

Convergence of QR Algorithm

Invariant Subspaces

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Examples:

1. For $A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & -2 & 0 \\ 1 & 1 & -1 \end{bmatrix}$, $A(\text{span}\{e_1, e_3\}) \subseteq \text{span}\{e_1, e_3\}$.

2. For $A = \begin{bmatrix} 4 & 3 & -5 \\ 0 & -3 & 3 \\ 0 & -2 & 3 \end{bmatrix}$, $A(\text{span}\{e_1\}) \subseteq \text{span}\{e_1\}$ and
 $A(\text{span}\{e_1 + e_2 + e_3, e_1 - e_2\}) \subseteq \text{span}\{e_1 + e_2 + e_3, e_1 - e_2\}$.

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Facts:

1. The trivial subspaces \mathbb{F}^n and $\{0\}$ are always invariant with respect to every $A \in \mathbb{F}^{n \times n}$.
2. $V \subseteq \mathbb{F}^n$ is a one dimensional subspace of \mathbb{F}^n invariant with respect to $A \in \mathbb{F}^{n \times n}$ if and only if $V = \text{span}\{v\}$ for some eigenvector v of A .
3. Eigenvectors of $A \in \mathbb{F}^{n \times n}$ span invariant subspaces.

Invariant Subspaces

Theorem: Let $A \in \mathbb{F}^{n \times n}$. The first k columns of an invertible $S \in \mathbb{F}^{n \times n}$ span a subspace of \mathbb{F}^n invariant with respect to A if and only if

$$S^{-1}AS = \left[\begin{array}{c|c} A_{11} & A_{12} \\ \hline & A_{22} \end{array} \right]$$

where $A_{11} \in \mathbb{F}^{k \times k}$, $A_{12} \in \mathbb{F}^{k \times n-k}$ and $A_{22} \in \mathbb{F}^{n-k \times n-k}$.

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Corollary: Let $A \in \mathbb{F}^{n \times n}$ and $S = [s_1 \ \cdots \ s_n] \in \mathbb{F}^{n \times n}$ be a invertible matrix. Then the first k columns of S span subspaces of \mathbb{F}^n that are invariant with respect to A for each $k = 1, \dots, n-1$, if and only if $S^{-1}AS$ is an upper triangular matrix.

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Schur's Theorem: Given $A \in \mathbb{C}^{n \times n}$, there exists an orthonormal basis $\{q_1, \dots, q_n\}$ of \mathbb{C}^n such that

$$A(\text{span}\{q_1, \dots, q_k\}) \subseteq \text{span}\{q_1, \dots, q_k\}$$

for each $k = 1, \dots, n-1$.

Subspace Iteration

Given $A \in \mathbb{F}^{n \times n}$, recall that the Power Method is essentially about producing a series of vectors

$$x, Ax, A^2x, \dots$$

which under suitable scaling converges to a dominant eigenvector of A under suitable conditions.

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The scalings will replace x by other vectors in $\mathcal{S} := \text{span}\{x\}$ and depending on their choices the iterations will converge to some vector in the one dimensional invariant eigenspace $\mathcal{T} := \text{span}\{v\}$ where v is a dominant eigenvector of A .

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We could do this for higher dimensional subspaces \mathcal{S} !

Subspace iteration, Simultaneous iteration and the QR algorithm

Principal angles and distance between subspaces

Let $\mathcal{S}_1, \mathcal{S}_2$ be two subspaces of \mathbb{F}^n with $\dim \mathcal{S}_1 = l$, $\dim \mathcal{S}_2 = m$ where $l \leq m$.

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$$\sigma_1 \geq \cdots \geq \sigma_l \geq 0$$

are the singular values of $U_2^T U_1$ then the **principal angles between \mathcal{S}_1 and \mathcal{S}_2** are defined as

$$\theta_i = \arccos \sigma_i, \quad i = 1, \dots, l.$$

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Given a subspace \mathcal{T} and sequence of subspaces $\{\mathcal{S}_m\}$ of \mathbb{F}^n ,

$$\lim_{m \rightarrow \infty} \mathcal{S}_m = \mathcal{T} \Leftrightarrow d(\mathcal{S}_m, \mathcal{T}) \rightarrow 0 \text{ as } m \rightarrow \infty.$$

Convergence in Subspace iterations

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Let $\{v_1, \dots, v_n\}$ be a basis of \mathbb{F}^n where $Av_i = \lambda_i v_i$, $i = 1, \dots, n$.

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Then for *any* subspace \mathcal{S} of \mathbb{F}^n such that $\dim \mathcal{S} = k$, and $\mathcal{S} \cap \mathcal{U}_k = \{0\}$,

$$\lim_{m \rightarrow \infty} A^m(\mathcal{S}) = \mathcal{T}_k$$

linearly at the rate $|\lambda_{k+1}|/|\lambda_k|$.

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Exercise: Since $|\lambda_k| > |\lambda_{k+1}|$, prove the following:

(a) $\text{Null}(A^m) \subseteq \mathcal{U}_k$ for all $m = 1, 2, \dots$

(b) $\dim A^m(\mathcal{S}) = k$ for all $m = 1, 2, \dots$

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- (ii) Orthonormalize $Aq_1^{(m)}, \dots, Aq_k^{(m)}$ to form an orthonormal basis $q_1^{(m+1)}, \dots, q_k^{(m+1)}$ of $A^{m+1}(S)$.

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In particular if A is upper Hessenberg and the unitary Q_m are such that A_m are also always upper Hessenberg, then $a_{k+1,k}^{(m)}$ is the only nonzero entry of $A_{12}^{(m)}$ and

$$\lim_{m \rightarrow \infty} |a_{k+1,k}^{(m)}| = 0 \Leftrightarrow \lim_{m \rightarrow \infty} A^m(S) = \mathcal{T}_k.$$

For either limits, the convergence is linear at the rate $|\lambda_{k+1}|/|\lambda_k|$.

Simultaneous iterations in subspace iterations

For each $j = 1, \dots, m-1$, $q_1^{(m)}, \dots, q_j^{(m)}$ is an orthonormal basis of $A^m(\text{span}\{q_1^{(0)}, \dots, q_j^{(0)}\})$

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So if for each $j = 1, \dots, k$,

$$|\lambda_j| > |\lambda_{j+1}| \text{ and } \text{span}\{q_1^{(0)}, \dots, q_j^{(0)}\} \cap \text{span}\{v_{j+1}, \dots, v_n\} = \{0\},$$

then *for large enough* m ,

$$\{q_1^{(m)}, \dots, q_k^{(m)}\},$$

is *nearly* an orthonormal basis of the invariant subspace \mathcal{T}_k with respect to A with the *additional* property that for each $j = 1, \dots, k-1$,

$$\{q_1^{(m)}, \dots, q_j^{(m)}\},$$

are *nearly* orthonormal bases of j -dimensional invariant subspaces $\text{span}\{v_1, \dots, v_j\}$ with respect to A .

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Due to Schur's Theorem, this is equivalent to finding an orthonormal basis q_1, \dots, q_n of \mathbb{C}^n such that q_1, \dots, q_j is an orthonormal basis of an invariant subspace of \mathbb{C}^n with respect to A for each $j = 1, \dots, n-1$.

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To check the progress of the simultaneous iterations set

$Q_m = \begin{bmatrix} q_1^{(m)} & \cdots & q_n^{(m)} \end{bmatrix}$ and check if $A_m := Q_m^* A Q_m$ is getting close to an upper triangular matrix.

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- (ii) compute the Q of a QR decomposition of AQ_0 .

QR algorithm and Simultaneous iterations

If we choose the basis of the columns of Q_0 , A and q_1, \dots, q_n get replaced by their representations in the new basis.

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So the iteration is

- (i) find $Q_0^* A Q_0 (Q_0^* q_1) [= A_1 e_1], \dots, Q_0^* A Q_0 (Q_0^* q_n) [= A_1 e_n]$,
that is, consider A_1 ;
- (ii) compute the Q , say Q_1 , of a QR decomposition of A_1 .

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Feeling very optimistic about the progress, we form $A_2 = Q_1^* A_1 Q_1$.

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This completes the second iteration of the QR algorithm!

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This completes the second iteration of the QR algorithm!

Now we have the choice of performing the next iteration in three different bases, viz., e_1, \dots, e_n , the columns of Q_0 or the columns of Q_1 . If we choose the last option then the third iteration is

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i.e., consider A_2 ;
- (ii) compute the Q , say Q_2 , of a QR decomposition of A_2 .

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i.e., consider A_2 ;
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To check for convergence form $A_3 := Q_2^* A_2 Q_2$.

This the third iteration of the QR algorithm!

QR algorithm and Simultaneous iterations

If we choose the basis of the columns of Q_0 , A and q_1, \dots, q_n get replaced by their representations in the new basis.

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that is, consider A_1 ;
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Now we have the choice of performing the next iteration in three different bases, viz., e_1, \dots, e_n , the columns of Q_0 or the columns of Q_1 . If we choose the last option then the third iteration is

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i.e., consider A_2 ;
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This the third iteration of the QR algorithm!

Hence QR algorithm executes Simultaneous iteration with suitable change of basis at each iteration.