```
In [1]: # This Python 3 environment comes with many helpful analytics libraries installed
        # It is defined by the kaggle/python Docker image: https://github.com/kaggle/docker-pyt/
        # For example, here's several helpful packages to load
        import numpy as np # linear algebra
        import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
        # Input data files are available in the read-only "../input/" directory
        # For example, running this (by clicking run or pressing Shift+Enter) will list all file
        import os
        for dirname, _, filenames in os.walk('/kaggle/input'):
            for filename in filenames:
                print(os.path.join(dirname, filename))
        # You can write up to 20GB to the current directory (/kaggle/working/) that gets preser
        # You can also write temporary files to /kaggle/temp/, but they won't be saved outside \epsilon
        /kaggle/input/dogs-vs-cats/test1.zip
        /kaggle/input/dogs-vs-cats/train.zip
        /kaggle/input/dogs-vs-cats/sampleSubmission.csv
        Data
In [2]:
        import os
        import zipfile
```

```
In [2]: import os import zipfile import pandas as pd from tqdm import tqdm import tensorflow as tf import matplotlib.pyplot as plt import matplotlib.image as mping from tensorflow.keras.optimizers import RMSprop
In [3]: work_path = './cats_and_dogs_filtered' os.mkdir(work_path)

In [4]: local_zip = '../input/dogs-vs-cats/test1.zip' zip_ref = zipfile.ZipFile(local_zip,'r') zip_ref.extractall(work_path)

local_zip = '../input/dogs-vs-cats/train.zip' zip_ref = zipfile.ZipFile(local_zip,'r') zip_ref.extractall(work_path)

zip_ref.close()
```

```
In [5]: train_path = os.path.join(work_path, 'train')
test_path = os.path.join(work_path, 'test1')
```

```
In [6]: train_df = pd.DataFrame({'image_name':os.listdir(train_path)})
    train_df['label'] = train_df['image_name'].apply(lambda x: x.split('.')[0])
    train_df

Out[6]: image_name label
```

```
0
          cat.2364.jpg
                          cat
    1
          cat.4566.jpg
                          cat
    2
          cat.2311.jpg
                          cat
    3
          dog.4811.jpg
          dog.2935.jpg
    4
                          dog
          cat.4039.jpg
24995
                          cat
24996
          cat.5098.jpg
                          cat
24997
           cat.591.jpg
                          cat
24998
          cat.5809.jpg
                          cat
24999
        dog.10160.jpg
                          dog
```

25000 rows × 2 columns

```
In [7]: test_df = pd.DataFrame({'image_name':os.listdir(test_path)})
   test_df['label'] =test_df['image_name'].apply(lambda x: x.split('.')[0])
   test_df
```

Out[7]: image_name label 0 8791.jpg 8791 1 10695.jpg 10695 2 8333.jpg 8333 3 6525.jpg 6525 4 6482.jpg 6482 12495 6756.jpg 6756 12496 6487.jpg 6487 12497 7640.jpg 7640 12498 2117.jpg 2117 12499 899.jpg 899

12500 rows × 2 columns

```
In [8]: dog_path_train = os.path.join(train_path, 'dog')
    os.mkdir(dog_path_train)
    dog_df_train = train_df[train_df.label=='dog']
    for n in tqdm(dog_df_train.image_name):
        os.rename((os.path.join(train_path, n)), (os.path.join(dog_path_train, n)))
```

100%| | 33887.98it/s

```
In [9]: cat_path_train = os.path.join(train_path, 'cat')
         os.mkdir(cat_path_train)
         cat_df_train = train_df[train_df.label=='cat']
         for n in tqdm(cat_df_train.image_name):
             os.rename((os.path.join(train_path, n)), (os.path.join(cat_path_train, n)))
               | 12500/12500 [00:00<00:00, 37334.26it/s]
In [10]: #check
         base_dir = './cats_and_dogs_filtered'
         print(' Contents of base directory')
         print(os.listdir(base_dir))
         print('\n Contents of Train directory')
         train_path = f'{base_dir}/train'
         print(os.listdir(train_path))
         print('\n Contents of validation directory')
         print(os.listdir(test_path)[:5])
          Contents of base directory
         ['train', 'test1']
          Contents of Train directory
         ['dog', 'cat']
          Contents of validation directory
         ['8791.jpg', '10695.jpg', '8333.jpg', '6525.jpg', '6482.jpg']
In [11]: train dir = os.path.join(base dir, 'train')
         validation_dir = os.path.join(base_dir,'test1')
         train_cats_dir = os.path.join(train_dir,'cat')
         train_dogs_dir = os.path.join(train_dir,'dog')
In [12]: | train_cats_names = os.listdir(train_cats_dir)
         train dogs names = os.listdir(train dogs dir)
         print(train_cats_names[:5])
         print(train dogs names[:5])
         ['cat.2364.jpg', 'cat.4566.jpg', 'cat.2311.jpg', 'cat.3824.jpg', 'cat.5978.jpg']
         ['dog.4811.jpg', 'dog.2935.jpg', 'dog.2309.jpg', 'dog.1948.jpg', 'dog.2809.jpg']
In [13]: #number
         print(f'numbers of cats in training set = {len(train cats names)}')
         print(f'numbers of dogs in training set = {len(train_dogs_names)}')
         print(f'numbers of cats and dogs in validation set = {len(os.listdir(validation_dir))}']
         numbers of cats in training set = 12500
         numbers of dogs in training set = 12500
         numbers of cats and dogs in validation set = 12500
```

```
In [14]: #image 확인
         %matplotlib inline
         nrows = 4
         ncols = 4
         pic_index = 0
         fig = plt.gcf()
         fig.set_size_inches(nrows*4,ncols*4)
         next_cat_pic = [os.path.join(train_cats_dir,fname) for fname in train_cats_names[pic_in(
         next_dog_pic = [os.path.join(train_dogs_dir,fname) for fname in train_dogs_names[pic_in(
         for i ,img_path in enumerate(next_cat_pic+next_dog_pic):
             sp = plt.subplot(nrows,ncols,i+1)
             sp.axis('off')
             img = mpimg.imread(img_path)
             plt.imshow(img)
         plt.show()
```

















Model

```
In [15]: def create_model():
           model = tf.keras.models.Sequential([
             tf.keras.layers.Conv2D(16,(3,3), activation = 'relu', input_shape=(150,150,3)),
             tf.keras.layers.MaxPooling2D(2,2),
             tf.keras.layers.Conv2D(32,(3,3), activation = 'relu'),
             tf.keras.layers.MaxPooling2D(2,2),
             tf.keras.layers.Conv2D(64,(3,3), activation = 'relu'),
             tf.keras.layers.MaxPooling2D(2,2),
             tf.keras.layers.Flatten(),
             tf.keras.layers.Dense(512, activation = 'relu'),
             tf.keras.layers.Dense(1, activation='sigmoid')
           ])
           model.compile(optimizer=RMSprop(lr=0.001),
                         loss='binary_crossentropy',
                         metrics=['accuracy'])
           return model
```

```
In [16]: | model = create_model()
         model.summary()
         2022-05-15 16:25:50.260096: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93
         7] successful NUMA node read from SysFS had negative value (-1), but there must be at
         least one NUMA node, so returning NUMA node zero
         2022-05-15 16:25:50.371942: I tensorflow/stream executor/cuda/cuda gpu executor.cc:93
         7] successful NUMA node read from SysFS had negative value (-1), but there must be at
         least one NUMA node, so returning NUMA node zero
         2022-05-15 16:25:50.372922: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93
         7] successful NUMA node read from SysFS had negative value (-1), but there must be at
         least one NUMA node, so returning NUMA node zero
         2022-05-15 16:25:50.374218: I tensorflow/core/platform/cpu_feature_guard.cc:142] This
         TensorFlow binary is optimized with oneAPI Deep Neural Network Library (oneDNN) to use
         the following CPU instructions in performance-critical operations: AVX2 AVX512F FMA
         To enable them in other operations, rebuild TensorFlow with the appropriate compiler f
         lags.
         2022-05-15 16:25:50.374557: I tensorflow/stream executor/cuda/cuda gpu executor.cc:93
         7] successful NUMA node read from SysFS had negative value (-1), but there must be at
         least one NUMA node, so returning NUMA node zero
         2022-05-15 16:25:50.375342: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93
         7] successful NUMA node read from SysFS had negative value (-1), but there must be at
         least one NUMA node, so returning NUMA node zero
         2022-05-15 16:25:50.376079: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93
```

2022-05-15 16:25:50.376079: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93 7] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-05-15 16:25:52.560239: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93 7] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-05-15 16:25:52.561257: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93 7] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-05-15 16:25:52.562053: I tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:93 7] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-05-15 16:25:52.563342: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1510] C reated device /job:localhost/replica:0/task:0/device:GPU:0 with 15403 MB memory: -> d evice: 0, name: Tesla P100-PCIE-16GB, pci bus id: 0000:00:04.0, compute capability: 6.

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 148, 148, 16)	448
max_pooling2d (MaxPooling2D)	(None, 74, 74, 16)	0
conv2d_1 (Conv2D)	(None, 72, 72, 32)	4640
max_pooling2d_1 (MaxPooling2	(None, 36, 36, 32)	0
conv2d_2 (Conv2D)	(None, 34, 34, 64)	18496
max_pooling2d_2 (MaxPooling2	(None, 17, 17, 64)	0
flatten (Flatten)	(None, 18496)	0
dense (Dense)	(None, 512)	9470464
dense_1 (Dense)	(None, 1)	513
T-t-1 0 404 561	=======================================	========

Total params: 9,494,561 Trainable params: 9,494,561

```
Non-trainable params: 0
         /opt/conda/lib/python3.7/site-packages/keras/optimizer_v2/optimizer_v2.py:356: UserWar
         ning: The `lr` argument is deprecated, use `learning_rate` instead.
           "The `lr` argument is deprecated, use `learning_rate` instead.")
In [17]: #이미지전처리
         from tensorflow.keras.preprocessing.image import ImageDataGenerator
         train_datagen = ImageDataGenerator(rescale=1./255,
               rotation_range=40,
               width shift range=0.2,
               height_shift_range=0.2,
               shear_range=0.2,
               zoom_range=0.2,
               horizontal_flip=True,
               fill_mode='nearest',
               validation_split=0.2
         train_generator = train_datagen.flow_from_directory(
             train dir,
             target_size=(150,150),
             batch_size=50,
             class_mode='binary',
             subset='training'
         )
         validation generator = train datagen.flow from directory(
             train_dir, # same directory as training data
             target_size=(150, 150),
             batch_size=50,
             class_mode='binary',
             subset='validation')
```

```
Found 20000 images belonging to 2 classes. Found 5000 images belonging to 2 classes.
```

```
In [18]: class mycallback(tf.keras.callbacks.Callback):
    def on_epoch_end(self,epoch,logs={}):
        if(logs.get('val_accuracy')>=0.90):
            self.model.stop_training = True
callback = mycallback()
```

Training

```
In [19]: history = model.fit(
          train generator,
          steps per epoch = train generator.samples//50,#batch size,
          epochs = 30,
          verbose=1,
          validation_data = validation_generator,
          validation_steps = validation_generator.samples//50,#batch_size,
          callbacks=[callback]
       )
       2022-05-15 16:25:55.805190: I tensorflow/compiler/mlir/mlir graph optimization pass.c
       c:185] None of the MLIR Optimization Passes are enabled (registered 2)
       Epoch 1/30
       2022-05-15 16:25:57.927405: I tensorflow/stream_executor/cuda/cuda_dnn.cc:369] Loaded
       cuDNN version 8005
       0.6075 - val loss: 0.5825 - val accuracy: 0.7028
       Epoch 2/30
       400/400 [============== ] - 216s 539ms/step - loss: 0.5991 - accuracy:
       0.6782 - val loss: 0.5586 - val accuracy: 0.6972
       Epoch 3/30
       0.7054 - val_loss: 0.5299 - val_accuracy: 0.7314
       400/400 [============= ] - 217s 540ms/step - loss: 0.5403 - accuracy:
       0.7287 - val loss: 0.5360 - val accuracy: 0.7230
       Epoch 5/30
       400/400 [============== ] - 217s 542ms/step - loss: 0.5253 - accuracy:
       0.7383 - val_loss: 0.4996 - val_accuracy: 0.7584
       Epoch 6/30
       400/400 [============= ] - 217s 542ms/step - loss: 0.5131 - accuracy:
       0.7442 - val loss: 0.5276 - val accuracy: 0.7336
       Epoch 7/30
       400/400 [=============== ] - 218s 545ms/step - loss: 0.5009 - accuracy:
       0.7580 - val_loss: 0.4924 - val_accuracy: 0.7634
       Epoch 8/30
       400/400 [============= ] - 220s 551ms/step - loss: 0.4883 - accuracy:
       0.7666 - val loss: 0.4596 - val accuracy: 0.7784
       Epoch 9/30
       0.7735 - val loss: 0.4295 - val accuracy: 0.8036
       Epoch 10/30
       400/400 [============== ] - 223s 557ms/step - loss: 0.4688 - accuracy:
       0.7784 - val loss: 0.4398 - val accuracy: 0.7966
       Epoch 11/30
       400/400 [============== ] - 221s 551ms/step - loss: 0.4609 - accuracy:
       0.7871 - val_loss: 0.4554 - val_accuracy: 0.7858
       Epoch 12/30
       400/400 [============= ] - 222s 554ms/step - loss: 0.4586 - accuracy:
       0.7864 - val loss: 0.4958 - val accuracy: 0.7546
       Epoch 13/30
       0.7940 - val_loss: 0.4062 - val_accuracy: 0.8128
       Epoch 14/30
       400/400 [============= ] - 222s 555ms/step - loss: 0.4331 - accuracy:
       0.8012 - val_loss: 0.4581 - val_accuracy: 0.7854
       Epoch 15/30
       400/400 [=============== ] - 224s 559ms/step - loss: 0.4224 - accuracy:
       0.8083 - val_loss: 0.4109 - val_accuracy: 0.8086
       Epoch 16/30
       400/400 [============= ] - 225s 562ms/step - loss: 0.4194 - accuracy:
       0.8076 - val_loss: 0.4474 - val_accuracy: 0.7950
       Epoch 17/30
```

```
0.8118 - val loss: 0.3881 - val accuracy: 0.8236
Epoch 18/30
400/400 [============= ] - 224s 560ms/step - loss: 0.4122 - accuracy:
0.8159 - val_loss: 0.4182 - val_accuracy: 0.8102
Epoch 19/30
400/400 [============ ] - 222s 555ms/step - loss: 0.4095 - accuracy:
0.8165 - val_loss: 0.3832 - val_accuracy: 0.8344
Epoch 20/30
400/400 [============== ] - 231s 577ms/step - loss: 0.3978 - accuracy:
0.8224 - val_loss: 0.3972 - val_accuracy: 0.8264
Epoch 21/30
400/400 [============== ] - 228s 568ms/step - loss: 0.4025 - accuracy:
0.8227 - val loss: 0.3812 - val accuracy: 0.8320
Epoch 22/30
400/400 [=============== ] - 228s 569ms/step - loss: 0.3969 - accuracy:
0.8257 - val_loss: 0.3711 - val_accuracy: 0.8380
Epoch 23/30
400/400 [============ ] - 230s 574ms/step - loss: 0.3959 - accuracy:
0.8281 - val loss: 0.3717 - val accuracy: 0.8426
Epoch 24/30
400/400 [============== ] - 229s 572ms/step - loss: 0.3872 - accuracy:
0.8299 - val_loss: 0.4125 - val_accuracy: 0.8234
Epoch 25/30
400/400 [============= ] - 233s 581ms/step - loss: 0.3831 - accuracy:
0.8300 - val loss: 0.4313 - val accuracy: 0.8140
Epoch 26/30
400/400 [============== ] - 235s 588ms/step - loss: 0.3837 - accuracy:
0.8309 - val_loss: 0.5735 - val_accuracy: 0.7570
Epoch 27/30
400/400 [============ ] - 227s 569ms/step - loss: 0.3838 - accuracy:
0.8320 - val loss: 0.3967 - val accuracy: 0.8364
Epoch 28/30
400/400 [============ ] - 220s 547ms/step - loss: 0.3821 - accuracy:
0.8345 - val loss: 0.3679 - val accuracy: 0.8480
Epoch 29/30
400/400 [============ ] - 226s 564ms/step - loss: 0.3806 - accuracy:
0.8357 - val loss: 0.4853 - val accuracy: 0.8132
Epoch 30/30
400/400 [============= ] - 223s 557ms/step - loss: 0.3667 - accuracy:
0.8382 - val_loss: 0.3574 - val_accuracy: 0.8494
```

Accuracy

```
acc = history.history['accuracy']
In [20]:
         val_acc = history.history['val_accuracy']
         loss = history.history['loss']
         val_loss = history.history['val_loss']
         plt.figure(figsize=(8, 8))
         plt.subplot(2, 1, 1)
         plt.plot(acc, label='Training Accuracy')
         plt.plot(val_acc, label='Validation Accuracy')
         plt.legend(loc='lower right')
         plt.ylabel('Accuracy')
         plt.ylim([min(plt.ylim()),1])
         plt.title('Training and Validation Accuracy')
         plt.subplot(2, 1, 2)
         plt.plot(loss, label='Training Loss')
         plt.plot(val_loss, label='Validation Loss')
         plt.legend(loc='upper right')
         plt.ylabel('Cross Entropy')
         plt.ylim([0,1.0])
         plt.title('Training and Validation Loss')
         plt.xlabel('epoch')
         plt.show()
```

