

Port Midterm

26/2/22

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$$

Jacobi (iterative method) :-

$$x_1^{(k+1)} = \frac{1}{a_{11}} (b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)}) \quad \text{--- (1)}$$

$$x_2^{(k+1)} = \frac{1}{a_{22}} (b_2 - a_{21}x_1^{(k)} - a_{23}x_3^{(k)})$$

Gauss seidel :- $x_1^{(k+1)}$ = same as (1)

$$x_2^{(k+1)} = \frac{1}{a_{22}} (b_2 - a_{21}x_1^{(k+1)} - a_{23}x_3^{(k)})$$

$$Ax = b \quad \text{--- IF } A^{-1}$$

$$Mx = (M - A)x + b$$

M - pre conditioner
non-singular

$$x = (I - M^{-1}A)x + M^{-1}b$$

Use fixed pt iteratⁿ

$$x^{(k+1)} = (I - M^{-1}A)x^{(k)} + M^{-1}b$$

$x^{(k)}$ will converge if $\rho(B) < 1$ B - iterative matrix spectral radius max of eigen values of B

Let

$$A = D - L - U$$

For Jacobi :- $M = D$

$$x^{(k+1)} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} \frac{1}{a_{11}}a_{12} & \frac{1}{a_{11}}a_{13} \\ \frac{1}{a_{22}}a_{21} & \frac{1}{a_{22}}a_{23} \\ \frac{1}{a_{33}}a_{31} & \frac{1}{a_{33}}a_{32} \end{bmatrix} x^{(k)} + \begin{bmatrix} \frac{b_1}{a_{11}} \\ \frac{b_2}{a_{22}} \\ \frac{b_3}{a_{33}} \end{bmatrix}$$

(OR)

$$A = D - L - U$$

$$M - A = D - A = L + U$$

$$Dx^{(k+1)} = (L + U)x^{(k)} + b$$

Gauss Seidel:-

$$M = \cancel{E} D - L$$

In order to speed up the convergence of Gauss-Seidel, we can introduce the parameter w_k

$$M = \frac{1}{w_k} D - L$$

Successive Over Relaxation (SOR)

Why there is

Successive Under Relaxation

$$M - A = \left(\frac{1}{w_k} - 1\right) D + U$$

$$\left(\frac{1}{w_k} D - L\right) x^{(k+1)} = \left(\left(\frac{1}{w_k} - 1\right) D + U\right) x^{(k)} + b$$

$$x^{(k+1)} = \left(\frac{1}{w_k} D - L\right)^{-1} \left(\left(\frac{1}{w_k} - 1\right) D + U\right) x^{(k)} + b$$

Done using Row Oriented Forward Substitution

Stopping criteria:-

- i) $\|x^n - x\| < \text{Tol}$
- ii) $r^{(n)} = Ax^{(n)} - b \quad \|r^{(n)}\| < \text{tol}$
- iii) $\|x^n - x^{n-1}\| < \text{tol}$

Optimal w_k (for speedy convergence):-

$$w_{\text{opt}} = \frac{2}{1 + \sqrt{1 - \rho\left(\frac{B_J}{J}\right)^2}}$$

In Case of American, we have to impose the side condition $y \geq g$ at each iteration. $D^{-1}(L+U)$

Correction vector: $x^{(k)} - x^{(k-1)}$

$$b - A_{ii} x_i^{(k)} = b - \sum_{j=1}^n a_{ij} x_j^{(k)} = a_{ii} x_i^{(k-1)} - \sum_{j=1, j \neq i}^n a_{ij} x_j^{(k-1)}$$

$$x_i^{(k)} = x_i^{(k-1)} + \frac{1}{a_{ii}} \frac{r_i^{(k)}}{a_{ii}} \quad \text{--- } r_i^{(k)} \text{ also has } x^{(k)} \text{ terms}$$

Projected
Gauss-Seidel

$$x_i^{(k)} = \max \left\{ 0, x_i^{(k-1)} + \frac{1}{a_{ii}} \frac{r_i^{(k)}}{a_{ii}} \right\} \quad \text{--- to accommodate } y \geq 0$$

$$y_i = -r_i^{(k)} + a_{ii} (x_i^{(k)} - x_i^{(k-1)})$$

Crager's problem has a unique min

28/2/24 - Friday

- u'' of

$$u(0) = 0 = u(1)$$

$$v \in C_0^\infty(\Omega)$$

$$-\int u'' v \, dx = \int f v \, dx$$

$$-\int v d(u') = -(uv)' + \int u' v' \, dx = \int f v \, dx$$

u', v' - weak sense

$$u \in L^p(\Omega) \quad \text{Lebesgue}$$

u', v' - weak sense

$$L^p(\Omega) = \{ u \in \Omega : \int_\Omega (u(x))^p \, dx < \infty \}$$

If $u \in L^2, u' \in L^2 \Leftrightarrow u \in H^1(\Omega) \rightarrow$ this in appendix C2 in book

$$H^1(\Omega) \subset C_0^\infty(\Omega)$$

f^m have need to be infinitely differentiable

$$u \in C_0^\infty(\Omega), v \in C_0^\infty(\Omega):$$

$$\int_\Omega D^\alpha u(x) v(x) \, dx = (-1)^{|\alpha|} \int_\Omega u(x) D^\alpha v(x) \, dx, \quad |\alpha| \leq k, \quad \forall v \in C_0^\infty(\Omega)$$

(Pf by using by parts)

Let $u \in L^1(\Omega)$

$$\int_{\Omega} w_{\alpha}(x) v(x) \cdot dx = (-1)^{|\alpha|} \int_{\Omega} u(x) D^{\alpha} v(x) \cdot dx \quad \forall v \in C_0^{\infty}(\Omega) \quad \text{--- (2)}$$

w_{α} is the weak α^{th} derivative (see (1) or (2))

For $u \in C^{\alpha}$, $w_{\alpha} = u$ (the weak α^{th} derivative of u is u^{α} itself) RHS of

The 1st weak derivative of $|x| = \text{sgn}(x)$

For L^p f's,

$$W_p^k(\Omega) = \{u \in L^p(\Omega) : D^{\alpha}(u) \in L^p(\Omega), |\alpha| \leq k\} \quad \text{--- Sobolev space}$$

$$\|u\|_{W_p^k(\Omega)} = \left(\sum_{|\alpha| \leq k} \|D^{\alpha} u\|_{L^p(\Omega)}^p \right)^{1/p}, \quad 1 \leq p < \infty$$

$$H^k(\Omega) = W_2^k(\Omega) = \{u \in L^2, D^{\alpha} u \in L^2\}$$

Hilbert space

$$(u, v) = \sum_{|\alpha| \leq k} (D^{\alpha} u, D^{\alpha} v) \quad \text{--- inner product}$$

norm of u, v

$$H^1(\Omega) = \left\{ u \in L^2(\Omega) : \frac{\partial u}{\partial x_j} \in L^2(\Omega) \quad j=1, \dots, n \right\}$$

weak derivatives - $u \in L^2(\Omega)$ may not be diff

$$\|u\|_{H^1(\Omega)}^2 = \left(\|u\|_{L^2(\Omega)}^2 + \sum_{j=1}^n \left\| \frac{\partial u}{\partial x_j} \right\|_{L^2(\Omega)}^2 \right)$$

~~H_E^1~~

$$-u'' = f$$

$$u(0)=0, u(1)=1$$

We want u from H_E^1

$$H_E^1(\Omega) = \{u \in H^1(\Omega) : u(0)=0, u(1)=1\}$$

whatever condition u are applied on v also - so $v \in H_E^1$

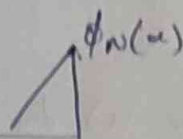
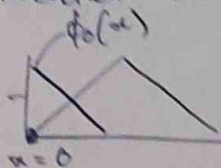
$$-\int u' v' \cdot dx = \int f v \cdot dx$$

$$-(v u')' + \int v' u' \cdot dx = \int f v \cdot dx$$

$$\begin{aligned} \int v' u' \cdot dx &= \int f v \cdot dx + v(1) u'(1) - u'(0) v(0) \\ &= \int f v \cdot dx + u'(1) \end{aligned}$$

2/10/20

Dirichlet BVP



$$\begin{aligned} -u'' &= f \\ -u'(0) &= \alpha \\ u'(1) &= \beta \end{aligned}$$

$$u_h(x) = \sum_{i=1}^N U_i \phi_i(x)$$

Neumann BVP

$$u_h(x) = \sum_{i=0}^{N+1} U_i \phi_i(x)$$

Robin

$$-u'' = f$$

$$u(0) - u'(0) = \alpha$$

$$u(1) + u'(1) = \beta$$

$$H_R^1(\Omega) = \{u \in \Omega : u(0) - u'(0) = \alpha, u(1) + u'(1) = \beta\}$$

find $u \in H_R^1(\Omega)$ s.t.

$$\int \tilde{u} v' dx = \int f v dx + (\text{boundary cond})$$

Consider the obstacle problem. In order to solve using FEM, we define

$$\forall v \in H_R^1(\Omega)$$

$$K = \{v \in C^0[-1, 1] : v(-1) = v(1) = 0, v(x) \geq g(x) \forall x \in \Omega, v \text{ is piecewise linear}\}$$

The solⁿ u of obstacle problem

$$\text{find } u \in C^0(x) \text{ s.t.}$$

$$\left. \begin{aligned} u''(u-g) &= 0, -u'' \geq 0, u-g \geq 0 \\ u(-1) &= u(1) = 0 \end{aligned} \right\} \textcircled{1}$$

$$u \in K \text{ and } \forall v \in K \quad v-g \geq 0$$

\therefore The FEM tells

$$\text{As } -u'' > 0 \text{ if } v \in K \Rightarrow v-g \geq 0$$

$$\int -u''(v-g) dx \geq 0 \quad \forall v \in K \rightarrow \textcircled{2}$$

$$\text{From } \textcircled{1}, \int -u''(u-g) dx = 0 \rightarrow \textcircled{3}$$

$$\textcircled{2} - \textcircled{3} \Rightarrow \int -u''(v-u) dx \geq 0 \rightarrow \textcircled{4}$$

① doesn't contain q explicitly whereas it is inside the space \mathcal{K} .

$$\textcircled{2} - \int_{-1}^1 -d(u')(v-u) \cdot dx \geq 0$$

$$\left[-u'(v-u) \right]_{-1}^1 \xrightarrow{0} + \int_{-1}^1 u'(v-u)' \cdot dx \geq 0$$

$$\therefore v \in \mathcal{K}, v(-1) = u(-1) = v(1) = u(1) = 0$$

Weak formulation

find $u \in \mathcal{K} \rightarrow$

$$\int_{-1}^1 u'(v-u)' \cdot dx \geq 0 \quad \forall v \in \mathcal{K} \quad \textcircled{3}$$

Since $\textcircled{3}$ is known as variational inequality

If we consider an approximation $w \in \mathcal{K}$ for $u \in \mathcal{K}$

$$\int_{-1}^1 w'(v-w)' \cdot dx \geq 0 \quad \forall v \in \mathcal{K}$$

$$\sum_{i=1}^N \int_{-1}^1 \phi_i'(x) (\phi_j(x) - \phi_i(x))' \cdot dx \geq 0 \quad \forall j$$

$$w_n(x) = \sum_{i=0}^{N+1} w_i \phi_i(x)$$

In $\textcircled{3}$, when $v=u$, the integral vanishes.

$\therefore \textcircled{3}$ is a minimization problem

$$\left(\frac{\partial y}{\partial \tau} - \frac{\partial^2 y}{\partial x^2} \right) (y-q) = 0$$

$$\frac{\partial y}{\partial \tau} - \frac{\partial^2 y}{\partial x^2} \geq 0, y-q \geq 0$$

$$y(x,0) = q(x,0)$$

$$y(x_{\min}, \tau) = q(x_{\min}, \tau)$$

$$y(x_{\max}, \tau) = q(x_{\max}, \tau)$$

K - competing / admissible f^m

$$K = \left\{ v \in C^0 : \frac{\partial v}{\partial \tau} \text{ is piecewise } C^0, v(x, \tau) \geq q(x, \tau) \forall x, \tau \right. \\ \left. v(x, 0) = q(x, 0), v(x_{\min}, \tau) = q(x_{\min}, \tau), v(x_{\max}, \tau) = q(x_{\max}, \tau) \right\}$$

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$$v \geq q : \frac{\partial y}{\partial \tau} - \frac{\partial^2 y}{\partial x^2} \geq 0$$

$$\textcircled{1} \leftarrow \int_{x_{\min}}^{x_{\max}} \left(\frac{\partial y}{\partial \tau} - \frac{\partial^2 y}{\partial x^2} \right) (v - q) \cdot dx \geq 0$$

$y, v \in K$

$$\textcircled{2} \leftarrow \int_{x_{\min}}^{x_{\max}} \left(\frac{\partial y}{\partial \tau} - \frac{\partial^2 y}{\partial x^2} \right) (q - y) \cdot dx \leq 0$$

From $\textcircled{1}$ and $\textcircled{2}$,

$$\int_{x_{\min}}^{x_{\max}} \left(\frac{\partial y}{\partial \tau} - \frac{\partial^2 y}{\partial x^2} \right) (v - y) \cdot dx \geq 0$$

~~By parts~~

By parts

$$\int_{x_{\min}}^{x_{\max}} \left[\frac{\partial y}{\partial \tau} (v - y) + \frac{\partial y}{\partial x} \left(\frac{\partial v}{\partial x} - \frac{\partial y}{\partial x} \right) \right] \cdot dx \geq 0$$

$$\textcircled{3} \leftarrow \int_{x_{\min}}^{x_{\max}} \left[\frac{\partial y}{\partial \tau} (v - y) + \frac{\partial y}{\partial x} \left(\frac{\partial v}{\partial x} - \frac{\partial y}{\partial x} \right) \right] \cdot dx \geq 0$$

~~if $v \in K$~~

$\textcircled{3}$ becomes a minimization problem

$$I(y; v) = \int_{x_{\min}}^{x_{\max}} f \cdot dx \geq 0 \quad \forall v \in K$$

$$\min_{v \in K} I(y; v) = I(y, y) = 0$$

For American optⁿ, we require $e^2, \hat{y} \in K$

and we expect the solⁿ \hat{y}

$$\inf_{v \in K} I(\hat{y}; v) = 0$$

$$K = \text{span}\{\phi_i\}$$

ϕ_i 's are hat f_i

$$\textcircled{4} \hat{y} = \sum_i w_i(z) \phi_i(x)$$

$$v = \sum_i v_i(z) \phi_i(x)$$

$$\int_{x_{\min}}^{x_{\max}} \left(\sum_i \frac{\partial w}{\partial z} \phi_i \right) \sum_i (v_i - w_i) \phi_i(x) dx$$

$$+ \sum_i w_i(z) \phi_i(x) \left(\sum_j (v_j(z) - w_j(z)) \phi_j'(x) \right) dx \geq 0$$

$$- \sum_i \sum_j \frac{\partial w_i}{\partial z} (v_j - w_j) \int \phi_i(x) \phi_j'(x) dx + \sum_i \sum_j w_i (v_j - w_j) \int \phi_i' \phi_j' dx \geq 0$$

$$\left(\frac{\partial w}{\partial z} \right)^T B (v - w) + w^T A (v - w) \geq 0 \Rightarrow w(v - w)^T \left[B \frac{\partial w}{\partial z} + A w \right] \geq 0$$

$$B = \int \phi_i \phi_j dx \quad A = \int \phi_i' \phi_j' dx$$

$$B^T = B \quad A = \int \phi_i' \phi_j' dx$$

$\textcircled{5}$ can be discretized by $\theta \in [0, 1]$ method

$$(v^{(n+1)} - w^{(n+1)}) \left[B \frac{1}{\Delta z} (w^{(n+1)} - w^{(n)}) + \theta A w^{(n+1)} + (1 - \theta) A w^{(n)} \right] \geq 0$$

rewritten as

$\theta = 0 \Rightarrow$ explicit

$\theta = \frac{1}{2} \Rightarrow$ CN

$$(v^{(n+1)} - w^{(n+1)}) \left[(B + \Delta z \theta A) w^{(n+1)} - (B - \Delta z (1 - \theta) A) w^{(n)} \right] \geq 0$$

$$r = (B - \Delta z (1 - \theta) A) w^{(n)}$$

$$C = B + \Delta z \theta A$$

$$(v^{(n+1)} - w^{(n+1)})^T (C w^{(n+1)} - r) \geq 0$$

$$y(x, z) \geq q(x, z)$$

$$\sum w_i(z_i) \phi_i(x) \geq q(x, z) \rightarrow \textcircled{*}$$

In order to incorporate the side condition $w_j(z) \geq g(x_j, z)$

Suppose statement holds for n

Let $q_1 = v_{\lambda, w_1}$ then $\|q_1\|_2 = 1$ and $Aq_1 = \lambda q_1$

Let $\{q_1, w_2, w_3, \dots, w_n\}$ be L.I. in \mathbb{C}^n .

Then let $S = [q_1, w_2, w_3, \dots, w_n] \in \mathbb{C}^{n \times n}$

$$\tilde{Q} = [q_1, q_1, \dots, q_n]$$

$$\tilde{Q}^* A \tilde{Q} = \begin{bmatrix} q_1^* \\ \vdots \\ q_n^* \end{bmatrix} A [q_1, \dots, q_n]$$

$$= \begin{bmatrix} q_1^* A q_1 & q_1^* A q_2 & \dots \\ q_2^* A q_1 & q_2^* A q_2 & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

$$\tilde{Q}^* A \tilde{Q} = \left[\begin{array}{c|c} \lambda q_1^* q_1 & * \\ \hline \lambda q_2^* q_1 & \tilde{A} \\ \vdots & \\ \lambda q_n^* q_1 & \end{array} \right] = \left[\begin{array}{c|c} \lambda & * \\ \hline 0 & \tilde{A} \end{array} \right] = \left[\begin{array}{c|c} \lambda & * \\ \hline 0 & \tilde{Q}_1^* \tilde{\tau} \tilde{Q}_1 \end{array} \right]$$

$$= \left[\begin{array}{c|c} 1 & \\ \hline & \tilde{Q}_1 \end{array} \right] \left[\begin{array}{c|c} \lambda & * \\ \hline & \tilde{\tau} \\ \vdots & \vdots \end{array} \right] \left[\begin{array}{c|c} * & \\ \hline & \tilde{Q}_1^* \end{array} \right]$$

If A is Hermitian $\rightarrow \tau$ is real diagonal.

If τ is real diagonal $\rightarrow A$ is Hermitian

Hermitian matrix have only real eigen values.

$$Av = \lambda v$$

FEM

$$r = (B - \Delta t(I - \theta)A)w^{(n)}$$

$$C := B + \Delta t \theta A$$

for all $v \geq q$

$$(v - w)^T (cw - r) \geq 0, w \geq q$$

$$\begin{cases} (v - w)^T (cw - r) \geq 0 \\ (v^T - w^T)(cw - r) \geq 0 \\ v^T cw - v^T r - w^T cw + w^T r \geq 0 \\ v^T cw - v^T r \geq w^T cw - w^T r \end{cases}$$

Assume w satisfies FDM.

$$(v - w)^T (cw - r) = (v - q)^T (cw - r) - (w - q)^T (cw - r) \geq 0$$

Assume w satisfies FEM

$$w \geq q$$

$$(v - w)^T (cw - r) \geq 0$$

$$v^T (cw - r) \geq w^T (cw - r)$$

Take $v = q$

$$(q - w)^T (cw - r) \geq 0$$

$$\Rightarrow (cw - r)^T (w - q) \leq 0$$

We know $w \geq q$. If we show $cw - r \geq 0$ then $(cw - r)^T (w - q) = 0$

Suppose k^{th} comp. of $cw - r$ is $-ve$.

If I take k^{th} comp. of v is as large as possible.

then k^{th} comp. of $v^T (cw - r)$ is too small which is a contradiction?

$$\therefore (cw - r) \geq 0.$$

FEM and FDM are giving the same solⁿ for the basis elements.

The implementation of FEM PSOR.

ADI Alternating direction implicit.

FDM

$$A = C, b = r$$

$$cw - r \geq 0, w \geq q$$

$$(cw - r)^T (w - q) = 0$$

If we discretize the PDEs corresponding to exotic q^u given in ① or the 2-D heat conduction given in ② by any implicit scheme like BTCS or the CN then the bandwidth of the matrix A ($AU=F$) will be large.

∴ It takes enormous CPU time & memory to solve the sys of linear algebraic eq^{ns}.

In order to overcome this computational complexities, one can use ADI (Alternating direction implicit scheme)

$$\begin{pmatrix} \diagup & & & \\ 0 & \diagdown & & \\ & \diagup & \diagdown & \\ & & \diagup & \diagdown & 0 \\ & & & \diagdown & \diagup \end{pmatrix} = \begin{pmatrix} \diagup & & & \\ 0 & \diagdown & & \\ & \diagup & \diagdown & \\ & & \diagup & \diagdown & 0 \end{pmatrix} + \begin{pmatrix} & & & \\ & & & \\ & & \textcircled{0} & \\ & & \textcircled{0} & \textcircled{0} \end{pmatrix}$$

$$t^n \rightarrow t^{n+1} \Rightarrow t^n \rightarrow t^{n+1/2} \rightarrow t^{n+1}$$

When we progress from t^n to t^{n+1} , we introduce $t^{n+1/2}$ and the whole scheme will be returned in the following manner

- i) $t^n \rightarrow t^{n+1/2}$ — α implicit & γ explicit or vice-versa
 ii) $t^{n+1/2} \rightarrow t^{n+1}$ — $\alpha \gamma$ " " " "

$$\frac{U_{lm}^{n+1/2} - U_{lm}^n}{(\delta t/2)} = \left(\frac{U_{lm}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l-1m}^{n+1/2}}{h^2} \right) + \left(\frac{U_{lm+1}^n - 2U_{lm}^n + U_{lm-1}^n}{h^2} \right) \quad \text{--- (3)}$$

$$\frac{U_{lm}^{n+1} - U_{lm}^{n+1/2}}{(\delta t/2)} = \left(\frac{U_{l+m}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l+1m}^{n+1/2}}{h^2} \right) + \left(\frac{U_{lm+1}^{n+1} - 2U_{lm}^{n+1} + U_{lm-1}^{n+1}}{h^2} \right)$$

Starting from the given initial conditions, solve ③. By using solⁿ of ③, solve ④.

In order to incorporate the side condition $w_j(z) \geq g_j(z)$

7/10/24 - Abgent

17/10/24 - Thuv

$$V(S, t) \rightarrow \frac{\partial V}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 V}{\partial S^2} + (r - \delta) S \frac{\partial V}{\partial S} - rV = 0 \rightarrow \text{Called I-O only although } S \text{ up + both are there}$$

$$V(S_1, S_2, t)$$

$$dS_1 = \mu_1 S_1 dt + \sigma_1 S_1 dW_1$$

$$dS_2 = \mu_2 S_2 dt + \sigma_2 S_2 dW_2$$

$$E(dW^{(1)}, dW^{(2)}) = r dt$$

$$\text{Cor} \left(\frac{dS_1}{S_1}, \frac{dS_2}{S_2} \right) = E(\sigma_1 dW^{(1)}, \sigma_2 dW^{(2)}) = \sigma_1 \sigma_2 dt$$

$$\frac{\partial V}{\partial t} + \frac{1}{2} \sum_{i,j=1}^n \rho_{ij} \sigma_i \sigma_j S_i S_j \frac{\partial^2 V}{\partial S_i \partial S_j} + \sum_{i=1}^n (r - \delta_i) S_i \frac{\partial V}{\partial S_i} - rV = 0$$

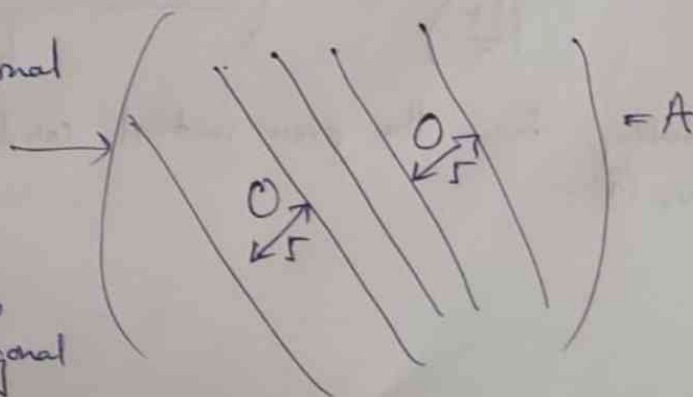
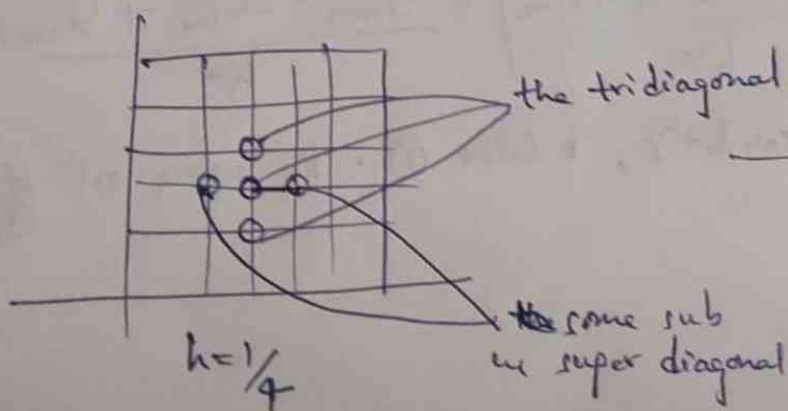
$$\Omega = (S_{\min}^1, S_{\max}^1) \times (S_{\min}^2, S_{\max}^2) \times \dots \times [0, T]$$

$$\frac{\partial V}{\partial t} + \frac{1}{2} \left(\sigma_1^2 S_1^2 \frac{\partial^2 V}{\partial S_1^2} + \sigma_2^2 S_2^2 \frac{\partial^2 V}{\partial S_2^2} + 2 \sigma_1 \sigma_2 S_1 S_2 \frac{\partial^2 V}{\partial S_1 \partial S_2} \right) \rightarrow ①$$

2D Parabolic PDE

$$\frac{\partial u}{\partial t} = \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \quad (x, y) \in (0, 1) \times (0, 1) \quad t \in [0, T]$$

$$\frac{U_{lm}^{n+1} - U_{lm}^n}{\delta t} = \left(\frac{U_{l+1,m}^{n+1} - 2U_{lm}^{n+1} + U_{l-1,m}^{n+1}}{h^2} \right) + \left(\frac{U_{l,m+1}^{n+1} - 2U_{lm}^{n+1} + U_{l,m-1}^{n+1}}{h^2} \right)$$



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Transform

$$V(S, A, t) = \tilde{V}(S, R, t) = SH(R, t)$$

$$R = \frac{A}{S}$$

$$V_t = SH_t$$

$$V_S = H + S \frac{\partial H}{\partial R} \left(-\frac{A}{S^2} \right) = H + \frac{\partial H}{\partial R} \left(-\frac{A}{S} \right)$$

$$V_{SS} = \frac{\partial H}{\partial R} \cdot \left(-\frac{A}{S^2} \right) + H_{RR} \left(-\frac{A}{S} \right) \left(-\frac{A}{S^2} \right) + \left(\frac{+A}{S^2} \right) H_R$$

$$V_A = \cancel{SH_R} \cdot \cancel{\frac{\partial R}{\partial A}} + SH_R \cdot \frac{\partial R}{\partial A} = \cancel{SH_R} \cdot \frac{1}{S}$$

$$SH_t + \frac{\sigma^2 S^2}{2} H_{RR} \cdot \frac{A^2}{S^3} + rS \left(H - H_R \left(\frac{A}{S} \right) \right) + SH_R - rSH = 0$$

$$H_t + \frac{\sigma^2}{2} R^2 H_{RR} - H_R R r + H_R = 0$$

$$\boxed{\frac{\partial H}{\partial t} + \frac{\sigma^2}{2} R^2 \frac{\partial^2 H}{\partial R^2} + (-rR) H_R = 0}$$

$$H(R, t) = \left(1 - \frac{1}{T} R t \right)^+$$

$$\text{As } R_T \rightarrow \infty, H = 0 \quad H(R_T, T) = 0$$

$$R_t = \frac{1}{S_t} \int_0^t S_\theta d\theta$$

The integral R_t is bdd. \therefore When $S \rightarrow 0$, $R \rightarrow \infty$

This is the European call option.

We cannot exercise the call option.

$$H \rightarrow 0 \text{ as } R \rightarrow \infty$$

$$\left. \frac{\partial H}{\partial R} \right|_{R=0} = \frac{3H_0'' + 4H_1'' - H_2''}{2\delta R} + O(\delta R^2)$$

Once we obtain H , we can obtain $V = SH$

When A_{t_k} is on discrete time intervals, then

$$A_{t_k} = \frac{1}{k} \sum_{i=1}^k S_{t_i} \quad k=1:M$$

$$A_{t_k} = \frac{(k-1)A_{t_{k-1}} + S_{t_k}}{k} = A_{t_{k-1}} + \frac{(S_{t_k} - A_{t_{k-1}})}{k}$$

$$A_{t_{k-1}} = \frac{kA_{t_k} - S_{t_k}}{k-1} = A_{t_k} - \frac{(S_{t_k} - A_{t_k})}{k-1}$$

We can observe that A_t is constant and it jumps at t_k with $\frac{(A_{t_k} - S_{t_k})}{k-1}$ in b^n time intervals

From no arbitrage

Jump at k^{th} step:

$$A^-(s) = A^+(s) + \frac{1}{k-1} (A^+(s) - s), \quad s = S_{t_k}$$

From no arbitrage principle we can, from the continuity of value of that optⁿ at t_k for any realizatⁿ of the random walk:-

$$V(s, A^+, t_k) = V(s, A^-, t_k)$$

For any fixed s, u, A , the equatⁿ defines the jump at t_k .

For the numerical calculatⁿ of this jump conditⁿ, if we discretize the A axis into A_1, A_2, \dots, A_J , then for each time period b^n two consecutive samplings, $t_{k+1} \rightarrow t_k$, the option value is independent of A bcz in the discretization of A_t , A_t is piecewise const. $\therefore \frac{\partial V}{\partial A} = 0$. So for each j , we get 1-D BS PDE.

$(j=1:J)$
each of them are independent of one another.

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$$dR_t = (1 + (r^2 - \mu)R_t) \cdot dt + \sigma R_t \cdot dW_t$$

$$dR_t \Big|_{t=0} = dt \quad R_t = 0$$

For the left hand bdy condⁿ, we face some difficulties.
For ex; if $R_0 = 0$, $dR_0 = dt$ by R_t won't remain at 0.
 \therefore We can't expect R_T to be zero.

\therefore To obtain the bdy condⁿ, we use the PDE directly.
At $R=0$, iff $\frac{\partial^2 H}{\partial R^2}$ is bdd (or H is bdd)

$$\frac{\partial H}{\partial t} + \frac{r^2 R^2}{2} \frac{\partial^2 H}{\partial R^2} + (1 - rR) \frac{\partial H}{\partial R} = 0$$

Suppose Claim: $R^2 \frac{\partial^2 H}{\partial R^2}$ is bdd as $R \rightarrow 0$

PT: Suppose $R^2 \frac{\partial^2 H}{\partial R^2} = c \Rightarrow \frac{\partial^2 H}{\partial R^2} = c \left(\frac{1}{R^2} \right)$

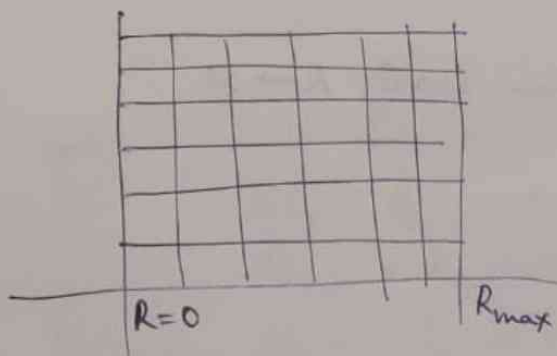
$$\frac{\partial^2 H}{\partial R^2} = \frac{c}{R^2}$$

$$H = -c \ln R + dR + e$$

As $R \rightarrow 0$, H is unbdd. \Rightarrow (we assumed H is bdd)

\therefore when $R=0$, $\frac{\partial H}{\partial t} + \frac{\partial H}{\partial R} = 0$, $R=0$

$$H(R_T, T) = \left(1 - \frac{R_T}{T}\right)^+$$



$$\frac{H_m^{n+1} - H_m^n}{\delta t} + \frac{H_{m+1}^{n+1} - H_m^{n+1}}{\delta R} = 0$$

$$\frac{\partial H}{\partial R} = \frac{H_{m+1}^n - H_m^n}{\delta R}$$

$$= D^+ D^+ H_m^n$$

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study

$$\begin{cases} dX(t) = a(t, X) \cdot dt + b(t, X) dW_t \\ X(0) = X_0 \end{cases}$$

$$\int_0^t dX(s) = \int_0^t a(s, X) \cdot ds + \int_0^t b(s, X) \cdot dW_s$$

$$X(t) - X(0) = \quad \quad \quad$$

$$dX = \mu X dt + \sigma X \cdot dW_t \rightarrow \textcircled{1}$$

$$\frac{dX}{X} = \mu \cdot dt + \sigma dW_t$$

$$d(\ln X) = \frac{1}{X} \cdot dX - \frac{1}{2} X^2 \cdot \sigma^2 X^2$$

$$= \frac{1}{X} \cdot dX - \frac{\sigma^2}{2} \cdot dt$$

$$d(\ln X) = \left(\mu - \frac{\sigma^2}{2} \right) \cdot dt + \sigma dW_t$$

$$\int_a^b f(x) \cdot dW_t = \sum_{i=0}^n f(t_{i-1}) \delta W_i \quad \delta W_i = W_{t_{i+1}} - W_{t_i} = z_i \sqrt{\Delta t}$$

$$= \cancel{x_i} \sqrt{\Delta t}$$

$$Y = f(t, X)$$

$$dY = f_t \cdot dt + f_x \cdot dX + \frac{1}{2} f_{xx} \cdot (dX)^2$$

where $dX \cdot dX$ can be interpreted using

$$\begin{array}{cc} & dt & dW_t \\ dt & 0 & 0 \\ dW_t & 0 & dt \end{array}$$

The solⁿ of BS diffusion eqⁿ $\textcircled{1}$,

$$\text{is } \therefore X = X_0 \exp \left\{ \left(\mu - \frac{\sigma^2}{2} \right) t + \sigma W_t \right\}$$

In principle, it is difficult to obtain closed form analytical solⁿ for SDEs. \therefore One has to seek numerical solⁿ

Glasserman 6th chapter (or Leydel 3rd chapter)

Euler

$$y'(t) = f(t, y), \quad t \in (0, 1)$$

$$y(0) = x$$

$$\frac{y_{n+1} - y_n}{h} = f(t_n, y_n)$$

T.E (Truncatⁿ error)

$$= LHC - RHC$$

Euler - Maruyama

$$dX(t) = a(t, X(t)) dt + b(t, X(t)) dW_t$$

$$X(0) = X_0$$

$$t \in [0, T]$$

$$h = \frac{T}{N}$$

$$\int_{t_n}^{t_{n+1}} dX(s) = \int_{t_n}^{t_{n+1}} a(s, X(s)) ds + \int_{t_n}^{t_{n+1}} b(s, X(s)) dW(s)$$

$$X(t_{n+1}) - X(t_n)$$

$$= a(t_n, X_n) \Delta t$$

$$+ b(t_n, X_n) \Delta W_{n+1}$$

$$Z_i \in N(0, 1)$$

$$\Delta W_{n+1} = Z_i \sqrt{\Delta t}$$

But of GBM, the order of Euler-Maruyama scheme get diminished by $\frac{1}{2}$. TE of

All the schemes like Runge-Kutta, Adam's etc can be done in stochastic case also.

$$\frac{1}{\sigma} = \log \Leftrightarrow \sigma = \log \Leftrightarrow \log = \sigma$$

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$X(t)$

Euler Maruyama is $O(\sqrt{h}) < O(h)$ (of Euler-scheme) as the order got diminished due to approximation of diffusion term. In order to enhance the order, we have to consider more no of terms in Brownian eqⁿ.

$$X(t+h) = X(t) + a(X(t))h + \underbrace{b(X(t)) [W(t+h) - W(t)]}_{O(\sqrt{h})}$$

$$db(X(t)) = \cancel{b_t dt} + b_x dX + \frac{1}{2} b_{xx} dX \cdot dX$$

$$= b'(X(t)) \cdot dX(t) + \frac{1}{2} b''(X(t)) b^2(X(t)) dt$$

$$= b'(X(t)) \left[a(X(t)) dt + b(X(t)) dW_t \right]$$

$$+ \frac{1}{2} b''(X(t)) b^2(X(t)) dt$$

$$= \left[a b' + \frac{1}{2} b'' b^2 \right] \cdot dt + \underbrace{b b'}_{\sigma_b} dW_t$$

$[t, t+h], t \leq u \leq t+h$

$$b(X(u)) \approx b(X(t)) + \underbrace{\mu_b(X(t)) [u-t]}_{O(u-t)} + \underbrace{\sigma_b [W(u) - W(t)]}_{O(h)}$$

$\therefore W(u) - W(t)$ is of order of $\sqrt{u-t}$

\therefore We want to retain the 1st order convergence of Euler-scheme, we drop $\mu_b(X(t)) [u-t]$ as we use $\sigma_b [W(u) - W(t)]$

$$b(X(u)) \approx b(X(t)) + \sigma_b [W(u) - W(t)]$$

$$\int_0^t dX(t) = \int_0^t a(X(u)) \cdot du + \int_0^t b(X(u)) \cdot dW_u$$

\therefore The integral in $\int_t^{t+h} b(X(u)) \cdot dW_u = \int_t^{t+h} \left(b(X(t)) + \sigma_b [W(u) - W(t)] \right) dW_u$

\equiv

$$\begin{aligned}
 \int_t^{t+h} b(X(u)) \cdot dW_u &= \int_t^{t+h} (b(X(t)) + \sigma_b(X(t))) \cdot dW_u \\
 &= b(X(t)) [W(t+h) - W(t)] + \sigma_b(X(t)) \int_t^{t+h} (W(u) - W(t)) \cdot dW_u \\
 &= \text{"} + \frac{\sigma_b(X(t))}{2} \int_t^{t+h} W(u) \cdot dW_u - \sigma_b(X(t)) W(t) (W(t+h) - W(t)) \\
 &= \text{"} + \frac{\sigma_b(X(t))}{2} \int_t^{t+h} W(u) \cdot dW_u - \sigma_b(X(t)) W(t) (W(t+h) - W(t))
 \end{aligned}$$

$$Y(t) = \int_0^t W(u) \cdot dW_u$$

$$Y(0) = 0$$

$$dY(t) = W(t) \cdot dW_t$$

$$Y(t) = \frac{1}{2} W^2(t) - \frac{1}{2} t$$

$$\begin{aligned}
 &= \text{"} + \frac{\sigma_b}{2} [W^2(t) - W^2(t+h)] - \frac{\sigma_b}{2} h \\
 &= \text{"} + \frac{1}{2} b b' \left[\underbrace{(W(t+h) - W(t))^2}_{h Z_i^2} - h \right]
 \end{aligned}$$

$$X(t+h) = a(X(t))h + b(X(t)) \underbrace{[W(t+h) - W(t)]}_{\sqrt{h} Z_i} + \frac{1}{2} b b' \left\{ \underbrace{[W(t+h) - W(t)]^2}_{h Z_i^2} - h \right\}$$

Convergence
Truncation error (in random walk case):

$$E[\|X(T) - \hat{X}(t_n)\|] \leq Ch^p \rightarrow \text{strong sense}$$

$$E[\|E(X(T)) - E(\hat{X}(t_n))\|] \leq \rightarrow \text{weak sense}$$

$$\{\hat{X}(0), \hat{X}(h), \hat{X}(2h), \dots, \hat{X}_n\} \quad n = \lfloor \frac{T}{h} \rfloor$$

$$\left. \begin{aligned} \mathbb{E}[\|\hat{X}(nh) - X(T)\|] &\leq ch^{\beta} \mathbb{E}(\|\hat{X}(nh) - X(T)\|^2) \\ \mathbb{E}\left[\sup_{0 \leq t \leq T} \|\hat{X}(\lfloor \frac{t}{h} \rfloor h) - X(t)\| \right] \end{aligned} \right\} \text{Strong}$$

$$f \in \mathcal{C}_p^{2\beta+2}$$

\mathcal{C}_p - polynomial

$$\|\mathbb{E}(f(\hat{X}(nh)) - \mathbb{E}(f(X(T)))\| \leq ch^{\beta} \text{Weak} \quad \textcircled{2}$$

depends on the polynomial f

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$f \in \mathcal{C}_p^{2\beta+2}$ consists of $f: \mathbb{R}^d \rightarrow \mathbb{R}$ whose derivatives of order $0, 1, \dots, 2\beta+2$ are polynomially bounded.

Lower order in strong convergence can be higher order in weaker sense.

We can extend 1-D to 2-D:-

$$dX_1(t) = a(X_1(t)) \cdot dt + b(X_1(t)) \cdot dW_t$$

$$dX_2(t) = a(X_2(t)) \cdot dt + b(X_2(t)) \cdot dW_t$$

Second-order scheme

H.W

$$\mathcal{L}^0 := a \frac{d}{dx} + \frac{1}{2} b^2 \frac{d^2}{dx^2}$$

$$\mathcal{L}^1 := b \cdot \frac{d}{dx}$$

$$X(t+h) = X(t) + \underbrace{\int_t^t a(X(u)) \cdot du}_{=0} + \int_t^{t+h} b(X(u)) \cdot dW_u$$

$$\begin{aligned} \textcircled{*} a(X(u)) &= a(X(t)) + \int_t^u \mathcal{L}^0(a(X(s))) \cdot ds + \int_t^u \mathcal{L}^1(a(X(s))) \cdot dW_s \\ &= a(X(t)) + \mathcal{L}^0 a(X(t)) \underbrace{\int_t^u ds}_{=h} + \mathcal{L}^1 a(X(t)) \cdot \int_t^u dW_s \end{aligned}$$

$$\textcircled{*} b(X(u)) = b(X(t))$$

$$\begin{aligned} \cancel{X(t+h)} &= X(t) + h a(X(t)) + \mathcal{L}^0 a(X(t)) h \\ X(t+h) &= X(t) + \int_t^{t+h} a(X(t)) \cdot du + \mathcal{L}^0 a(X(t)) \int_t^{t+h} \int_t^u ds \cdot du \\ &\quad + \mathcal{L}^1 a(X(t)) \int_t^{t+h} \int_t^u dW(s) \cdot du \\ &\quad + \int_t^{t+h} b(X(t)) \cdot du + \int_t^{t+h} W_b \cdot du \end{aligned}$$

& double integrals you have to evaluate

Ex CIBOR

$$6.21) \frac{dL_i(t)}{dt} = L_i(t) \mu_i(L(t), t) + L_i(t) \sigma_i(t)^T dW(t)$$

6.22) Stochastic Volatility Model