

Sumo Robot Report

This is the project report for the robot “Interpreter” made for the class MAE 6194

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Spring 2017

The George Washington University

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Introduction

Resources

This document describes the procedures for running a hexrotor in an XU4. Below are the resources.

- Code: <https://github.com/fdcl-gwu/OdroidXU4>
- Repo for this documentation: https://github.com/fdcl-gwu/OdroidXU4_Documentation
- Manuals, backups and other resources: Google Drive (FDCL/Tutorials/ODROID_XU4)



Figure 1: Pinout for CON10