

```
In [47]: import numpy as np
import pandas as pd
import matplotlib.pyplot as mp
np.random.seed(100)
```

Using cvxopt library to solve the optimization problem of SVM

```
In [48]: from cvxopt import matrix, solvers
```

```
In [49]: x = np.random.uniform(low =0, high = 1, size=(100,2))
```

```
In [50]: d =[]
colors =[]
for i in range(len(x)):
    if (x[i][1] < 0.2*(np.sin(10*x[i][0])) + 0.3) or ((x[i][1] - 0.8)**2 + (x[i][0]-0.5)**2 < 0.0225):
        d.append(1)
        colors.append("r")
    else:
        d.append(-1)
        colors.append("b")
d = np.asarray(d)
```

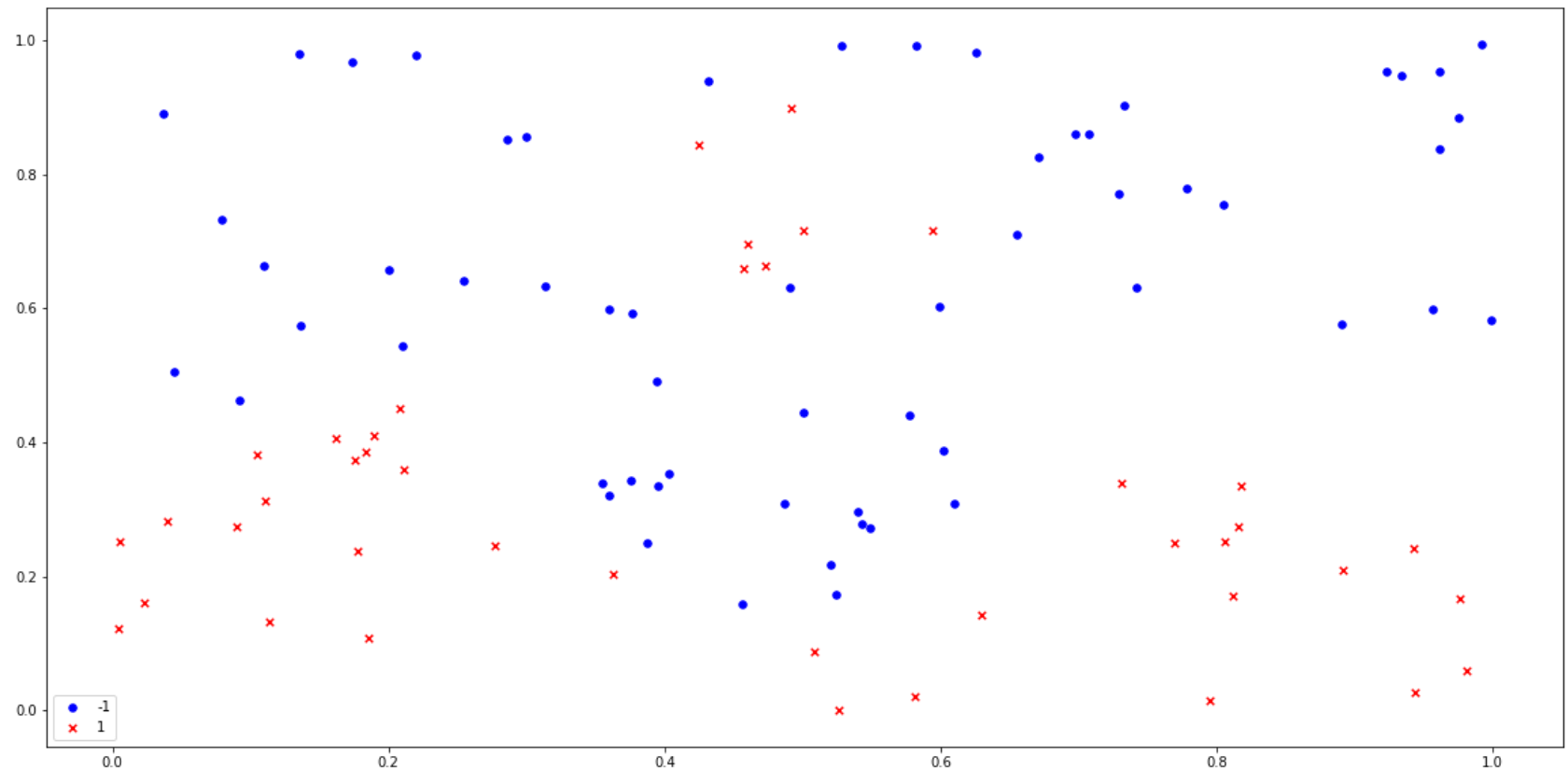
```
In [51]: d.reshape(1,-1).shape
```

```
Out[51]: (1, 100)
```

```
In [52]: fig, ax = mp.subplots(figsize = (20,10))
cdict = {1: 'red', -1: 'blue'}
markers = {1: 'x', -1: 'o'}
for g in np.unique(d):
    ix = np.where(d == g)
    ax.scatter(x[:,0][ix], x[:,1][ix], c = cdict[g], marker = markers[g], label = g, s = 30)

ax.legend(loc = 'lower left')
```

Out[52]: <matplotlib.legend.Legend at 0x23f13959d68>



Kernel Function

I am using a polynomial kernel of degree 3

```
In [62]: def kernel(X, Y):  
#       K = np.zeros((X.shape[0], Y.shape[0]))  
  
#       for i, x in enumerate(X):  
#           for j, y in enumerate(Y):  
#               K[i, j] = np.exp(-0.5*np.linalg.norm(x - y) ** 2)  
  
return (1+X.dot(Y.T))**3
```

Finding Alpha values using cvxopt library to solve the optimization problem of SVM

```
In [63]: def train_svm():  
    n, k = x.shape  
    y_matrix = d.reshape(1, -1) * 1.  
    H = np.dot(y_matrix.T, y_matrix) * kernel(x, x)  
    P = matrix(H)  
    q = matrix(-np.ones((n, 1)))  
    G = matrix(np.diag(np.ones(n) * -1))  
    h = matrix(np.zeros(n))  
    A = matrix(y_matrix)  
    b = matrix(np.zeros(1))  
  
    # solvers.options['abstol'] = 1e-10  
    # solvers.options['reltol'] = 1e-10  
    # solvers.options['feastol'] = 1e-10  
  
    return solvers.qp(P, q, G, h, A, b)
```

```
In [64]: parameters = train_svm()
```

	pcost	dcost	gap	pres	dres
0:	-6.4862e+01	-1.9051e+02	4e+02	1e+01	3e+00
1:	-2.3482e+02	-3.8691e+02	2e+02	6e+00	2e+00
2:	-3.1394e+02	-4.9169e+02	2e+02	5e+00	1e+00
3:	-5.3124e+02	-7.5929e+02	3e+02	5e+00	1e+00
4:	-1.4735e+03	-1.7590e+03	3e+02	4e+00	1e+00
5:	-2.1726e+03	-2.5225e+03	4e+02	4e+00	1e+00
6:	-6.5390e+03	-7.2515e+03	7e+02	4e+00	1e+00
7:	-2.8736e+04	-3.0840e+04	2e+03	4e+00	1e+00
8:	-5.0928e+04	-5.4486e+04	4e+03	4e+00	1e+00
9:	-1.1426e+05	-1.2310e+05	9e+03	4e+00	1e+00
10:	-2.5077e+05	-2.7840e+05	3e+04	4e+00	1e+00
11:	-4.4253e+05	-5.0925e+05	7e+04	3e+00	1e+00
12:	-7.9750e+05	-9.6717e+05	2e+05	3e+00	8e-01
13:	-1.2592e+06	-1.5351e+06	3e+05	1e+00	4e-01
14:	-1.3478e+06	-1.3794e+06	3e+04	9e-02	2e-02
15:	-1.3483e+06	-1.3486e+06	3e+02	9e-04	2e-04
16:	-1.3483e+06	-1.3483e+06	3e+00	9e-06	2e-06
17:	-1.3483e+06	-1.3483e+06	3e-02	9e-08	2e-08

Optimal solution found.

Finding Bias using the alpha values

```
In [65]: def bias(alphas):

# Threshold to find the support vectors
# Instead of zero tolerance, I am using some floating point tolerance

    threshold = 1e-5
    sv = (alphas > threshold).reshape(-1, )
    b = []
    for i in range(len(d[sv])):
        sum = 0
        for j in range(len(x)):
            # print(x[sv][i])
            # print(kernel(x[j].reshape(1,2), x[sv][i].reshape(1,2)))
            # print(f)
            sum += alphas[j]*d[j]*kernel(x[j].reshape(1,2), x[sv][i].reshape(1,2))
            # print(sum)
        b.append(d[sv][i] - sum)

    # print(b)
    # print(f)
    b = np.mean(b)
    # print(b)
    return b, sv
```

```
In [68]: alphas = np.array(parameters['x'][:, 0])
print(len(alphas))
b, sv = bias(alphas)

print('Alpha values of support vectors:', alphas[sv])
print('bias = ', b)
```

100

Alpha values of support vectors: [141624.83651654 97252.79769487 219453.89958003 114956.89032222
105263.05297173 44391.42974999 551375.68098238 443111.91242398
57475.12259771 921738.6130395]
bias = 228.77513944812785

Plotting support vectors

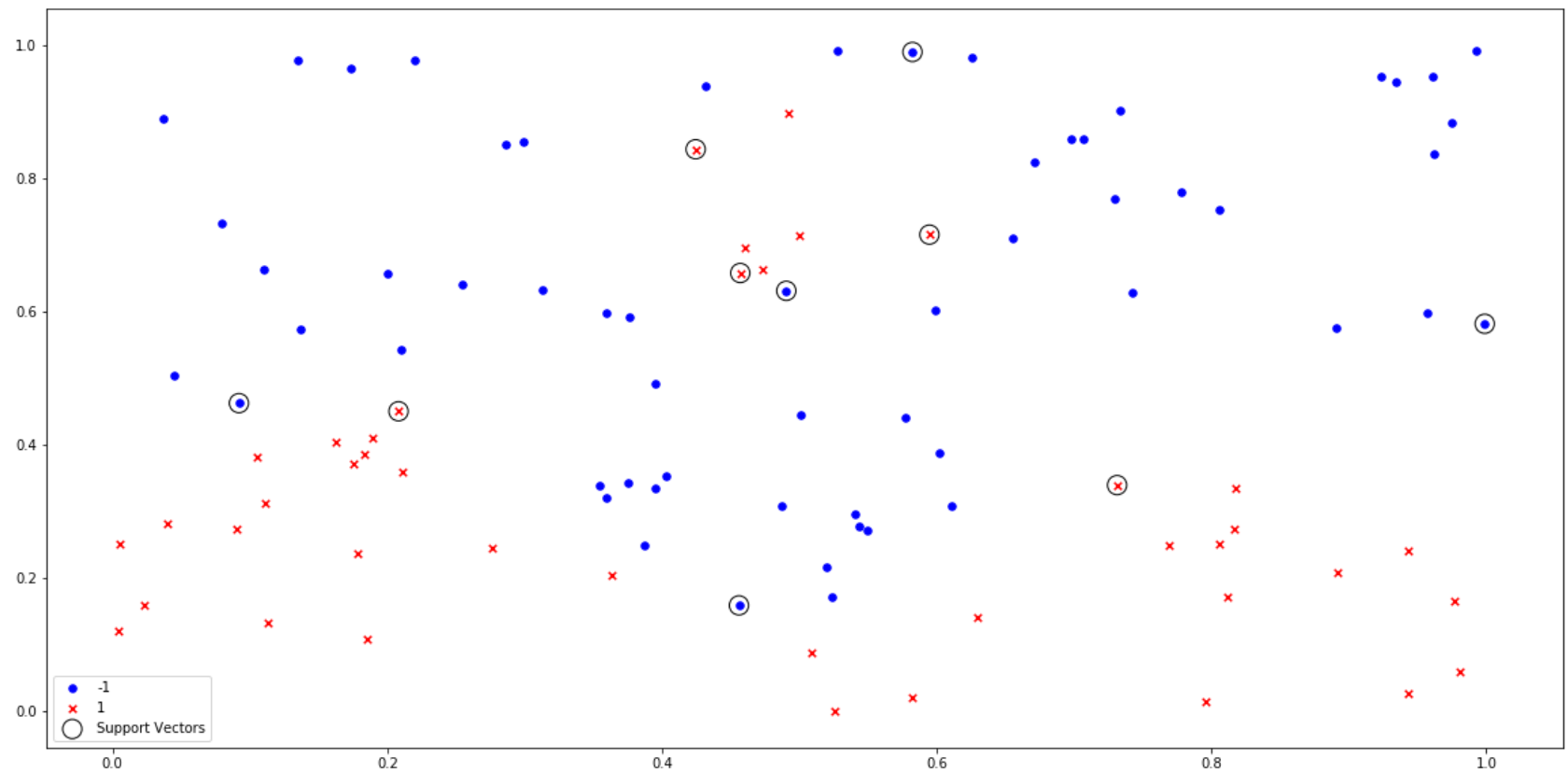
```

In [73]: fig, ax = mp.subplots(figsize = (20,10))
cdict = {1: 'red', -1: 'blue'}
markers = {1:'x', -1:'o'}
for g in np.unique(d):
    ix = np.where(d == g)
    ax.scatter(x[:,0][ix], x[:,1][ix], c = cdict[g], marker = markers[g], label = g, s = 30)

support_vectors = x[sv]
ax.scatter(support_vectors[:,0], support_vectors[:,1], s=200, facecolors='none', edgecolors='black', label =
"Support Vectors")
ax.legend(loc='lower left')

```

Out[73]: <matplotlib.legend.Legend at 0x23f142d9da0>



Finding the three hyperplanes

```
In [74]: def decision_function(x, y):  
    p = []  
    for i in x:  
        for j in y:  
            p.append(kernel(i,j))  
    return np.array(p).reshape(x.shape[0], y.shape[0])
```

```

In [76]: xx = np.linspace(0,1,100)
yy = np.linspace(0,1,100)
XX, YY = np.meshgrid(xx, yy)
# print(XX.shape)
xy = np.c_[XX.ravel(), YY.ravel()]
#print(xy)

df = decision_function(x,xy)
#print(((alphas*d).reshape(1,XX.shape[0])).dot(kxy))
Z = (((alphas*d).reshape(1,XX.shape[0])).dot(df)) +b).reshape(XX.shape)

fig, ax = mp.subplots(figsize = (20,10))
contour = ax.contour(XX, YY, Z, colors=['blue', 'black', 'red'], levels = [-1,0,1], alpha = 0.6, linestyles
= ['--', '-', '--'])

fmt = {}
strs = ['H-', 'H', 'H+']
for l, s in zip(contour.levels, strs):
    fmt[l] = s

# Label every other level using strings
ax.clabel(contour, contour.levels[::2], inline = True, inline_spacing = 10, fmt=fmt, fontsize=20)

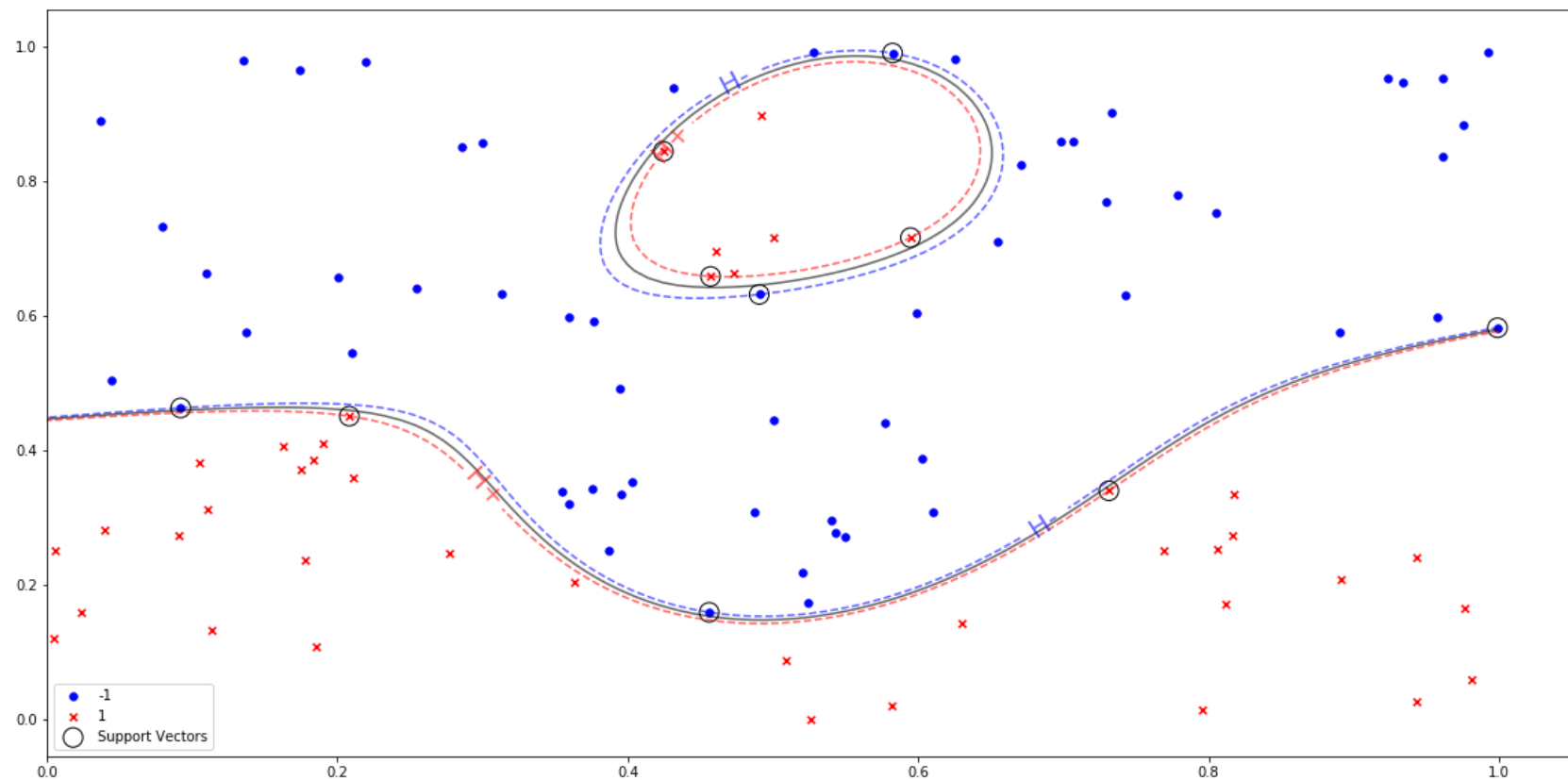
cdict = {1: 'red', -1: 'blue'}
markers = {1: 'x', -1: 'o'}
for g in np.unique(d):
    ix = np.where(d == g)
    ax.scatter(x[:,0][ix], x[:,1][ix], c = cdict[g], marker = markers[g], label = g, s = 30)

# ax.scatter(x[:,0], x[:,1], c= colors, s=10, label = ('blue'))
# ax.scatter(x[:,0], x[:,1], c= colors, s=10, label = ('red'))

# ax.legend()
support_vectors = x[sv]
ax.scatter(support_vectors[:,0], support_vectors[:,1], s=200, facecolors='none', edgecolors='black', label =
"Support Vectors")
ax.legend(loc='lower left')

```


Out[76]: <matplotlib.legend.Legend at 0x23f14971ba8>



```
In [45]: # def af(x):  
#         if x >= 0:  
#             return 1  
#         else:  
#             return -1
```

```

In [ ]: # def predict(x,y):

#     f=[]
#     for k in range(len(x)):
#         p=[]
#         for i in range(len(x[0])):
#             q = np.asarray([x[0][i], y[0][i]])
#             sum = 0
#             for j in range(len(x[0])):
#                 r = np.asarray([x[0][j], y[0][j]])
#                 sum += alphas[j] * d[j] * kernel(r.reshape(1,2), q.reshape(1,2))
#             p.append(af(sum+b))
#         f.append(p)

#     return np.asarray(f).T

```

```

In [ ]: # u = []
# v = []
# for i in range(len(x)):
#     if predict(b, x[i]) == 1:
#         u.append(x[i])
#     elif predict(b,x[i]) == -1:
#         v.append(x[i])
# u = np.asarray(u)
# v = np.asarray(v)

```

```
In [119]: # import numpy as np
# import matplotlib.pyplot as plt
# from sklearn import svm
# from sklearn.datasets import make_blobs

# # we create 40 separable points
# X, y = make_blobs(n_samples=40, centers=2, random_state=6)

# # fit the model, don't regularize for illustration purposes
# clf = svm.SVC(kernel='linear', C=1000)
# clf.fit(X, y)

# plt.scatter(X[:, 0], X[:, 1], c=y, s=30, cmap=plt.cm.Paired)

# # plot the decision function
# ax = plt.gca()
# xlim = ax.get_xlim()
# ylim = ax.get_ylim()

# # create grid to evaluate model
# xx = np.linspace(xlim[0], xlim[1], 30)
# yy = np.linspace(ylim[0], ylim[1], 30)
# YY, XX = np.meshgrid(yy, xx)
# # print(xx)
# # print(XX)
# # print(o)
# xy = np.vstack([XX.ravel(), YY.ravel()]).T
# Z = clf.decision_function(xy).reshape(XX.shape)
# # print(Z)
# # print(f)

# # plot decision boundary and margins
# ax.contour(XX, YY, Z, colors='k', levels=[-1, 0, 1], alpha=0.5,
#           linestyles=['--', '-', '--'])
# # plot support vectors
# ax.scatter(clf.support_vectors_[:, 0], clf.support_vectors_[:, 1], s=100,
#           linewidth=1, facecolors='none', edgecolors='k')
# plt.show()
```

In []:

In []: