

# DIFFERENTIATE-AND-FIRE TIME-ENCODING OF FINITE-RATE-OF-INNOVATION SIGNALS

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## 1. INTRODUCTION

- Time-encoding or *event-driven sampling* is an alternative paradigm to Shannon sampling.
- We propose a differentiate-and-fire time-encoding machine (DIF-TEM) inspired by the *magnocellular pathway* in the human visual system.
- We propose kernel-based time-encoding of FRI signals with DIF-TEM via Fourier-domain analysis.

## 2. DIFFERENTIATE-AND-FIRE TIME-ENCODING MACHINE

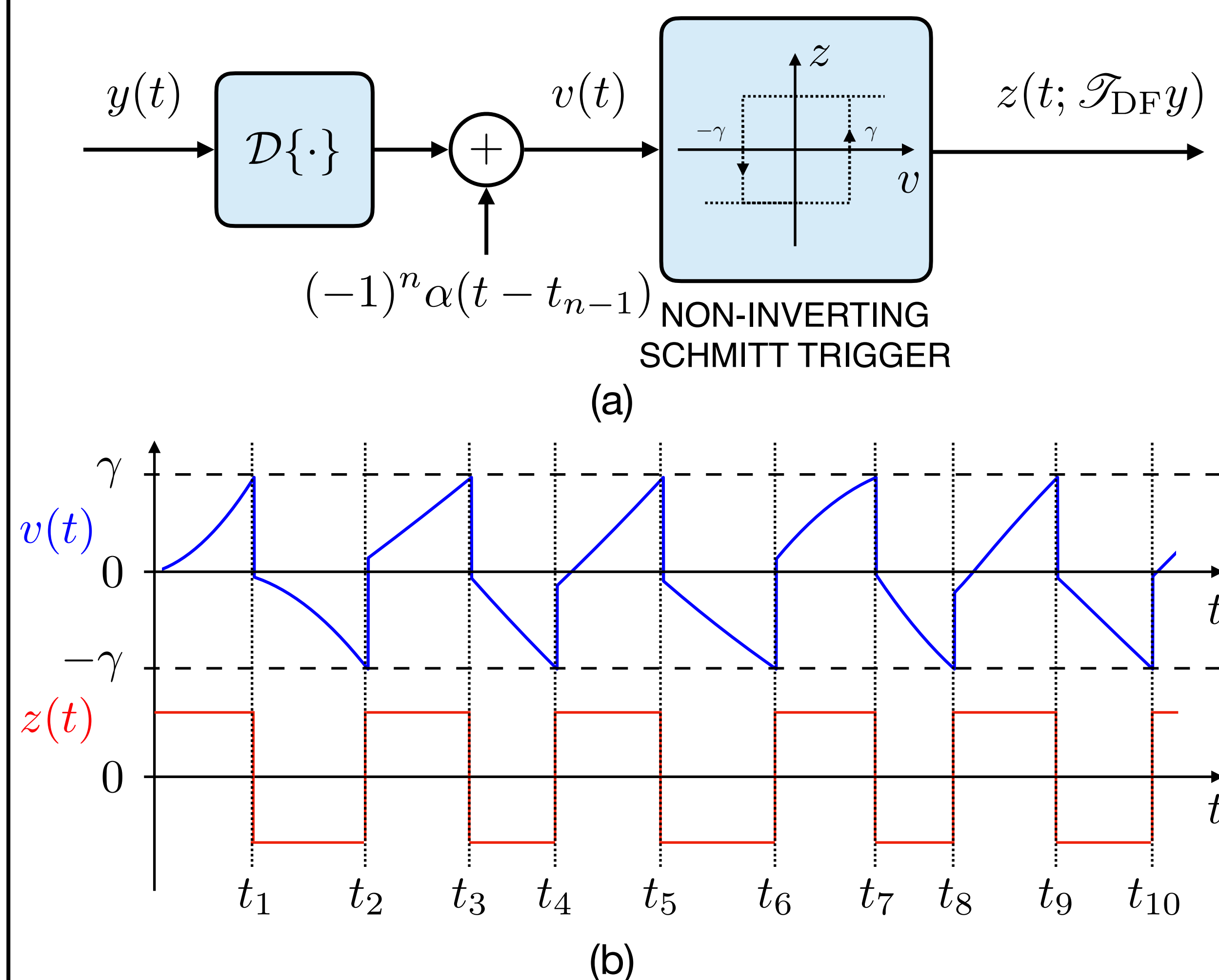


Fig 1: (a) A DIF-TEM with linear bias and a Schmitt trigger with threshold  $\gamma$ ; (b) the sum  $v(t)$  of the differentiated signal and the bias, and the output bilevel signal  $z(t)$  that transitions at the trigger times  $\mathcal{T}_{DF}y$ .

- Lemma (*t*-transform):** Let  $y \in \mathcal{C}^1(\mathbb{R})$ . The output  $\mathcal{T}_{DF}y = \{t_n\}_{n \in \mathbb{Z}}$  satisfies

$$(\mathcal{D}y)(t_n) = (-1)^{n+1}(\gamma - \alpha(t_n - t_{n-1})).$$

- Corollary (*Sampling sets of DIF-TEM*):** Let  $y \in \mathcal{C}^1(\mathbb{R})$  with  $\|\mathcal{D}y\|_\infty \leq \beta$ . The output  $\mathcal{T}_{DF}y = \{t_n\}_{n \in \mathbb{Z}}$  satisfies

$$d(\mathcal{T}_{DF}y) \doteq \sup_{n \in \mathbb{Z}} |t_n - t_{n-1}| \leq \frac{\gamma + \beta}{\alpha}.$$

## 3. TIME-ENCODING OF FRI SIGNALS

- Consider the  $T$ -periodic FRI signal  $x \in L^2([0, T])$

$$x(t) = \sum_{m \in \mathbb{Z}} \sum_{k=0}^{K-1} c_k \varphi(t - \tau_k - mT) \quad (1)$$

- The Fourier coefficients of  $x(t)$

$$\hat{x}_m = \frac{1}{T} \hat{\varphi}(m\omega_0) \sum_{k=0}^{K-1} c_k e^{-j\omega_0 m \tau_k}, \quad \omega_0 = \frac{2\pi}{T} \quad (2)$$

- $\{c_k\}_{k=0}^{K-1}$  and  $\{\tau_k\}_{k=0}^{K-1}$  can be recovered using  $\geq 2K + 1$  measurements using Prony's method [1]

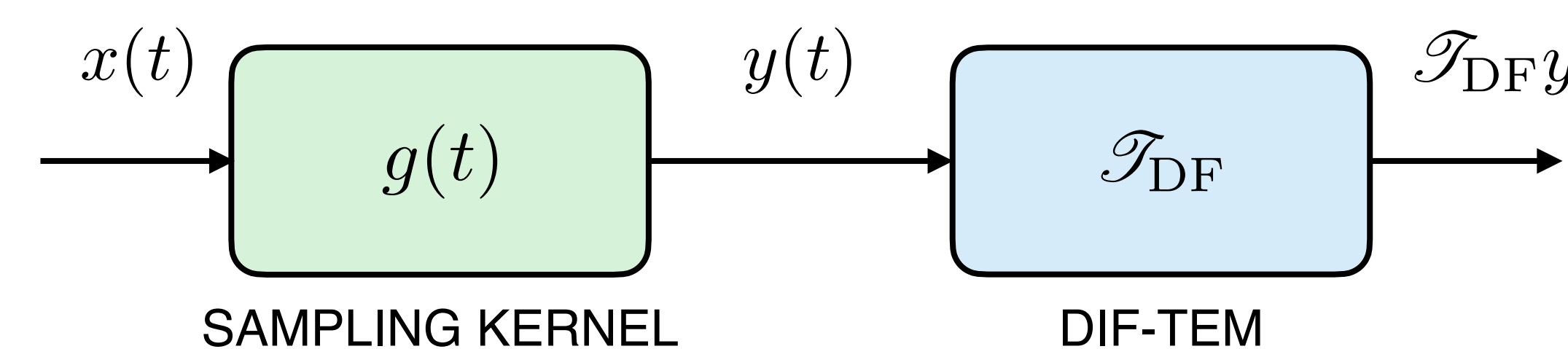


Fig 2: Kernel-based time-encoding of using a sampling kernel that satisfies the alias-cancellation conditions [2] and DIF-TEM.

- The filtered signal and measurements

$$y(t) = \sum_{m \in \mathbb{Z}} \hat{x}_m \hat{g}(m\omega_0) e^{j\omega_0 m t} = \sum_{m=-M}^M \hat{x}_m e^{j\omega_0 m t} \quad (3)$$

$$\Rightarrow y_n \doteq (\mathcal{D}y)(t_n) = \sum_{m=-M}^M \hat{x}_m \cdot (j\omega_0 m) \cdot e^{j\omega_0 m t_n}$$

- Proposition (*Sufficient condition for perfect recovery*):** Let the FRI signal  $x(t)$  be observed using a sampling kernel  $g(t)$  that satisfies alias-cancellation conditions and a DIF-TEM with parameters  $\alpha, \gamma > 0$ . The time instants  $\{t_n\}_{n=1}^L \subset \mathcal{T}_{DF} \cap [0, T]$  constitute a sufficient representation of  $x(t)$  if  $L \geq 2K + 1$  and the parameters of the DIF-TEM satisfy

$$\frac{\gamma + \|x * \mathcal{D}g\|_\infty}{\alpha} \leq \frac{T}{L}. \quad (4)$$

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## 4. SIMULATION RESULTS

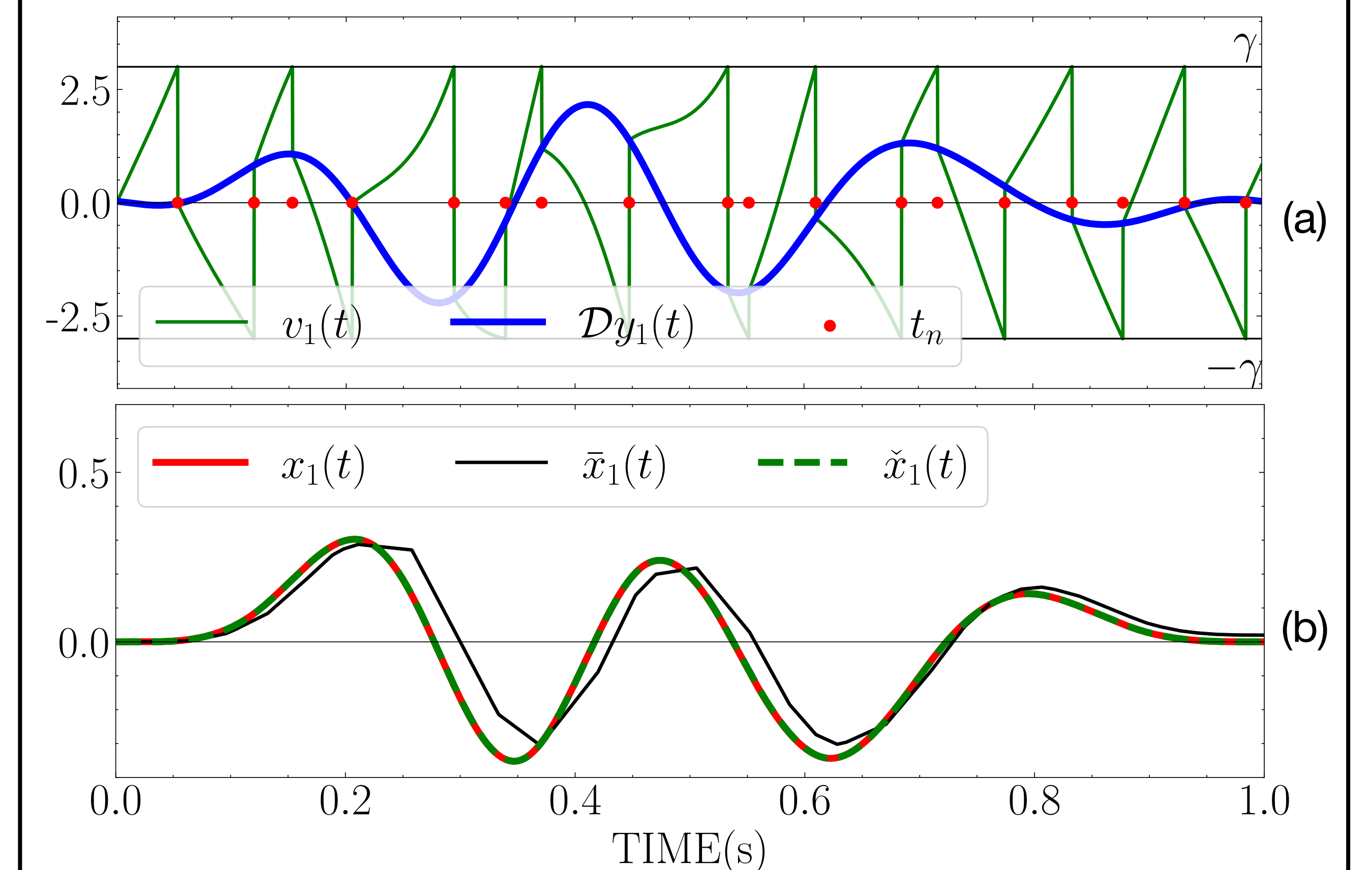


Fig 3: Reconstruction of cubic B-spline pulses from time-encoding using DIF-TEM: (a) derivative signal  $\mathcal{D}y_1(t)$  and input to the Schmitt trigger  $v_1(t)$ ; (b) input signal  $x_1(t)$ , reconstruction using proposed method  $\tilde{x}_1(t)$  and using an integrator  $\bar{x}_1(t)$ .

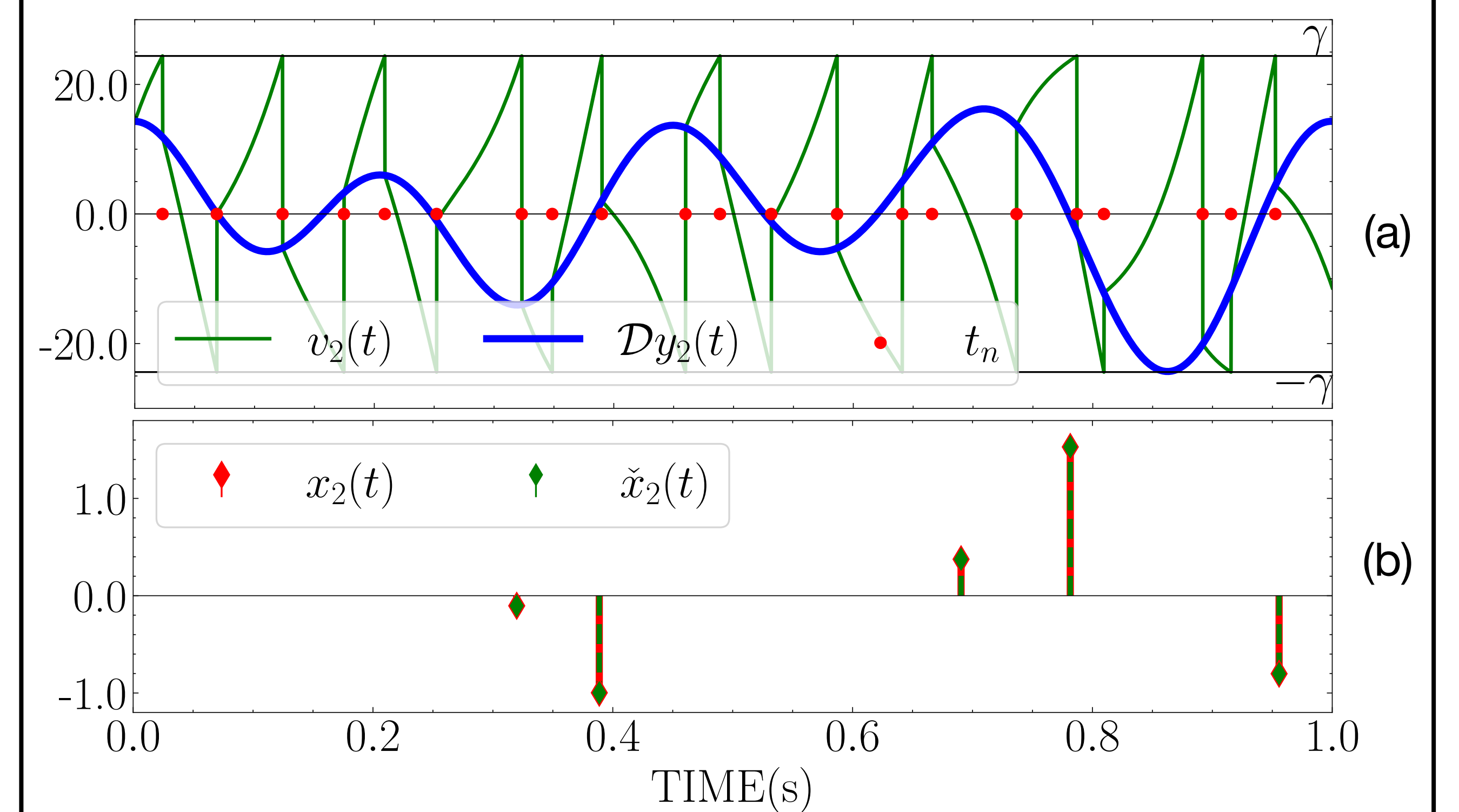


Fig 4: Reconstruction of Dirac impulses from time-encoding using DIF-TEM: (a) derivative signal  $\mathcal{D}y_2(t)$  and input to the Schmitt trigger  $v_2(t)$ ; (b) input  $x_2(t)$  and reconstruction  $\tilde{x}_2(t)$ .

## 5. KEY REFERENCES

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