CS 412

APRIL 28TH - DEEP LEARNING

Convolitional DN Leward NN

Course Grading

Regrade requests

Blackboard

- "current percentage
- Likely to be a very small curve
- At least 90,80,70

Asseys for Milliam 85 C-mg/m, cos

13-ry 80 s

- 135-or

- 135-or

- 35-or

Administrivia

HW5 Out

Due Thursday – last chance to use late days

Midterm regrades \leftarrow

• If you get them in today, I'll finish them today

Final Exam

- Current plan per the general final schedule: 24 hour take-home exam on Wednesday May 6th
- Midnight-to-midnight CDT
- If this doesn't work scheduling-wise, let me know ASAP

Course evaluations

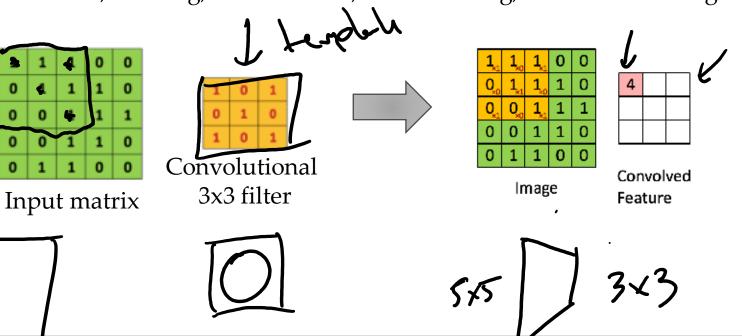
Deep learn

Main CNN idea for text:

Compute vectors for n-grams and group them afterwards

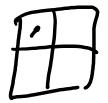
Example: "this takes too long" compute vectors for:

This takes, takes too, too long, this takes too, takes too long, this takes too long

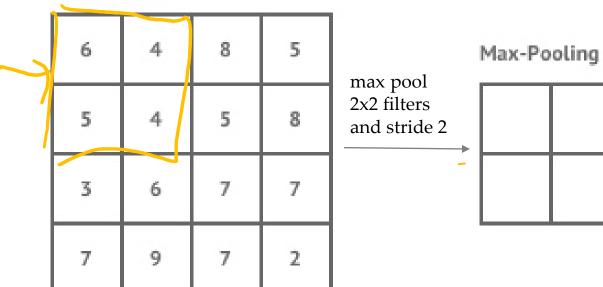


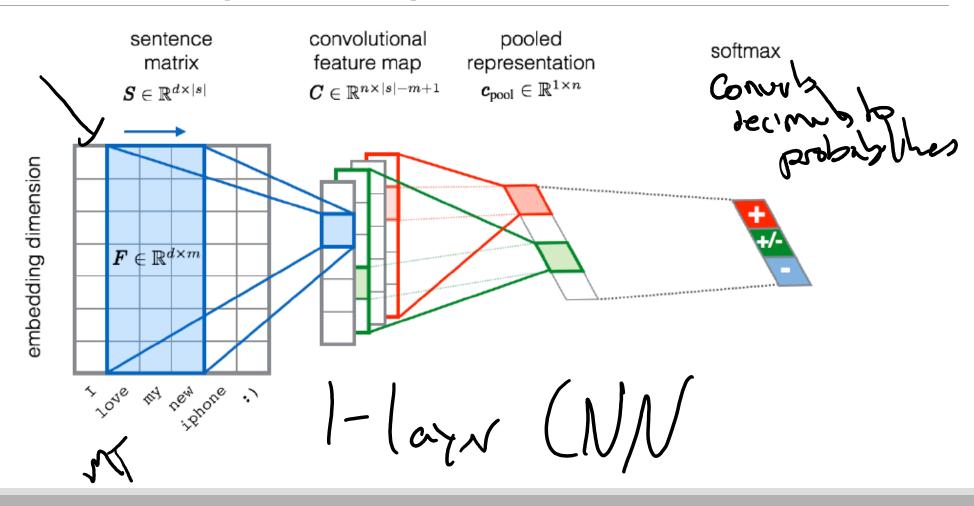
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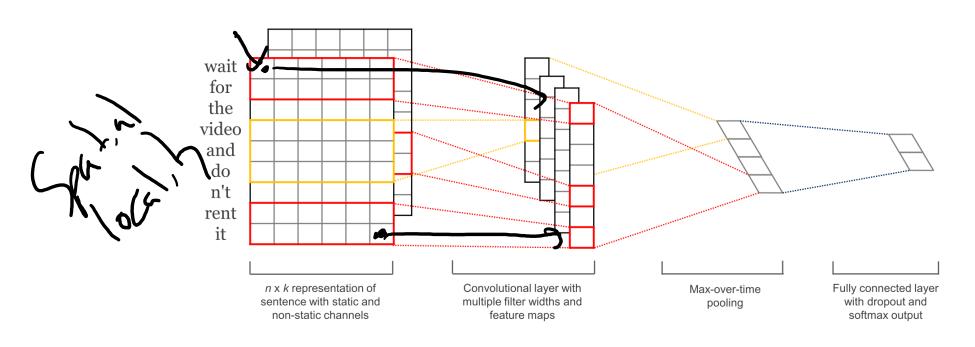
Compute vectors for n-grams and group them afterwards



Feature Map







CNN Architecture Service Comment (1) formal

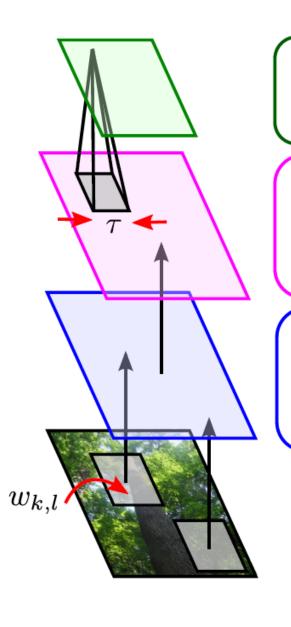
Intuition: Neural network with specialized connectivity structure,

- Stacking multiple layers of feature extractors
- Low-level layers extract local features.
- High-level layers extract learn global patterns.

A CNN is a list of layers that transform the input data into an output class/prediction.

There are a few distinct types of layers:

- Convolutional layer
- Non-linear layer
- Pooling layer



$$x_{i,j} = \max_{|k| < au, |l| < au} y_{i-k,j-l}$$
 pooling mean or subsample also used stage

Feature maps of a larger region are combined.

$$y_{i,j} = f(a_{i,j})$$
e.g. $f(a) = [a]_+$ non-linear $f(a) = \operatorname{sigmoid}(a)$

Feature maps are trained with neurons.

must go between

 $a_{i,j} = \sum_{k,l} w_{k,l} z_{i-k,j-l}$ convolutional stage

Each sub-region yields a feature map, representing its feature.

Shared weights

 $z_{i,j}$ Q

each input image

Children image

Shr Shr Jeily

Images are segmented into sub-regions.

CNN Architecture: Convolutional Layer

The core layer of CNNs

The convolutional layer consists of a set of filters.

• Each filter covers a spatially small portion of the input data.

Each filter is convolved across the dimensions of the input data, producing a multidimensional feature map.

• As we convolve the filter, we are computing the dot product between the parameters of the filter and the input.

Intuition: the network will learn filters that activate when they see some specific type of feature at some spatial position in the input.

The key architectural characteristics of the convolutional layer is local connectivity and shared weights.

CNN Convolutional Layer: Local Connectivity

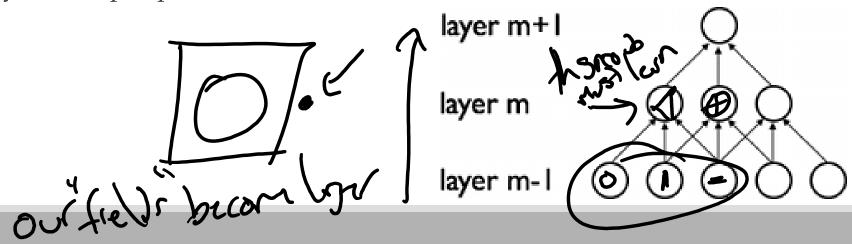
Neurons in layer m are only connected to 3 adjacent neurons in the m-1 layer.

Neurons in layer m+1 have a similar connectivity with the layer below.

Each neuron is unresponsive to variations outside of its receptive field with respect to the input.

Receptive field: small neuron collections which process portions of the input data

The architecture thus ensures that the learnt feature extractors produce the strongest response to a spatially local input pattern.



CNN Convolutional Layer: Shared Weights

We show 3 hidden neurons belonging to the same feature map (the layer right above the input layer).

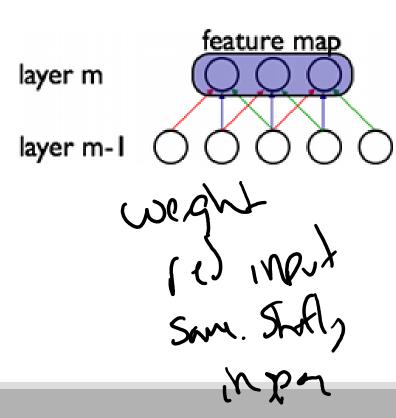
Weights of the same color are shared—constrained to be identical.

Gradient descent can still be used to learn such shared parameters, with only a small change to the original algorithm.

The gradient of a shared weight is simply the sum of the gradients of the parameters being shared.

Replicating neurons in this way allows for features to be detected regardless of their position in the input.

Additionally, weight sharing increases learning efficiency by greatly reducing the number of free parameters being learnt.



CNN Architecture: Non-linear Layer

Intuition: Increase the nonlinearity of the entire architecture without affecting the receptive fields of the convolution layer

A layer of neurons that applies the non-linear activation function, such as,

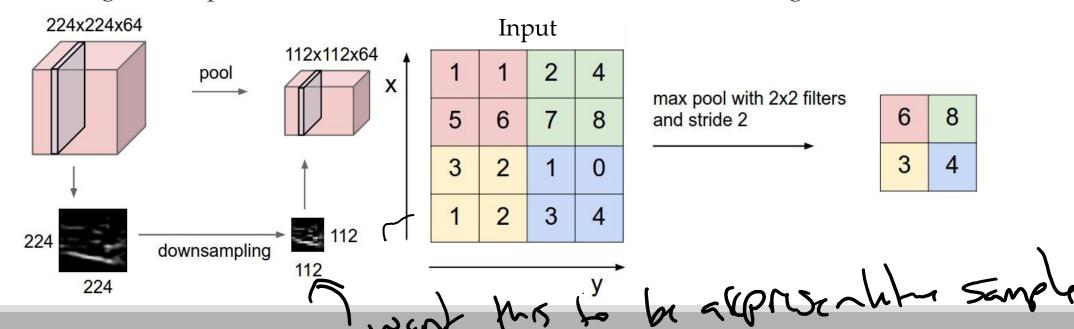
- $f(x) = \max(0, x)$
- $f(x) = \tanh x$
- $f(x) = |\tanh x|$
- $f(x) = (1 + e^{-x})^{-1}$

Rell 15 popler

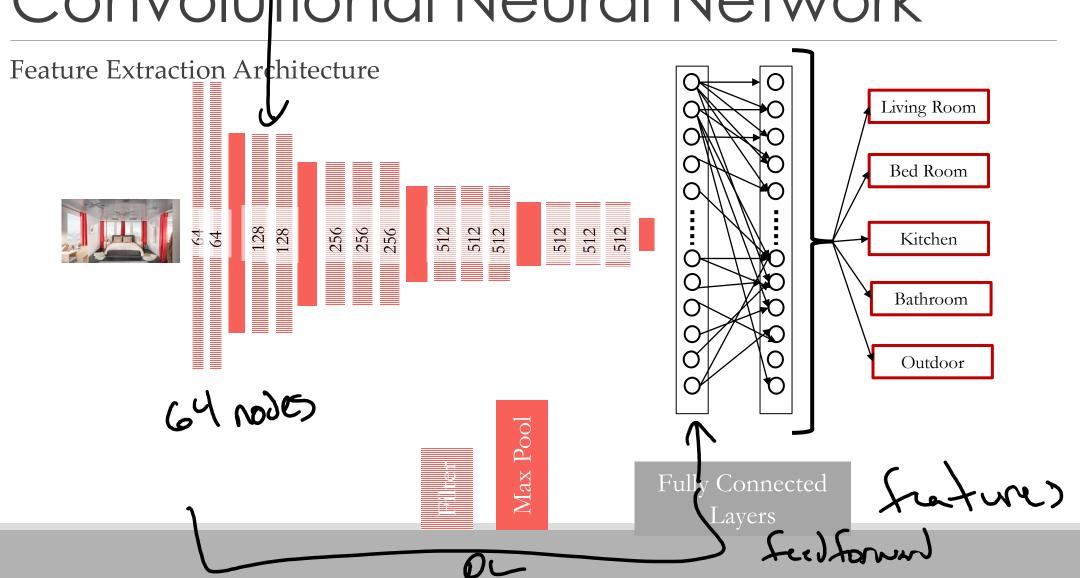
CNN Architecture: Pooling Layer

Intuition: to progressively reduce the spatial size of the representation to reduce the amount of parameters and computation in the network, and hence to also control overfitting

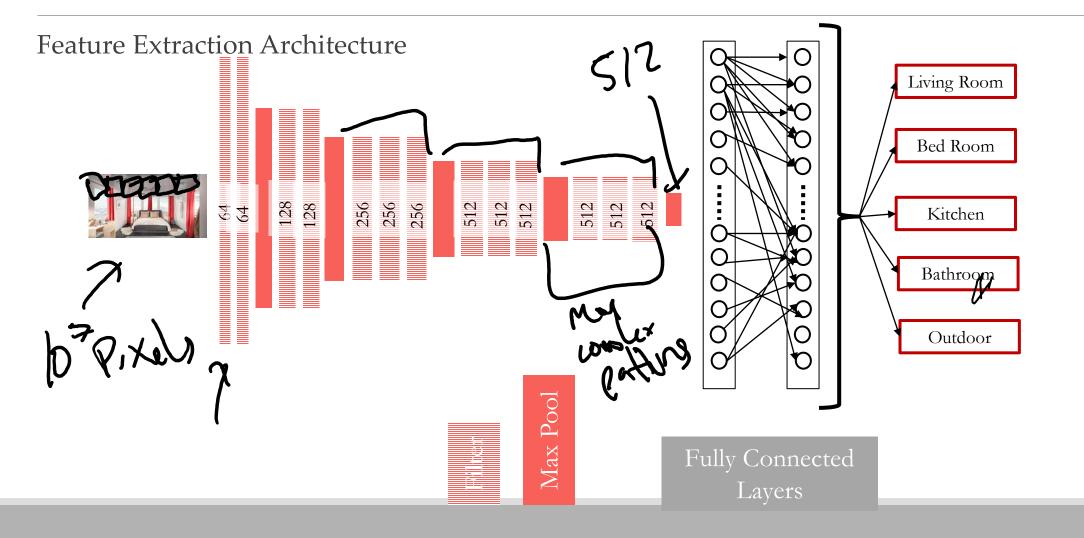
Pooling partitions the input image into a set of non-overlapping rectangles and, for each such sub-region, outputs the maximum value of the features in that region.



Convolutional Neural Network Feature Extraction Architecture



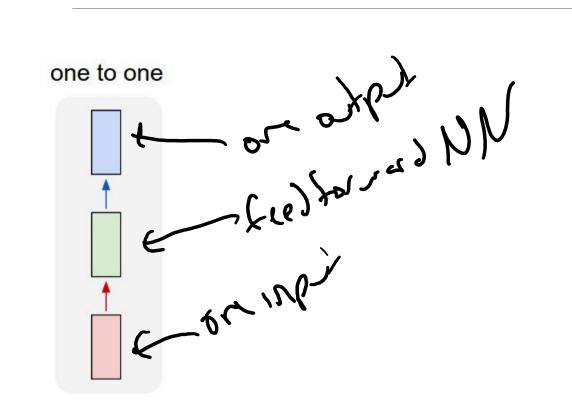
Convolutional Neural Network



Convolutional neural networks

- Preserve spatial locality
- Good for images + speech

- Preserve temporal locality Am SSIO
- Good for sequence to sequence translation



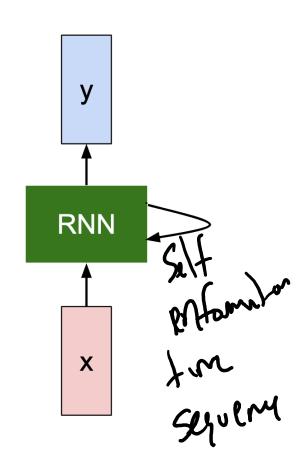
Sequent Recurrent Neural Networks

M1 72 73 many to many one to many one to one many to one C many to many $X_1 X_2 X_3$ X, X2 73

Recurrent Neural Networks (RNNs) learn temporal patterns

$$h_t = f_W(h_{t-1}, x_t)$$

- The RNN maintains some sort of "memory" of its current state
- The new state h_t is some function of the previous state and the input x

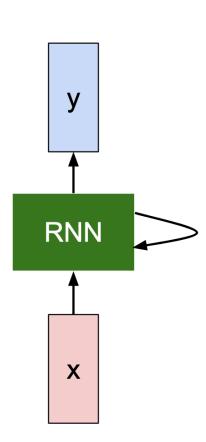


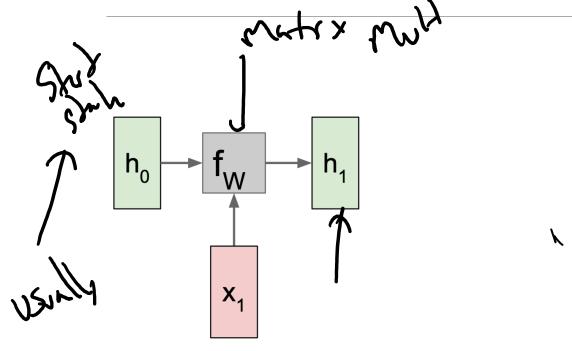
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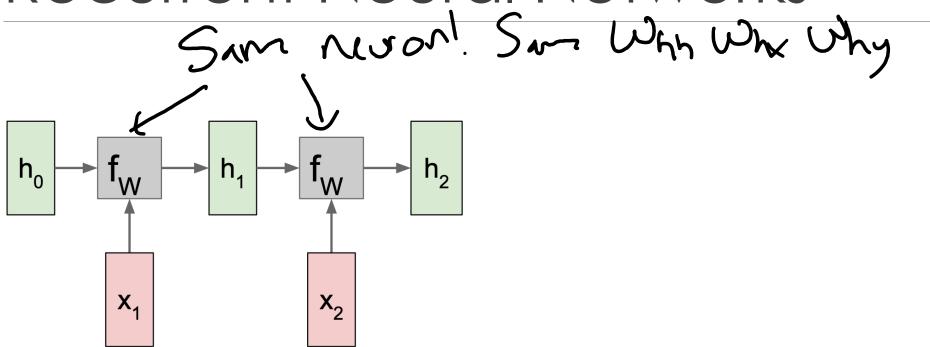
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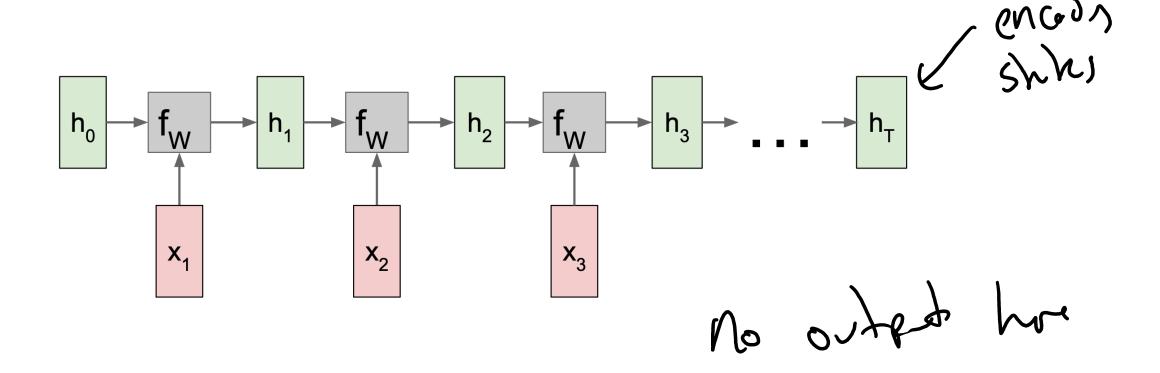
Commonly, we use the following $h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t)$ $y_t = W_{hy}h_t$ Where all W are learned matrices

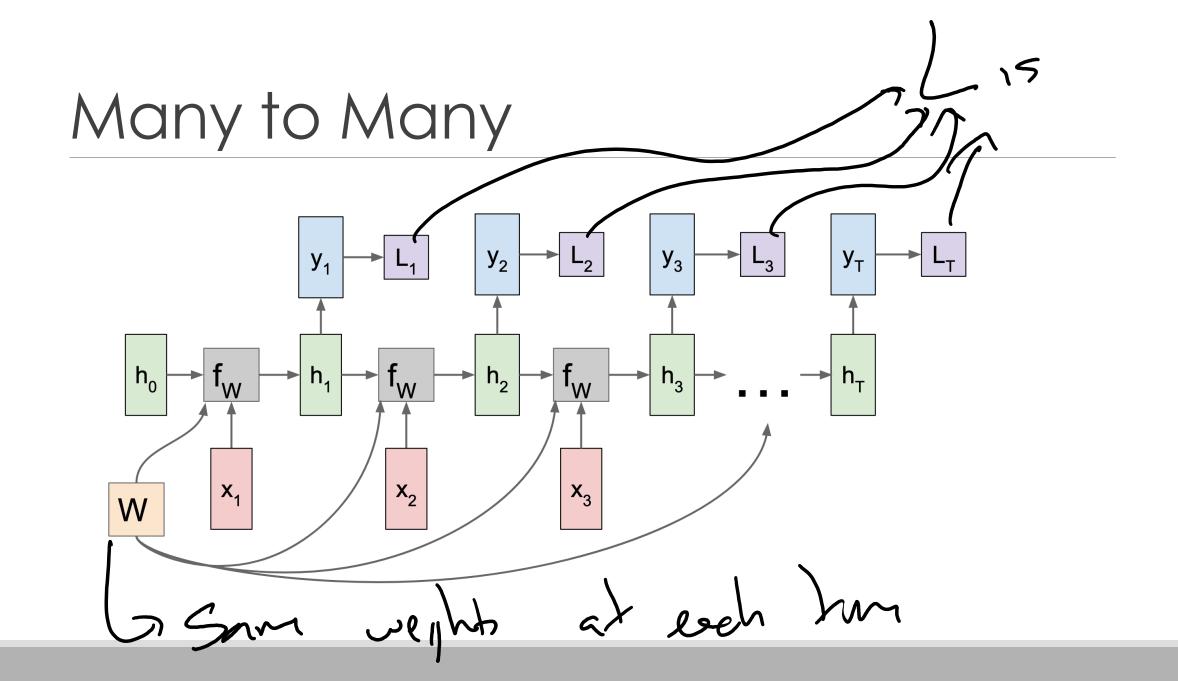
Where M_{t} are learned matrices

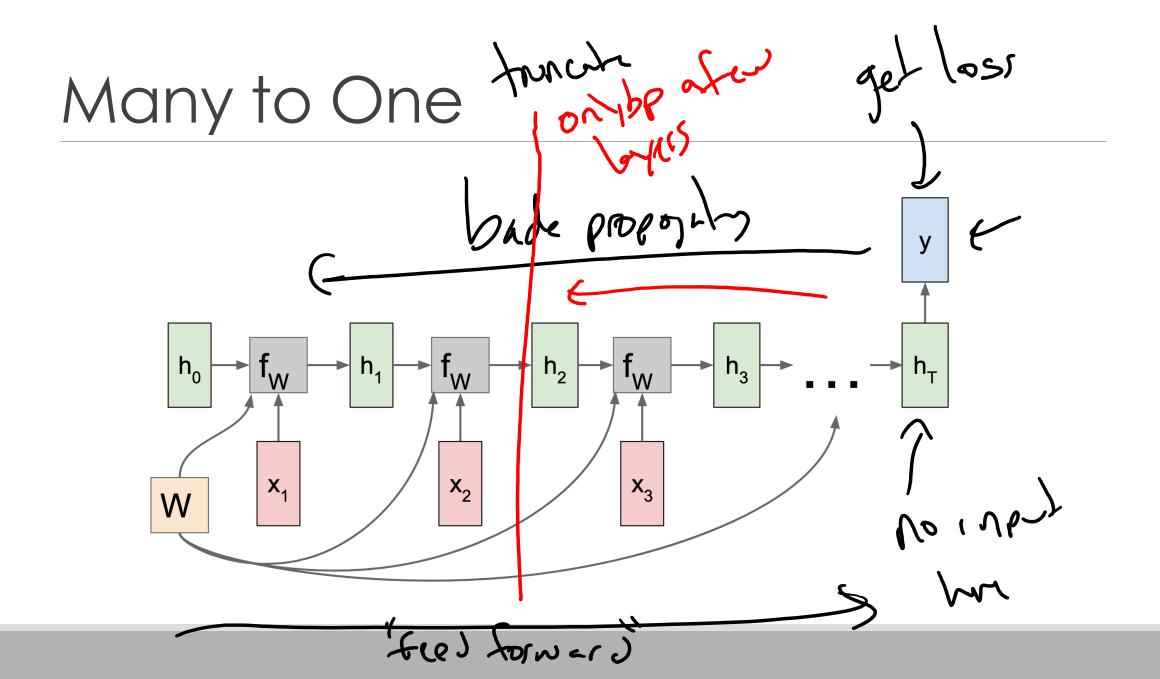




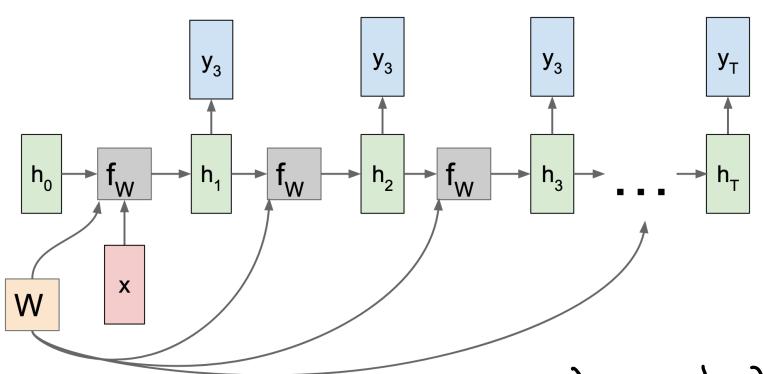








One to Many



go though all ponts to get loss

Usage

Good for time series data - Josha ma Segvente Sequenced data & different Size) for imply and outputs Gradient training

- Exploding gradient
- Vanishing gradient -
 - · LSTM -
 - GRU

[Salqdlum topicap to gadent dppm

Conclusion

Deep learning algorithms

- Structure —
- Purpose
- Training

Globs of well > ophrate

How do we extract relevant features?

- Time locality RNN
- Space locality CWV
- 。???

auto encore futro ANN

> post strau MAP MJE

Next Class

Ethical considerations

Exam discussion

Package Resources PyTorch

	Name	Languag e	Link	Note
7	Pylearn2	Python	http://deeplearning.net/software/pylearn2/	A machine learning library built on Theano
\dashv	Theano	Python	http://deeplearning.net/software/theano/	A python deep learning library
	Caffe	C++	http://caffe.berkeleyvision.org/	A deep learning framework by Berkeley
۸[Torch	Lua	http://torch.ch/	An open source machine learning framework
	Overfeat	Lua	http://cilvr.nyu.edu/doku.php?id=code:start	A convolutional network image processor
	Deeplearning 4j	Java	http://deeplearning4j.org/	A commercial grade deep learning library
	Word2vec	С	https://code.google.com/p/word2vec/	Word embedding framework
	GloVe	С	http://nlp.stanford.edu/projects/glove/	Word embedding framework
	Doc2vec	С	https://radimrehurek.com/gensim/models/do c2vec.html	Language model for paragraphs and documents
	StanfordNLP	Java	http://nlp.stanford.edu/	A deep learning-based NLP package
>	TensorFlow	Python	http://www.tensorflow.org	A deep learning based python library

