

```
In [ ]: !pip install torch-fidelity
```

Collecting torch-fidelity

Downloading torch_fidelity-0.3.0-py3-none-any.whl.metadata (2.0 kB)

Requirement already satisfied: numpy in /usr/local/lib/python3.11/dist-packages (from torch-fidelity) (1.26.4)

Requirement already satisfied: Pillow in /usr/local/lib/python3.11/dist-packages (from torch-fidelity) (11.1.0)

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Requirement already satisfied: typing-extensions>=4.8.0 in /usr/local/lib/python3.11/dist-packages (from torch->torch-fidelity) (4.12.2)

Requirement already satisfied: networkx in /usr/local/lib/python3.11/dist-packages (from torch->torch-fidelity) (3.4.2)

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Collecting nvidia-cuda-nvrtc-cu12==12.4.127 (from torch->torch-fidelity)

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Collecting nvidia-cuda-runtime-cu12==12.4.127 (from torch->torch-fidelity)

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Collecting nvidia-cuda-cupti-cu12==12.4.127 (from torch->torch-fidelity)

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Collecting nvidia-cudnn-cu12==9.1.0.70 (from torch->torch-fidelity)

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Collecting nvidia-cublas-cu12==12.4.5.8 (from torch->torch-fidelity)

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Collecting nvidia-cufft-cu12==11.2.1.3 (from torch->torch-fidelity)

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Collecting nvidia-curand-cu12==10.3.5.147 (from torch->torch-fidelity)

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Collecting nvidia-cusolver-cu12==11.6.1.9 (from torch->torch-fidelity)

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Collecting nvidia-nvjitlink-cu12==12.4.127 (from torch->torch-fidelity)

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Installing collected packages: nvidia-nvjitlink-cu12, nvidia-curand-cu12, nvidia-cufft-cu12, nvidia-cuda-runtime-cu12, nvidia-cuda-nvrtc-cu12, nvidia-cuda-cupti-cu12, nvidia-cublas-cu12, nvidia-cusparsesparse-cu12, nvidia-cudnn-cu12, nvidia-cusolver-cu12, torch-fidelity
Attempting uninstall: nvidia-nvjitlink-cu12

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Found existing installation: nvidia-nvjitlink-cu12 12.5.82
Uninstalling nvidia-nvjitlink-cu12-12.5.82:
Successfully uninstalled nvidia-nvjitlink-cu12-12.5.82
Attempting uninstall: nvidia-curand-cu12
Found existing installation: nvidia-curand-cu12 10.3.6.82
Uninstalling nvidia-curand-cu12-10.3.6.82:
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Attempting uninstall: nvidia-cufft-cu12
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Attempting uninstall: nvidia-cuda-nvrtc-cu12
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Attempting uninstall: nvidia-cudnn-cu12
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```
In [ ]: import os
import numpy as np
import torch
import torch.nn as nn
import torch.nn.functional as F
from torch.utils.data import DataLoader, TensorDataset
from torch.optim import Adam
from torch.cuda.amp import GradScaler, autocast
from tqdm import tqdm
import matplotlib.pyplot as plt
from torch_fidelity import calculate_metrics
```

```
In [ ]: !pip install gdown
import gdown
import zipfile

file_id = "1cJyPQzV0zsCZQctNBuHCqxHn0Y7v7UiA"
output = "dataset.zip"
gdown.download(f"https://drive.google.com/uc?id={file_id}", output, quiet =

with zipfile.ZipFile("dataset.zip", "r") as zip_ref:
    zip_ref.extractall("/content/dataset")
```

```
Requirement already satisfied: gdown in /usr/local/lib/python3.11/dist-packa
ges (5.2.0)
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Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/py
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Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.11/dis
t-packages (from requests[socks]->gdown) (3.10)
Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.
11/dist-packages (from requests[socks]->gdown) (2.3.0)
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.
11/dist-packages (from requests[socks]->gdown) (2025.1.31)
Requirement already satisfied: PySocks!=1.5.7,>=1.5.6 in /usr/local/lib/pyth
on3.11/dist-packages (from requests[socks]->gdown) (1.7.1)
```

```
Downloading...
From (original): https://drive.google.com/uc?id=1cJyPQzV0zsCZQctNBuHCqxHn0Y7
v7UiA
From (redirected): https://drive.google.com/uc?id=1cJyPQzV0zsCZQctNBuHCqxHn0
Y7v7UiA&confirm=t&uuid=c3609420-c9d5-48b7-8078-ac84e41c92cb
To: /content/dataset.zip
100%|██████████| 304M/304M [00:08<00:00, 34.5MB/s]
```

```
In [ ]: data_dir = "/content/dataset/Samples"
        npy_files = [f for f in os.listdir(data_dir) if f.endswith('.npy')]
```

```
In [ ]: images = []
        for file in npy_files:
            img = np.load(os.path.join(data_dir, file))
            images.append(torch.from_numpy(img).float())
```

```
In [ ]: images_tensor = torch.stack(images)
        print(f"Dataset loaded. Shape: {images_tensor.shape}, Min: {images_tensor.min()}")

Dataset loaded. Shape: torch.Size([10000, 1, 150, 150]), Min: 0.0, Max: 1.0
```

```
In [ ]: dataset = TensorDataset(images_tensor)
        dataloader = DataLoader(dataset, batch_size=32, shuffle=True)
```

```
In [ ]: device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
```

```
In [ ]: class Diffusion(nn.Module):
        def __init__(self, T = 1000, beta_starts = 1e-4, beta_end = 0.02, device = device):
            super().__init__()
            self.T = T
            self.device = device
            betas = torch.linspace(beta_starts, beta_end, T).to(device)
            alphas = 1 - betas
            alpha_bars = torch.cumprod(alphas, dim = 0)

            self.register_buffer('sqrt_alpha_bars', torch.sqrt(alpha_bars))
            self.register_buffer('sqrt_one_minus_alpha_bars', torch.sqrt(1 - alpha_bars))

        def q_sample(self, x0, t, noise = None):
            if noise is None:
                noise = torch.randn_like(x0)
            batch_size = x0.shape[0]
            sqrt_alpha_bar = self.sqrt_alpha_bars[t].view(batch_size, 1, 1, 1)
            sqrt_one_minus_alpha_bar = self.sqrt_one_minus_alpha_bars[t].view(batch_size, 1, 1, 1)
            return sqrt_alpha_bar * x0 + sqrt_one_minus_alpha_bar * noise

        def ddim_sample(self, model, n_samples, image_size, channels, steps=50):
            model.eval()
            with torch.no_grad():
                total_steps = self.T
                step_indices = torch.linspace(0, total_steps-1, steps, dtype=torch.long)
                timesteps = step_indices
                x = torch.randn(n_samples, channels, image_size, image_size, device=device)

                for i in range(len(timesteps) - 1, -1, -1):
                    t = timesteps[i].repeat(n_samples)
                    t_next = timesteps[i-1] if i > 0 else -1
                    predicted_noise = model(x, t)
                    alpha_bar_t = self.sqrt_alpha_bars[t]**2
                    alpha_bar_t_next = self.sqrt_alpha_bars[t_next]**2 if t_next >= 0 else 0
                    sigma = 0
                    x0_pred = (x - torch.sqrt(1 - alpha_bar_t) * predicted_noise) / torch.sqrt(alpha_bar_t - alpha_bar_t_next)
                    if t_next >= 0:
                        x = torch.sqrt(alpha_bar_t_next) * x0_pred + torch.sqrt(1 - alpha_bar_t_next) * predicted_noise
```

```

        noise_dir = torch.sqrt(1 - alpha_bar_t_next - sigma**2) * predicted_x0
        x = torch.sqrt(alpha_bar_t_next) * x0_pred + noise_dir
    else:
        x = x0_pred
    return x

```

```

In [ ]: class SinusoidalEmbedding(nn.Module):
    def __init__(self, dim):
        super().__init__()
        self.dim = dim

    def forward(self, t):
        device = t.device
        half_dim = self.dim // 2
        emb = torch.arange(half_dim, device=device).float()
        emb = torch.exp(-emb * (np.log(10000) / half_dim))
        emb = t[:, None] * emb[None, :]
        return torch.cat([torch.sin(emb), torch.cos(emb)], dim=1)

```

```

In [ ]: class UNetBlock(nn.Module):
    def __init__(self, in_channels, out_channels, time_dim):
        super().__init__()
        self.time_mlp = nn.Linear(time_dim, out_channels)
        self.conv1 = nn.Conv2d(in_channels, out_channels, 3, padding=1)
        self.conv2 = nn.Conv2d(out_channels, out_channels, 3, padding=1)
        self.norm1 = nn.GroupNorm(8, out_channels)
        self.norm2 = nn.GroupNorm(8, out_channels)
        self.relu = nn.ReLU()

    def forward(self, x, t):
        h = self.conv1(x)
        time_emb = self.relu(self.time_mlp(t))
        h = h + time_emb[:, :, None, None]
        h = self.norm1(h)
        h = self.relu(h)
        h = self.conv2(h)
        h = self.norm2(h)
        return self.relu(h)

```

```

In [ ]: class UNet(nn.Module):
    def __init__(self, time_dim=128):
        super().__init__()
        self.time_emb = SinusoidalEmbedding(time_dim)
        self.time_mlp = nn.Sequential(nn.Linear(time_dim, time_dim), nn.ReLU())

        # Downsampling
        self.down1 = UNetBlock(1, 64, time_dim)
        self.pool1 = nn.MaxPool2d(2) # 150 -> 75
        self.down2 = UNetBlock(64, 128, time_dim)
        self.pool2 = nn.MaxPool2d(2) # 75 -> 37

        # Bottleneck
        self.bottleneck = UNetBlock(128, 256, time_dim)

        # Upsampling

```

```

self.upconv1 = nn.ConvTranspose2d(256, 128, 2, stride=2) # 37 -> 74
self.up1 = UNetBlock(256, 128, time_dim)
self.upconv2 = nn.ConvTranspose2d(128, 64, 2, stride=2) # 74 -> 148
self.up2 = UNetBlock(128, 64, time_dim)

# Output
self.out = nn.Conv2d(64, 1, 1)

def forward(self, x, t):
    t_emb = self.time_emb(t)
    t_emb = self.time_mlp(t_emb)

    d1 = self.down1(x, t_emb)
    d2 = self.pool1(d1)
    d3 = self.down2(d2, t_emb)
    d4 = self.pool2(d3)

    b = self.bottleneck(d4, t_emb)

    u1 = self.upconv1(b)
    u1 = torch.cat([F.interpolate(u1, size=d3.shape[2:], mode='bilinear',
                                  align_corners=False), t_emb], 1)
    u2 = self.up1(u1, t_emb)
    u3 = self.upconv2(u2)
    u3 = torch.cat([F.interpolate(u3, size=d1.shape[2:], mode='bilinear',
                                  align_corners=False), t_emb], 1)
    u4 = self.up2(u3, t_emb)

    return self.out(u4)

```

```

In [ ]: diffusion = Diffusion(device=device).to(device)
model = UNet().to(device)
optimizer = Adam(model.parameters(), lr=1e-4)
scaler = GradScaler()
num_epochs = 50

```

<ipython-input-13-105fb84a9e88>:4: FutureWarning: `torch.cuda.amp.GradScaler(args...)` is deprecated. Please use `torch.amp.GradScaler('cuda', args...)` instead.

```

    scaler = GradScaler()

```

```

In [ ]: for epoch in range(num_epochs):
    model.train()
    total_loss = 0
    for batch in tqdm(dataloader, desc=f"Epoch {epoch+1}/{num_epochs}"):
        x0 = batch[0].to(device)
        t = torch.randint(0, diffusion.T, (x0.shape[0],), device=device)
        noise = torch.randn_like(x0)
        xt = diffusion.q_sample(x0, t, noise)
        with autocast():
            predicted_noise = model(xt, t)
            loss = F.mse_loss(predicted_noise, noise)
        optimizer.zero_grad()
        scaler.scale(loss).backward()
        scaler.step(optimizer)
        scaler.update()
        total_loss += loss.item()
    avg_loss = total_loss / len(dataloader)

```



```

print(f"Epoch {epoch+1}/{num_epochs}, Avg Loss: {avg_loss:.6f}")
# Save checkpoint every 10 epochs
if (epoch + 1) % 10 == 0:
    torch.save(model.state_dict(), f'diffusion_model_epoch_{epoch+1}.pt')

```

```

Epoch 1/50: 0%|          | 0/313 [00:00<?, ?it/s]<ipython-input-14-9e358da
0f5fd>:9: FutureWarning: `torch.cuda.amp.autocast(args...)` is deprecated. P
lease use `torch.amp.autocast('cuda', args...)` instead.
    with autocast():
Epoch 1/50: 100%|██████████| 313/313 [01:24<00:00, 3.70it/s]
Epoch 1/50, Avg Loss: 0.061173
Epoch 2/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 2/50, Avg Loss: 0.008365
Epoch 3/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 3/50, Avg Loss: 0.006109
Epoch 4/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 4/50, Avg Loss: 0.004949
Epoch 5/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]
Epoch 5/50, Avg Loss: 0.004373
Epoch 6/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 6/50, Avg Loss: 0.004251
Epoch 7/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 7/50, Avg Loss: 0.003748
Epoch 8/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 8/50, Avg Loss: 0.003838
Epoch 9/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]
Epoch 9/50, Avg Loss: 0.003494
Epoch 10/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]
Epoch 10/50, Avg Loss: 0.003297
Epoch 11/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]
Epoch 11/50, Avg Loss: 0.003168
Epoch 12/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 12/50, Avg Loss: 0.003616
Epoch 13/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]
Epoch 13/50, Avg Loss: 0.003116
Epoch 14/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 14/50, Avg Loss: 0.002822
Epoch 15/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 15/50, Avg Loss: 0.002839
Epoch 16/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 16/50, Avg Loss: 0.002829
Epoch 17/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 17/50, Avg Loss: 0.002805
Epoch 18/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 18/50, Avg Loss: 0.002809
Epoch 19/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]
Epoch 19/50, Avg Loss: 0.002782
Epoch 20/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 20/50, Avg Loss: 0.002889
Epoch 21/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

```

Epoch 21/50, Avg Loss: 0.002983

Epoch 22/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 22/50, Avg Loss: 0.002647

Epoch 23/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]

Epoch 23/50, Avg Loss: 0.002530

Epoch 24/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 24/50, Avg Loss: 0.002551

Epoch 25/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 25/50, Avg Loss: 0.002328

Epoch 26/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 26/50, Avg Loss: 0.002647

Epoch 27/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 27/50, Avg Loss: 0.002692

Epoch 28/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 28/50, Avg Loss: 0.002683

Epoch 29/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 29/50, Avg Loss: 0.002508

Epoch 30/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]

Epoch 30/50, Avg Loss: 0.002139

Epoch 31/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 31/50, Avg Loss: 0.002213

Epoch 32/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 32/50, Avg Loss: 0.002151

Epoch 33/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]

Epoch 33/50, Avg Loss: 0.002427

Epoch 34/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 34/50, Avg Loss: 0.002314

Epoch 35/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 35/50, Avg Loss: 0.002134

Epoch 36/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 36/50, Avg Loss: 0.002307

Epoch 37/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 37/50, Avg Loss: 0.001954

Epoch 38/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 38/50, Avg Loss: 0.002340

Epoch 39/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]

Epoch 39/50, Avg Loss: 0.002319

Epoch 40/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]

Epoch 40/50, Avg Loss: 0.001903

Epoch 41/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]

Epoch 41/50, Avg Loss: 0.002443

Epoch 42/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 42/50, Avg Loss: 0.001773

Epoch 43/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]

Epoch 43/50, Avg Loss: 0.002127

Epoch 44/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]

Epoch 44/50, Avg Loss: 0.002165

Epoch 45/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]

Epoch 45/50, Avg Loss: 0.002119

```
Epoch 46/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 46/50, Avg Loss: 0.001924
Epoch 47/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 47/50, Avg Loss: 0.002269
Epoch 48/50: 100%|██████████| 313/313 [01:22<00:00, 3.79it/s]
Epoch 48/50, Avg Loss: 0.002248
Epoch 49/50: 100%|██████████| 313/313 [01:22<00:00, 3.80it/s]
Epoch 49/50, Avg Loss: 0.002209
Epoch 50/50: 100%|██████████| 313/313 [01:22<00:00, 3.78it/s]
Epoch 50/50, Avg Loss: 0.002010
```

```
In [ ]: generated_images = diffusion.ddim_sample(model, n_samples=1000, image_size=1
generated_images = torch.clamp(generated_images, 0, 1)
```

```

-----
OutOfMemoryError                                Traceback (most recent call last)
<ipython-input-17-c4d3fef7a10e> in <cell line: 0>()
----> 1 generated_images = diffusion.ddim_sample(model, n_samples=1000, image_size=150, channels=1, steps=50)
      2 generated_images = torch.clamp(generated_images, 0, 1)

<ipython-input-9-77580367b9d0> in ddim_sample(self, model, n_samples, image_size, channels, steps)
      30         t = timesteps[i].repeat(n_samples)
      31         t_next = timesteps[i-1] if i > 0 else -1
----> 32         predicted_noise = model(x, t)
      33         alpha_bar_t = self.sqrt_alpha_bars[t]**2
      34         alpha_bar_t_next = self.sqrt_alpha_bars[t_next]**2 if t_next
>= 0 else 1.0

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/module.py in _wrapped_call_impl(self, *args, **kwargs)
    1734         return self._compiled_call_impl(*args, **kwargs) # type: ignore[misc]
    1735     else:
-> 1736         return self._call_impl(*args, **kwargs)
    1737
    1738     # torchrec tests the code consistency with the following code

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/module.py in _call_impl(self, *args, **kwargs)
    1745         or _global_backward_pre_hooks or _global_backward_hooks
    1746         or _global_forward_hooks or _global_forward_pre_hooks):
-> 1747         return forward_call(*args, **kwargs)
    1748
    1749     result = None

<ipython-input-12-b7592765fa37> in forward(self, x, t)
      27         t_emb = self.time_mlp(t_emb)
      28
----> 29         d1 = self.down1(x, t_emb)
      30         d2 = self.pool1(d1)
      31         d3 = self.down2(d2, t_emb)

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/module.py in _wrapped_call_impl(self, *args, **kwargs)
    1734         return self._compiled_call_impl(*args, **kwargs) # type: ignore[misc]
    1735     else:
-> 1736         return self._call_impl(*args, **kwargs)
    1737
    1738     # torchrec tests the code consistency with the following code

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/module.py in _call_impl(self, *args, **kwargs)
    1745         or _global_backward_pre_hooks or _global_backward_hooks
    1746         or _global_forward_hooks or _global_forward_pre_hooks):

```

```

s):
-> 1747             return forward_call(*args, **kwargs)
    1748
    1749             result = None

<ipython-input-11-05f8304e98a8> in forward(self, x, t)
    10
    11     def forward(self, x, t):
--> 12         h = self.conv1(x)
    13         time_emb = self.relu(self.time_mlp(t))
    14         h = h + time_emb[:, :, None, None]

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/module.py in _wrapped_call_impl(self, *args, **kwargs)
    1734         return self._compiled_call_impl(*args, **kwargs) # type: ignore[misc]
    1735     else:
-> 1736         return self._call_impl(*args, **kwargs)
    1737
    1738     # torchrec tests the code consistency with the following code

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/module.py in _call_impl(self, *args, **kwargs)
    1745         or _global_backward_pre_hooks or _global_backward_hooks
    1746         or _global_forward_hooks or _global_forward_pre_hooks):
-> 1747             return forward_call(*args, **kwargs)
    1748
    1749             result = None

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/conv.py in forward(self, input)
    552
    553     def forward(self, input: Tensor) -> Tensor:
--> 554         return self._conv_forward(input, self.weight, self.bias)
    555
    556

/usr/local/lib/python3.11/dist-packages/torch/nn/modules/conv.py in _conv_forward(self, input, weight, bias)
    547         self.groups,
    548     )
--> 549     return F.conv2d(
    550         input, weight, bias, self.stride, self.padding, self.dilation, self.groups
    551     )

```

OutOfMemoryError: CUDA out of memory. Tried to allocate 5.37 GiB. GPU 0 has a total capacity of 14.74 GiB of which 916.12 MiB is free. Process 5293 has 13.84 GiB memory in use. Of the allocated memory 11.57 GiB is allocated by PyTorch, and 2.14 GiB is reserved by PyTorch but unallocated. If reserved but unallocated memory is large try setting PYTORCH_CUDA_ALLOC_CONF=expandable_segments:True to avoid fragmentation. See documentation for Memory Management (<https://pytorch.org/docs/stable/notes/cuda.html#environment-variables>)

```
In [ ]: generated_images_rgb = generated_images.repeat(1, 3, 1, 1).cpu()
real_images_rgb = images_tensor[:1000].repeat(1, 3, 1, 1)
metrics = calculate_metrics(
    input1=generated_images_rgb,
    input2=real_images_rgb,
    fid=True,
    cuda=True,
    isc=False,
    kid=False
)
fid = metrics['frechet_inception_distance']
print(f"FID Score: {fid}")
```

```
In [ ]: fig, axes = plt.subplots(1, 5, figsize=(15, 3))
for i in range(5):
    axes[i].imshow(generated_images[i].squeeze().cpu().numpy(), cmap='gray')
    axes[i].axis('off')
plt.suptitle("Generated Strong Lensing Images")
plt.show()
```