

# The Matrix Eigenvalue Problem

# The Matrix Eigenvalue Problem

Let  $A \in \mathbb{C}^{n \times n}$ . The eigenvalue problem for  $A$  consists of finding all  $x \in \mathbb{C}^n \setminus \{0\}$  and  $\lambda \in \mathbb{C}$  such that

$$Ax = \lambda x.$$

The scalars  $\lambda \in \mathbb{C}$  are called the eigenvalues of  $A$  and the corresponding non zero vector  $x$  is called an eigenvector of  $A$ .

- ▶ The eigenvalues of  $A$  are the roots of  $\det(A - sI)$ .
- ▶  $A \in \mathbb{C}^{n \times n}$  can have at most  $n$  distinct eigenvalues.
- ▶ Any set of eigenvectors of  $A$  corresponding to distinct eigenvalues is a linearly independent set.
- ▶ Matrices  $A$  and  $B$  are said to be similar if there exists a nonsingular matrix  $S$  such that  $B = S^{-1}AS$ . If  $S$  is a unitary matrix, then  $A$  and  $B$  are said to be unitarily similar.
- ▶ Similar matrices have the same eigenvalues.

# The Matrix Eigenvalue Problem

- ▶ If  $Av = \lambda v$  for some  $v \neq 0$ , and  $B = S^{-1}AS$ , then  $BS^{-1}v = \lambda S^{-1}v$ .
- ▶ A matrix  $A$  is said to be (unitarily) diagonalizable if it is (unitarily) similar to a diagonal matrix.
- ▶ (Unitary) diagonalizability of an  $n \times n$  matrix  $A$  is equivalent to the existence of a (orthonormal) basis of  $\mathbb{C}^n$  consisting of eigenvectors of  $A$ .
- ▶ Not every matrix is diagonalizable.
- ▶ Given any matrix  $A \in \mathbb{C}^{n \times n}$ , there exists an invertible matrix  $X$  and a block diagonal matrix  $J = \text{diag}(J_{\lambda_1}, \dots, J_{\lambda_p})$ , with

$$J_{\lambda_i} = \begin{bmatrix} \lambda_i & 1 & & & \\ & \lambda_i & 1 & & \\ & & \ddots & \ddots & \\ & & & \lambda_i & 1 \\ & & & & \lambda_i \end{bmatrix}, \quad i = 1, \dots, p,$$

such that  $A = XJX^{-1}$ .  $J$  is called the *Jordan Canonical form* of  $A$ .

# Schur's Theorem



**Issai Schur**  
**(1875-1941)**

# Schur's Theorem



Issai Schur  
(1875-1941)

$$\begin{aligned} A^* &= A \\ T^* &= (Q^* A Q)^* \\ &= Q^* A^* (Q^*)^* \\ &= Q^* A Q \\ &= T \end{aligned}$$

$$\begin{aligned} A A^* &= A^* A \\ \Leftrightarrow T T^* &= T^* T \end{aligned}$$

**Schur's Theorem:** Given any matrix  $A \in \mathbb{C}^{n \times n}$ , there exists a unitary matrix  $Q$  and an upper triangular matrix  $T$  such that  $Q^* A Q = T$ .

$T$  is called a Schur form of  $A$ .

# Spectral Theorems

**Spectral Theorem for Hermitian Matrices**  $A \in \mathbb{C}^{n \times n}$  is Hermitian if and only if there exists a unitary matrix  $Q$  and a real diagonal matrix  $D$  such that  $Q^* A Q = D$ .

# Spectral Theorems

**Spectral Theorem for Hermitian Matrices**  $A \in \mathbb{C}^{n \times n}$  is Hermitian if and only if there exists a unitary matrix  $Q$  and a real diagonal matrix  $D$  such that  $Q^* A Q = D$ .

**Spectral Theorem for Normal Matrices**  $A \in \mathbb{C}^{n \times n}$  is normal if and only if there exists a unitary matrix  $Q$  and a diagonal matrix  $D$  such that  $Q^* A Q = D$ .

Prove the following:

- ① If  $AA^* = A^*A$  and  $\exists$  a unitary  $Q$  such that  $Q^* A Q = T$  where  $T$  is upper triangular, then,  $T^* T = T T^*$ .
- ② If  $T$  is upper triangular &  $T^* T = T T^*$ , then  $T$  is diagonal.
- ③ Hence prove Spectral Theorem for Normal Matrices.

# Spectral Theorems

**Spectral Theorem for Hermitian Matrices**  $A \in \mathbb{C}^{n \times n}$  is Hermitian if and only if there exists a unitary matrix  $Q$  and a real diagonal matrix  $D$  such that  $Q^* A Q = D$ .

**Spectral Theorem for Normal Matrices**  $A \in \mathbb{C}^{n \times n}$  is normal if and only if there exists a unitary matrix  $Q$  and a diagonal matrix  $D$  such that  $Q^* A Q = D$ .

**Spectral Theorem for Symmetric Matrices**  $A \in \mathbb{R}^{n \times n}$  is symmetric if and only if there exists a real orthogonal matrix  $Q$  and a real diagonal matrix  $D$  such that  $Q^T A Q = D$ .

$A \in \mathbb{R}^{n \times n}$  &  $A^T = A \Rightarrow A^* = A$ . Let  $\lambda \in \mathbb{C}$  and  $v \in \mathbb{C}^n, v \neq 0$ , such that  $Av = \lambda v \Rightarrow v^* A v = \lambda v^* v \Rightarrow v^* A v = \lambda \|v\|_2^2$  ①

s. From ① & ②  $0 = v^* A v - v^* A v = (\lambda - \bar{\lambda}) \|v\|_2^2 \Rightarrow \lambda = \bar{\lambda}$  (as  $v \neq 0$ )

Also  $Av = \lambda v \Rightarrow A(\operatorname{Re} v) + i A(\operatorname{Im} v) = \lambda \operatorname{Re} v + i \lambda \operatorname{Im} v$

$\Rightarrow A \operatorname{Re} v = \lambda \operatorname{Re} v$  &  $A(\operatorname{Im} v) = \lambda(\operatorname{Im} v)$  [As  $\lambda$  is real] (as  $A^* = A$ ) - ②

So  $A$  has only real eigenvalues and corresponding eigenvectors can be chosen to be real!