```
clear all;
close all;
% Set Parameters:
nt = 100; %Number of Temporal Grid Points
nx = 100; %Number of Spatial Grid Points
T = 2.8; %Final Time
c = 1; %Speed
nIntegrationTerms = 100; %Number of Nodes for the IntegrateTrapazoidal Routine
%f = @(x)
df_{dx} = (x) \exp(-((x-0.5).^2)./0.005) + 3 \exp(((-(x).^2))/0.005) + 2 \exp(-((x+0.5).^2)/0.005) + 2 \exp(-((x+0.5).^2)/0.005) + 3 \exp(-((x
005); % Initial condition.
% --- INITIALIZE THE GRIDS:
t = linspace(0,T,nt); %Initial Time, End Time, Spacing
x = linspace(-8,8,nx); % Left End point, Right End Point, Spacing
uStore=zeros(nx,nt); %Initialize Storage Matrix
for j=1:nt; %loop over time
           uTemp=zeros(nx,1); %initialize temporary variable to give the illusion of time \checkmark
evolution
           for k=1:nx; %loop over space
                      a = x(k) - c*t(j); %lower integration value
                     b = x(k) + c*t(j); %upper integration value
                        uStore(k,j) = integrateTrapezoidal(df dx,a,b,nIntegrationTerms);
                        uTemp(k) =uStore(k, j);
           end
                      %plot(x, uTemp);
                      %axis([-8, 8, -2, 2])
                      %pause(0.1) %How long of a pause between frames
end
LEP = -8; %left bound
REP = 8; %right bound
h=(REP-LEP)/nx; %spacing
% --- Generate a first derivative matrix:
row = zeros(1,nx); % Initialize n row vector of length
                                                    % n with zeros.
row(2) = 1;
row(nx) = -1;
col = zeros(nx,1); % Initialize n column vector of length
                                                     % n with zeros.
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```
col(2) = -1;
col(nx) = 1;

D1 = toeplitz(col,row)/(2*h);

D1x = D1*uStore;

for v=1:nt;
    uTemp=zeros(nx,1);
    for q=1:nx;
        uTemp(q)=D1x(q,v);
    end

    plot(x,uTemp)
    axis([-8, 8, -2, 2])
    pause(0.1) %How long of a pause between frames
end
```