
EE 779: Assignment 1: Q.1

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```
close all
clear all

% read input data
x = getdata(' ../assgn1_data/assgn1_data/S01.dat ');
x = x';
```

Q1 (a): 3×3 Toeplitz correlation matrix for the signal data using

Autocorrelation matrix

```
p = 2;
r = find_correlation(x);

Rxx_autocorr_AR2 = [r(1) r(2) r(3),
                    r(2) r(1) r(2),
                    r(3) r(2) r(1)];
```

```
% Rxx_autocorr_AR2
Rxx_autocorr_AR2
```

Rxx_autocorr_AR2 =

```
7.8935    7.3366    6.8760
7.3366    7.8935    7.3366
```

6.8760 7.3366 7.8935

Q1 (b): Second order linear prediction parameters and error

```
% Second order filter parameters are obtained by solving Yule-Walker
% equation. Prediction error variance is found.
temp = Rxx_autocorr_AR2(2:end,2:end);
r_AR2 = -[r(2),r(3)]';
a_AR2 = inv(temp)*r_AR2;
a_AR2 = [1,a_AR2.']*';

error_sq_AR2 = 0;
for j = 1:p+1
    error_sq_AR2 = error_sq_AR2 + a_AR2(j)*conj(r(j));
end

error_AR2 = sqrt(abs(error_sq_AR2));

error_sq_AR2
a_AR2

error_sq_AR2 =

    1.0714

a_AR2 =

    1.0000
   -0.8802
   -0.0530
```

Q1 (c): Error signal

After applying filter to the original data, error signal was calculated. The variance of this error signal was found approximately equal to the theoretical value calculated in part(a). Percentage change is found to be 0.28%.

```
err_pred_AR2 = zeros(length(x),1);
err_pred_AR2 = a_AR2(1)*x + (a_AR2(2)*[0 x(1:end-1)]' + a_AR2(3)*[0 0
    x(1:end-2)]')';
error_sq_pred_AR2 = var(err_pred_AR2);

error_sq_pred_AR2
error_sq_AR2
percentage_change = (error_sq_pred_AR2 - error_sq_AR2)/error_sq_AR2;
percentage_change
```

```
fig = figure();
plot(err_pred_AR2);
title('Prediction error for AR2');
xlabel('n');
ylabel('e[n]');
set(gcf, 'Position', get(0, 'Screensize'));
saveas(fig, '../results/Q1/Prediction error for AR2', 'jpg');
```

```
error_sq_pred_AR2 =
```

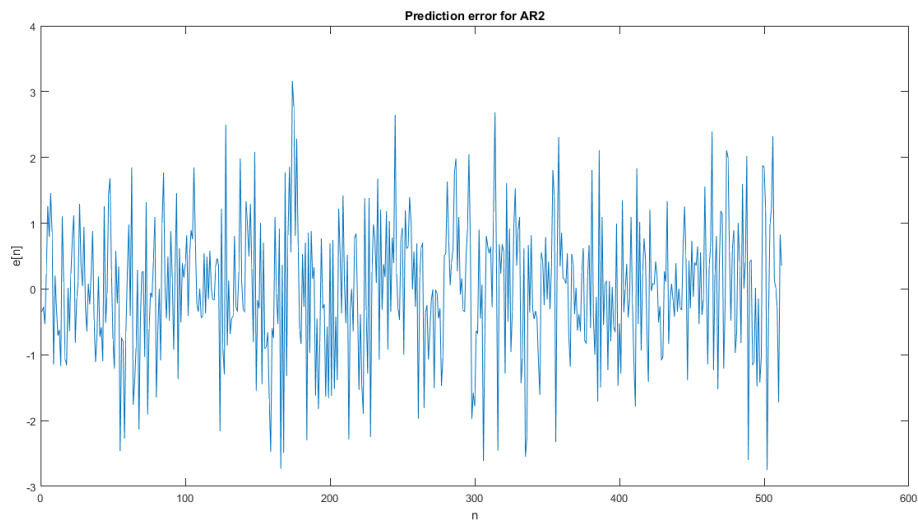
```
1.0684
```

```
error_sq_AR2 =
```

```
1.0714
```

```
percentage_change =
```

```
-0.0028
```



Q1 (d): first order linear prediction filter

First order parameters are found out. It is found that prediction error variance for first order (1.0744) is more than that of second order (1.0714) calculated in part(a). Note that the difference between theoretical value and calculated value of error is same for both AR1 and AR2

```
p = 1;
Rxx_autocorr_AR1 = Rxx_autocorr_AR2(1:2,1:2);
```

```
Rxx_autocorr_AR1
temp = Rxx_autocorr_AR1(2:end,2:end);
r_AR1 = -[r(2)]';
a_AR1 = inv(temp)*r_AR1;
a_AR1 = [1,a_AR1.']*';
error_sq_AR1 = 0;
for j = 1:p+1
    error_sq_AR1 = error_sq_AR1 + a_AR1(j)*conj(r(j));
end

error_AR1 = sqrt(abs(error_sq_AR1));

error_sq_AR1
error_sq_AR2

% prediction using AR1

err_pred_AR1 = zeros(length(x),1);
err_pred_AR1 = a_AR1(1)*x + (a_AR1(2)*[0 x(1:end-1)]')';
error_sq_pred_AR1 = var(err_pred_AR1);

fig = figure();
plot(err_pred_AR1);
title('Prediction error for AR1');
xlabel('n');
ylabel('e[n]');
set(gcf, 'Position', get(0, 'Screensize'));
saveas(fig,'../results/Q1/Prediction error for AR1','jpg');

Rxx_autocorr_AR1 =

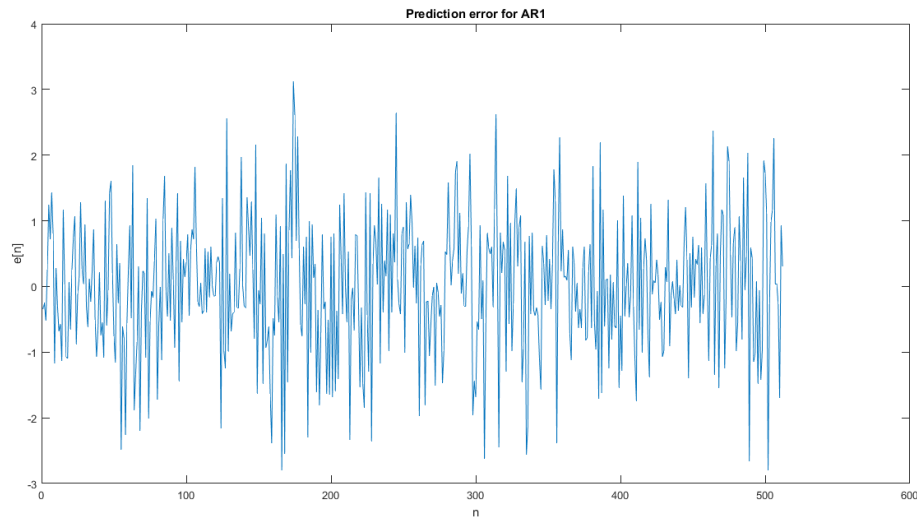
    7.8935    7.3366
    7.3366    7.8935

error_sq_AR1 =

    1.0744

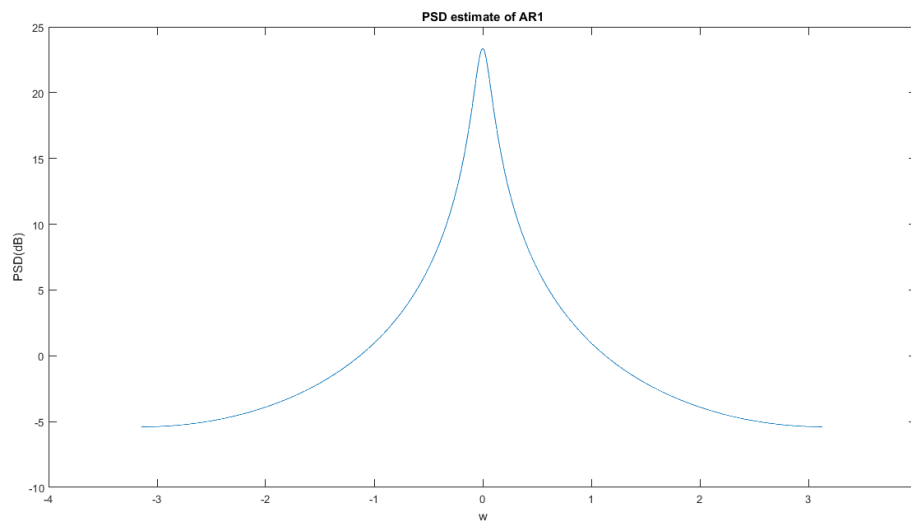
error_sq_AR2 =

    1.0714
```



Q1 (e): AR spectral plot for first order model

```
[h,w] = freqz(error_AR1,[a_AR1.'],'whole',1024);  
psd_AR1 = (abs(fftshift(h))).^2;  
freq = w - pi;  
plot(freq,10*log10(psd_AR1));  
title('PSD estimate of AR1');  
xlabel('w');  
ylabel('PSD(dB)');  
set(gcf, 'Position', get(0, 'Screensize'));  
saveas(fig,'../results/Q1/PSD estimate of AR1','jpg');
```



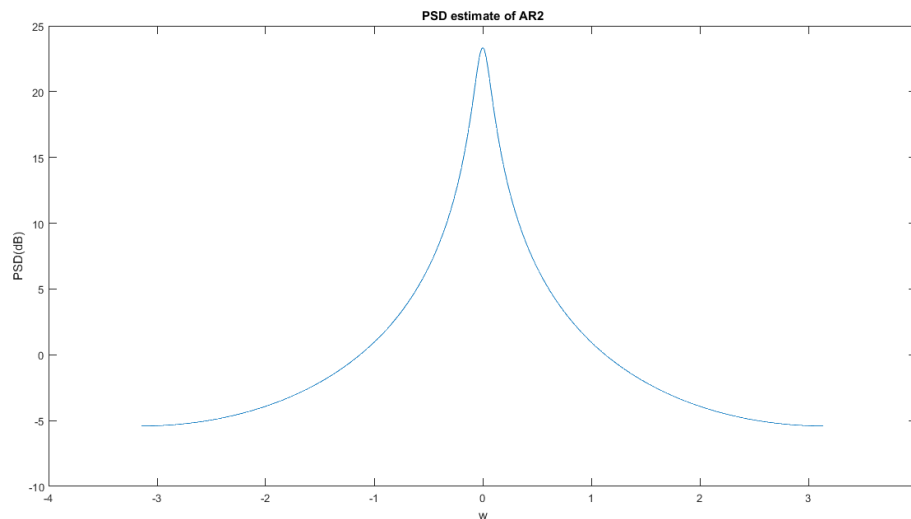
Q1 (f): AR spectral plot for second order model

```
[h,w] = freqz(error_AR2,[a_AR1.'],'whole',1024);
```

```

psd_AR2 = (abs(fftshift(h))).^2;
freq = w - pi;
plot(freq,10*log10(psd_AR2));
title('PSD estimate of AR2');
xlabel('w');
ylabel('PSD(dB)');
set(gcf, 'Position', get(0, 'Screensize'));
saveas(fig,'../results/Q1/PSD estimate of AR2','jpg');

```



Q1 (g): Periodogram Method and best method

PSD estimates using periodogram method ($N = 512$) and Blackman Tukey (best method in Assignment 1). It is observed that AR models perform better in terms of modelling actual PSD compared to other nonparametric methods in this case. This signifies that the signal is indeed an AR process (which is true, as it was told in Assignment 1, it is an AR1 process). We can compare PSD estimates with the true signal PSD which was calculated in assignment_1.

```

fft_len = 1024;
N = 512;
% zero padding signal
x_padded = zeros(fft_len,1);
x_padded(1:N) = x(1:N);
fft_xN = fftshift(fft(x_padded, fft_len));
psd_prdgrm = (abs(fft_xN).^2)/N;
fig = figure;
freq = linspace(-pi,pi,fft_len);
plot(freq,10*log10(psd_prdgrm));
title('PSD estimate using periodogram');
xlabel('w');
ylabel('PSD(dB)');
set(gcf, 'Position', get(0, 'Screensize'));
saveas(fig,'../results/Q1/PSD estimate using periodogram','jpg');

% Best method (Blackman Tukey) from Assignment 1

```

```

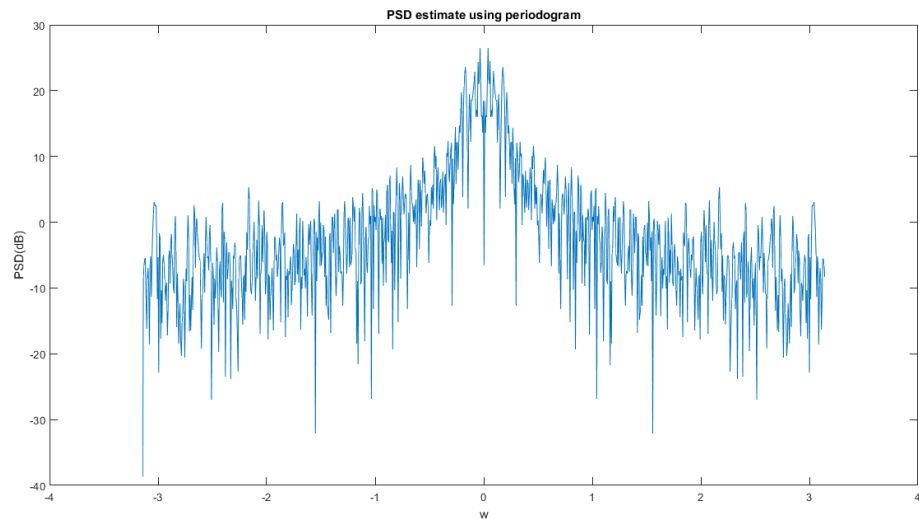
N = length(x);
M = 32;
fft_len = 1024;
rxw_padded = zeros(fft_len,1);
rx_pos = find_correlation(x);

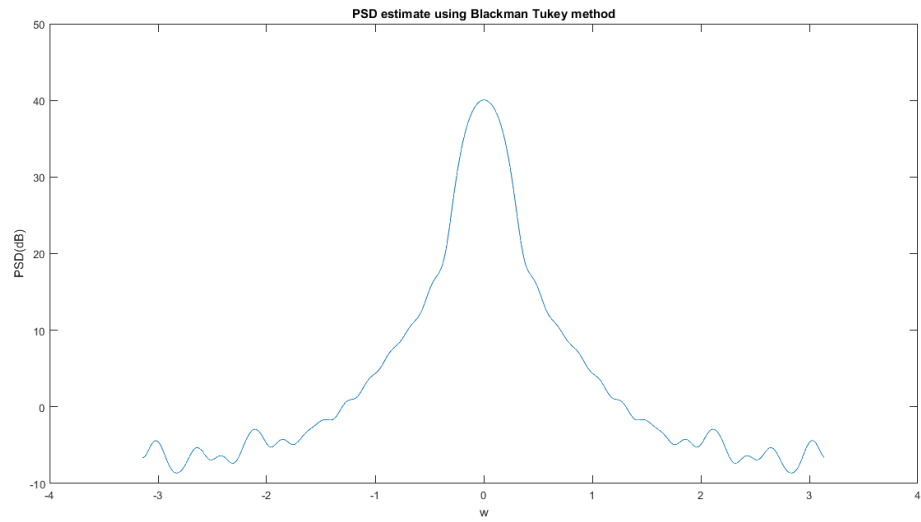
pos_len = length(x);
rx = zeros(2*pos_len - 1,1);
rx(pos_len) = rx_pos(1);
for t = 2:length(rx_pos)
    rx(pos_len + t - 1) = rx_pos(t);
    rx(pos_len - t + 1) = rx_pos(t);
end

w = zeros(length(rx),1);
w(N - M : N + M) = bartlett(2*M + 1);
rxw_padded(1:length(rx)) = rx.*w;
psd_bmt_32 = (abs(fftshift(fft(rxw_padded,fft_len))))).^2;
fig = figure;
freq = linspace(-pi,pi,fft_len);
plot(freq,10*log10(psd_bmt_32));

title('PSD estimate using Blackman Tukey method');
xlabel('w');
ylabel('PSD(dB)');
set(gcf, 'Position', get(0, 'Screensize'));
saveas(fig,'../results/Q1/PSD estimate using Blackman Tukey
    method','jpg');

```





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