tf_echo output

kamakshi@kamakshi-ZenBook-Pro-15-UX550GE-UX550GE:~/catkin_ws$ rosrun tf tf_echo world talk

At time 1573185893.564
- Translation: [1.000, 2.000, 3.000]
- Rotation: in Quaternion [0.382, 0.596, -0.381, 0.595]
        in RPY (radian) [3.140, 1.570, 2.000]
        in RPY (degree) [179.909, 89.954, 114.592]
At time 1573185894.264
- Translation: [1.000, 2.000, 3.000]
- Rotation: in Quaternion [0.382, 0.596, -0.381, 0.595]
        in RPY (radian) [3.140, 1.570, 2.000]
        in RPY (degree) [179.909, 89.954, 114.592]
At time 1573185895.264
- Translation: [1.000, 2.000, 3.000]
- Rotation: in Quaternion [0.382, 0.596, -0.381, 0.595]
        in RPY (radian) [3.140, 1.570, 2.000]
        in RPY (degree) [179.909, 89.954, 114.592]
At time 1573185896.264

rqt_tf_tree output