Neal Jean Blog

Fréchet Inception Distance

Jul 15, 2018

TL;DR: FID measures the distance between the Inception-v3 activation distributions for generated and real samples

I often run into things that are new to me (but not explained in that particular paper) when I'm reading. A recent example is Fréchet Inception Distance (FID), a method for measuring the quality of generated image samples.

Inception Score

Before FID, the Inception Score (IS) was the original method for measuring the quality of generated samples. (Salimans et al., 2016) proposed applying an Inception-v3 network pre-trained on ImageNet to generated samples and then comparing the conditional label distribution with the marginal label distribution:

$$IS = \exp(\mathbb{E}_{x \sim p_{g}} D_{KL}(p(y|x)||p(y)))$$

Ideally, the generator should:

- 1. Generate images **with meaningful objects**, so that the conditional label distribution p(y|x) is *low entropy*.
- 2. Generate **diverse** images, so that the marginal label distribution $p(y) = \int_{x} p(y|x)p_{g}(x)$ is high entropy.

Higher scores are better, corresponding to a larger KL-divergence between the two distributions.

Fréchet Inception Distance

The FID is supposed to improve on the IS by actually *comparing* the statistics of generated samples to real samples, instead of evaluating generated samples in a vacuum.¹ (Heusel, Ramsauer, Unterthiner, Nessler, & Hochreiter, 2017) propose using the Fréchet distance between two multivariate Gaussians,

FID =
$$||\mu_r - \mu_g||^2 + \text{Tr}(\Sigma_r + \Sigma_g - 2(\Sigma_r \Sigma_g)^{1/2}),$$

where $X_r \sim \mathcal{N}(\mu_r, \Sigma_r)$ and $X_g \sim \mathcal{N}(\mu_g, \Sigma_g)$ are the 2048-dimensional activations of the Inception-v3 pool3 layer for real and generated samples respectively.²

Lower FID is better, corresponding to more similar real and generated samples as measured by the distance between their activation distributions.

Measuring progress

It's helpful to look at some of the IS and FID scores that have been reported to get a feel for what good/bad scores look like and see how different models compare.

These scores are for unsupervised models on CIFAR-10:³

Paper	IS	FID
Real CIFAR-10 data (Salimans et al., 2016)	11.24	_
Unsupervised representation learning with deep convolutional generative adversarial networks (DCGAN) (Radford, Metz, & Chintala, 2015)	6.16 ⁴	37.1 ⁵
Conditional image generation with PixelCNN decoders (van den Oord et al., 2016)	4.60 ⁶	65.9 ⁶
Adversarially learned inference (ALI) (Dumoulin et al., 2016)	5.34 ⁷	_
Improved techniques for training GANs (Salimans et al., 2016)	6.86	_
Improving generative adversarial networks with denoising		

feature matching (Warde-Farley & Bengio, 2016)	7.72	_
Learning to generate samples from noise through infusion training (Bordes, Honari, & Vincent, 2017)	4.62	_
BEGAN: Boundary equilibrium generative adversarial networks (Berthelot, Schumm, & Metz, 2017)	5.62	_
MMD GAN: Towards deeper understanding of moment matching network (Li, Chang, Cheng, Yang, & Póczos, 2017)	6.17	_
Improved training of Wasserstein GANs (Gulrajani, Ahmed, Arjovsky, Dumoulin, & Courville, 2017)	7.86	_
Coulomb GANs: Provably optimal Nash equilibrium via potential fields (Unterthiner et al., 2017)	_	27.3
GANs trained by a two time-scale update rule converge to a local Nash equilibrium (Heusel, Ramsauer, Unterthiner, Nessler, & Hochreiter, 2017)	-	24.8
Autoregressive quantile networks for generative modeling (AIQN) (Ostrovski, Dabney, & Munos, 2018)	5.29	49.5
Spectral normalization for generative adversarial networks (SN-GAN) (Miyato, Kataoka, Koyama, & Yoshida, 2018)	8.22	21.7
Learning implicit generative models with the method of learned moments (Ravuri, Mohamed, Rosca, & Vinyals, 2018)	7.90	18.9

There are no universally agreed-upon performance metrics for unsupervised learning, and people have already pointed out many shortcomings of these Inception-based methods (Barratt & Sharma, 2018). Until something better comes

along though, they're going to show up in every paper so it's worth knowing what they are.

Footnotes

- 1. Implementations are available for both TF and PyTorch.
- 2. Other feature layers of the Inception-v3 network can also be used, with different dimensionalities. Note that at least d samples are needed to estimate the Gaussian statistics for d-dimensional features.
- 3. It's hard to tell if different papers are using consistent methodology for computing IS and FID (e.g., some use 5k samples for FID while others use 50k), and some papers report different numbers for the same model. I tried to pick the best score reported by each paper for their own method where possible and yolo'd the rest.
- 4. Reported by (Huang, Li, Poursaeed, Hopcroft, & Belongie, 2017).
- 5. Reported by (Ostrovski, Dabney, & Munos, 2018).
- 6. Reported by (Ostrovski, Dabney, & Munos, 2018). 2
- 7. Reported by (Warde-Farley & Bengio, 2016).

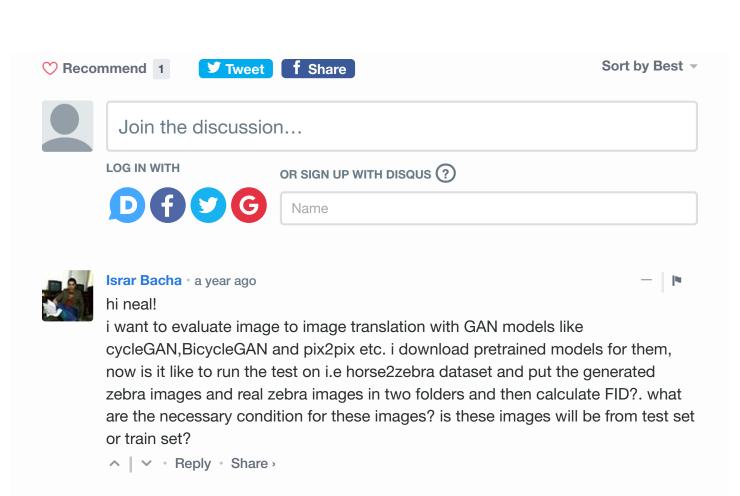
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Disgus' Privacy Policy

4 Comments





Nitin Bansal • 2 years ago

Hi Neal!



I had a small query though. When I load the Inception model, I find the pretrained model is based on an Imagenet Dataset. Now supposing that I am doing a task based on CIFAR10 Dataset on GAN. Does it make sense to use Inception model pretrained on Imagenet? As it has 1000 activations in the last layers, and even the size of kernels used also would be larger, Since the size of Imagenet Image would be bigger than CIFAR10/100.

Any comments or sugggestion on this point.

Regards,

Nitin Bansal

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weai Jean Woo 7 Nitin Bansai • 2 years ago

Hi Nitin, I think it's standard to use the Inception model trained on ImageNet and also to resize your images to match - check out this TF implementation:

https://github.com/tensorfl...





Nitin Bansal → Neal Jean • 2 years ago

Thank you for the prompt reply Neal!

I will definitely go through this code. Thanks for the pointer. Regards,

Nitin Bansal

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