CS 412

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MAR 3<sup>RD</sup> – NEURAL NETWORKS HTF – CHAPTER 11

### A Note about Python Classes

class NeuralNetwork:

def \_init\_(self,x=[[]],y=[],numLayers=2,numNodes=2,eta=0.001,maxIter=10000):

To create a new NeuralNetwork object call NeuralNetwork(x,y)

This will create an object for which all other parameters are "defaults".

If a user does not specify the numLayers, then it will be 2

This prevents the coder from needing to build multiple constructors

#### A Note about Python Classes

```
class NeuralNetwork:

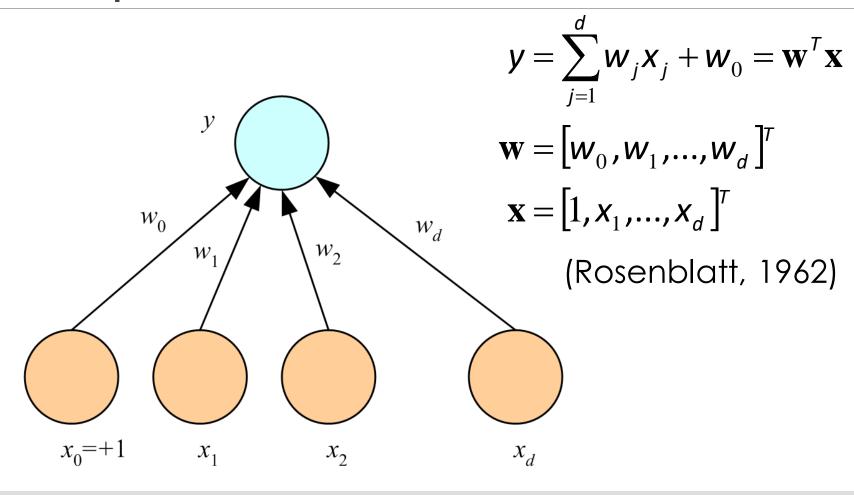
DON'T PUT VARIABLES HERE --- they'll be static for all objects

def _init_(self,x=[[]],y=[],numLayers=2,numNodes=2,eta=0.001,maxIter=10000):

def yourfunction(self,input="default"):
    self.attribute=input // this is how you give a specific object an attribute
```

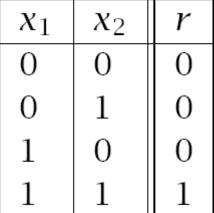
In the test code, I will only create one instance of the NeuralNetwork, so static variables won't impact the solution, but this is a property of python that you should know

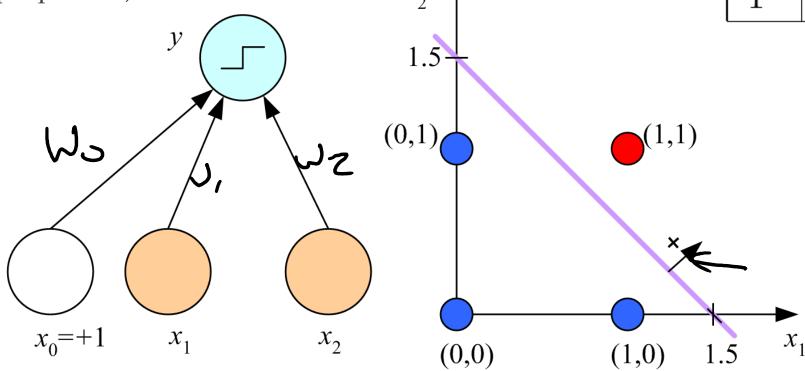
You will, however, likely need to add your own helper functions and attributes, and this will be helpful



#### Learning Boolean AND

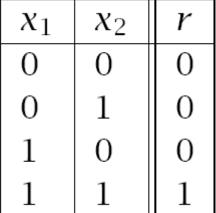
What are the weights for this perceptron? (purple line)

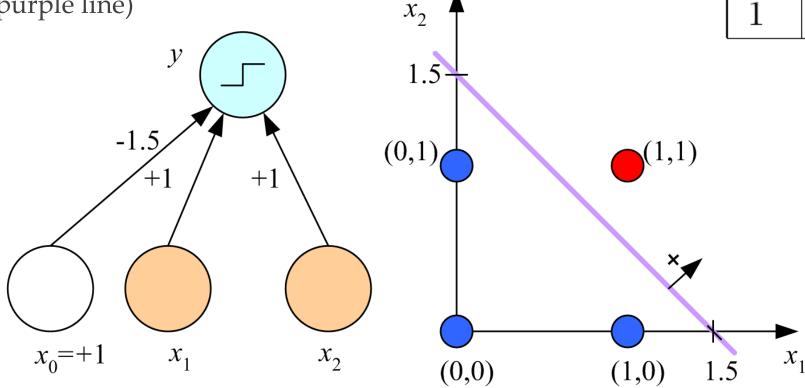




### Learning Boolean AND

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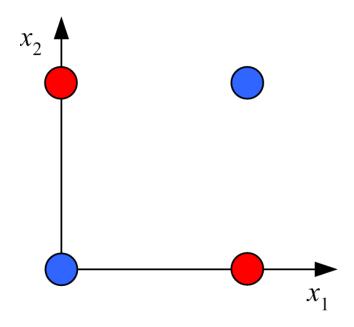


#### XOR

| $x_1$ | <i>x</i> <sub>2</sub> | r |
|-------|-----------------------|---|
| 0     | 0                     | 0 |
| 0     | 1                     | 1 |
| 1     | 0                     | 1 |
| 1     | 1                     | 0 |

No  $w_0$ ,  $w_1$ ,  $w_2$  satisfy:

$$w_0 \le 0$$
  
 $w_2 + w_0 > 0$   
 $w_1 + w_2 + w_0 > 0$   
 $w_1 + w_2 + w_0 \le 0$ 



What is the problem with the simple perceptron?

• It can't model non-linear data

How do we fix this?

- SVM fixed this by using the kernel methods
- Can the perceptron? Yes, but that's not what the neural network does

What is the problem with the simple perceptron?

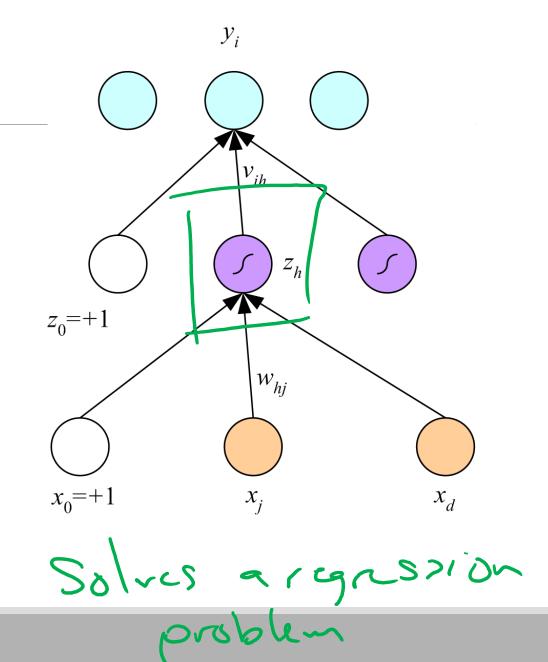
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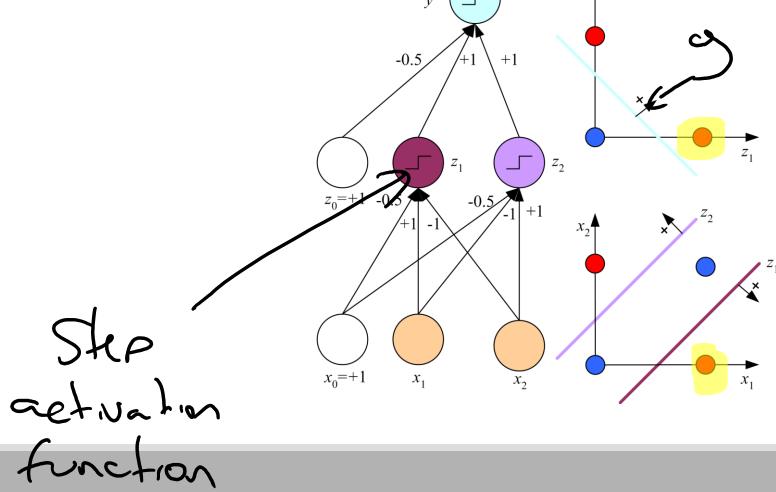
- SVM fixed this by using the kernel methods
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Let's add multiple layers to the perceptron

 At each level we have a **regression** model defined by the activation function and **always** a constant w<sub>0</sub>

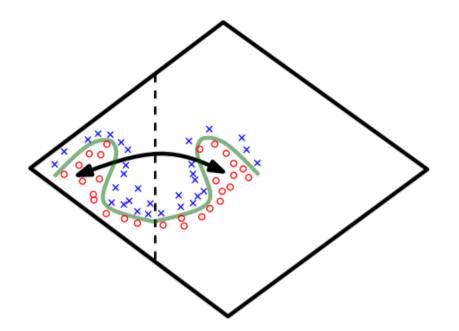


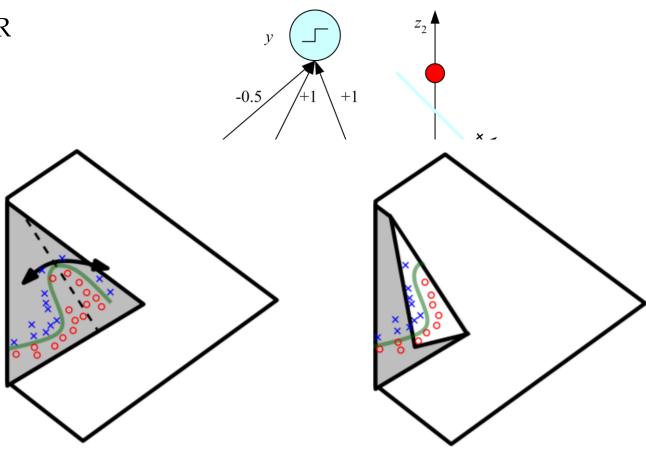
How do we use this to solve the XOR problem?



How do we use this to solve the XOR problem?

• What is happening here?





#### How to Train

Training to minimize sum-squared error

$$\ell(W) = \frac{1}{2} \sum_{j} [y^{j} - g(w_{0} + \sum_{i} w_{i} x_{i}^{j})]^{2}$$

- What type of neural network do we think this is?
  - How do we minimize it?

how many layers

g(x)= activation function

#### How to Train



• Training to minimize sum-squared error

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  - How do we minimize it?
    - Stochastic gradient descent --- what do we need?

$$\frac{\partial \ell(W)}{\partial w_k} =$$



#### How to Train

Training to minimize sum-squared error

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- What type of neural network do we think this is? Chambale andreation 3
  - How do we minimize it?
    - Stochastic gradient descent --- what do we need?

$$\frac{\partial \ell(W)}{\partial w_k} = -\sum_{j} [y^j - g(w_0 + \sum_{i} w_i x_i^j)] \underbrace{x_k^j g'(w_0 + \sum_{i} w_i x_i^j)}_{\mathcal{CK}^2}$$

# Gradient descent for 1-hidden layer – Back-propagation: Computing $\frac{\partial \ell(W)}{\partial w_i^k}$

$$\ell(W) = \frac{1}{2} \sum_{j} [y^{j} - out(\mathbf{x}^{j})]^{2}$$

$$Out(\mathbf{x}) = g\left(\sum_{k'} w_{k'}g(\sum_{i'} w_{i'}^{k'}x_{i'})\right)$$

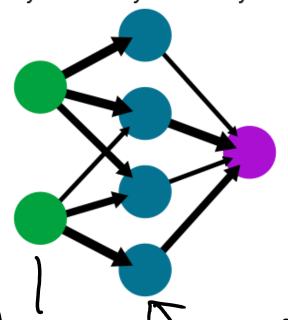
$$\frac{\partial \ell(W)}{\partial w_{i}^{k}} = \sum_{j=1}^{m} -[y - out(\mathbf{x}^{j})] \frac{\partial out(\mathbf{x}^{j})}{\partial w_{i}^{k}}$$
Dropped  $\mathbf{w}_{0}$  to make derivation simpler

A simple neural network
input hidden output layer layer

## Back-propagation Algorithm

A simple neural network

input hidden output layer layer layer



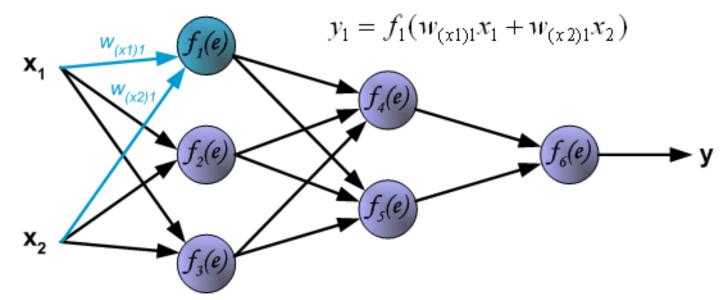
$$out(\mathbf{x}) = g\left(w_0 + \sum_k w_k g(w_0^k + \sum_i w_i^k x_i)\right)$$

Sigmoid function: 
$$g(z) = \frac{1}{1 + exp(-z)}$$
  $g(z) = \frac{1}{1 + exp(-z)}$ 

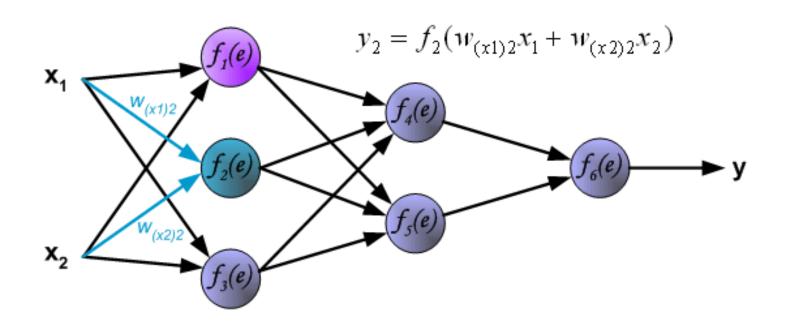
(Rummelhart et al. 1986)

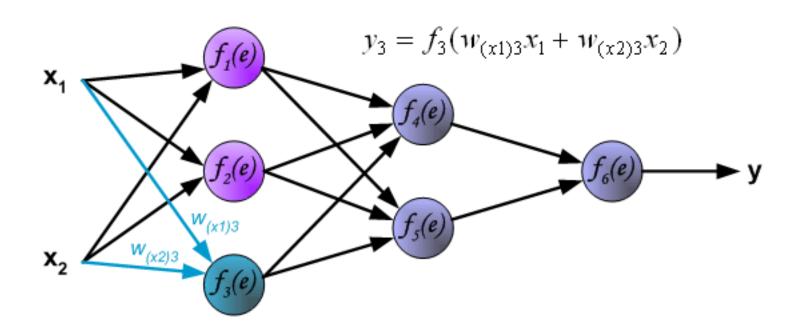
Non-convex function of 'w's

**Back-prop**: find local optima

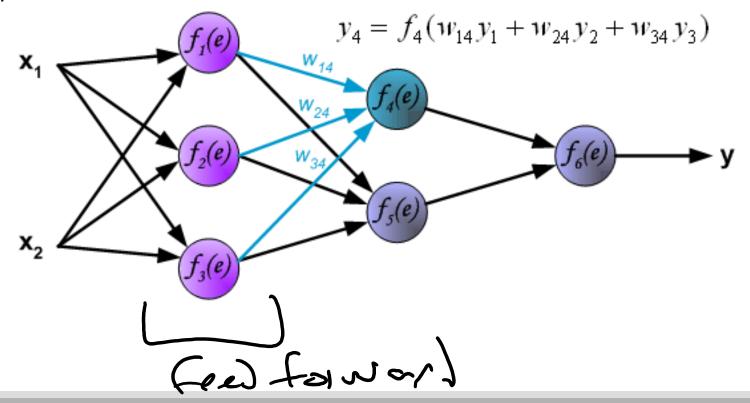


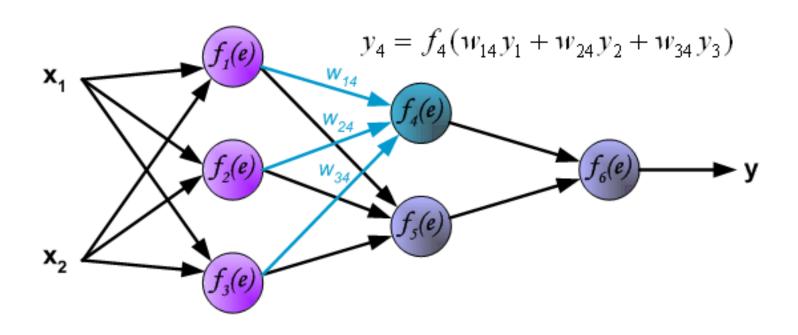
Stepli. feed forward U/point or set of pounts

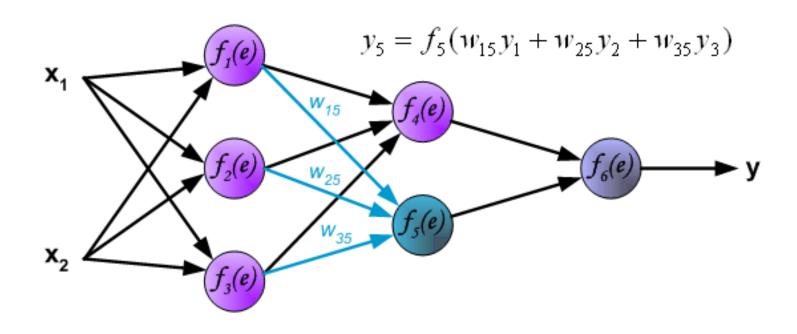




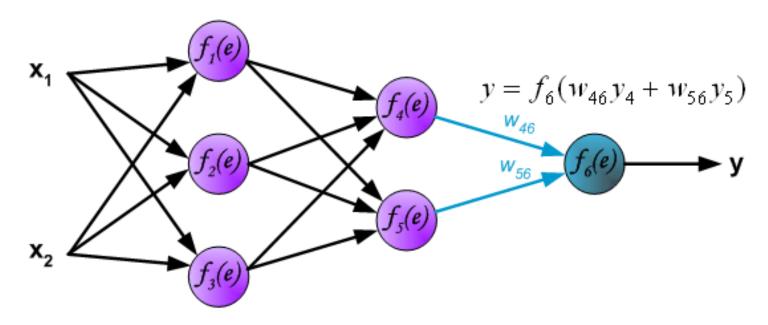
Propagation of signals through the hidden layer. Symbols  $w_{mn}$  represent weights of connections between output of neuron m and input of neuron n in the next layer.







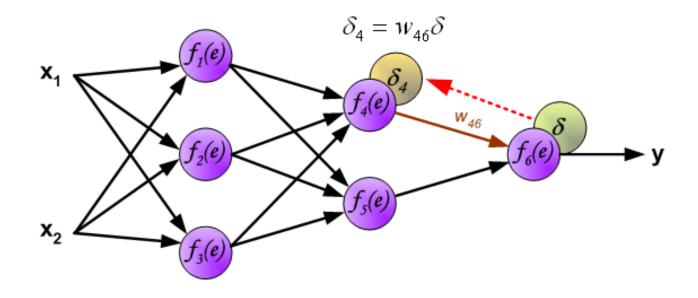
Propagation of signals through the output layer.



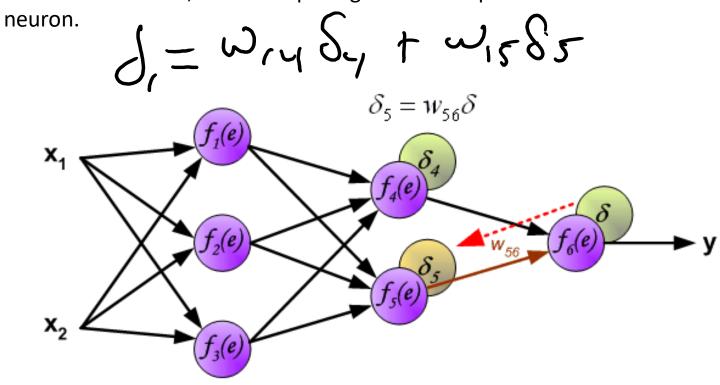
In the next algorithm step the output signal of the network *y* is compared with the desired output value (the target), which is found in training data set. The difference is called error signal *d* of output layer neuron

Coss-entopy essenting  $\delta = z - y$   $f_{3}(e)$   $f_{3}(e)$   $f_{3}(e)$   $f_{3}(e)$   $f_{3}(e)$   $f_{4}(e)$   $f_{5}(e)$   $f_{5}(e)$ 

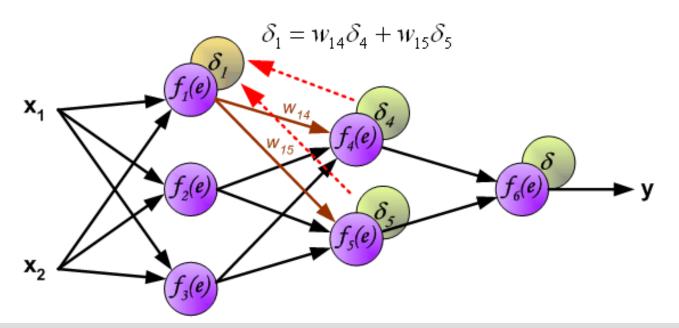
The idea is to propagate error signal *d* (computed in single teaching step) back to all neurons, which output signals were input for discussed neuron.



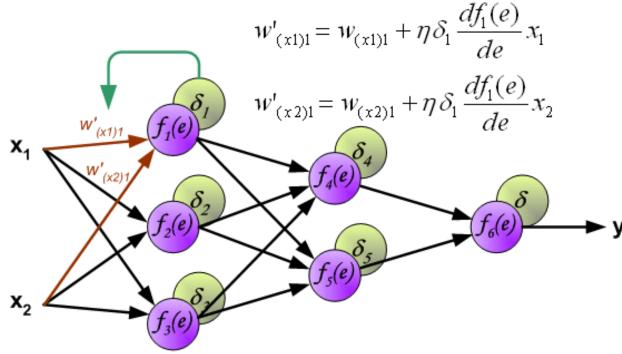
The idea is to propagate error signal *d* (computed in single teaching step) back to all neurons, which output signals were input for discussed



The weights' coefficients  $w_{mn}$  used to propagate errors back are equal to this used during computing output value. Only the direction of data flow is changed (signals are propagated from output to inputs one after the other). This technique is used for all network layers. If propagated errors came from few neurons they are added. The illustration is below:



When the error signal for each neuron is computed, the weights coefficients of each neuron input node may be modified. In formulas below df(e)/de represents derivative of neuron activation function (which weights are modified)



#### Definitions

For each neuron (*j*), the output of that neuron is

$$o_j = g(\sum_{k=1}^n w_{kj} o_k)$$

For the first layer of neurons,  $o_k$  is just the input variables  $x_k$ 

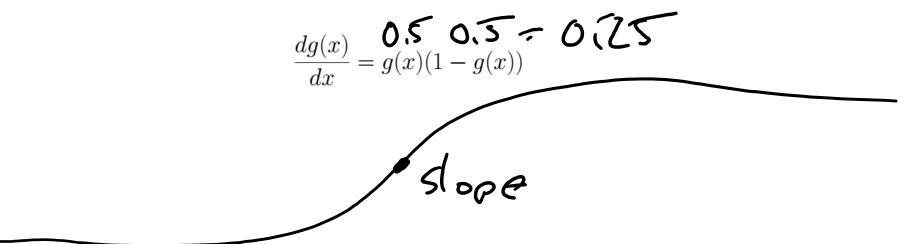
#### Definitions

For each neuron (j), the output of that neuron is

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To find the correct direction for our gradient descent, we need to find the partial derivative of the error with respect to each weight.

- This will depend on our activation function
- $\circ$  By selecting the sigmoid as our activation function g(x), we get the following derivative



Then, to find how each weight impacts the final error, given by the squared error function for each sample:

$$E = \frac{1}{2}(y - f(x)^2)$$

We then need to find  $\frac{\partial E}{\partial w_{ij}}$  in order to determine the direction of descent. We can a calculate this by:

$$\frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j} \frac{\partial net_j}{\partial w_{ij}}$$

$$net_j = \sum_{k=1}^n w_{kj} o_k$$

$$f_{net_k} = \sum_{k=1}^n w_{kj} o_k$$

$$\frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j} \frac{\partial net_j}{\partial w_{ij}}$$

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$$\frac{\partial E}{\partial o_j} =$$

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$$rac{\partial E}{\partial o_j} = \sum_{\ell \in L} \left( rac{\partial E}{\partial \mathrm{net}_\ell} rac{\partial \mathrm{net}_\ell}{\partial o_j} 
ight) = \sum_{\ell \in L} \left( rac{\partial E}{\partial o_\ell} rac{\partial o_\ell}{\partial \mathrm{net}_\ell} w_{j\ell} 
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- $\circ$  This is for the arbitrary neuron j, yet it depends on other neurons l
- This is the sensitivity from the back propagation
- Think about the error for the output neuron

What are each of these terms?

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 $\frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j} \frac{\partial net_j}{\partial w_{ij}}$   $net_j = \sum_{k=1}^n w_{kj} o_k$ 

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$$rac{\partial E}{\partial o_j} = rac{\partial E}{\partial y} = rac{\partial}{\partial y} rac{1}{2} (t-y)^2 = y-t$$

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$$\frac{\partial o_j}{\partial net_j} =$$

$$\frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j} \frac{\partial net_j}{\partial w_{ij}}$$

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$$\frac{\partial o_j}{\partial net_j} = \frac{\partial}{\partial net_j} g(net_j) = g(net_j)(1 - g(net_j))$$

When g(x) is the sigmoid (a big advantage of using the sigmoid!)

$$\frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j} \frac{\partial net_j}{\partial w_{ij}}$$

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A nice and straightforward derivative here

Bringing it all together, we get

$$rac{\partial E}{\partial w_{ij}} = \delta_j o_i \hspace{1cm} \delta_j = rac{\partial E}{\partial o_j} rac{\partial o_j}{\partial \mathrm{net}_j} =$$

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$$rac{\partial E}{\partial w_{ij}} = \delta_j o_i \qquad \qquad \delta_j = rac{\partial E}{\partial o_j} rac{\partial o_j}{\partial \mathrm{net}_j} = egin{cases} (o_j - t_j) o_j (1 - o_j) & ext{if $j$ is an output neuron,} \ (\sum_{\ell \in L} w_{j\ell} \delta_\ell) o_j (1 - o_j) & ext{if $j$ is an inner neuron.} \end{cases}$$

Notice that  $\frac{\partial o_j}{\partial net_i} = o_j(1 - o_j)$  is here included in the sensitivity delta

What should the final change in our weights be then?

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$$\Delta w_{ij} = -\eta \frac{\partial E}{\partial w_{ij}} = -\eta \delta_j o_i$$
 Calculate Sensitivity (plus actuation derivative)

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$$\Delta w_{ij} = -\eta rac{\partial E}{\partial w_{ij}} = -\eta \delta_j o_i$$

#### Where:

- η: learning rate
- $\delta_i$ : the back-propogation factor (the sensitivity) for neuron j
- $o_i$ : the output of the neuron i (which is input into j with weight  $w_{ii}$ )

This is considered one learning iteration: we adjust all of our weights in one iteration

Can be multiple data points in one "batch"

• Can be one single point at a time Smoke

What are some strengths?

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#### What are some strengths?

- Sigmoid gives us some advantages as far as differentials
- We adjust based on new feedback
  - We can actually adjust partially based on new points (no need to retrain the whole network with new data)
- With random start weights, hopefully each neuron finds its own novel trend in the data

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#### Weaknesses?

- Gradient descent finds local minima
  - May want to train several neural networks with random start weights
  - Keep the best (or some k best)
- Has difficulty with plateaus (regions where there is little change in the output)

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which sho

# Convergence of backprop

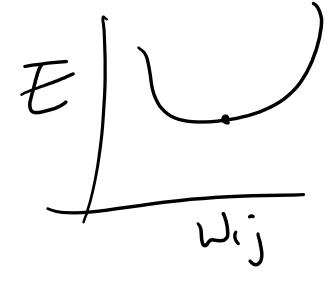
Simple Perceptron leads to convex optimization

Gradient descent reaches global minima



Multilayer neural nets **not convex** 

- Gradient descent could get stuck in local minima
- Hard to set learning rate
- Selecting number of hidden units and layers = fuzzy process
- Nonetheless, neural nets are one of the most used ML approaches



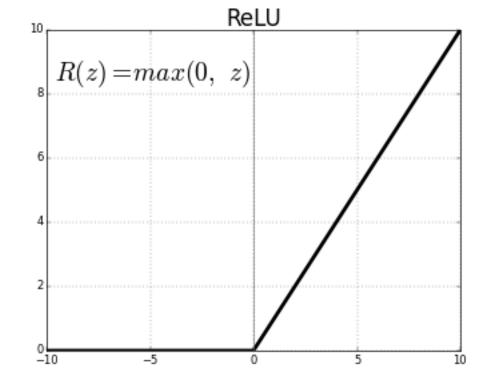


#### Neural Networks:

- For the written neural networks problems, we will use the ReLU activation function
  - It's easier to calculate
  - It is common in practice
- Keep this in mind, because this will be the outputs of the hidden nodes

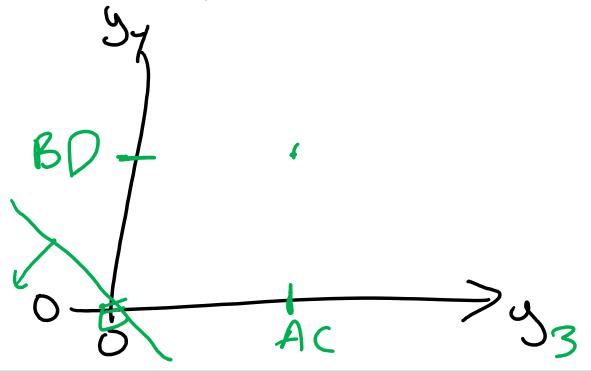
What is its derivative?

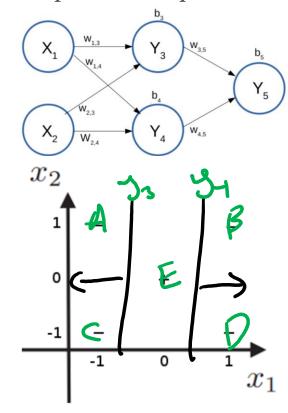
Skefunction



Given the following neural network, and weights/offsets in {-1,0,1} fit the following data such that all of the negative values have output 0 and the positive point has positive output

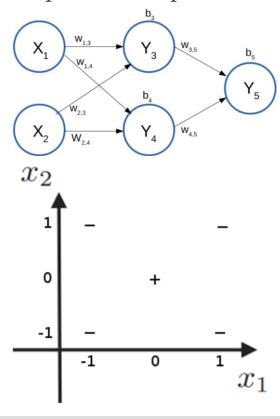
Use ReLU as your activation function



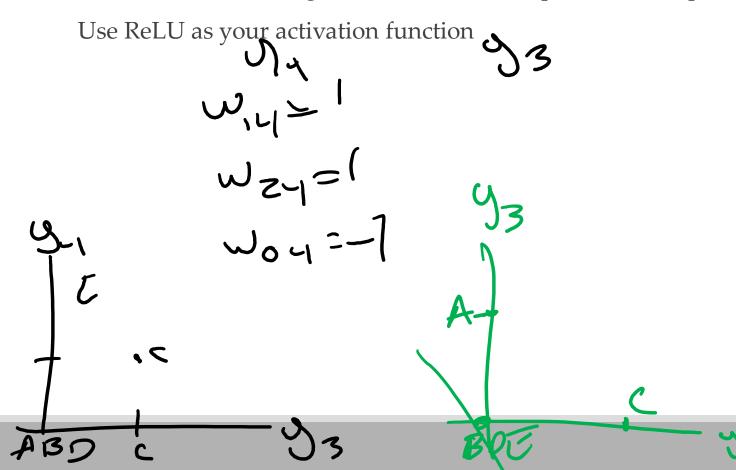


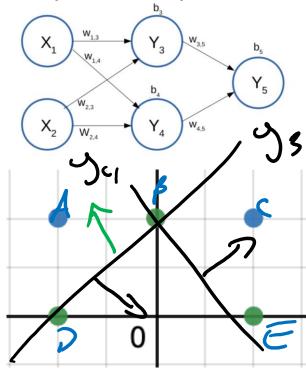
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