



NPTEL ONLINE CERTIFICATION COURSES

DIGITAL CONTROL IN SMPCs AND FPGA-BASED PROTOTYPING

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Module 01: Introduction to Digital Control in SMPCs

Lecture 07: Recap of Fixed and Variable Frequency Modulation Techniques

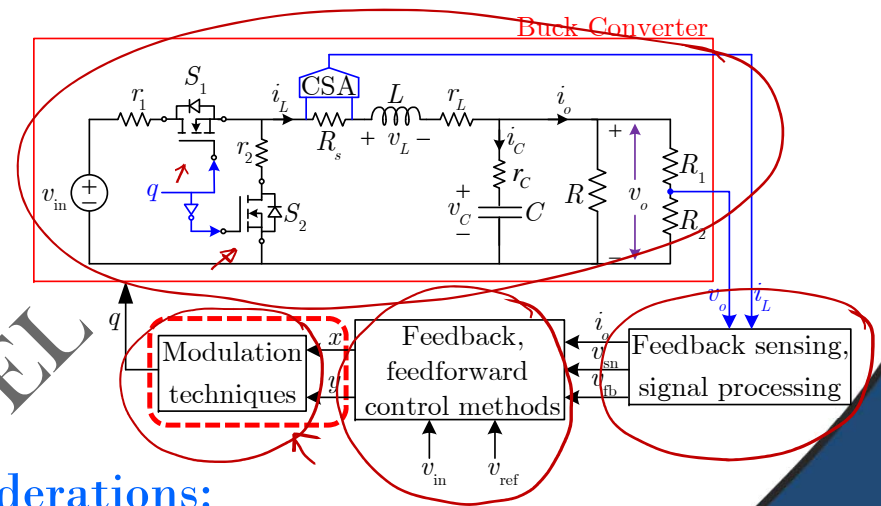


CONCEPTS COVERED

- Overview of fixed and variable frequency modulation techniques
- Summary of fixed frequency control methods
- Summary of variable frequency control methods
- Ripple parameters under fixed and variable frequency modulation
- Benefits and shortcomings in various modulation – Summary

Summary of Modulation Techniques

- Fixed frequency modulation
 - Pulse width modulation
 - Phase shift modulation
 - Pulse skipping modulation
- Variable frequency modulation
 - Constant on-time modulation
 - Constant off-time modulation
 - Hysteresis control



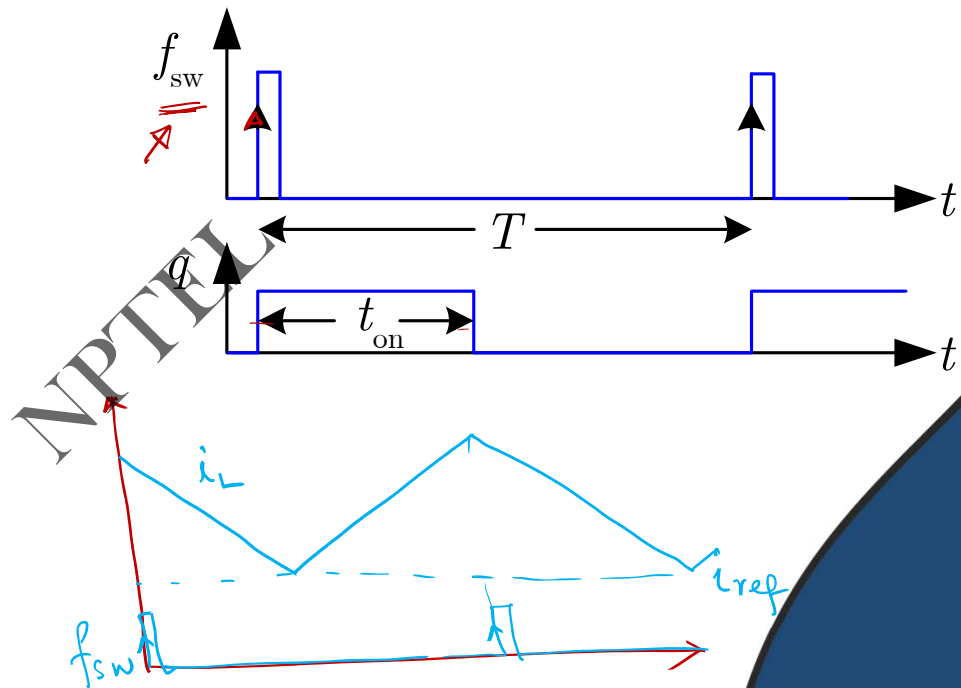
■ Considerations:

ripple parameters, losses, stability,
performance, switching frequency

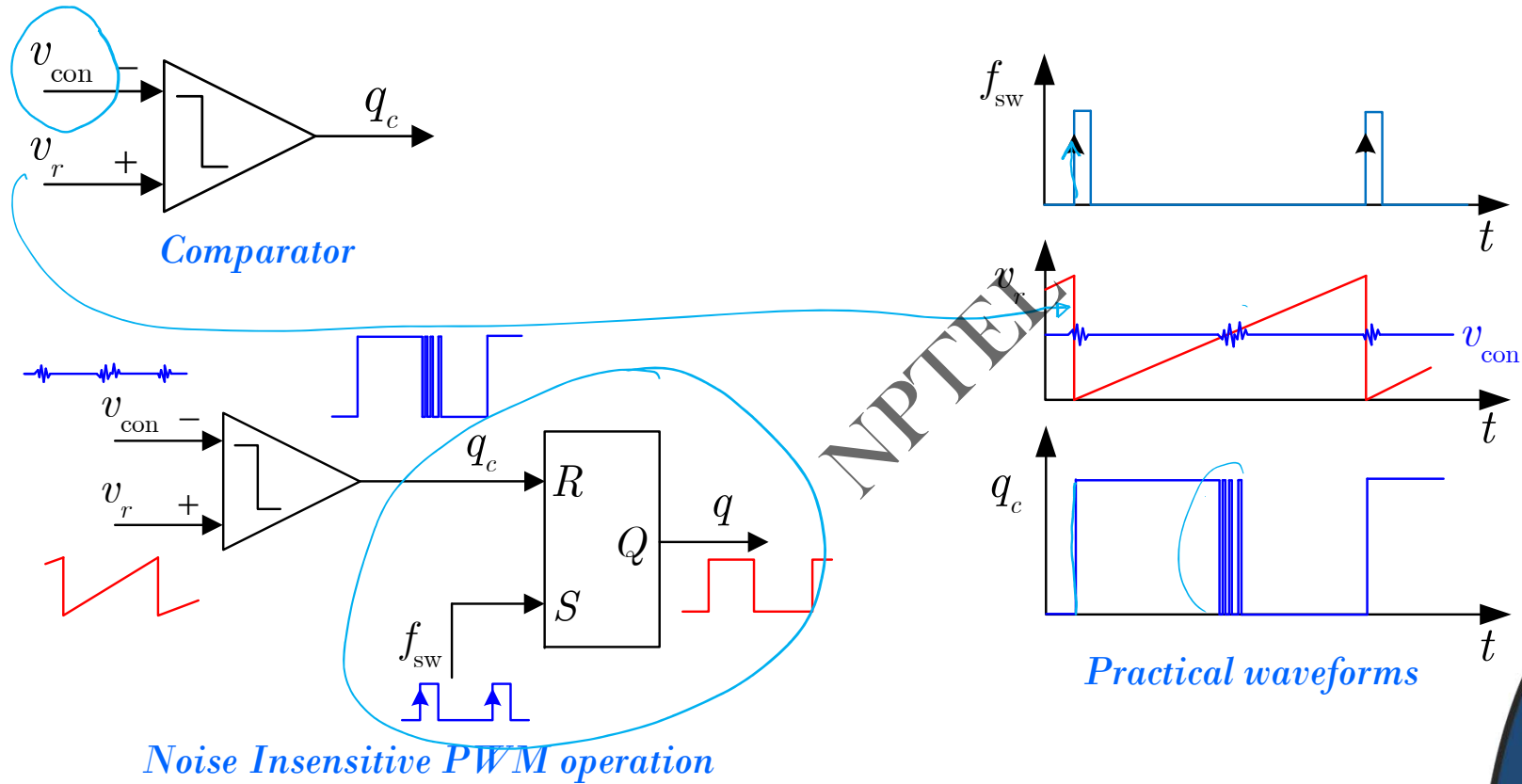
Why so many modulation techniques?

Fixed Frequency Control

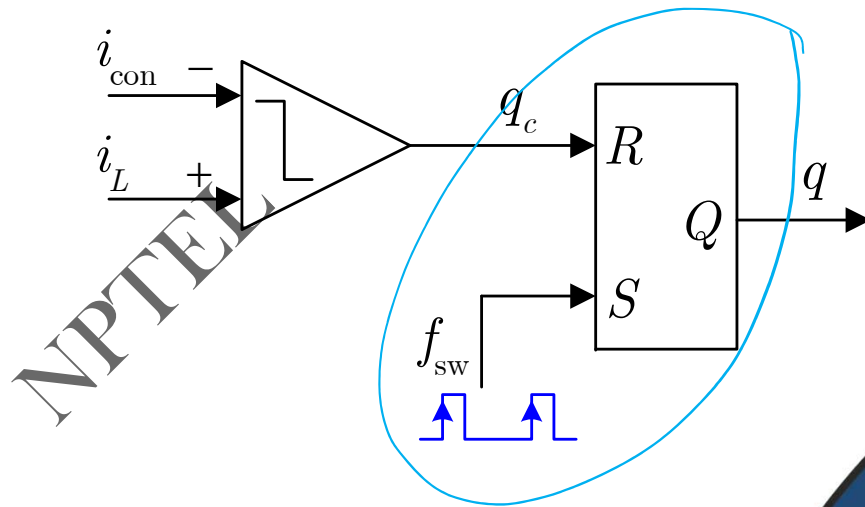
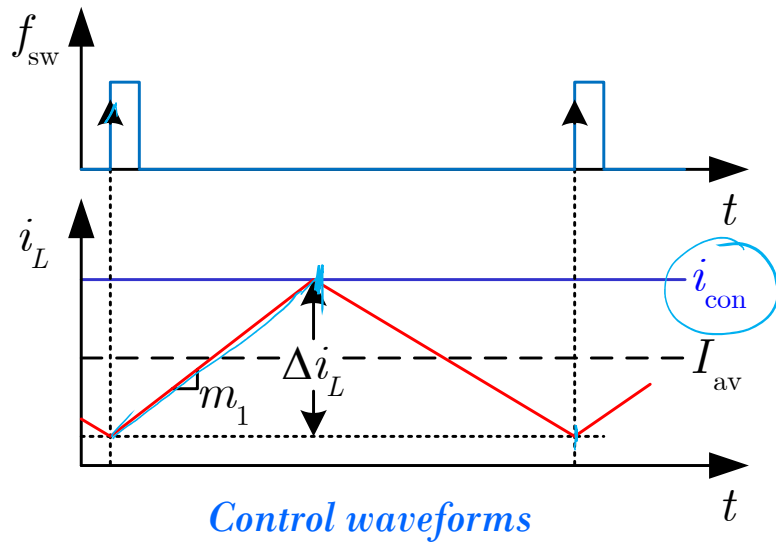
- Trailing-edge (TE) PWM
 - TE voltage mode control
 - Peak current mode control (CMC)
 - Average current mode control
- Leading-edge (LE) PWM
 - LE voltage mode control
 - Valley current mode control
- Voltage mode or current mode pulse skip control



Trailing-edge PWM: Voltage Mode Control

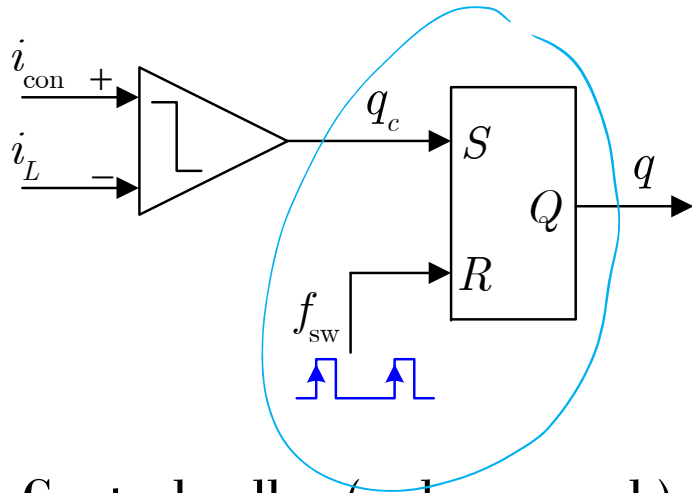


Trailing-edge PWM: Peak Current Mode Control

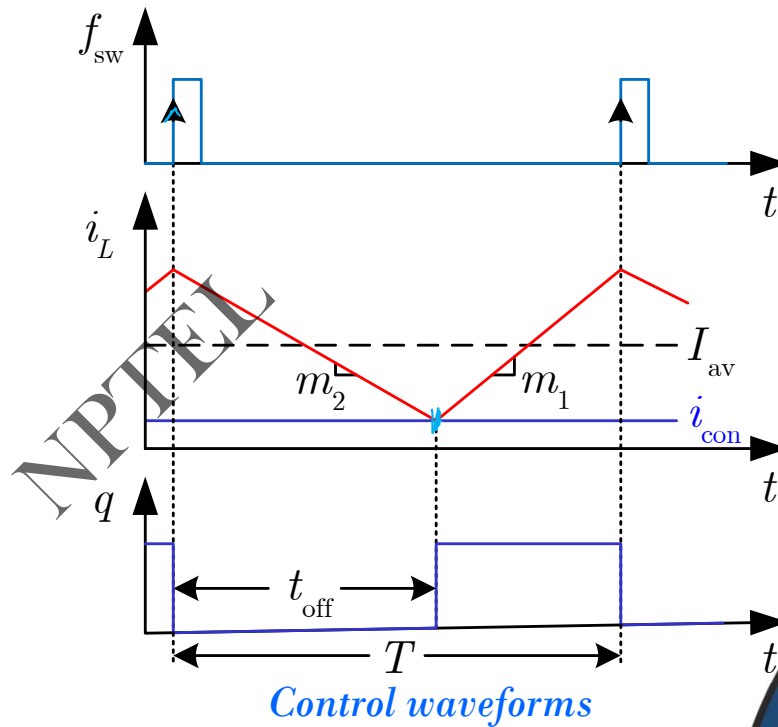


- Control peak value of inductor current (known as Peak current mode control)

Leading-edge PWM: Valley Current Mode Control



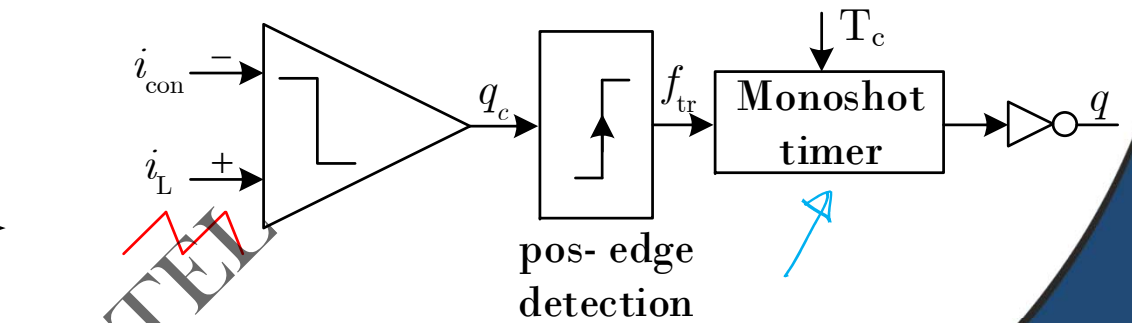
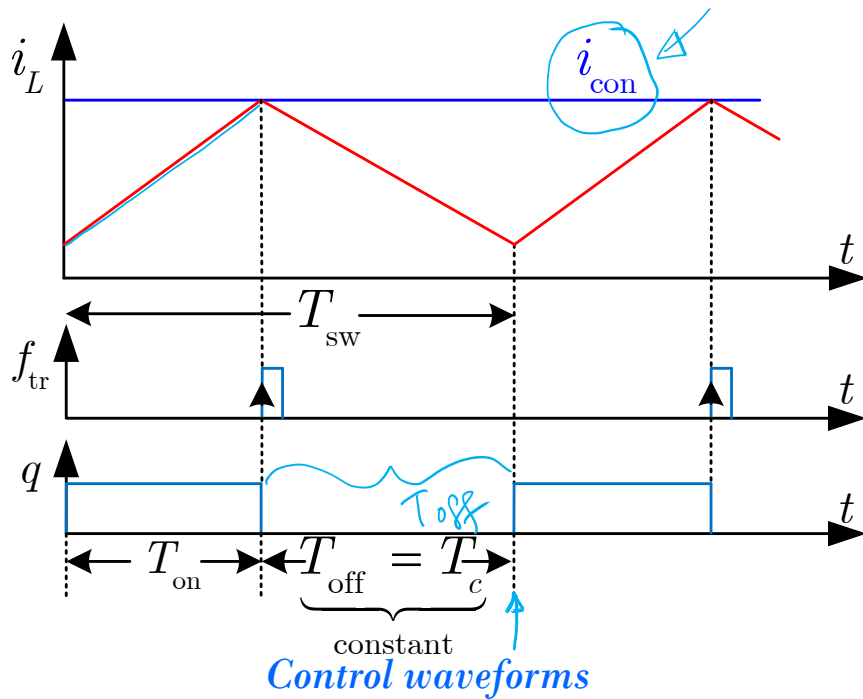
- Control valley (or lower peak) current
- Also known as Valley current mode control



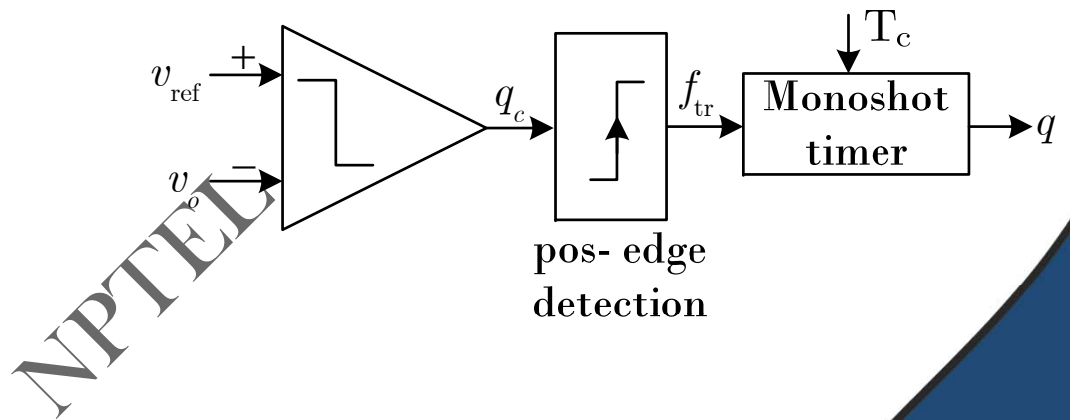
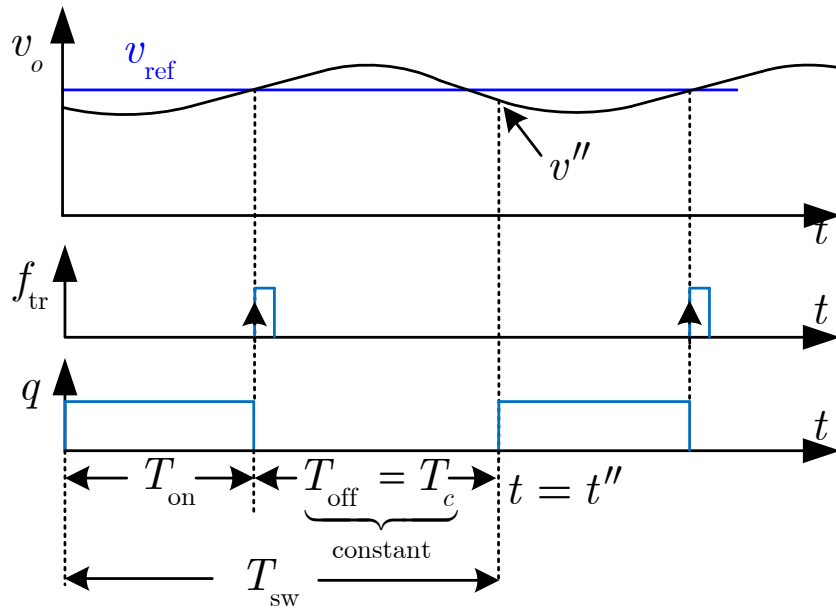
Variable Frequency Control

- Constant-off time (analogous to TE PWM)
 - Voltage control or peak current control
- Constant-on time (analogous to LE PWM)
 - Voltage control or valley current control
 - Current or voltage based adaptive on-time PFM control
- Hysteresis voltage or current control methods

Constant Off-time Control



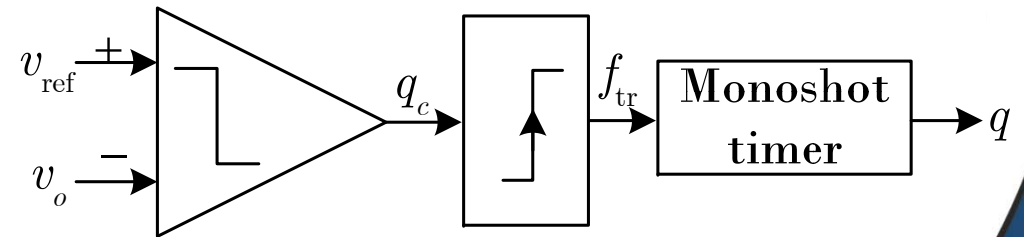
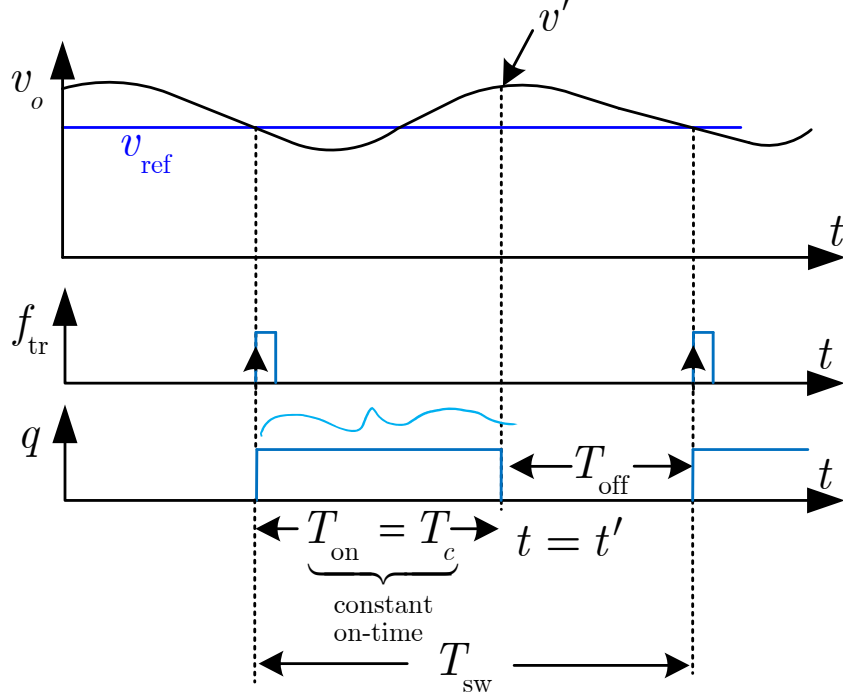
Constant Off-time Control | Voltage based implementation



Why minimum on-time in constant off-time control ??

[For details, refer to Lecture~21, NPTEL “Control and Tuning Methods ...” course ([link](#))

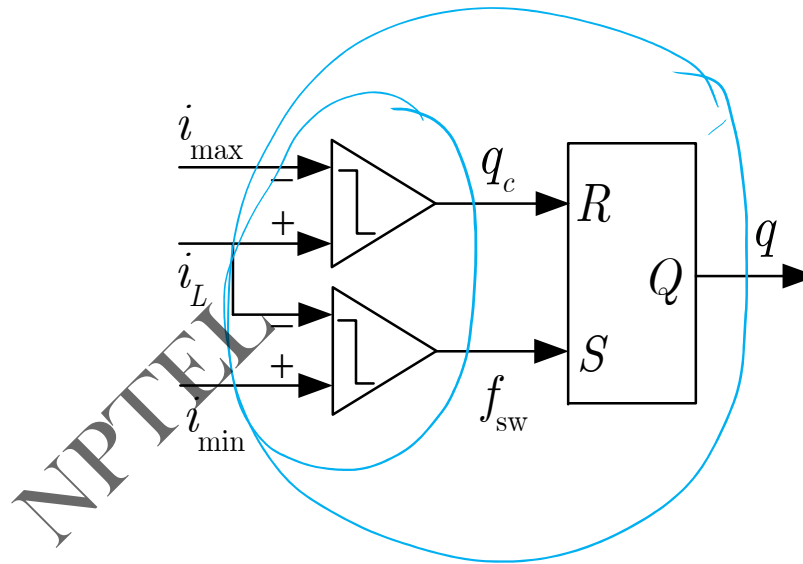
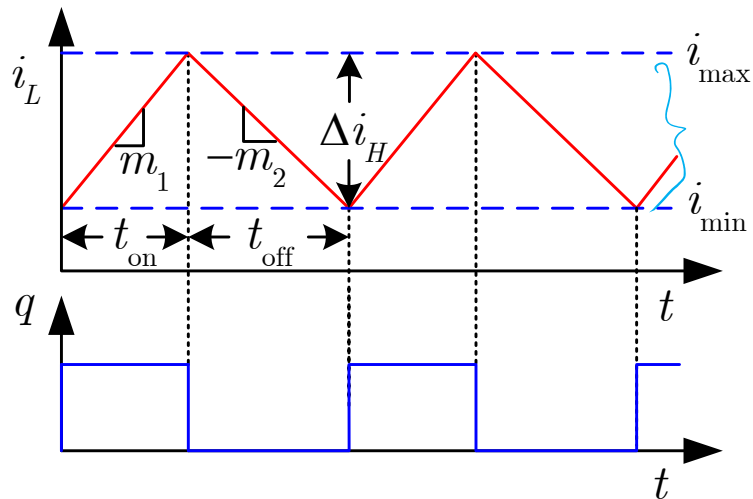
Constant On-time Modulation



Why minimum off-time in constant on-time control ??

[For details, refer to Lecture~20, NPTEL "Control and Tuning Methods ..." course ([link](#))

Current Hysteresis Control



[For details, refer to Lecture~22, NPTEL “Control and Tuning Methods ...” course ([link](#))

Worst Case Inductor Current Ripple: Buck Converter in CCM

Modulation Technique	Current Ripple (Δi_L)	Worst case scenario
Pulse width modulation	$\frac{T}{L} \times V_o \left(1 - \frac{V_o}{V_{in}} \right)$	<u>Highest input voltage</u>
Constant on-time modulation	$\frac{T_{on}}{L} \times (V_{in} - V_o)$	<u>Highest input voltage</u>
Constant off-time modulation	$\frac{T_{off}}{L} \times V_o$	Insensitive to operating conditions

[For details, refer to Lecture~23, NPTEL “Control and Tuning Methods ...” course ([link](#))

Worst Case RMS Inductor Current: Buck Converter in CCM

Modulation Technique	RMS Current ($i_{L,rms}$)	Worst case scenario
Pulse width modulation	$\sqrt{I_o^2 + \frac{1}{12} \left[\frac{TV_o}{L} \left(1 - \frac{V_o}{V_{in}} \right) \right]^2}$	Highest input voltage and <u>highest load current</u>
Constant on-time modulation	$\sqrt{I_o^2 + \frac{1}{12} \left[\frac{T_{on}}{L} (V_{in} - V_o) \right]^2}$	Highest input voltage and <u>highest load current</u>
Constant off-time modulation	$\sqrt{I_o^2 + \frac{1}{12} \left(\frac{V_o T_{off}}{L} \right)^2}$	<u>Highest load current</u>

[For details, refer to Lecture~23, NPTEL “Control and Tuning Methods ...” course ([link](#))

Switching Frequency: Buck Converter in CCM

Modulation Technique	Switching frequency (f_{sw})	Worst case scenario
Pulse width modulation	$f_{sw} = f_{ext}$	Insensitive to system and operating conditions
Constant on-time modulation	$f_{sw} = \frac{1}{T_{on}} \times \left(\frac{V_o}{V_{in}} \right)$	Highest switching frequency at lowest input voltage
Constant off-time modulation	$f_{sw} = \frac{1}{T_{off}} \times \left(1 - \frac{V_o}{V_{in}} \right)$	Highest switching frequency at highest input voltage

[For details, refer to Lecture~23, NPTEL “Control and Tuning Methods ...” course ([link](#))

Worst Case Inductor Current Ripple: Boost Converter in CCM

Modulation Technique	Current Ripple (Δi_L)	Worst case scenario
Pulse width modulation	$\frac{T}{L} \times \left[\frac{V_{in}}{V_o} (V_o - V_{in}) \right]$	Input voltage equals to half of the output voltage
Constant on-time modulation	$\frac{T_{on}}{L} \times V_{in}$	Highest input voltage
Constant off-time modulation	$\frac{T_{off}}{L} \times (V_o - V_{in})$	<u>Lowest input voltage</u>

[For details, refer to Lecture~23, NPTEL “Control and Tuning Methods ...” course ([link](#))

Switching Frequency: Boost Converter in CCM

Modulation Technique	Switching frequency (f_{sw})	Worst case scenario
Pulse width modulation	$f_{sw} = f_{ext}$	Insensitive to system and operating conditions
Constant on-time modulation	$f_{sw} = \frac{1}{T_{on}} \times \left(1 - \frac{V_{in}}{V_o}\right)$	Highest switching frequency at lowest input voltage
Constant off-time modulation	$f_{sw} = \frac{1}{T_{off}} \times \frac{V_{in}}{V_o}$	Highest switching frequency at highest input voltage

[For details, refer to Lecture~23, NPTEL “Control and Tuning Methods ...” course ([link](#))

Fixed vs Variable Frequency Current Mode Control – Comparison

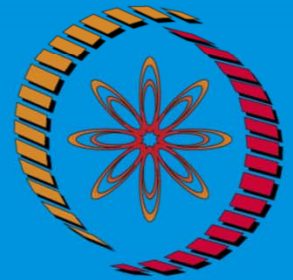
- Switching frequency
- Ripple parameters
- Transient performance
- Stability status

NPTEL

[For details, refer to Lecture~23, NPTEL “Control and Tuning Methods ...” course ([link](#))

CONCLUSION

- Overview of fixed and variable frequency modulation techniques
- Summary of fixed frequency control methods
- Summary of variable frequency control methods
- Ripple parameters under fixed and variable frequency modulation
- Benefits and shortcomings in various modulation – Summary



**THANK
YOU !**