```
Requirement already satisfied: gdown in /usr/local/lib/python3.11/dist-packa
          Requirement already satisfied: beautifulsoup4 in /usr/local/lib/python3.11/d
          ist-packages (from gdown) (4.13.3)
          Requirement already satisfied: filelock in /usr/local/lib/python3.11/dist-pa
          ckages (from gdown) (3.17.0)
          Requirement already satisfied: requests[socks] in /usr/local/lib/python3.11/
          dist-packages (from gdown) (2.32.3)
          Requirement already satisfied: tqdm in /usr/local/lib/python3.11/dist-packag
          es (from gdown) (4.67.1)
          Requirement already satisfied: soupsieve>1.2 in /usr/local/lib/python3.11/di
           st-packages (from beautifulsoup4->gdown) (2.6)
          Requirement already satisfied: typing-extensions>=4.0.0 in /usr/local/lib/py
          thon3.11/dist-packages (from beautifulsoup4->gdown) (4.12.2)
          Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/py
          thon3.11/dist-packages (from requests[socks]->gdown) (3.4.1)
          Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.11/dis
          t-packages (from requests[socks]->gdown) (3.10)
          Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.
          11/dist-packages (from requests[socks]->gdown) (2.3.0)
          Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.
          11/dist-packages (from requests[socks]->gdown) (2025.1.31)
          Requirement already satisfied: PySocks!=1.5.7,>=1.5.6 in /usr/local/lib/pyth
          on3.11/dist-packages (from requests[socks]->gdown) (1.7.1)
   In [2]: import gdown
            import zipfile
            file id = "1ZEyNME043u3qhJAwJeBZxFBEYc pVYZQ"
            output = "dataset.zip"
            gdown.download(f"https://drive.google.com/uc?id={file_id}", output, quiet =
            with zipfile.ZipFile("dataset.zip", "r") as zip ref:
              zip ref.extractall("/content/dataset")
          Downloading...
           From (original): https://drive.google.com/uc?id=1ZEyNMEO43u3qhJAwJeBZxFBEYc
          pVYZQ
           From (redirected): https://drive.google.com/uc?id=1ZEyNMEO43u3qhJAwJeBZxFBEY
           c pVYZQ&confirm=t&uuid=414d338e-b352-47d5-98f5-32e4038999bf
          To: /content/dataset.zip
          100%|
                     | 1.13G/1.13G [00:14<00:00, 79.2MB/s]
   In [3]: import os
            import numpy as np
            import matplotlib.pyplot as plt
            from sklearn.model selection import train test split
            from sklearn.metrics import roc curve, auc
            import torch
            import torch.nn as nn
            import torch.optim as optim
            from torch.utils.data import Dataset, DataLoader
            import torchvision.models as models
Loading [MathJax]/extensions/Safe.js
```

In [1]: !pip install gdown

```
from tqdm import tqdm
   In [4]: np.random.seed(42)
   In [5]: class LensingDataset(Dataset):
              def init (self, data paths, labels, transform = None):
                self.data paths = data paths
                self.labels = labels
                self.transform = transform
              def __len__(self):
                return len(self.data paths)
              def getitem (self, idx):
                img = np.load(self.data paths[idx])
                if img.shape != (1, 150, 150):
                  img = img.reshape(1, 150, 150)
                img tensor = torch.from numpy(img).float()
                if self.transform:
                  img tensor = self.transform(img tensor)
                if img tensor.shape[0] == 1:
                  img tensor = img tensor.repeat(3, 1, 1)
                return img tensor, self.labels[idx]
   In [6]: def check_data_integrity(data_loader):
                try:
                    inputs, labels = next(iter(data loader))
                    print(f"Data check - Input shape: {inputs.shape}, Labels shape: {lab
                    print(f"Data check - Input dtype: {inputs dtype}, Labels dtype: {lab
                    print(f"Data check - Labels unique values: {torch.unique(labels)}")
                    return True
                except Exception as e:
                    print(f"Data integrity check failed: {e}")
                    return False
   In [7]: def load data(base dir):
              class folders = ['no', 'sphere', 'vort']
              data paths = []
              labels = []
              for class idx, folder in enumerate(class folders):
                folder path = os.path.join(base dir, folder)
                if not os.path.exists(folder path):
                  print(f"Warning: Folder {folder path} does not exist")
                  continue
                npy files = [f for f in os.listdir(folder path) if f.endswith('.npy')]
                file list = [os.path.join(folder path, f) for f in npy files]
Loading [MathJax]/extensions/Safe.js paths.extend(file_list)
```

import torchvision.transforms as transforms

```
labels.extend([class_idx] * len(file_list))
           unique labels, counts = np.unique(labels, return counts=True)
           print("Class distribution:")
           for label, count in zip(unique labels, counts):
             print(f" Class {label}: {count} samples")
           return data paths, labels
 In [8]: def get model(model name, num classes=3):
             if model name == 'resnet50':
                 model = models.resnet50(weights=models.ResNet50 Weights.IMAGENET1K V
                 model.fc = nn.Linear(model.fc.in features, num classes)
             elif model name == 'efficientnet b0':
                 model = models.efficientnet b0(weights=models.EfficientNet B0 Weight
                 model.classifier[1] = nn.Linear(model.classifier[1].in_features, num
             elif model name == 'densenet121':
                 model = models.densenet121(weights=models.DenseNet121 Weights.IMAGEN
                 model.classifier = nn.Linear(model.classifier.in features, num class
             else:
                 raise ValueError(f"Model {model name} not supported")
             return model
In [18]: def train model(model, train loader, val loader, criterion, optimizer, sched
           best model wts = None
           best auc = 0.0
           history = {
               'train_loss' : [], 'val_loss' : [],
               'train_acc' : [], 'val_acc' : []
           if not check data integrity(train_loader) or not check_data_integrity(val_
             print("Data integrity check failed. Aborting training.")
             return model, history
           for epoch in range(num epochs):
             print(f'Epoch {epoch+1}/{num epochs}')
             print('-' * 10)
             model.train()
             train loss = 0.0
             train corrects = 0
             for inputs, labels in tqdm(train loader, desc = "Training"):
               try:
                 inputs = inputs.to(device)
                 labels = labels.to(device)
                 optimizer.zero grad()
                 with torch.set grad enabled(True):
                   outputs = model(inputs)
                   , preds = torch.max(outputs, 1)
                   loss = criterion(outputs, labels)
```

```
loss.backward()
                      optimizer.step()
                  except Exception as e:
                    print(f"Error during training: {e}")
                    continue
                if scheduler:
                  scheduler.step()
                train loss += loss.item() * inputs.size(0)
                train corrects += torch.sum(preds == labels.data)
                epoch train loss = train loss / len(train loader.dataset)
                epoch train acc = float(train corrects) / len(train loader.dataset)
                history['train loss'].append(epoch train loss)
                history['train acc'].append(epoch train acc)
                print(f'Train Loss: {epoch train loss:.4f} Acc: {epoch train acc:.4f}')
                model.eval()
                val loss = 0.0
                val corrects = 0
                all labels = []
                all probs = []
                for inputs, labels in tqdm(val loader, desc="Validation"):
                  try:
                    inputs = inputs.to(device)
                    labels = labels.to(device)
                    with torch.no grad():
                      outputs = model(inputs)
                      , preds = torch.max(outputs, 1)
                      loss = criterion(outputs, labels)
                      probs = nn.Softmax(dim = 1)(outputs)
                    val loss += loss.item() * inputs.size(0)
                    val corrects += torch.sum(preds == labels.data)
                    all labels.append(labels.cpu().numpy())
                    all probs.append(probs.cpu().numpy())
                  except Exception as e:
                    print(f"Error during validation: {e}")
                    continue
                if len(all labels) == 0 or len(all probs) == 0:
                  print("No valid validation batches. Skipping ROC calculation.")
                  continue
                epoch val loss = val loss / len(val loader.dataset)
Loading [MathJax]/extensions/Safe.js val_acc = float(val_corrects) / len(val_loader.dataset)
```

```
history['val loss'].append(epoch val loss)
                history['val acc'].append(epoch_val_acc)
                print(f'Val Loss: {epoch val loss:.4f} Acc: {epoch val acc:.4f}')
                try:
                  all labels = np.concatenate(all labels)
                  all probs = np.concatenate(all probs)
                  unique labels = np.unique(all labels)
                  mean auc = 0
                  class count = 0
                  for class idx in range(3):
                    if class idx not in unique labels and len(unique labels) < 3:</pre>
                      print(f"Warning: Class {class idx} not in validation set")
                      continue
                    binary labels = (all labels == class idx).astype(int)
                    fpr, tpr, = roc curve(binary labels, all probs[:, class idx])
                    roc auc = auc(fpr, tpr)
                    mean auc += roc auc
                    class count += 1
                  mean auc /= max(1, class count)
                  print(f'Mean AUC: {mean auc:.4f}')
                  if mean auc > best auc:
                    best auc = mean auc
                    best_model_wts = model.state_dict().copy()
                except Exception as e:
                  print(f"Error calculating ROC/AUC: {e}")
                  continue
                print(f'Best validation AUC: {best auc:.4f}')
                if best model wts is not None:
                  model.load state dict(best model wts)
              return model, history
  In [19]: def evaluate model(model, test loader, device='cuda'):
                model.eval()
                all labels = []
                all probs = []
                all preds = []
                with torch.no grad():
                    for inputs, labels in tqdm(test_loader, desc="Testing"):
                        try:
                             inputs = inputs.to(device)
                             labels = labels.to(device)
                             outputs = model(inputs)
Loading [MathJax]/extensions/Safe.js
```

```
, preds = torch.max(outputs, 1)
            probs = nn.Softmax(dim=1)(outputs)
            all labels.append(labels.cpu().numpy())
            all probs.append(probs.cpu().numpy())
            all preds.append(preds.cpu().numpy())
        except Exception as e:
            print(f"Error during evaluation: {e}")
            continue
if not all labels or not all probs or not all preds:
    print("No valid test batches. Cannot evaluate model.")
    return 0, 0, None
all labels = np.concatenate(all labels)
all probs = np.concatenate(all probs)
all preds = np.concatenate(all preds)
# Calculate accuracy
accuracy = np.mean(all preds == all labels)
print(f'Test Accuracy: {accuracy:.4f}')
# Plot ROC curves and calculate AUC
plt.figure(figsize=(10, 8))
class_names = ['No Substructure', 'Sphere Substructure', 'Vortex Substru
colors = ['blue', 'red', 'green']
mean auc = 0
class count = 0
# Get unique classes in test set
unique labels = np.unique(all labels)
for i, class name in enumerate(class names):
    # Skip classes that don't exist in the test set
    if i not in unique labels and len(unique labels) < 3:</pre>
        print(f"Warning: Class {i} not in test set")
        continue
    try:
        binary labels = (all labels == i).astype(int)
        fpr, tpr, = roc curve(binary labels, all probs[:, i])
        roc auc = auc(fpr, tpr)
        mean auc += roc auc
        class count += 1
        plt.plot(fpr, tpr, color=colors[i], lw=2,
                label=f'{class_name} (AUC = {roc auc:.3f})')
    except Exception as e:
        print(f"Error calculating ROC for class {i}: {e}")
        continue
mean_auc /= max(1, class_count) # Avoid division by zero
```

```
# Plot diagonal line
plt.plot([0, 1], [0, 1], 'k--', lw=2)
plt.xlim([0.0, 1.0])
plt.ylim([0.0, 1.05])
plt.xlabel('False Positive Rate')
plt.ylabel('True Positive Rate')
plt.title(f'ROC Curves (Mean AUC = {mean_auc:.3f})')
plt.legend(loc="lower right")
plt.grid(True)

return accuracy, mean_auc, plt
```

```
In [20]: def main(base dir, model name='efficientnet b0', batch size=16, num epochs=1
                # Check if CUDA is available
                if torch.cuda.is available():
                    device = torch.device("cuda")
                    # Print CUDA information for debugging
                    print(f"Using CUDA: {torch.cuda.get device name(0)}")
                    print(f"CUDA device count: {torch.cuda.device count()}")
                    print(f"CUDA version: {torch.version.cuda}")
                else:
                    device = torch.device("cpu")
                    print("CUDA not available, using CPU")
                # Load data
                try:
                    data paths, labels = load data(base dir)
                except Exception as e:
                    print(f"Error loading data: {e}")
                    return None, 0, 0
                # Split data
                try:
                    train paths, test paths, train labels, test labels = train test spli
                        data paths, labels, test size=0.2, random state=42, stratify=lab
                    )
                    train paths, val paths, train labels, val labels = train test split(
                        train paths, train labels, test size=0.2, random state=42, strat
                except Exception as e:
                    print(f"Error splitting data: {e}")
                    return None, 0, 0
                print(f"Train samples: {len(train paths)}")
                print(f"Validation samples: {len(val paths)}")
                print(f"Test samples: {len(test paths)}")
                # Create datasets and dataloaders
                try:
                    train dataset = LensingDataset(train paths, train labels)
                    val dataset = LensingDataset(val paths, val labels)
                    test dataset = LensingDataset(test paths, test labels)
                    train loader = DataLoader(train dataset, batch size=batch size, shuf
Loading [MathJax]/extensions/Safe.js al loader = DataLoader(val dataset, batch size=batch size)
```

```
test loader = DataLoader(test dataset, batch size=batch size)
                    # Check if dataloaders work
                    check data integrity(train loader)
                except Exception as e:
                    print(f"Error creating datasets/dataloaders: {e}")
                    return None, 0, 0
                # Initialize model
                try:
                    model = get model(model name)
                    model = model.to(device)
                    print(f"Model initialized: {model name}")
                except Exception as e:
                    print(f"Error initializing model: {e}")
                    return None, 0, 0
                # Define loss function and optimizer
                criterion = nn.CrossEntropyLoss()
                optimizer = optim.Adam(model.parameters(), lr=0.001)
                scheduler = optim.lr scheduler.StepLR(optimizer, step size=7, gamma=0.1)
                # Train model
                try:
                    model, history = train model(
                        model, train loader, val loader, criterion, optimizer,
                        scheduler, num epochs=num epochs, device=device
                except Exception as e:
                    print(f"Error during training: {e}")
                    return model, 0, 0
                # Evaluate model
                try:
                    accuracy, mean auc, plt roc = evaluate model(model, test loader, dev
                except Exception as e:
                    print(f"Error during evaluation: {e}")
                    return model, 0, 0
                # Save model to Google Drive
                try:
                    model save path = os.path.join('/content/drive/MyDrive', f'{model na
                    torch.save(model.state dict(), model save path)
                    print(f"Model saved to {model save path}")
                except Exception as e:
                    print(f"Error saving model: {e}")
                # Plot training history
                try:
                    plt.figure(figsize=(12, 4))
                    plt.subplot(1, 2, 1)
                    plt.plot(history['train loss'], label='Train Loss')
                    plt.plot(history['val_loss'], label='Validation Loss')
                    plt.title('Loss over Epochs')
Loading [MathJax]/extensions/Safe.js | t.xlabel('Epoch')
```

```
plt.grid(True)
                 plt.subplot(1, 2, 2)
                  plt.plot(history['train_acc'], label='Train Accuracy')
                 plt.plot(history['val acc'], label='Validation Accuracy')
                 plt.title('Accuracy over Epochs')
                 plt.xlabel('Epoch')
                 plt.ylabel('Accuracy')
                 plt.legend()
                 plt.grid(True)
                 plt.tight layout()
                 plt.savefig('/content/drive/MyDrive/training history.png')
                 # Save ROC curve
                 if plt roc:
                      plt roc.savefig('/content/drive/MyDrive/roc curve.png')
             except Exception as e:
                 print(f"Error plotting results: {e}")
             print(f"Final test accuracy: {accuracy:.4f}")
             print(f"Final mean AUC: {mean auc:.4f}")
             return model, accuracy, mean auc
In [21]: def compare models(base dir, models to try=['resnet50', 'efficientnet b0',
             results = {}
             for model name in models to try:
                 print(f"\n\n{'='*50}")
                 print(f"Training model: {model name}")
                 print(f"{'='*50}\n")
                 try:
                      model, accuracy, mean auc = main(base dir, model name=model name
                      if model is not None:
                          results[model name] = {'accuracy': accuracy, 'auc': mean auc
                      else:
                          print(f"Training failed for {model name}")
                 except Exception as e:
                      print(f"Error in model comparison for {model name}: {e}")
             if not results:
                  print("No models were successfully trained")
                 return {}
             # Print comparison results
             print("\nModel Comparison Results:")
             print(f"{'Model':<15} {'Accuracy':<10} {'Mean AUC':<10}")</pre>
             print('-' * 35)
             for model name, metrics in results.items():
                  print(f"{model name:<15} {metrics['accuracy']:.4f} {metrics['auc</pre>
```

plt.ylabel('Loss')

plt.legend()

```
# Find best model
             best model = max(results.items(), key=lambda x: x[1]['auc'])
             print(f"\nBest model by AUC: {best model[0]} with AUC = {best model[1]['
             # Save results to a text file
             try:
                 with open('/content/drive/MyDrive/model comparison results.txt', 'w'
                     f.write("Model Comparison Results:\n")
                     f.write(f"{'Model':<15} {'Accuracy':<10} {'Mean AUC':<10}\n")</pre>
                     f.write('-' * 35 + '\n')
                     for model name, metrics in results.items():
                         f.write(f"{model name:<15} {metrics['accuracy']:.4f}</pre>
                                                                                   {m∈
                     f.write(f"\nBest model by AUC: {best model[0]} with AUC = {best
             except Exception as e:
                 print(f"Error saving results: {e}")
             return results
In [22]: data dir = "/content/dataset/dataset/train"
In [14]: from google.colab import drive
         drive.mount('/content/drive')
        Mounted at /content/drive
In [23]: model, accuracy, mean auc = main(data dir, model name='efficientnet b0', bat
        Using CUDA: Tesla T4
        CUDA device count: 1
        CUDA version: 12.4
        Class distribution:
          Class 0: 10000 samples
          Class 1: 10000 samples
          Class 2: 10000 samples
        Train samples: 19200
        Validation samples: 4800
        Test samples: 6000
        Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
        h.Size([16])
        Data check - Input dtype: torch.float32, Labels dtype: torch.int64
        Data check - Labels unique values: tensor([0, 1, 2])
        Model initialized: efficientnet b0
        Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
        h.Size([16])
        Data check - Input dtype: torch.float32, Labels dtype: torch.int64
        Data check - Labels unique values: tensor([0, 1, 2])
        Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
        h.Size([16])
        Data check - Input dtype: torch.float32, Labels dtype: torch.int64
        Data check - Labels unique values: tensor([0, 1, 2])
        Epoch 1/10
        ------
        Training: 100% | 1200/1200 [01:14<00:00, 16.07it/s]
```

Validation: 100% 300/300 [00:15<00:00, 19.38it/s] Val Loss: 0.8092 Acc: 0.6310 Mean AUC: 0.8201 Best validation AUC: 0.8201 Epoch 2/10 _ _ _ _ _ _ _ _ _ _ | 1200/1200 [00:58<00:00, 20.52it/s] Training: 100% Train Loss: 0.0007 Acc: 0.0005 Validation: 100% 300/300 [00:05<00:00, 57.54it/s] Val Loss: 0.6029 Acc: 0.7608 Mean AUC: 0.9168 Best validation AUC: 0.9168 Epoch 3/10 ------Training: 100% | 1200/1200 [00:58<00:00, 20.51it/s] Train Loss: 0.0005 Acc: 0.0007 Validation: 100% 300/300 [00:04<00:00, 60.23it/s] Val Loss: 0.3857 Acc: 0.8435 Mean AUC: 0.9587 Best validation AUC: 0.9587 Epoch 4/10 _ _ _ _ _ _ _ _ _ _ Training: 100% | 1200/1200 [00:58<00:00, 20.49it/s] Train Loss: 0.0006 Acc: 0.0005 300/300 [00:05<00:00, 59.53it/s] Validation: 100% Val Loss: 0.3235 Acc: 0.8762 Mean AUC: 0.9699 Best validation AUC: 0.9699 Epoch 5/10 _ _ _ _ _ _ _ _ _ _ Training: 100% | 1200/1200 [00:58<00:00, 20.54it/s] Train Loss: 0.0001 Acc: 0.0008 Validation: 100% | 300/300 [00:04<00:00, 60.99it/s] Val Loss: 0.3389 Acc: 0.8702 Mean AUC: 0.9697 Best validation AUC: 0.9699 Epoch 6/10 _ _ _ _ _ _ _ _ _ _ Training: 100% | 1200/1200 [00:58<00:00, 20.44it/s] Train Loss: 0.0003 Acc: 0.0007 Validation: 100% | 300/300 [00:04<00:00, 60.36it/s] Val Loss: 0.2999 Acc: 0.8931 Mean AUC: 0.9755 Best validation AUC: 0.9755 Epoch 7/10 -----Training: 100% | 1200/1200 [00:58<00:00, 20.45it/s] Train Loss: 0.0001 Acc: 0.0008

Validation: 100% 300/300 [00:04<00:00, 60.07it/s]

Val Loss: 0.2799 Acc: 0.9010

Mean AUC: 0.9757

Best validation AUC: 0.9757

Epoch 8/10

Training: 100% | 1200/1200 [00:58<00:00, 20.66it/s]

Train Loss: 0.0001 Acc: 0.0008

Validation: 100% 300/300 [00:05<00:00, 55.34it/s]

Val Loss: 0.2332 Acc: 0.9185

Mean AUC: 0.9856

Best validation AUC: 0.9856

Epoch 9/10

Training: 100% | 1200/1200 [00:58<00:00, 20.65it/s]

Train Loss: 0.0000 Acc: 0.0008

Validation: 100% 300/300 [00:05<00:00, 53.37it/s]

Val Loss: 0.2263 Acc: 0.9219

Mean AUC: 0.9856

Best validation AUC: 0.9856

Epoch 10/10

Training: 100% | 1200/1200 [00:58<00:00, 20.65it/s]

Train Loss: 0.0000 Acc: 0.0008

Validation: 100%| 300/300 [00:05<00:00, 52.76it/s]

Val Loss: 0.2383 Acc: 0.9254

Mean AUC: 0.9855

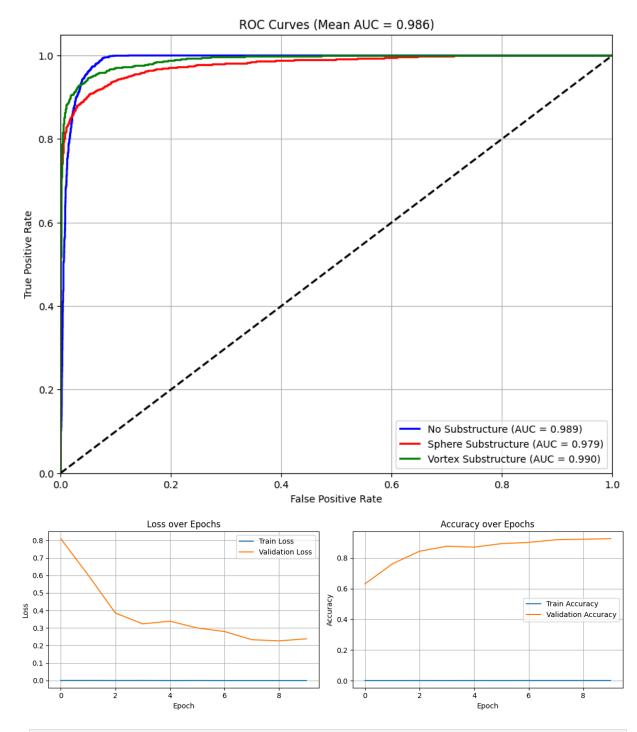
Best validation AUC: 0.9856

Testing: 100% | 375/375 [00:15<00:00, 23.93it/s]

Test Accuracy: 0.9223

Model saved to /content/drive/MyDrive/efficientnet b0 lensing classifier.pth

Final test accuracy: 0.9223 Final mean AUC: 0.9856



In [24]: results = compare_models(data_dir, models_to_try=['resnet50', 'efficientnet_

```
Training model: resnet50
_____
Using CUDA: Tesla T4
CUDA device count: 1
CUDA version: 12.4
Class distribution:
  Class 0: 10000 samples
  Class 1: 10000 samples
  Class 2: 10000 samples
Train samples: 19200
Validation samples: 4800
Test samples: 6000
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Downloading: "https://download.pytorch.org/models/resnet50-0676ba61.pth" to
/root/.cache/torch/hub/checkpoints/resnet50-0676ba61.pth
100% | 97.8M/97.8M [00:00<00:00, 172MB/s]
Model initialized: resnet50
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Epoch 1/10
_ _ _ _ _ _ _ _ _ _
Training: 100%
                       | 1200/1200 [01:52<00:00, 10.70it/s]
Train Loss: 0.0009 Acc: 0.0004
Validation: 100% 300/300 [00:09<00:00, 31.76it/s]
Val Loss: 1.1029 Acc: 0.3310
Mean AUC: 0.5027
Best validation AUC: 0.5027
Epoch 2/10
                 | 1200/1200 [01:51<00:00, 10.77it/s]
Training: 100%
Train Loss: 0.0009 Acc: 0.0004
Validation: 100% 300/300 [00:09<00:00, 31.33it/s]
Val Loss: 1.0991 Acc: 0.3333
Mean AUC: 0.5045
Best validation AUC: 0.5045
Epoch 3/10
-----
Training: 100% | 1200/1200 [01:51<00:00, 10.75it/s]
Train Loss: 0.0009 Acc: 0.0002
Validation: 100%| 300/300 [00:09<00:00, 31.34it/s]
```

Val Loss: 1.0987 Acc: 0.3356

Mean AUC: 0.5047

Best validation AUC: 0.5047

Epoch 4/10

Training: 100% | 1200/1200 [01:51<00:00, 10.77it/s]

Train Loss: 0.0009 Acc: 0.0002

Validation: 100%| 300/300 [00:09<00:00, 31.71it/s]

Val Loss: 1.1028 Acc: 0.3233

Mean AUC: 0.4941

Best validation AUC: 0.5047

Epoch 5/10

Training: 100% | 1200/1200 [01:50<00:00, 10.82it/s]

Train Loss: 0.0009 Acc: 0.0001

Validation: 100% | 300/300 [00:09<00:00, 31.71it/s]

Val Loss: 1.1056 Acc: 0.3381

Mean AUC: 0.4925

Best validation AUC: 0.5047

Epoch 6/10

Training: 100% | 1200/1200 [01:50<00:00, 10.82it/s]

Train Loss: 0.0009 Acc: 0.0005

Validation: 100% | 300/300 [00:09<00:00, 31.56it/s]

Val Loss: 1.0983 Acc: 0.3471

Mean AUC: 0.5148

Best validation AUC: 0.5148

Epoch 7/10

Training: 100%| | 1200/1200 [01:51<00:00, 10.79it/s]

Train Loss: 0.0009 Acc: 0.0002

Validation: 100% | 300/300 [00:09<00:00, 31.84it/s]

Val Loss: 1.0988 Acc: 0.3281

Mean AUC: 0.4996

Best validation AUC: 0.5148

Epoch 8/10

Training: 100% | 1200/1200 [01:51<00:00, 10.78it/s]

Train Loss: 0.0009 Acc: 0.0003

Validation: 100%| 300/300 [00:09<00:00, 31.63it/s]

Val Loss: 1.0997 Acc: 0.3331

Mean AUC: 0.4945

Best validation AUC: 0.5148

Epoch 9/10

Training: 100% | 1200/1200 [01:51<00:00, 10.80it/s]

Train Loss: 0.0009 Acc: 0.0003

Validation: 100%| 300/300 [00:09<00:00, 31.88it/s]

```
Val Loss: 1.0990 Acc: 0.3346
Mean AUC: 0.4865
Best validation AUC: 0.5148
Epoch 10/10
-----
Training: 100% | 1200/1200 [01:51<00:00, 10.79it/s]
Train Loss: 0.0009 Acc: 0.0004
Validation: 100% 300/300 [00:09<00:00, 31.87it/s]
Val Loss: 1.0988 Acc: 0.3281
Mean AUC: 0.4943
Best validation AUC: 0.5148
Testing: 100% | 375/375 [00:11<00:00, 31.91it/s]
Test Accuracy: 0.3407
Model saved to /content/drive/MyDrive/resnet50 lensing classifier.pth
Final test accuracy: 0.3407
Final mean AUC: 0.5092
Training model: efficientnet b0
_____
Using CUDA: Tesla T4
CUDA device count: 1
CUDA version: 12.4
Class distribution:
 Class 0: 10000 samples
 Class 1: 10000 samples
 Class 2: 10000 samples
Train samples: 19200
Validation samples: 4800
Test samples: 6000
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Model initialized: efficientnet b0
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Epoch 1/10
------
```

Train Loss: 0.0008 Acc: 0.0005

Validation: 100%| 300/300 [00:05<00:00, 53.72it/s]

Training: 100% | 1200/1200 [00:59<00:00, 20.22it/s]

Val Loss: 0.8767 Acc: 0.5575

Mean AUC: 0.8040

Best validation AUC: 0.8040

Epoch 2/10

```
Training: 100% | 1200/1200 [00:59<00:00, 20.34it/s]
Train Loss: 0.0004 Acc: 0.0007
Validation: 100%| 300/300 [00:05<00:00, 56.46it/s]
Val Loss: 0.5076 Acc: 0.7950
Mean AUC: 0.9326
Best validation AUC: 0.9326
Epoch 3/10
-----
Training: 100% | 1200/1200 [00:59<00:00, 20.17it/s]
Train Loss: 0.0005 Acc: 0.0006
Validation: 100% 300/300 [00:05<00:00, 56.48it/s]
Val Loss: 0.3957 Acc: 0.8494
Mean AUC: 0.9558
Best validation AUC: 0.9558
Epoch 4/10
------
Training: 100% | 1200/1200 [00:59<00:00, 20.22it/s]
Train Loss: 0.0005 Acc: 0.0006
Validation: 100% | 300/300 [00:05<00:00, 58.30it/s]
Val Loss: 0.3101 Acc: 0.8783
Mean AUC: 0.9717
Best validation AUC: 0.9717
Epoch 5/10
_ _ _ _ _ _ _ _ _ _
Training: 100% | 1200/1200 [00:58<00:00, 20.40it/s]
Train Loss: 0.0001 Acc: 0.0008
Validation: 100% 300/300 [00:04<00:00, 61.00it/s]
Val Loss: 0.3444 Acc: 0.8696
Mean AUC: 0.9738
Best validation AUC: 0.9738
Epoch 6/10
------
Training: 100% | 1200/1200 [00:58<00:00, 20.42it/s]
Train Loss: 0.0004 Acc: 0.0007
Validation: 100% 300/300 [00:04<00:00, 60.51it/s]
Val Loss: 0.2732 Acc: 0.8969
Mean AUC: 0.9779
Best validation AUC: 0.9779
Epoch 7/10
_ _ _ _ _ _ _ _ _
Training: 100% | 1200/1200 [00:59<00:00, 20.22it/s]
Train Loss: 0.0003 Acc: 0.0007
Validation: 100% 300/300 [00:05<00:00, 59.32it/s]
Val Loss: 0.2608 Acc: 0.9012
Mean AUC: 0.9795
Best validation AUC: 0.9795
Epoch 8/10
------
Training: 100% | 1200/1200 [00:59<00:00, 20.25it/s]
Train Loss: 0.0000 Acc: 0.0008
Validation: 100% 300/300 [00:05<00:00, 59.57it/s]
```

Val Loss: 0.2266 Acc: 0.9198

Mean AUC: 0.9859

Best validation AUC: 0.9859

Epoch 9/10

Training: 100% | 1200/1200 [00:59<00:00, 20.34it/s]

Train Loss: 0.0001 Acc: 0.0008

Validation: 100% | 300/300 [00:04<00:00, 62.23it/s]

Val Loss: 0.2285 Acc: 0.9206

Mean AUC: 0.9861

Best validation AUC: 0.9861

Epoch 10/10

Training: 100% | 1200/1200 [00:58<00:00, 20.63it/s]

Train Loss: 0.0000 Acc: 0.0008

Validation: 100% 300/300 [00:05<00:00, 56.92it/s]

Val Loss: 0.2378 Acc: 0.9260

Mean AUC: 0.9862

Best validation AUC: 0.9862

Testing: 100% | 375/375 [00:06<00:00, 61.41it/s]

Test Accuracy: 0.9267

Model saved to /content/drive/MyDrive/efficientnet_b0_lensing_classifier.pth

Final test accuracy: 0.9267

Final mean AUC: 0.9859

Training model: densenet121

Using CUDA: Tesla T4
CUDA device count: 1
CUDA version: 12.4
Class distribution:

Class 0: 10000 samples Class 1: 10000 samples Class 2: 10000 samples Train samples: 19200 Validation samples: 4800

Test samples: 6000

Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc

h.Size([16])

Data check - Input dtype: torch.float32, Labels dtype: torch.int64

Data check - Labels unique values: tensor([0, 1, 2])

Downloading: "https://download.pytorch.org/models/densenet121-a639ec97.pth"

to /root/.cache/torch/hub/checkpoints/densenet121-a639ec97.pth

100% | 30.8M/30.8M [00:00<00:00, 82.4MB/s]

```
Model initialized: densenet121
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Data check - Input shape: torch.Size([16, 3, 150, 150]), Labels shape: torc
h.Size([16])
Data check - Input dtype: torch.float32, Labels dtype: torch.int64
Data check - Labels unique values: tensor([0, 1, 2])
Epoch 1/10
_ _ _ _ _ _ _ _ _
Training: 100% | 1200/1200 [01:47<00:00, 11.20it/s]
Train Loss: 0.0009 Acc: 0.0004
Validation: 100% 300/300 [00:09<00:00, 32.55it/s]
Val Loss: 1.1730 Acc: 0.3333
Mean AUC: 0.5079
Best validation AUC: 0.5079
Epoch 2/10
_ _ _ _ _ _ _ _ _ _
Training: 100% | 1200/1200 [01:46<00:00, 11.29it/s]
Train Loss: 0.0009 Acc: 0.0004
Validation: 100% 300/300 [00:09<00:00, 32.30it/s]
Val Loss: 1.1325 Acc: 0.3317
Mean AUC: 0.5003
Best validation AUC: 0.5079
Epoch 3/10
_ _ _ _ _ _ _ _ _ _
Training: 100% | 1200/1200 [01:46<00:00, 11.30it/s]
Train Loss: 0.0009 Acc: 0.0004
Validation: 100% | 300/300 [00:09<00:00, 31.25it/s]
Val Loss: 1.1644 Acc: 0.3333
Mean AUC: 0.5114
Best validation AUC: 0.5114
Epoch 4/10
_____
Training: 100% | 1200/1200 [01:46<00:00, 11.26it/s]
Train Loss: 0.0009 Acc: 0.0002
Validation: 100%| 300/300 [00:09<00:00, 31.10it/s]
Val Loss: 1.1629 Acc: 0.3321
Mean AUC: 0.4953
Best validation AUC: 0.5114
Epoch 5/10
------
Training: 100% | 1200/1200 [01:47<00:00, 11.20it/s]
Train Loss: 0.0009 Acc: 0.0003
Validation: 100% | 300/300 [00:09<00:00, 31.32it/s]
Val Loss: 1.1045 Acc: 0.3333
Mean AUC: 0.4956
Best validation AUC: 0.5114
Epoch 6/10
_ _ _ _ _ _ _ _ _ _
Training: 100% | 1200/1200 [01:47<00:00, 11.14it/s]
```

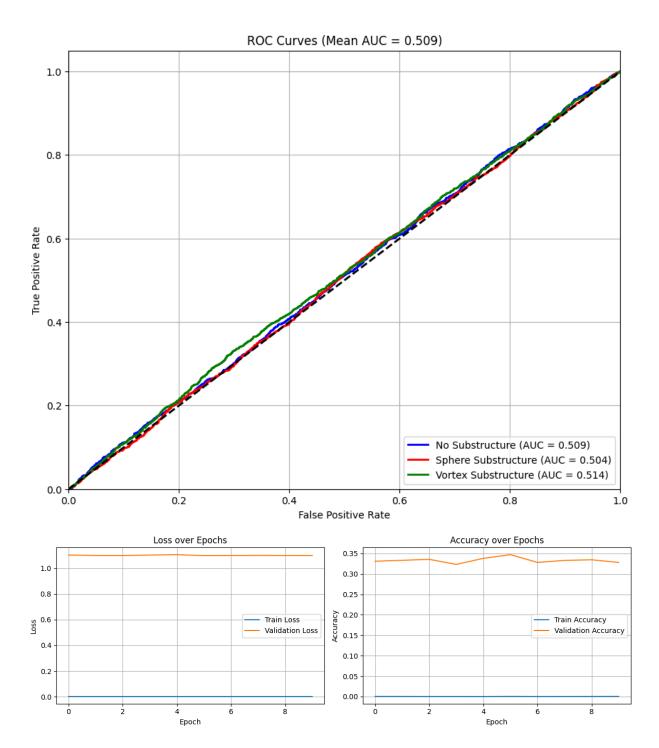
Loading [MathJax]/extensions/Safe.js 0.0009 Acc: 0.0002

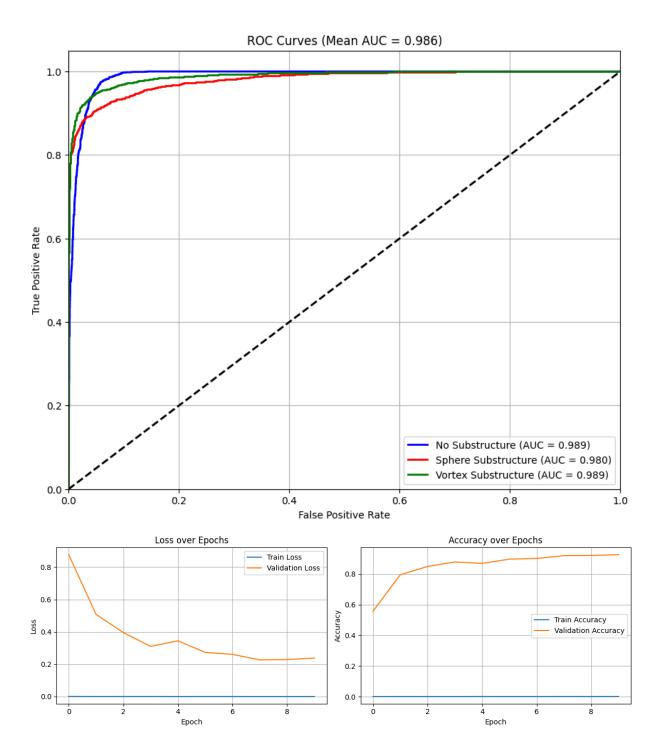
Validation: 100% 300/300 [00:09<00:00, 31.25it/s] Val Loss: 6.2354 Acc: 0.3333 Mean AUC: 0.5017 Best validation AUC: 0.5114 Epoch 7/10 _ _ _ _ _ _ _ _ _ _ Training: 100% | 1200/1200 [01:46<00:00, 11.22it/s] Train Loss: 0.0009 Acc: 0.0003 Validation: 100% 300/300 [00:09<00:00, 31.24it/s] Val Loss: 1.1089 Acc: 0.3333 Mean AUC: 0.5062 Best validation AUC: 0.5114 Epoch 8/10 ------Training: 100% | 1200/1200 [01:47<00:00, 11.21it/s] Train Loss: 0.0009 Acc: 0.0001 Validation: 100% 300/300 [00:09<00:00, 31.83it/s] Val Loss: 1.1016 Acc: 0.3358 Mean AUC: 0.5019 Best validation AUC: 0.5114 Epoch 9/10 _ _ _ _ _ _ _ _ _ _ Training: 100% | 1200/1200 [01:47<00:00, 11.17it/s] Train Loss: 0.0009 Acc: 0.0003 Validation: 100%| 300/300 [00:09<00:00, 31.28it/s] Val Loss: 1.0985 Acc: 0.3383 Mean AUC: 0.5073 Best validation AUC: 0.5114 Epoch 10/10 _ _ _ _ _ _ _ _ _ _ Training: 100% | 1200/1200 [01:47<00:00, 11.12it/s] Train Loss: 0.0009 Acc: 0.0004 Validation: 100% | 300/300 [00:09<00:00, 30.72it/s] Val Loss: 1.0991 Acc: 0.3477 Mean AUC: 0.5026 Best validation AUC: 0.5114 Testing: 100% | 375/375 [00:12<00:00, 31.12it/s] Test Accuracy: 0.3388 Model saved to /content/drive/MyDrive/densenet121 lensing classifier.pth Final test accuracy: 0.3388 Final mean AUC: 0.5093

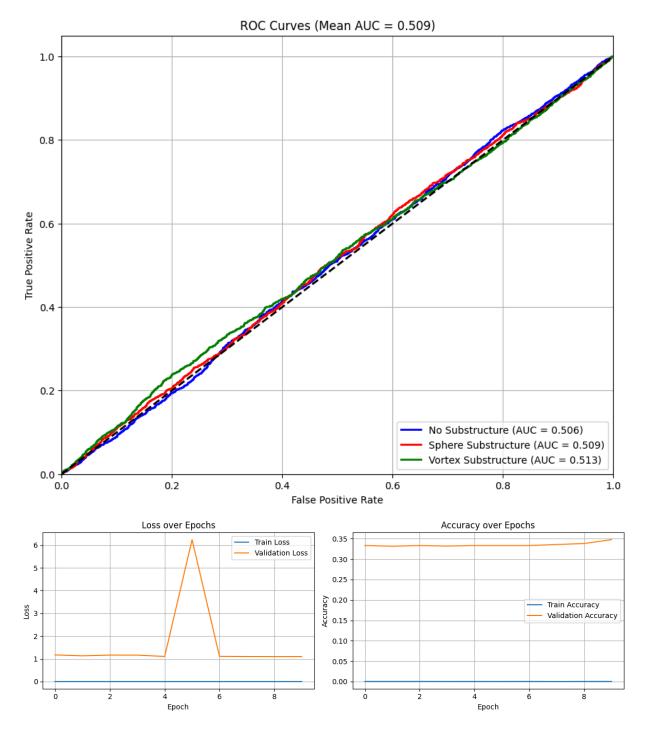
Model Comparison Results:

Model Accuracy Mean AUC ----resnet50 0.3407 0.5092 efficientnet_b0 0.9267 0.9859 densenet121 0.3388 0.5093

Best model by AUC: efficientnet b0 with AUC = 0.9859







This notebook was converted with convert.ploomber.io