Econ 512 HW 3

Kalyani Padmakumar

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The codes have been specified in the MATLAB file hw3' updatedcodes.m.Results are as follows:

1 Question 1: Result

The estimated beta vector is denoted by soll base here. More details are displayed along with the time to convergence:

```
coll_base =

2.5339
-0.0223
0.1157
-0.3540
0.0798
-0.4094

fval =

1.4270e+03

cutflag =

1

cutput =

struct with fields:

iterations: 909
funcCount: 1442
algorithm: 'Medie-Mead simplex direct search'
message: 'Optimization terminated: 'T the current x satisfies the termination criteria using OFTIONS.ToLX of 1.00000e-06 -1 and F(X) satisfies the convergence criteria

Elapsed time is 0.052605 seconds.

>>
```

2 Question 2: Result

The estimated beta vector is denoted by sol2 base here. More details are displayed along with the time to convergence:

```
sol2 base =

0.9225

0.01368
0.9196
0.9193
0.9142

fval2 =

7.1555e+12

exitflag2 =

1

output? =

sirvet with fields:

iterations: 1
functount: 14
srepairs: 1.0459
lasteplanght: 1.0450-4:1
firstonderopt: 3.127e+14
algorithm: 'quasi-newton'
message: 'Local minimum found.***Optimization completed because the size of the gradient is less than the selected value of the optimality tolerance.***AStopping (
Elapsed time is 0.009617 seconds.

>>>

Elapsed time is 0.009617 seconds.
```

3 Question 3: Result

The estimated beta vector is denoted by sol3 base here. More details are displayed along with the time to convergence:

```
sol3_base =

-22.9709
    1.0000
    0.9981
    1.0000
    1.0000
    1.0000

Elapsed time is 0.019607 seconds.
>>
```

4 Question 4: Result

The estimated beta vector is denoted by sol4'base here. More details are displayed along with the time to convergence:

5 Question 5: Result

In terms of time to convergence, the quasi-Newton method converges to the solution quickly, followed by Isqnonlin in question 3, then the nelder mead simplex method of estimation by NLS and then the nelder mead simplex method of estimation by MLE.

In order to check robustness, we have recalculated solutions for questions 1-4 for 10 sets of initial values for these parameters. Each set of initial value is denoted by beta0, where each beta0 is a column vector in r. r is a (10*6) matrix of numbers uniformly distributed between 0 and 10.

For each vector of initial values, I have calculated the norm of the difference between the new solution and the original solution obtained in questions 1/2/3/4. The results have been described below.

The vector x displays the norm of the difference between the new solution for each vector of initial values and the original solution obtained in question 1. For instance, the element in the first row and first column of x displays the norm of the difference between the solution (when the initial vector is the first column of r) and the solution obtained in question 1.Similarly, the vector w displays the norm of the difference between the new solution for each vector of initial values and the original solution obtained in question 2.Vector z displays the norm of the difference between the new solution for each vector of initial values and the original solution obtained in question 3.Vector a displays the norm of the difference between the new solution for each vector of initial values and the original solution obtained in question 4.

From below, it looks as though the Quasi Newton method is least sensitive to the initial condition.

```
>> x
x =
19.9119 18.4889 0.0214 21.7494 13.9297 6.2358 103.9806 50.2844 56.9082 9.2550
>> w
x =
11.1695 12.3861 12.9524 11.7805 10.5775 10.6273 15.0340 9.4687 12.8715 12.7597
>> z
z =
28.0022 29.1740 27.4122 29.9991 28.8116 14.7421 34.4744 31.0524 29.2188 31.9350
>> a
a =
24.3000 13.2364 14.4491 12.3916 11.9283 269.2220 15.4640 48.7763 50.7381 67.9637
>> |
```

(Please note that this is joint work with Ece Teoman and we referred to the web for help with certain commands.)