

CS 412

APRIL 17TH – MAXIMUM LIKELIHOOD

Maximum Likelihood Learning

Statistical learning

- Want to learn underlying (Gaussian) distributions

Estimating statistics (mean and variance)

Frequentist (MLE) vs. Bayesian (MAP) learning

Inferring distributions

Learning Gaussians from Data

Suppose you have $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, \sigma^2)$

But you don't know μ

MLE: For which μ is x_1, x_2, \dots, x_R most likely?

MAP: Which μ maximizes $p(\mu | x_1, x_2, \dots, x_R, \sigma^2)$?

Learning Gaussians from Data

Suppose you have $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, \sigma^2)$

But you don't know μ

Maximum Likelihood Estimator: For which μ is x_1, x_2, \dots, x_R most likely?

- Frequentist

Maximum A Posteriori: Which μ maximizes $p(\mu | x_1, x_2, \dots, x_R, \sigma^2)$?

- Bayesian

MLE for univariate Gaussian

Suppose you have $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, \sigma^2)$

But you don't know μ

MLE: For which μ is x_1, x_2, \dots, x_R most likely?

$$\mu^{mle} = \arg \max_{\mu} p(x_1, x_2, \dots, x_R \mid \mu, \sigma^2)$$

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$$= \arg \max_{\mu} \prod_{i=1}^R p(x_i \mid \mu, \sigma^2)$$

(by i.i.d)

$$= \arg \max_{\mu} \sum_{i=1}^R \log p(x_i \mid \mu, \sigma^2)$$

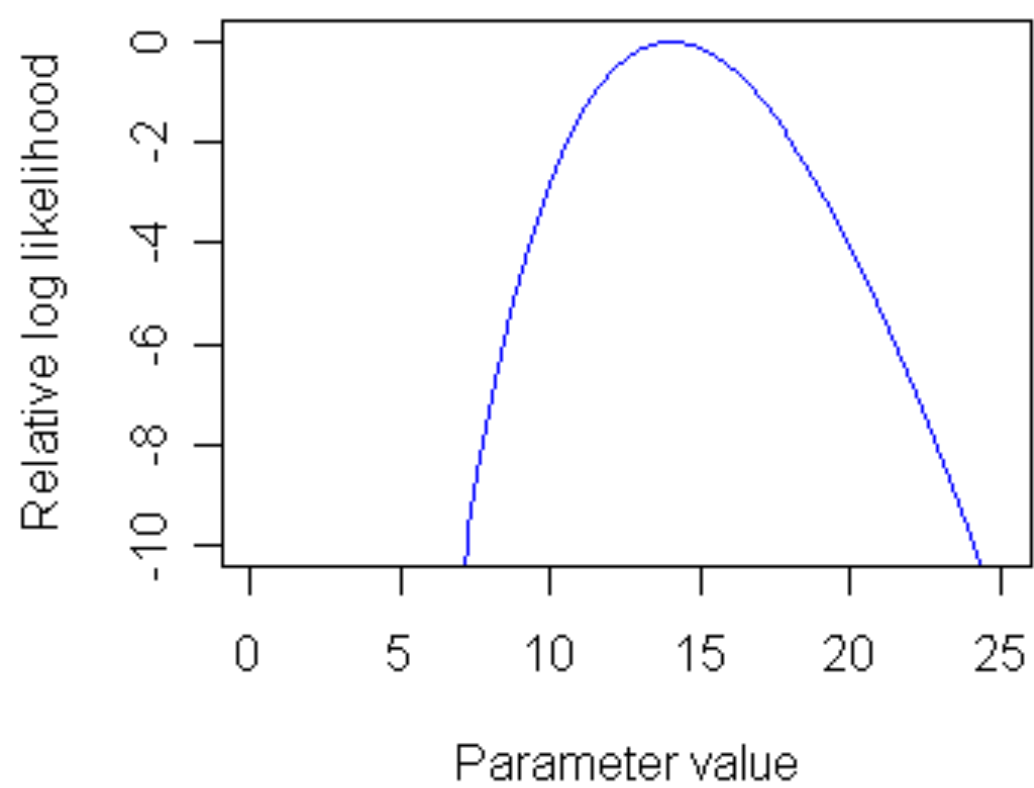
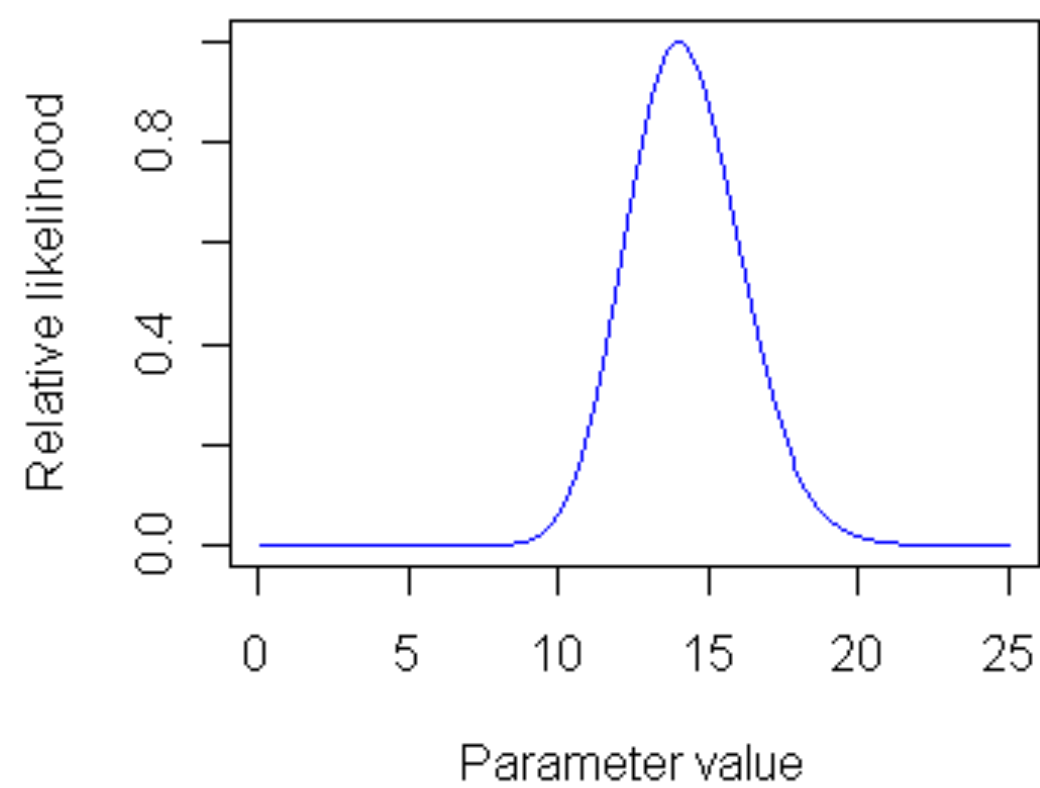
(monotonicity of log)

$$= \arg \max_{\mu} \frac{1}{\sqrt{2\pi} \sigma} \sum_{i=1}^R -\frac{(x_i - \mu)^2}{2\sigma^2}$$

(plug in formula for Gaussian)

$$\stackrel{\star}{=} \arg \min_{\mu} \sum_{i=1}^R (x_i - \mu)^2$$

(after simplification)



MLE

The best estimate for the mean of the population is the mean of the sample

$$\mu^{mle} = \frac{1}{R} \sum_{i=1}^R x_i$$

That matches our expectations!

We've already been using “maximum likelihood” with linear regression

MLE for univariate Gaussian

Suppose you have $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, \sigma^2)$

But you don't know μ or σ^2

MLE: For which $q = (\mu, \sigma^2)$ is x_1, x_2, \dots, x_R most likely?

$$\mu^{mle} = \frac{1}{R} \sum_{i=1}^R x_i$$

$$\sigma_{mle}^2 = \frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

Unbiased Estimators

An estimator of a parameter is unbiased if the expected value of the estimate is the same as the true value of the parameters.

If $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) N(\mu, \sigma^2)$ then

$$E[\mu^{mle}] = E\left[\frac{1}{R} \sum_{i=1}^R x_i\right] = \mu$$

μ^{mle} is unbiased

Biased Estimators

An estimator of a parameter is biased if the expected value of the estimate is different from the true value of the parameters.

If $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) N(\mu, \sigma^2)$ then

$$E[\sigma_{mle}^2] = E\left[\frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2\right] = E\left[\frac{1}{R} \left(\sum_{i=1}^R x_i - \frac{1}{R} \sum_{j=1}^R x_j\right)^2\right] \neq \sigma^2$$

σ_{mle}^2 is biased

MLE Variance Bias

If $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) N(\mu, \sigma^2)$ then

$$E[\sigma_{mle}^2] = E\left[\frac{1}{R}\left(\sum_{i=1}^R x_i - \frac{1}{R}\sum_{j=1}^R x_j\right)^2\right] = \left(1 - \frac{1}{R}\right)\sigma^2 \neq \sigma^2$$

Intuition check: consider the case of $R=1$

Why should our guts expect that σ_{mle}^2 would be an underestimate of true σ^2 ?

Unbiased estimate of Variance

If $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) N(\mu, \sigma^2)$ then

$$E[\sigma_{mle}^2] = E\left[\frac{1}{R}\left(\sum_{i=1}^R x_i - \frac{1}{R}\sum_{j=1}^R x_j\right)^2\right] = \left(1 - \frac{1}{R}\right)\sigma^2 \neq \sigma^2$$

So define $\sigma_{\text{unbiased}}^2 = \frac{\sigma_{mle}^2}{\left(1 - \frac{1}{R}\right)}$ So $E[\sigma_{\text{unbiased}}^2] = \sigma^2$

Unbiased estimate of Variance

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$$\sigma_{\text{unbiased}}^2 = \frac{1}{R-1} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

Unbiased estimation

Which is best?

- It depends on the task
- And doesn't make much difference once $R \rightarrow \text{large}$

$$\sigma_{mle}^2 = \frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

$$\sigma_{\text{unbiased}}^2 = \frac{1}{R-1} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

Unbiased estimation

- Assume $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, \sigma^2)$
- Suppose we had these estimators for the mean

$$\mu^{\text{suboptimal}} = \frac{1}{R + 7\sqrt{R}} \sum_{i=1}^R x_i$$

$$\mu^{\text{crap}} = x_1$$

Are either of these unbiased?

Will either of them asymptote to the correct value as R gets large?

Which is more useful?

MLE for m-dimensional Gaussian

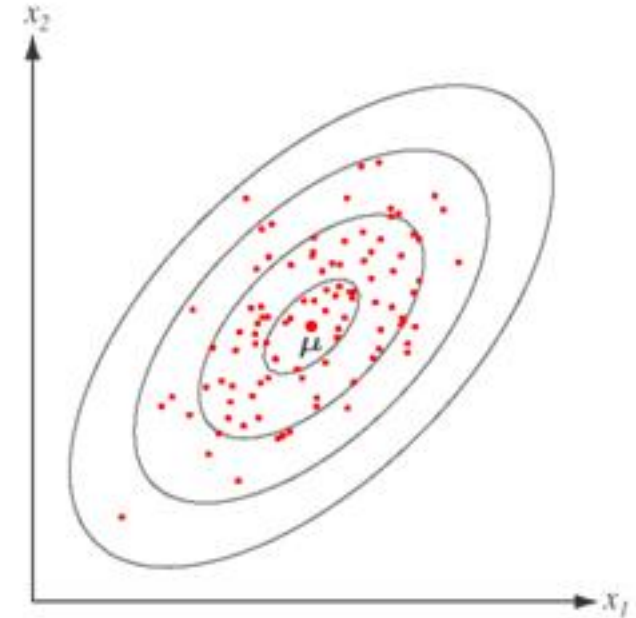
Suppose you have $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, S)$

But you don't know μ or S

MLE: For which $q = (\mu, S)$ is x_1, x_2, \dots, x_R most likely?

$$\boldsymbol{\mu}^{mle} = \frac{1}{R} \sum_{k=1}^R \mathbf{x}_k$$

$$\boldsymbol{\Sigma}^{mle} = \frac{1}{R} \sum_{k=1}^R (\mathbf{x}_k - \boldsymbol{\mu}^{mle})(\mathbf{x}_k - \boldsymbol{\mu}^{mle})^T$$



MLE for m-dimensional Gaussian

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$$\boldsymbol{\mu}^{mle} = \frac{1}{R} \sum_{k=1}^R \mathbf{x}_k$$

$$\mu_i^{mle} = \frac{1}{R} \sum_{k=1}^R x_{ki}$$

$$\boldsymbol{\Sigma}^{mle} = \frac{1}{R} \sum_{k=1}^R (\mathbf{x}_k - \boldsymbol{\mu}^{mle})(\mathbf{x}_k - \boldsymbol{\mu}^{mle})^T$$

Where $1 \leq i \leq m$

And x_{ki} is value of the i^{th} component of \mathbf{x}_k
(the i^{th} attribute of the k^{th} record)

And μ_i^{mle} is the i^{th} component of $\boldsymbol{\mu}^{mle}$

MLE for m-dimensional Gaussian

Suppose you have $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) N(\mu, S)$

But you don't know μ or S

MLE: For which $q = (\mu, S)$ is x_1, x_2, \dots, x_R most likely?

$$\boldsymbol{\mu}^{mle} = \frac{1}{R} \sum_{k=1}^R \mathbf{x}_k \qquad \mu_i^{mle} = \frac{1}{R} \sum_{k=1}^R x_{ki}$$

$$\boldsymbol{\Sigma}^{mle} = \frac{1}{R} \sum_{k=1}^R (\mathbf{x}_k - \boldsymbol{\mu}^{mle})(\mathbf{x}_k - \boldsymbol{\mu}^{mle})^T$$

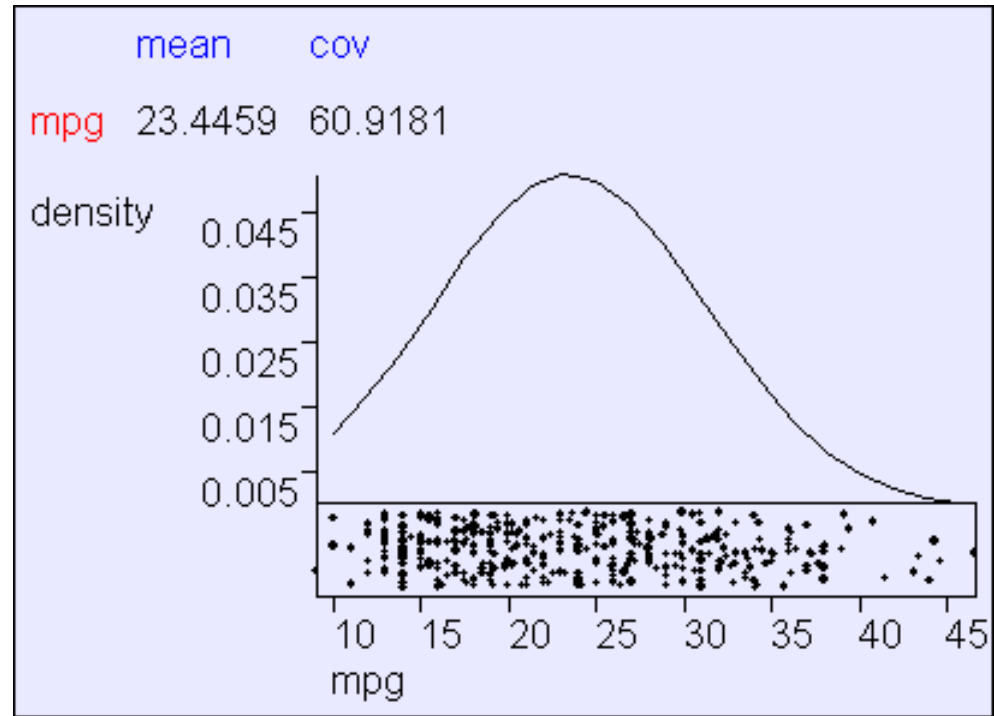
Where $1 \leq i \leq m, 1 \leq j \leq m$

And x_{ki} is value of the i^{th} component of \mathbf{x}_k (the i^{th} attribute of the k^{th} record)

And σ_{ij}^{mle} is the $(i,j)^{\text{th}}$ component of $\boldsymbol{\Sigma}^{mle}$

$$\sigma_{ij}^{mle} = \frac{1}{R} \sum_{k=1}^R (x_{ki} - \mu_i^{mle})(x_{kj} - \mu_j^{mle})$$

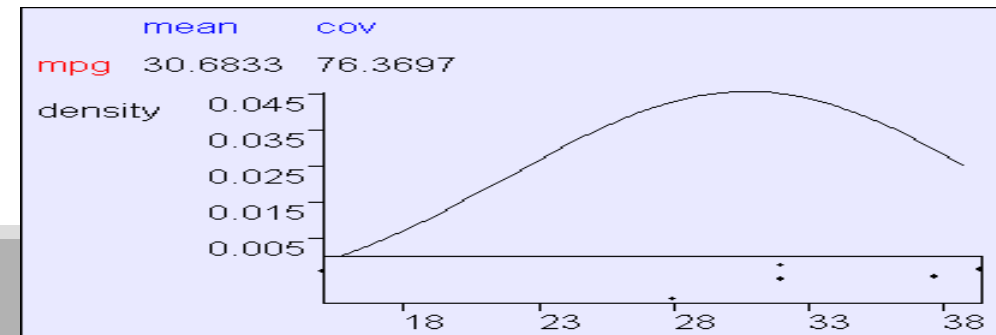
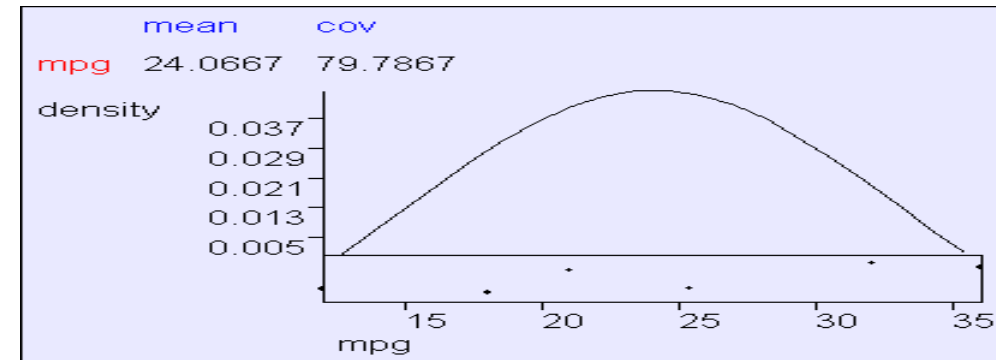
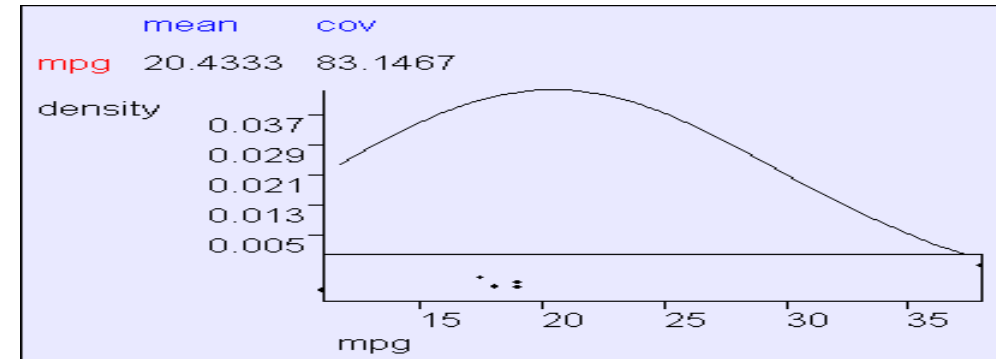
Gaussian MLE in action



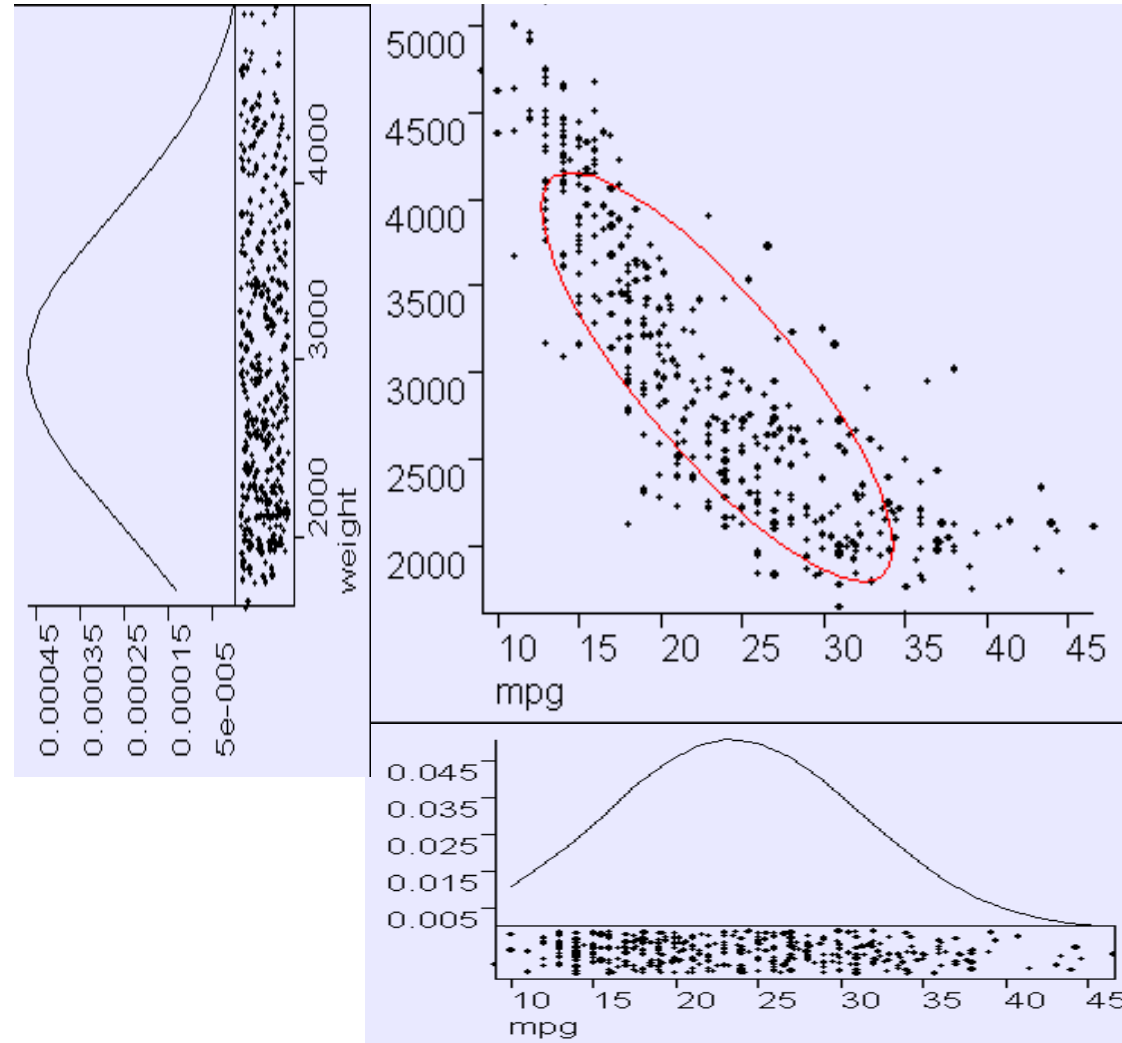
Data-starved Gaussian MLE

Using three subsets of MPG.

Each subset has 6 randomly-chosen cars.



Bivariate MLE in action



Multivariate Data

Multiple measurements (sensors)

d inputs/features/attributes: d-variate

N instances/observations/examples

$$\mathbf{X} = \begin{bmatrix} X_1^1 & X_2^1 & \cdots & X_d^1 \\ X_1^2 & X_2^2 & \cdots & X_d^2 \\ \vdots & & & \\ X_1^N & X_2^N & \cdots & X_d^N \end{bmatrix}$$

Multivariate Parameters

$$\Sigma \equiv \text{Cov}(\mathbf{X}) = E[(\mathbf{X} - \mu)(\mathbf{X} - \mu)^T] = \begin{bmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1d} \\ \sigma_{21} & \sigma_2^2 & \cdots & \sigma_{2d} \\ \vdots & & & \\ \sigma_{d1} & \sigma_{d2} & \cdots & \sigma_d^2 \end{bmatrix}$$

Mean : $E[\mathbf{x}] = \mu = [\mu_1, \dots, \mu_d]^T$

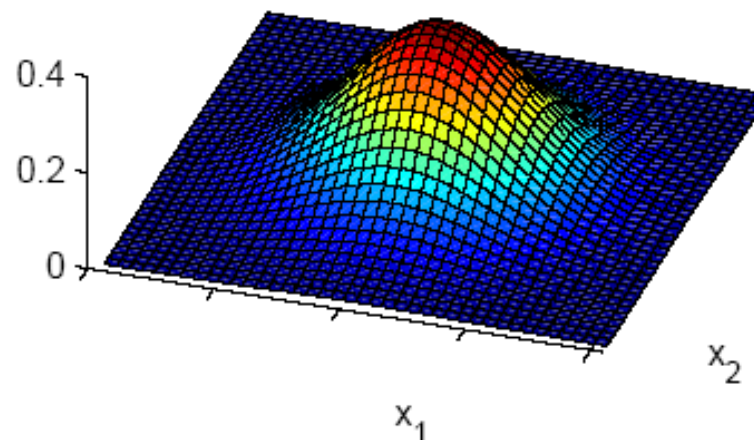
Covariance : $\sigma_{ij} \equiv \text{Cov}(X_i, X_j)$

Correlation : $\text{Corr}(X_i, X_j) \equiv \rho_{ij} = \frac{\sigma_{ij}}{\sigma_i \sigma_j}$

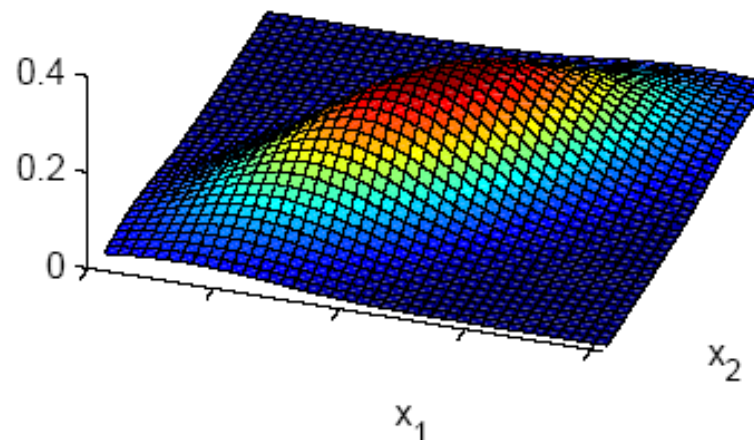
Bivariate Normal

How do changes in our underlying expectations of the generating models impact our decisions to classify?

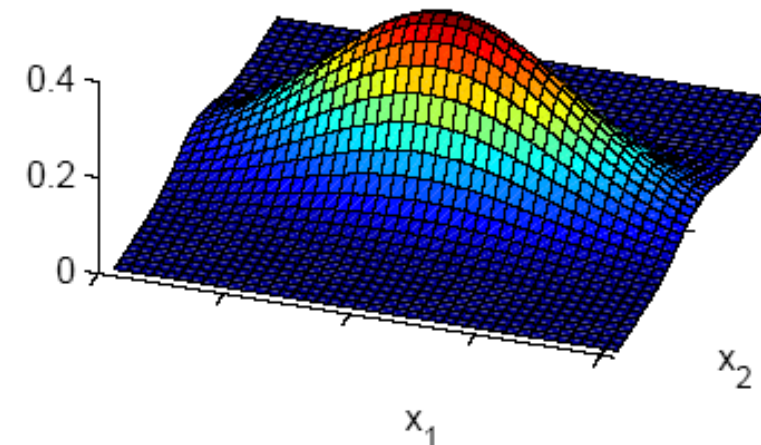
$$\text{Cov}(x_1, x_2) = 0, \text{Var}(x_1) = \text{Var}(x_2)$$



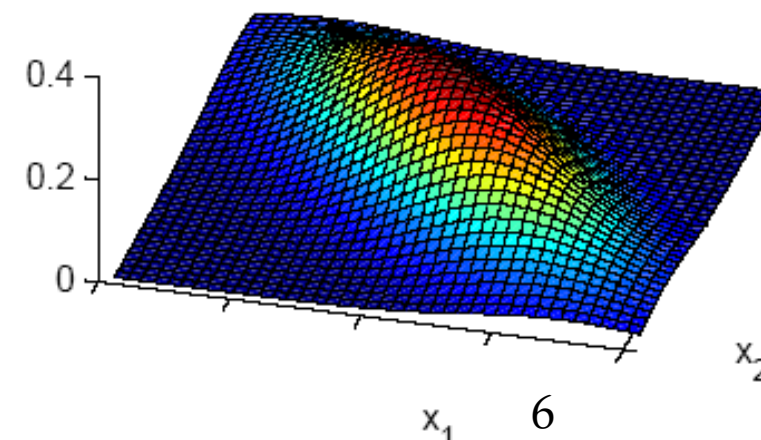
$$\text{Cov}(x_1, x_2) > 0$$



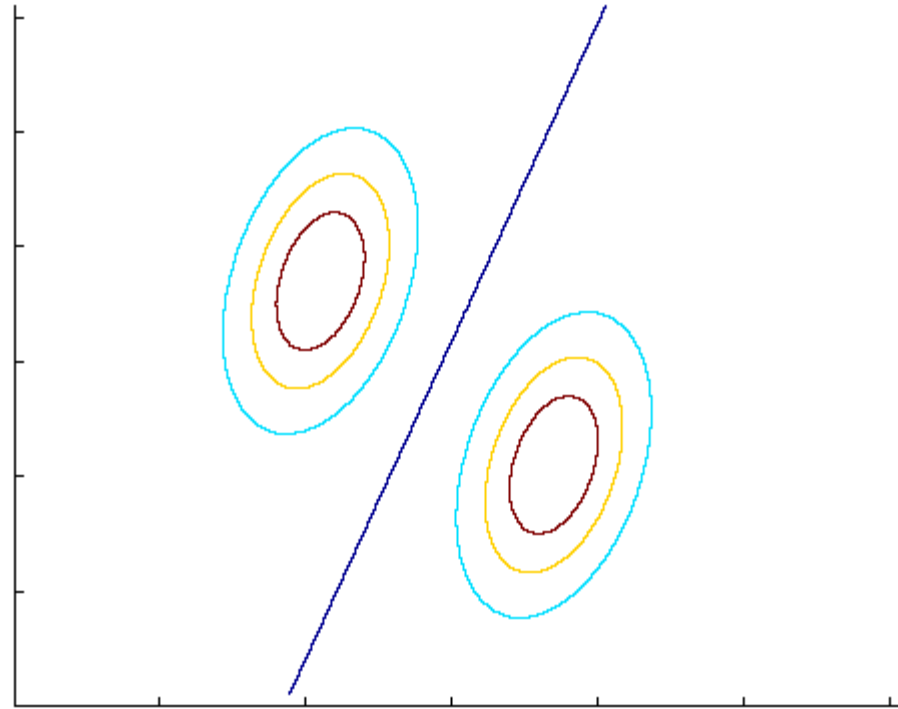
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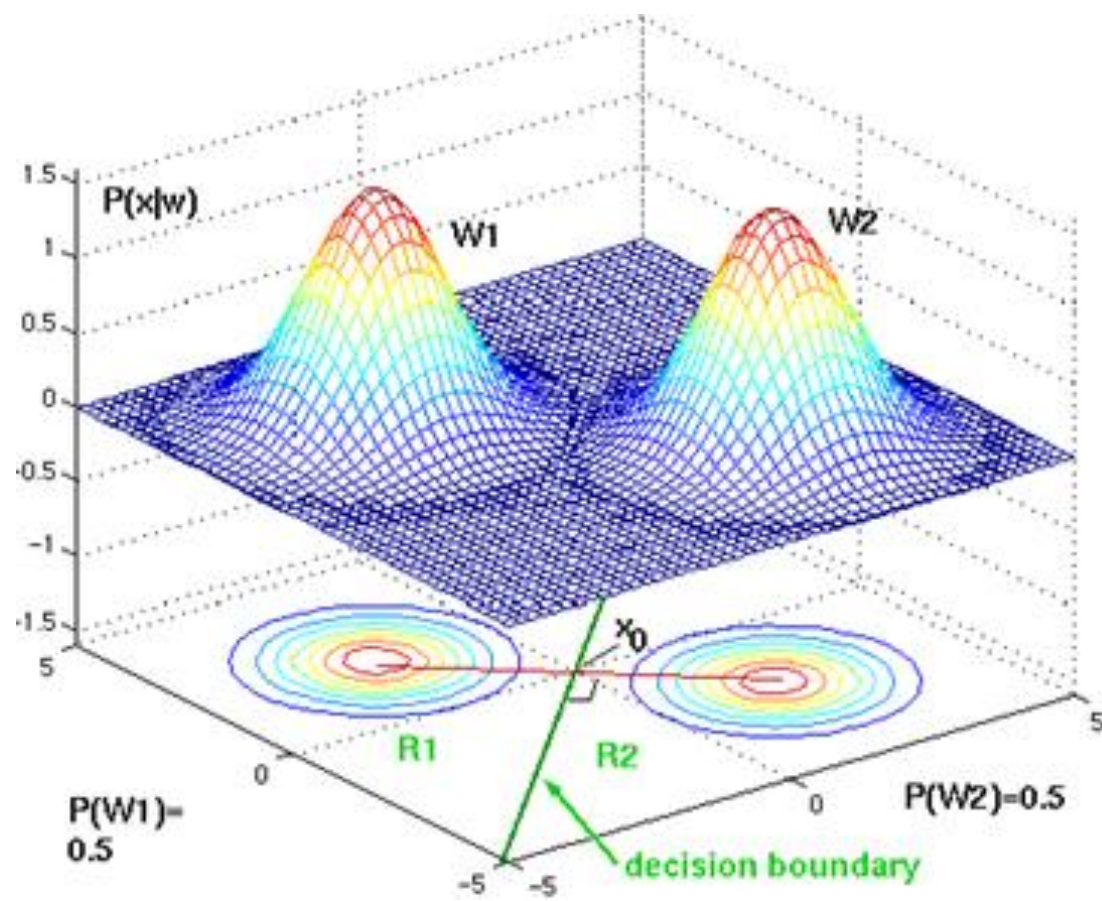
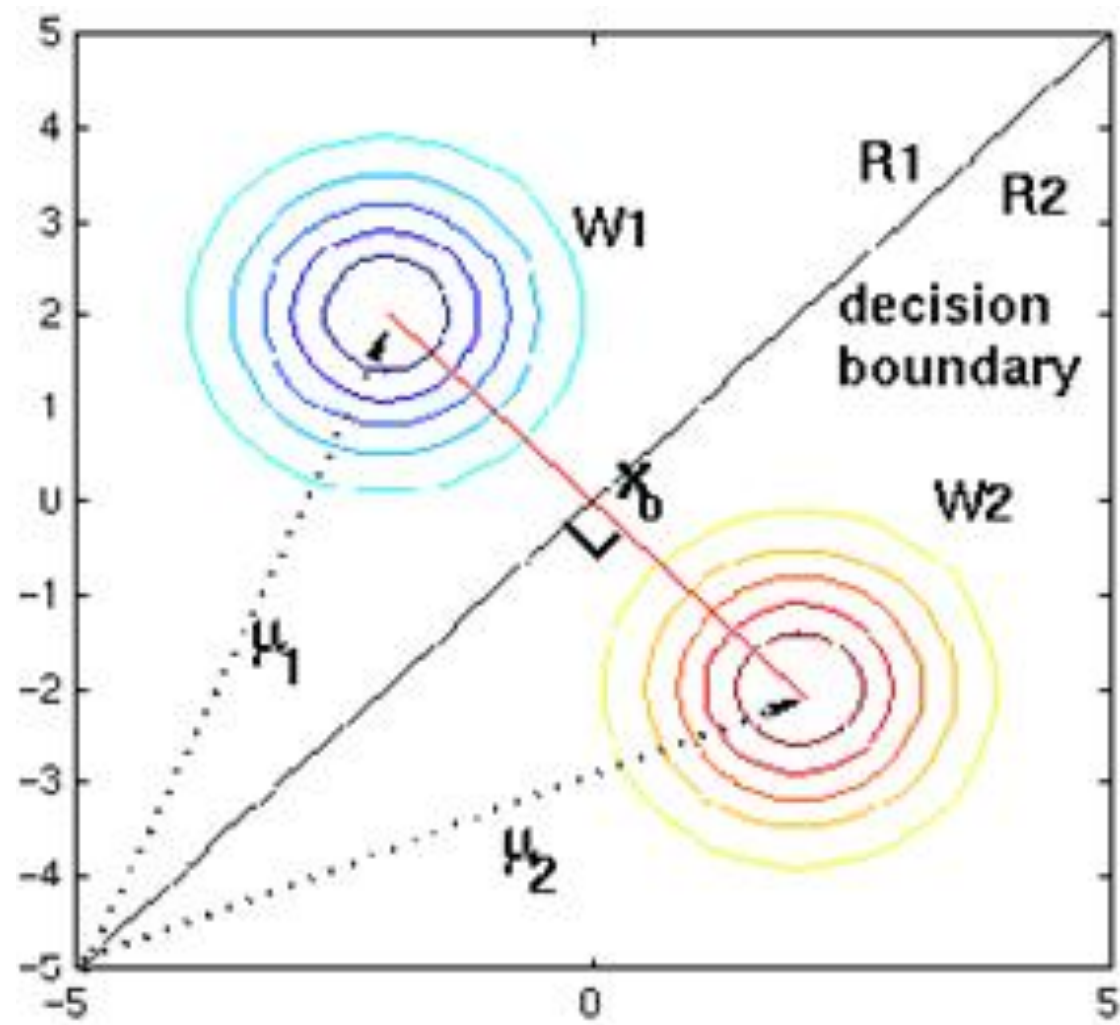


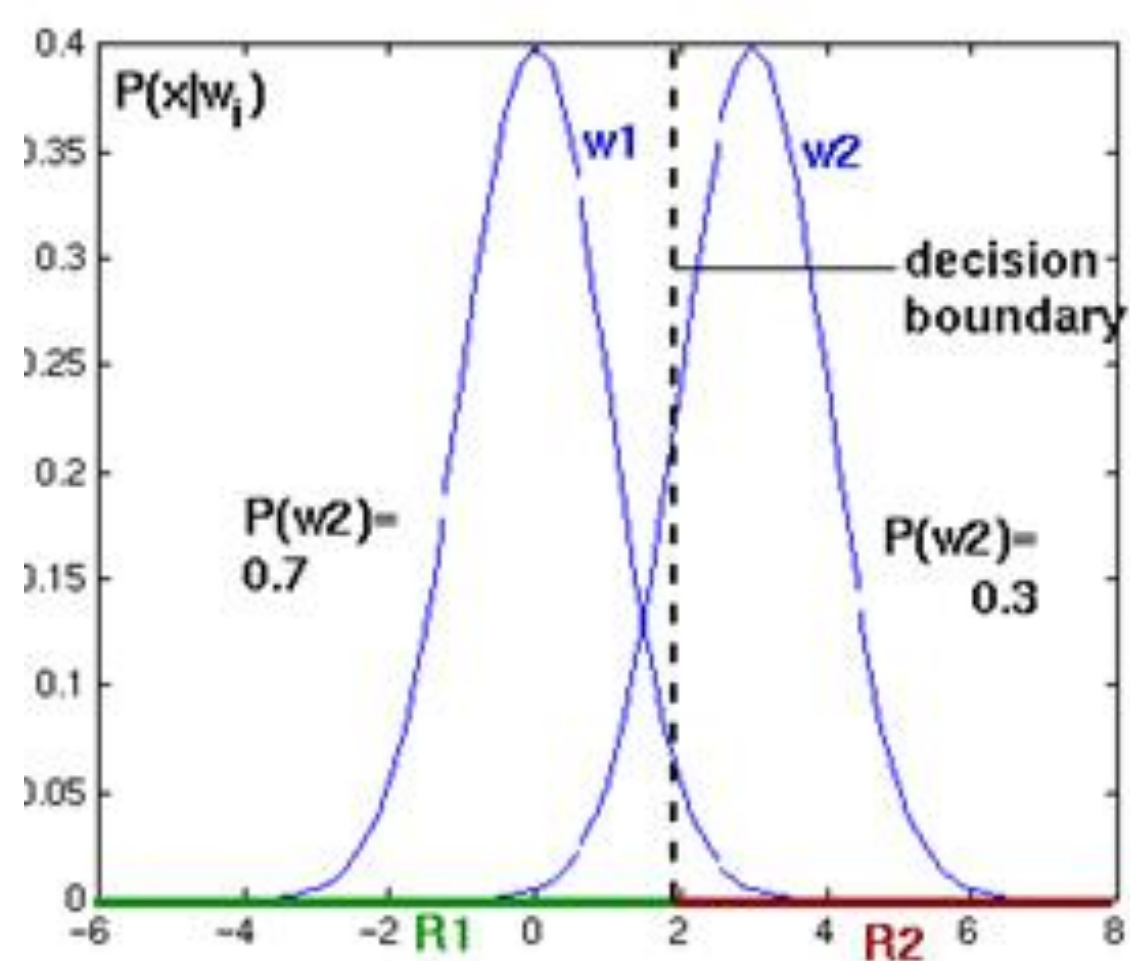
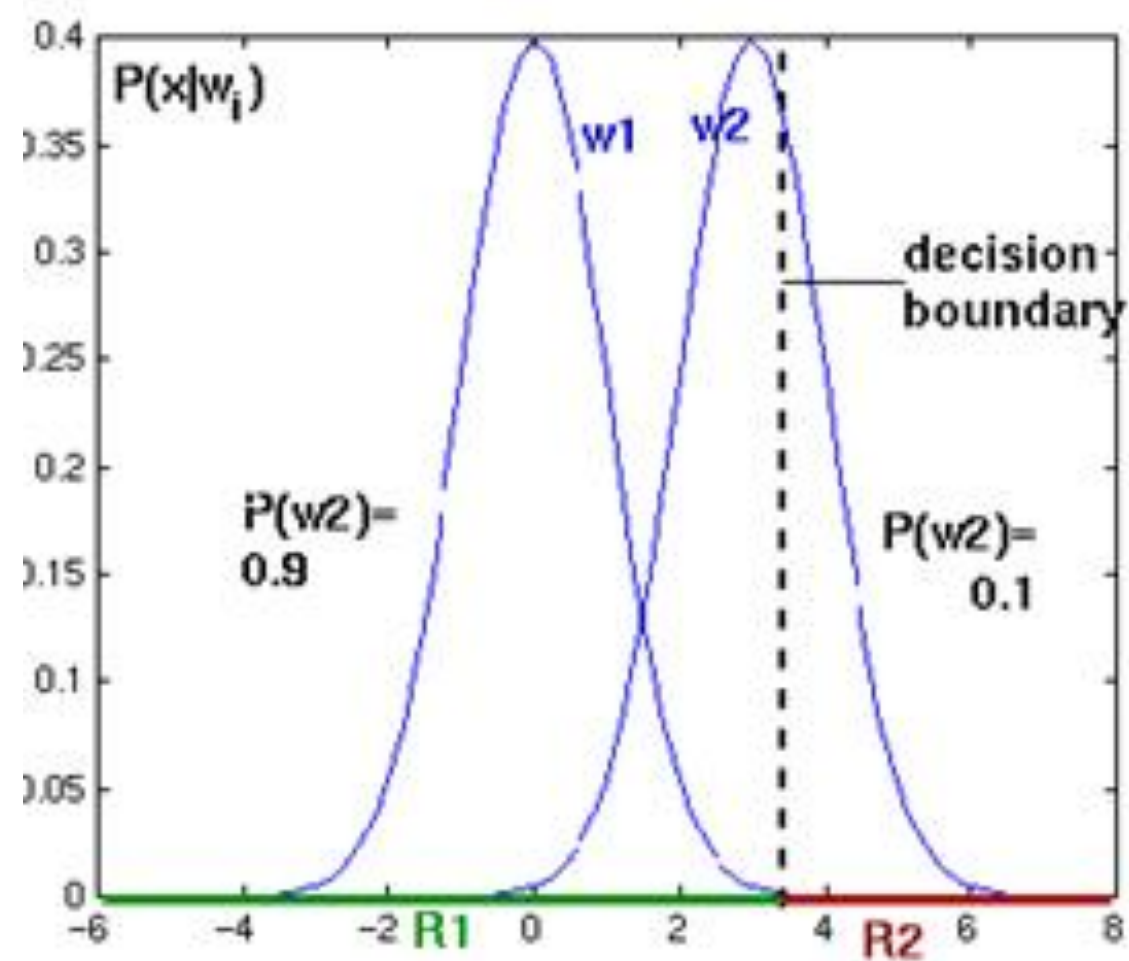
$$\text{Cov}(x_1, x_2) < 0$$



Common Covariance







Bayesian estimators

It seems much more natural to attempt to make statements about which parameter values are likely given the data you have collected

To put this on a rigorous probabilistic footing we want to make statements about the probability (density) of any particular parameter value given our data

Bayes theorem:

The diagram shows the equation for Bayes' theorem with four labels and arrows pointing to the corresponding parts of the formula:

- Posterior** points to $P(\theta | D)$
- Prior** points to $P(\theta)$
- Likelihood** points to $P(D | \theta)$
- Normalising constant** points to $P(D)$

$$P(\theta | D) = \frac{P(\theta)P(D | \theta)}{P(D)}$$

Bayes estimators

The single most important conceptual difference between Bayesian statistics and frequentist statistics is the notion that the parameters you are interested in are themselves random variables

This notion is encapsulated in the use of a subjective prior for your parameters

Remember that to construct a confidence interval we have to define the set of possible parameter values

A prior does the same thing, but also gives a weight to different values

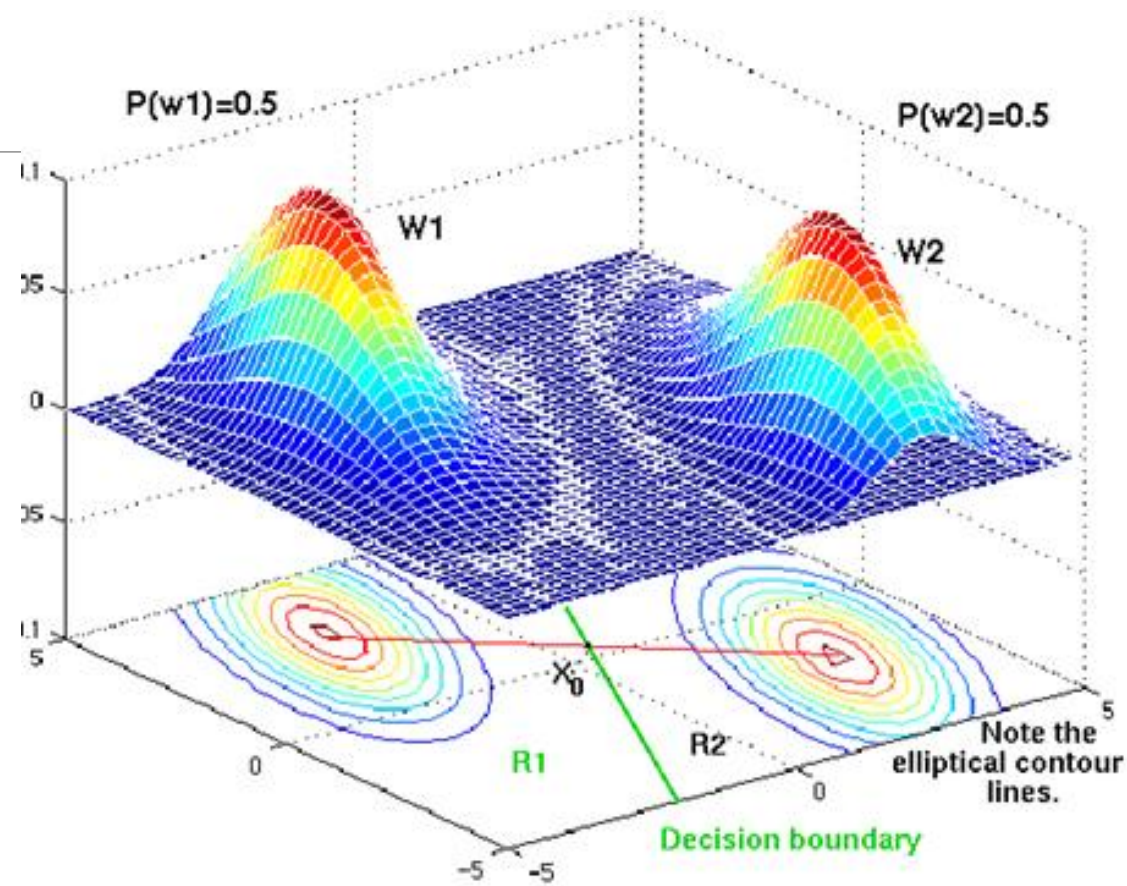
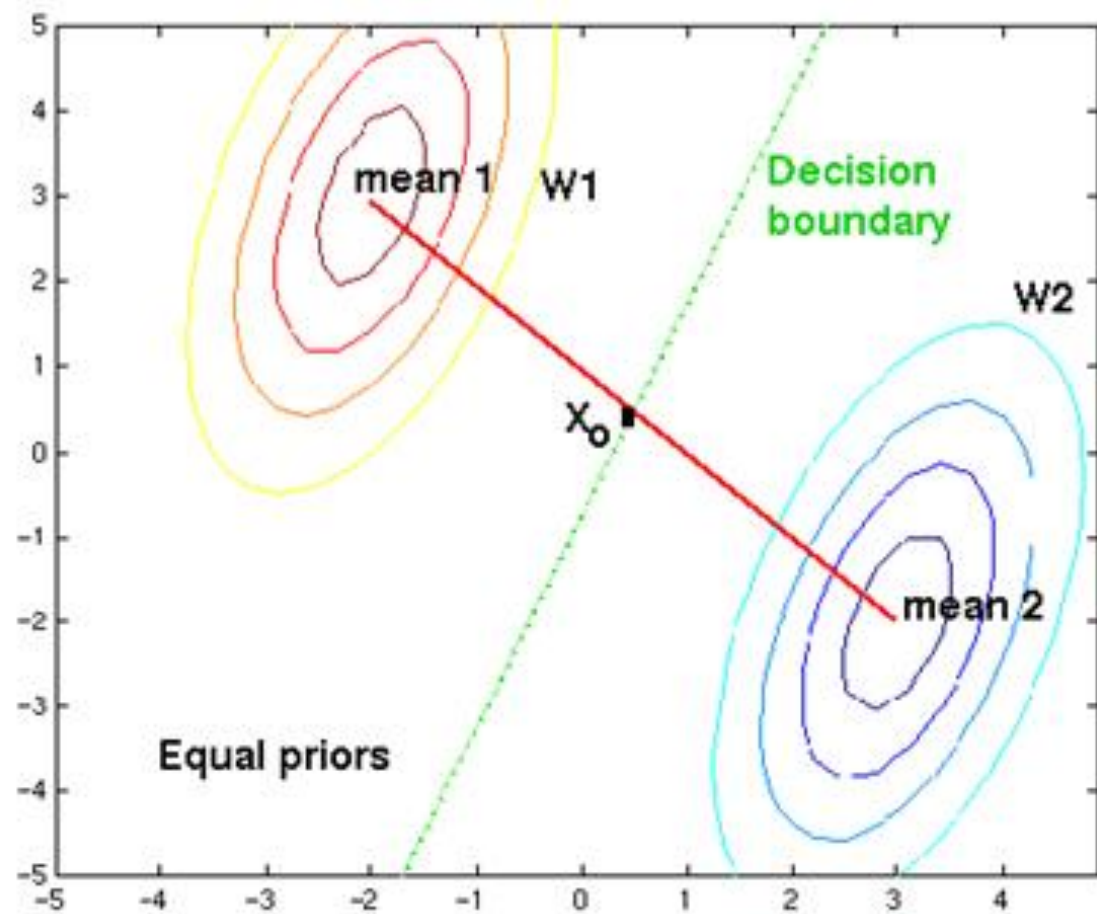
Example: Coin Tossing

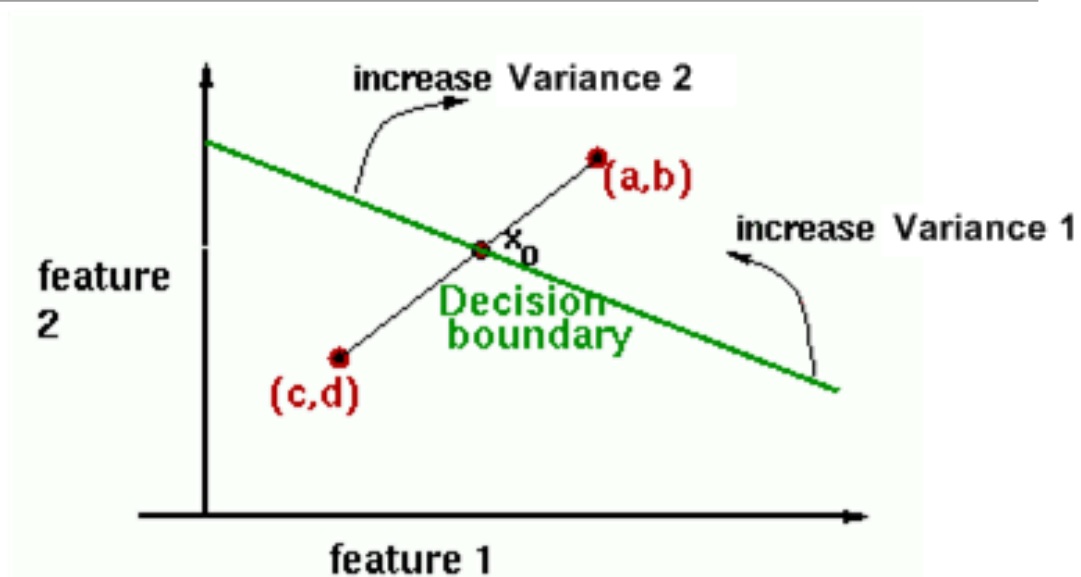
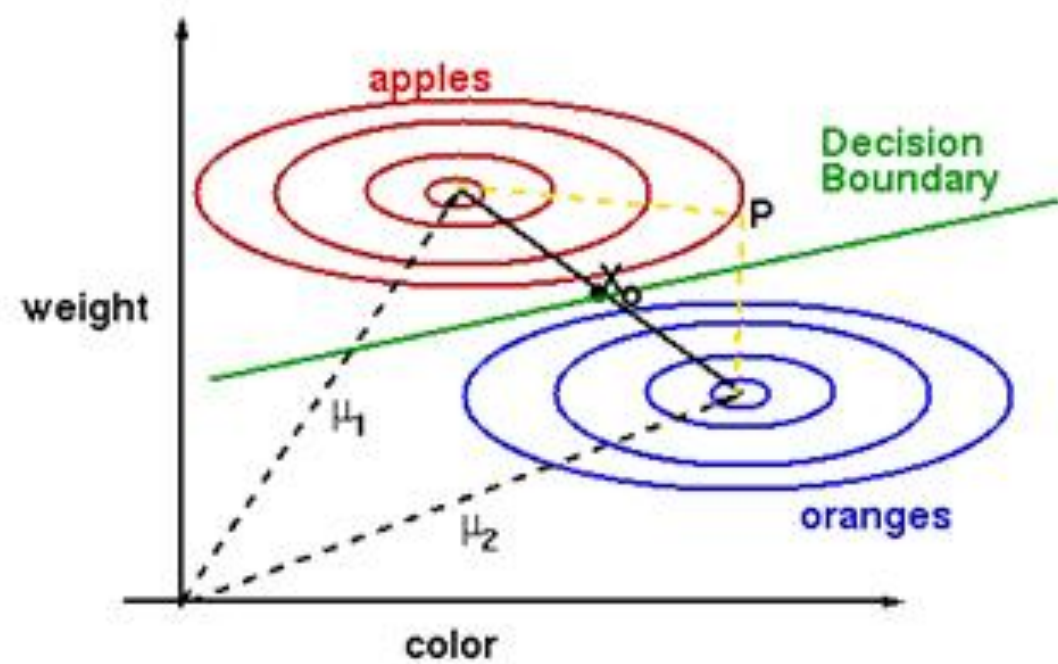
I toss a coin twice and observe two heads

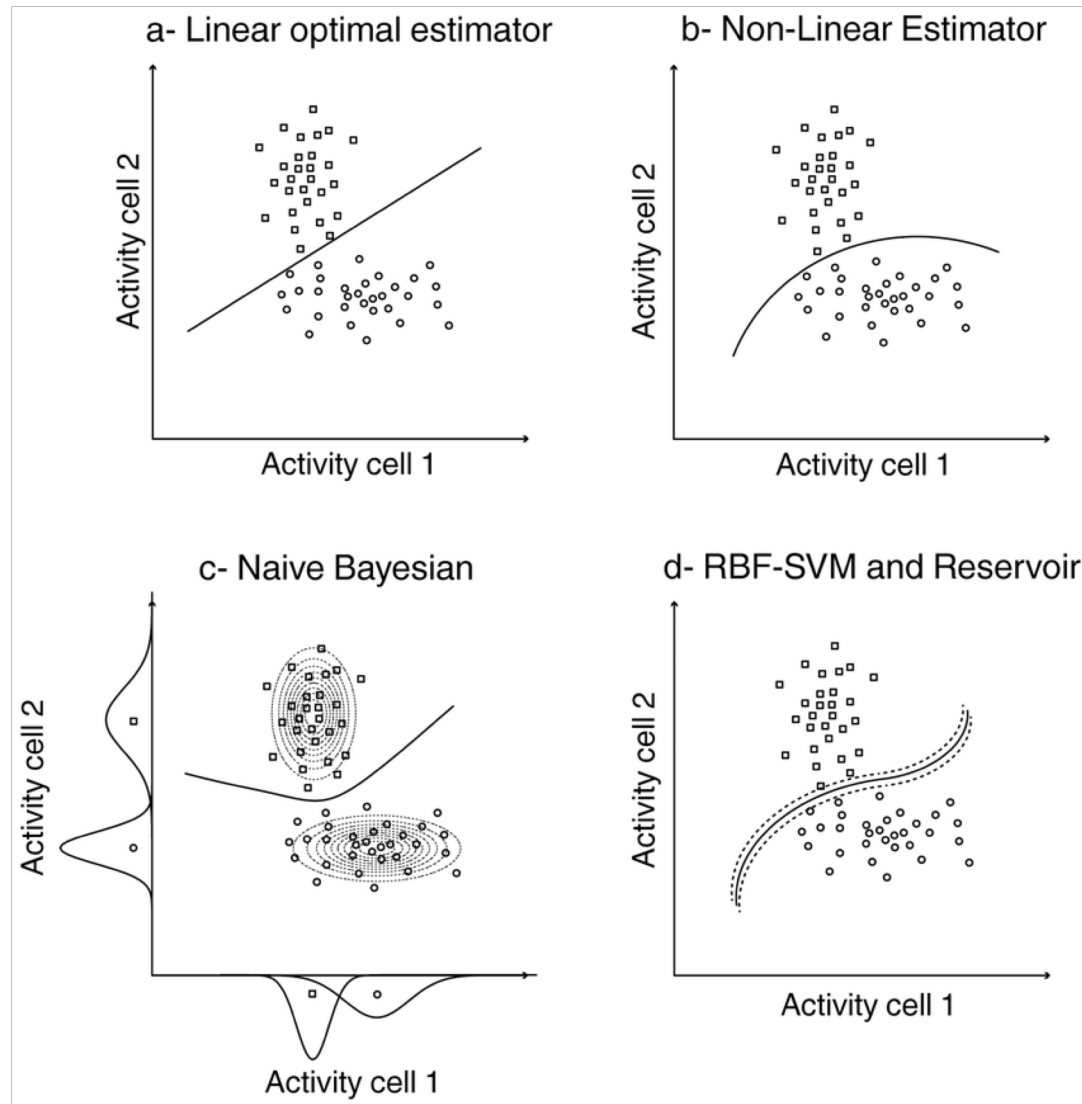
I want to perform inference about the probability of obtaining a head on a single throw for the coin in question

The point estimate/MLE for the probability is 1.0 – yet I have a very strong prior belief that the answer is 0.5

Bayesian statistics forces the researcher to be explicit about prior beliefs but, in return, can be very specific about what information has been gained by performing the experiment







MLP vs MAP

We've done maximum likelihood before
(Linear Regression)

- Constraints?
- Gaussian distributed data

We've done maximum a posteriori before
(Naïve Bayes)

- Constraints?
 - All features are independent (necessary computationally)
 - No cross correlation
- What if we calculate it exactly?
 - Bayesian estimator

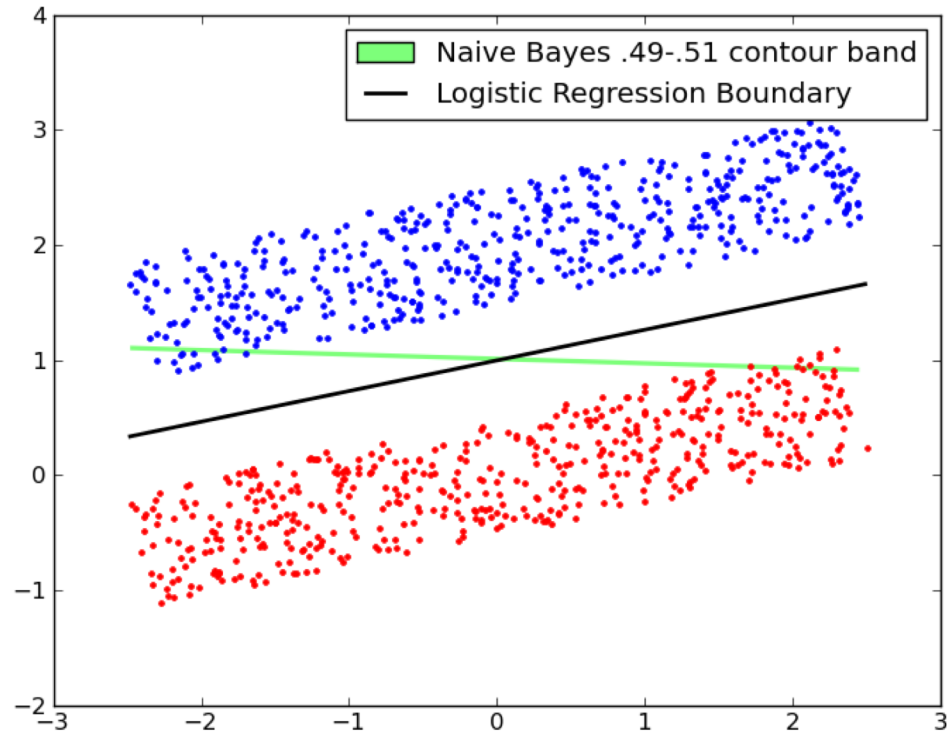
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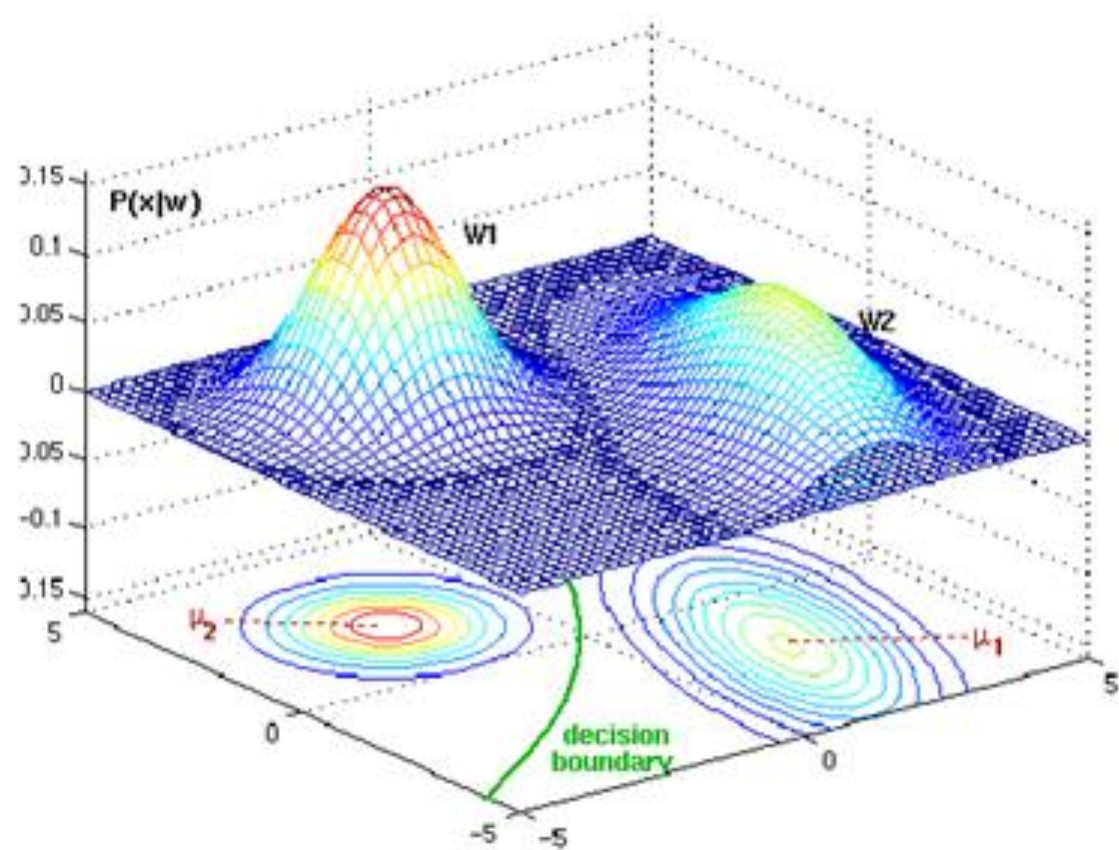
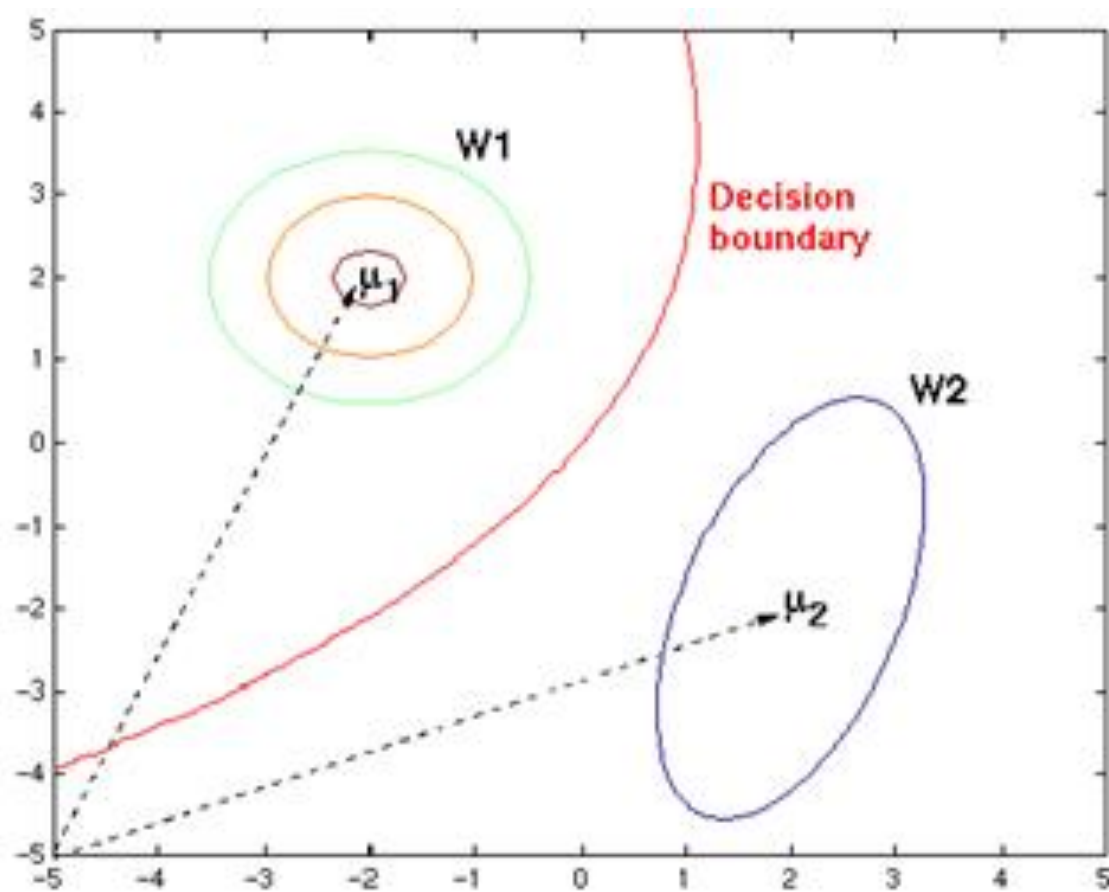
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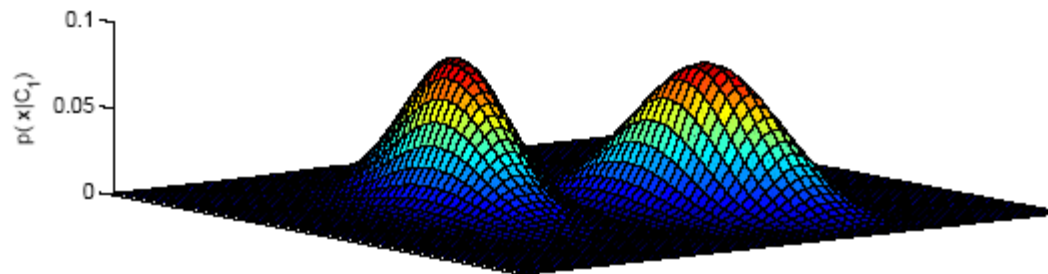
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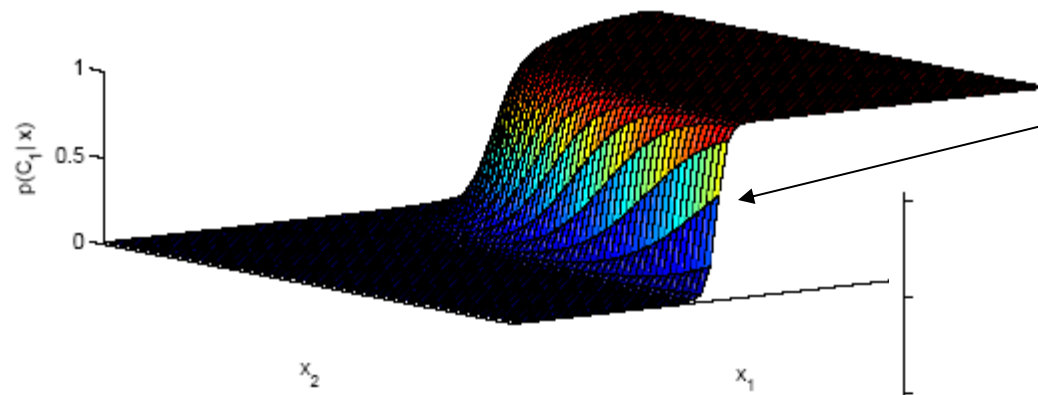
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likelihoods



posterior for C_1

discriminant:
 $P(C_1|\mathbf{x}) = 0.5$

