i'^{\mathsf{T}}$  with the kernel function

$$\sum_{i} K(x_i, x_i) \sum_{j} K(x_i, x_j) \alpha_j^{(r)} = n \lambda^{(r)} \sum_{k} K(x_i, x_k) \alpha_k^{(r)}$$

Reorder

$$\sum_{\substack{i \text{ 2021. Ng Yen Kaow}}} K(x_l, x_i) K(x_i, x_j) \alpha_j^{(r)} = n \lambda^{(r)} \sum_k K(x_l, x_k) \alpha_k^{(r)}$$

### Solving $\alpha_1, \dots, \alpha_n$

$$\sum_{i} \sum_{j} K(x_l, x_i) K(x_i, x_j) \alpha_j^{(r)} = n \lambda^{(r)} \sum_{k} K(x_l, x_k) \alpha_k^{(r)}$$

Replace  $K(x_i, x_j)$  with a matrix K where  $k_{ij} = K(x_i, x_j)$  (K is called a kernel matrix)

$$\sum_{i} \sum_{j} k_{li} k_{ij} \alpha_{j}^{(r)} = n \lambda^{(r)} \sum_{k} k_{lk} \alpha_{k}^{(r)}$$

 $= n\lambda^{(r)} \left( k_{21}\alpha_1^{(r)} + k_{21}\alpha_2^{(r)} + \cdots \right)$ 

For each l this gives one single equation with a linear combination of the variables  $\alpha_1^{(r)}, ..., \alpha_n^{(r)}$ 

$$e.g. \ l = 2$$

$$K_1^{\top} \quad K_2^{\top}$$

$$K_l \rightarrow \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} k_{11}^{\top} & k_{12}^{\top} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ k_{21} & k_{22} & \dots \\ \alpha_2^{(r)} \\ \vdots & \vdots & \ddots \end{bmatrix} = n\lambda^{(r)} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots & \vdots & \ddots \end{bmatrix}$$

$$(k_{21}k_{11} + k_{22}k_{21} + \dots)\alpha_1^{(r)} + (k_{21}k_{12} + k_{22}k_{22} + \dots)\alpha_2^{(r)} + \dots$$

Solving 
$$\alpha_1, \ldots, \alpha_n$$

$$K_1^T \quad K_2^T \quad \text{System of one equation}$$

$$K_l \rightarrow \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots \\ \vdots \end{bmatrix} = n\lambda^{(r)} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots \\ \vdots \end{bmatrix}$$

Repeat l for 1 to n

$$\begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots & \vdots & \ddots \end{bmatrix} = n\lambda^{(r)} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots & \vdots & \ddots \end{bmatrix}$$

System of *n* equations

This in matrix notation is

$$K^2 \alpha^{(r)} = n \lambda^{(r)} K \alpha^{(r)}$$

Each  $\alpha^{(r)}$  that fulfills the equation gives us a eigenvector  $u^{(r)}$  of the covariance matrix M' in terms of the data  $x_i'$ 

### Solving $\alpha_1, \dots, \alpha_n$

Removing K from both sides will only affect the  $\alpha^{(r)}$  with zero  $\lambda^{(r)}$  (proof omitted), leaving the final form of the eigenvalue system

$$K\alpha^{(r)} = n\lambda^{(r)}\alpha^{(r)}$$

Since  $\|\boldsymbol{u}\| = 1$ , we require  $n\lambda\boldsymbol{\alpha}^{\mathsf{T}}\boldsymbol{\alpha} = 1 \Rightarrow \|\boldsymbol{\alpha}\|^2 = 1/n\lambda \Rightarrow \|\boldsymbol{\alpha}\| = \sqrt{1/n\lambda}$ 

However,  $\alpha^*$  from the eigendecomposition of K has unit length and eigenvalue  $\lambda^* = n\lambda^{(r)}$ 

To correct for this, 
$$\alpha^{(r)} = \frac{\alpha^*}{\sqrt{n\lambda^{(r)}}} = \frac{\alpha^*}{\sqrt{n\lambda^*/n}} = \frac{\alpha^*}{\sqrt{\lambda^*}}$$

Since  $\lambda^{(r)} = \lambda^*/n$ , the relative importance of the eigenvectors can be determined from  $\lambda^*$ 

### Proof for $||u|| = 1 \Rightarrow n\lambda\alpha^{T}\alpha = 1$

 $\Box$  Since ||u|| = 1

$$\mathbf{u}^{\mathsf{T}}\mathbf{u} = 1$$

$$\left(\sum_{i} \alpha_{i} \mathbf{x}_{i}^{\prime\mathsf{T}}\right)^{\mathsf{T}} \left(\sum_{j} \alpha_{j} \mathbf{x}_{j}^{\prime\mathsf{T}}\right) = 1$$

$$\sum_{i} \sum_{j} \alpha_{i} \alpha_{j} \mathbf{x}_{i}^{\prime} \mathbf{x}_{j}^{\prime\mathsf{T}} = 1$$

$$\sum_{i} \sum_{j} \alpha_{i} K_{ij} \alpha_{j} = 1$$

 $\square \text{ Multiply } \alpha_i \text{ to } \sum_j K_{ij} \alpha_j = n\lambda \sum_k \alpha_k \text{ gives} \\ n\lambda \sum_i \sum_k \alpha_i \alpha_k = \sum_i \sum_j \alpha_i K_{ij} \alpha_j \\ n\lambda \sum_i \sum_k \alpha_i \alpha_k = 1 \\ n\lambda \boldsymbol{\alpha}^\top \boldsymbol{\alpha} = 1$ 

### Proof for $x^{T}xu = xux^{T}$

$$(v^{T}v)u = \begin{pmatrix} v_{1}v_{1} & \dots & v_{1}v_{n} \\ \vdots & \ddots & \vdots \\ v_{n}v_{1} & \dots & v_{n}v_{n} \end{pmatrix} \begin{pmatrix} u_{1} \\ \vdots \\ u_{n} \end{pmatrix}$$

$$= \begin{pmatrix} v_{1}v_{1}u_{1} + \dots + v_{1}v_{n}u_{n} \\ \vdots \\ v_{n}v_{1}u_{1} + \dots + v_{n}v_{n}u_{n} \end{pmatrix}$$

$$= \begin{pmatrix} (v_{1}u_{1} + \dots + v_{n}u_{n})v_{1} \\ \vdots \\ (v_{1}u_{1} + \dots + v_{n}u_{n})v_{n} \end{pmatrix}$$

$$= (v_1 u_1 + \dots + v_n u_n) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

### Projection of $\phi(x)$ on u

□ Given a point y, the projection of  $\phi(y)$  on the eigenvector  $u^{(r)}$  of M' can be computed using  $\alpha^{(r)}$  as

$$\phi(y)u^{(r)} = \sum_{i=1}^{n} \alpha_i^{(r)} \phi(y)^{\mathsf{T}} x_i'$$
$$= \sum_{i} \alpha_i^{(r)} K(y, x_i)$$

 This allows the principal components to be used for clustering existing datapoints as well as classifying out-of-sample datapoints into the clusters

### Normalizing M'

- $\square$  X' has been assumed to be normalized so far
- $\square$  To normalize a matrix X', subtract every column with the mean of the column:

$$x^* = x' - \frac{1}{n} \sum_{i=1}^n x_i'$$

The corresponding kernel,

$$K^{*}(x_{i}, x_{j}) = x_{i}^{*} x_{j}^{*} = \left(x' - \frac{1}{n} \sum_{i=1}^{n} x_{i}'\right) \left(x' - \frac{1}{n} \sum_{i=1}^{n} x_{i}'\right)$$

$$= K(x_{i}, x_{j}) - \frac{1}{n} \sum_{k=1}^{n} K(x_{i}, x_{k})$$

$$- \frac{1}{n} \sum_{k=1}^{n} K(x_{j}, x_{k}) + \frac{1}{n^{2}} \sum_{l,k=1}^{n} K(x_{l}, x_{k})$$

Or in matrix notation

$$K^* = K - 2\mathbf{1}_{1/n}K + \mathbf{1}_{1/n}K\mathbf{1}_{1/n}$$

#### Kernel functions

- A kernel function K implicitly defines a mapping  $\phi$  from an input space to some feature space
- Positive semi-definite functions are those that produce positive semi-definite kernel matrices
  - **Definition**. A symmetric function K is called positive semi-definite over  $\chi$  if and only if for every set of elements  $x_1, ..., x_n \in \chi$ , the matrix  $K = (x_{ij})$  where  $x_{ij} = K(x_i, x_j)$  is positive semidefinite
- □ Kernel functions must be positive semidefinite
   Hilbert space (ignore for now)
  - **Theorem**. A mapping  $\phi$  exists for  $K: \chi \to \mathcal{H}$  such that  $K(x, x') = \langle \phi(x), \phi(x') \rangle \iff K$  is a positive semi-definite symmetric matrix

#### Kernel functions

#### Properties

Symmetric	K(x,x') = K(x',x)
Cauchy-Schwarz inequality	$ K(x,x')  \le \sqrt{K(x,x)K(x',x')}$
Definiteness	$K(x,x) = \ \phi(x)\ ^2 \ge 0$

#### Kernel property conservation

Sum	$K, K'$ are kernels $\Rightarrow K + K'$ is kernel
Product	$K$ , $K'$ are kernels $\Rightarrow KK'$ is kernel
Scaling	$K$ is kernel $\Rightarrow \alpha K$ is kernel for positive real $\alpha$
Polynomial combination	$K$ is kernel $\Rightarrow p(K)$ is kernel for polynomial $p$ of degree $m$ with positive coefficients

#### Kernel functions

#### Common kernel functions

Linear	$K(x,x') = xx'^{\top}$
Cosine	$K(x, x') = xx'^{T} /   x     x'  $
Gaussian	$K(x,x') = \exp(-\gamma   x - x'  ^2)$
Polynomial	$K(x, x') = (\gamma x x'^{T} + c)^d \text{ for } \gamma, c \in \mathbb{R}^+, d \in \mathbb{N}^+$
Sigmoid	$K(x, x') = \tanh(\gamma x x'^{T} + c) \text{ for } \gamma, c \in \mathbb{R}^+$

See <a href="http://crsouza.com/2010/03/17/kernel-functions-for-machine-learning-applications">http://crsouza.com/2010/03/17/kernel-functions-for-machine-learning-applications</a> for a collection of uncommon kernel functions