



**NPTEL ONLINE CERTIFICATION COURSES**

# **DIGITAL CONTROL IN SMPCs AND FPGA-BASED PROTOTYPING**

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**Module 01: Introduction to Digital Control in SMPCs**

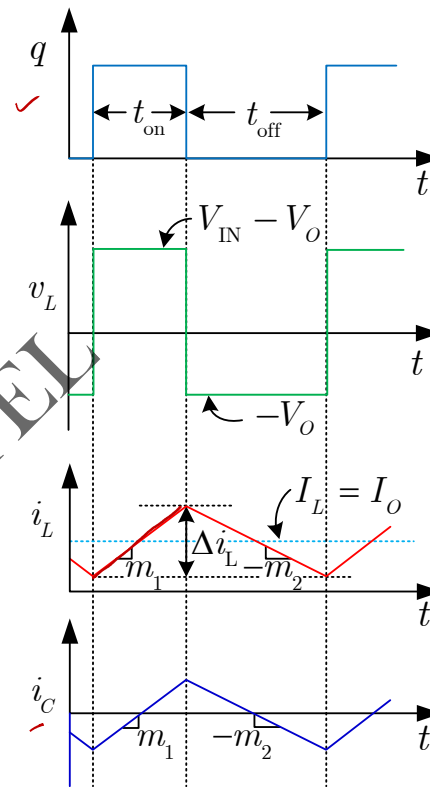
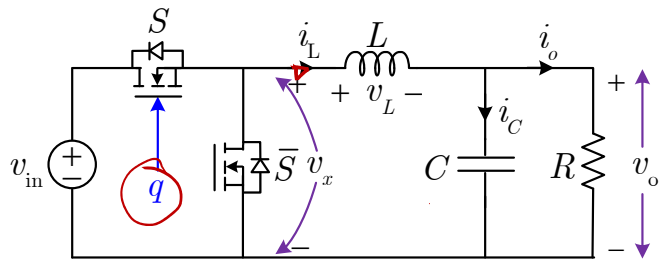
**Lecture 10: SMPC Topologies and Power Stage Design for Hardware Demonstrations**



## CONCEPTS COVERED

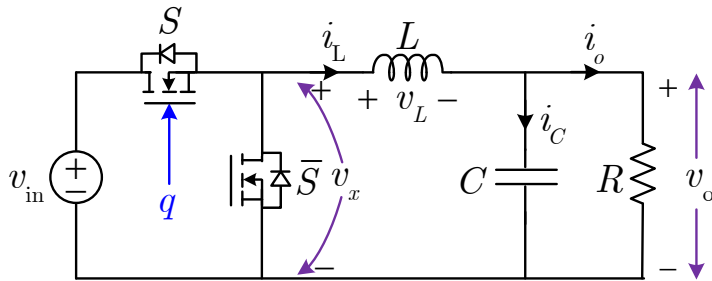
- Power stage design aspects of buck and boost converters
- Buck and boost converters under steady-state in CCM and DCM
- Full-bridge LLC converter – basic operations for varying frequency
- Conventional boost PFC and totem-pole PFC for AC/DC conversion

# Synchronous Buck Converter (CCM)



Steady-state waveforms

## Buck Converter Ripple Parameters



- Inductor current ripple ( $\Delta i_L$ ) of a buck converter

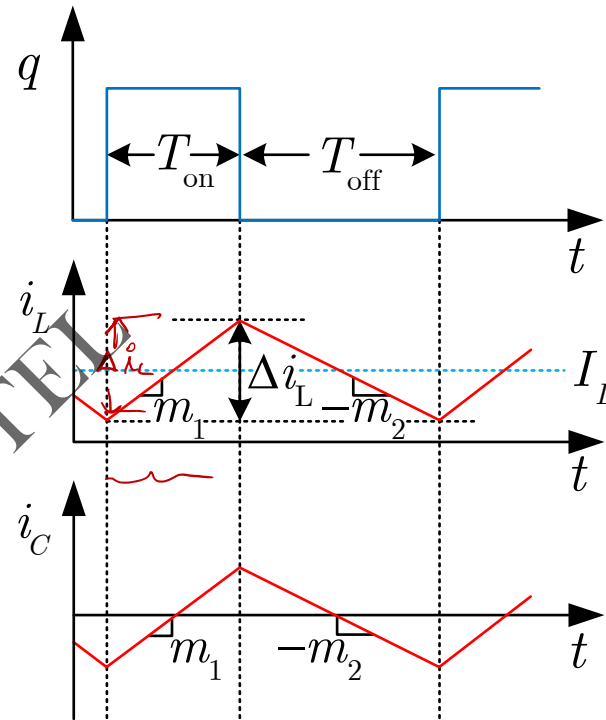
$$\Delta i_L = m_1 T_{\text{on}} \quad \text{where } m_1 = \frac{V_{\text{IN}} - V_O}{L}$$

$$\therefore \Delta i_L = \frac{V_{\text{IN}} - V_O}{L} \times T_{\text{on}}$$

$$T_{\text{on}} = DT$$

$$V_O = DV_{\text{IN}}$$

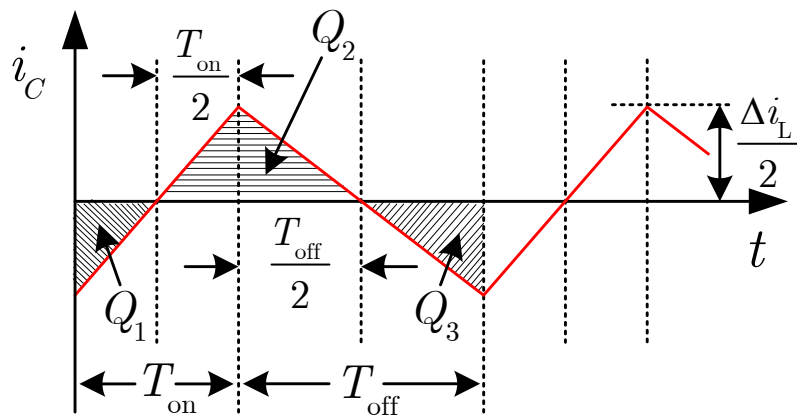
[ For details, refer to [Lecture~7, NPTEL “Power Stage Design of ...” course \(link\)](#) ]



Steady-state waveforms

$$\Delta i_L = D(1-D)V_{\text{IN}}T$$

## Capacitor Voltage Ripple – Ideal Buck Converter



Capacitor current waveform

Again  $Q_2 = C \times \Delta v_o$

$$\Delta v_o = \frac{V_o}{8LC} \times (T_{\text{on}} + T_{\text{off}}) \times T_{\text{off}}$$

$$Q_2 = \frac{1}{2} \times \frac{\Delta i_L}{2} \times \left( \frac{T_{\text{on}} + T_{\text{off}}}{2} \right)$$

$$= \frac{1}{8} \times (T_{\text{on}} + T_{\text{off}}) \times \Delta i_L$$

Substituting  $\Delta i_L = \frac{V_o}{L} \times T_{\text{off}}$

$$Q_2 = \frac{V_o}{8L} \times (T_{\text{on}} + T_{\text{off}}) \times T_{\text{off}}$$

□ Voltage ripple impact?

[ For details, refer to Lecture~7, NPTEL “Power Stage Design of ...” course ([link](#))]

## Ripple Parameters of a Buck Converter under PWM

### Under PWM

$$\underline{T_{\text{on}} + T_{\text{off}} = T_{\text{sw}} = \frac{1}{f_{\text{sw}}}} \quad (\text{fixed})$$

$$T_{\text{on}} = D \times T_{\text{sw}}$$

$$T_{\text{off}} = T_{\text{sw}} - T_{\text{on}} = (1 - D) \times T_{\text{sw}}$$

$$\underline{\Delta v_o} = \frac{V_o}{8LC} \times T_{\text{sw}} \times \underline{(1 - D)T_{\text{sw}}}$$

$$\Delta v_o = \left( \frac{V_o}{8LCf_{\text{sw}}^2} \right) \times (1 - D)$$

→ Voltage ripple is maximum at minimum  $D \rightarrow$  highest  $v_{\text{in}}$

$$\Delta i_L = \frac{V_o}{L} \times (1 - D)T_{\text{sw}}$$

$$\Rightarrow \Delta i_L = \frac{V_o}{Lf_{\text{sw}}} \times (1 - D)$$

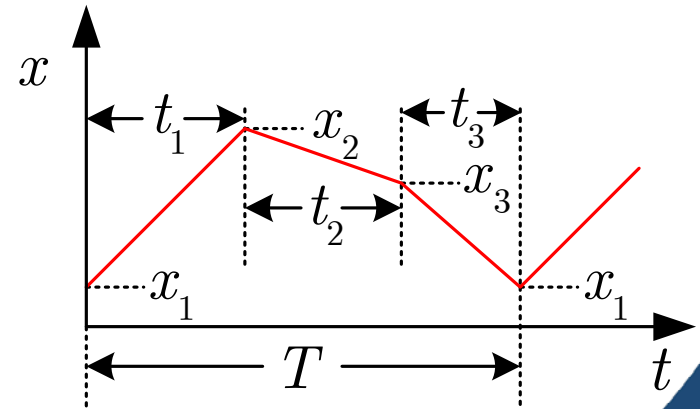
Current ripple is maximum at minimum  $D \rightarrow$  highest  $v_{\text{in}}$

Const.  
 $V_o = D V_{\text{in}}$

[ For details, refer to Lecture~7, NPTEL “Power Stage Design of ...” course ([link](#))]

## RMS Value of a Periodic Piecewise Linear Waveform

$$x_{\text{rms}}^2 = \frac{1}{T} \left[ \left( \frac{x_1^2 + x_1 x_2 + x_2^2}{3} \right) t_1 + \left( \frac{x_2^2 + x_2 x_3 + x_3^2}{3} \right) t_2 + \left( \frac{x_3^2 + x_3 x_1 + x_1^2}{3} \right) (T - t_1 - t_2) \right]$$

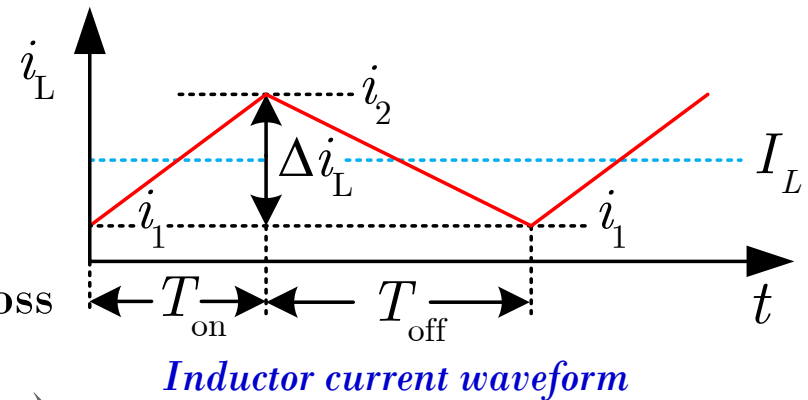


**Hint:**  $(x_{\text{rms}})^2 = \frac{1}{T} \left[ \int_0^T x^2(t) dt \right] = \frac{1}{T} \left[ \int_0^{t_1} x^2(t) dt + \int_{t_1}^{t_1+t_2} x^2(t) dt + \int_{t_1+t_2}^T x^2(t) dt \right]$

[ For details, refer to [Lecture~7, NPTEL “Power Stage Design of ...” course](#) ([link](#))]

## Buck Converter RMS Current

- For a given load current,
  - $i_{L,\text{RMS}}$  is maximum at maximum  $v_{in}$
  - Higher  $i_{L,\text{RMS}}$  implies higher conduction loss



- For a given input voltage,
  - $i_{L,\text{RMS}}$  increases with increasing  ~~$\Delta i_L$~~   $i_o$
  - Higher conduction loss at higher load current

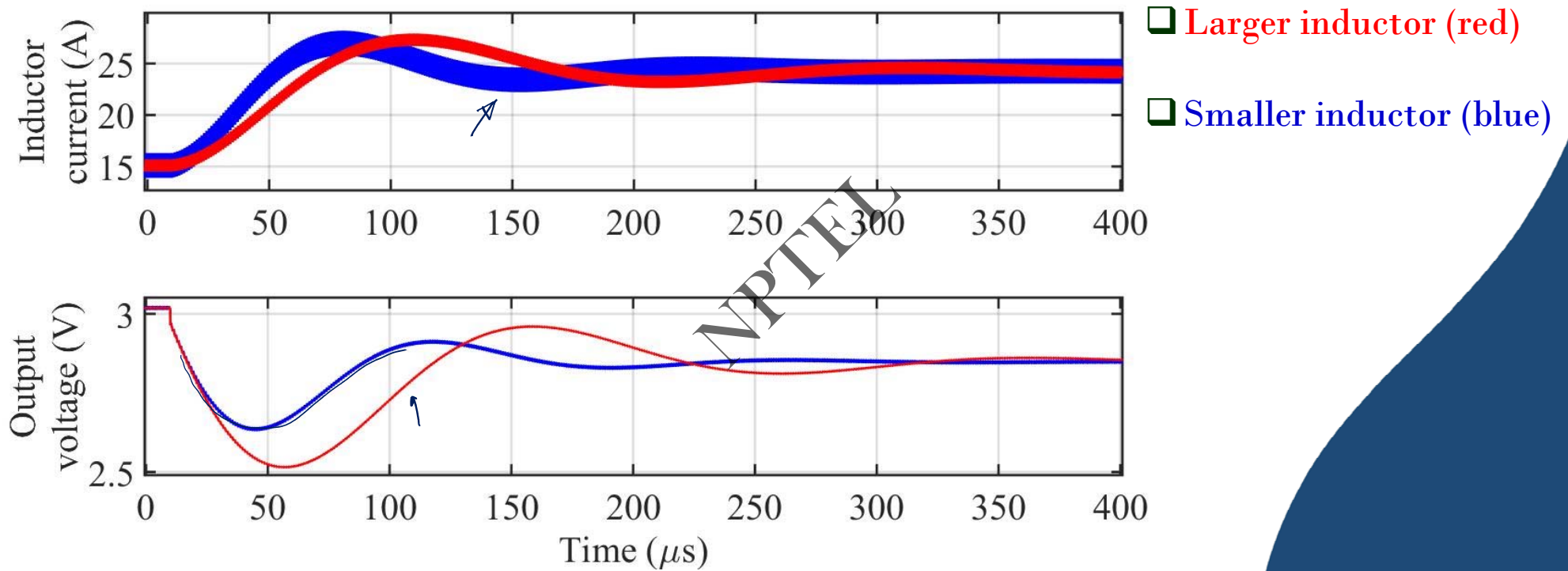
$$i_{L,\text{RMS}}^2 = I_o^2 + \frac{\Delta i_L^2}{12}$$

Worst case RMS current (also conduction loss) at  
**highest input voltage and highest load current**

[ For details, refer to Lecture~7, NPTEL “Power Stage Design of ...” course ([link](#)) ]



## *Design Consideration (Inductor)*



## *Design Consideration (Inductor)* **Large Inductor**

### Advantages

Smaller ripple current

$$\Delta i_L = \frac{V_o(1-D)}{f_{sw}} \times \frac{1}{L}$$

Smaller RMS current

$$(i_{L,RMS})^2 = I_o^2 + \frac{\Delta i_L^2}{12}$$

Lower conduction loss

Smaller voltage ripple

$$\Delta v_o = \frac{V_o(1-D)}{8Cf_{sw}^2} \times \frac{1}{L}$$

### Disadvantages

Larger size  
(bulky inductor)

Slower transient response!!

Higher voltage overshoot/  
undershoot!!

*Inductor should be  
carefully designed*

[ For details, refer to [Lecture~7, NPTEL](#)  
“Power Stage Design of ...” course ([link](#))]

## *Design Consideration (Capacitor)* Large Capacitor

### Advantages

Smaller output voltage ripple

$$\Delta v_o = \frac{V_o(1-D)}{8Cf_{sw}^2} \times \frac{1}{L}$$

Smaller output voltage undershoot/ overshoot

### Disadvantages

Larger size and poor reliability

Higher time and energy overhead during reference voltage transient

*Capacitor should be carefully selected*

[ For details, refer to Lecture~7, NPTEL “Power Stage Design of ...” course ([link](#))]

## Worst Case Inductor Current Ripple – Buck Converter in CCM

Modulation Technique	Current Ripple ( $\Delta i_L$ )	Worst case scenario
Pulse width modulation	$\frac{T}{L} \times V_o \left( 1 - \frac{V_o}{V_{in}} \right)$	Highest input voltage
Constant on-time modulation	$\frac{T_{on}}{L} \times (V_{in} - V_o)$	Highest input voltage
Constant off-time modulation	$\frac{T_{off}}{L} \times V_o$	Insensitive to operating conditions

Voltage reg.  
 $V_o \rightarrow \text{Const.}$

[ For details, refer to [Lecture~23, NPTEL “Stability and Performance ...” course](#) ([link](#))]

## *Worst Case RMS Inductor Current – Buck Converter in CCM*

Modulation Technique	RMS Current ( $i_{L,rms}$ )	Worst case scenario
Pulse width modulation	$\sqrt{I_o^2 + \frac{1}{12} \left[ \frac{TV_o}{L} \left( 1 - \frac{V_o}{V_{in}} \right) \right]^2}$	<u>Highest input voltage</u> and highest load current
Constant on-time modulation	$\sqrt{I_o^2 + \frac{1}{12} \left[ \frac{T_{on}}{L} (V_{in} - V_o) \right]^2}$	<u>Highest input voltage</u> and highest load <u>current</u>
Constant off-time modulation	$\sqrt{I_o^2 + \frac{1}{12} \left( \frac{V_o T_{off}}{L} \right)^2}$	<u>Highest load current</u>

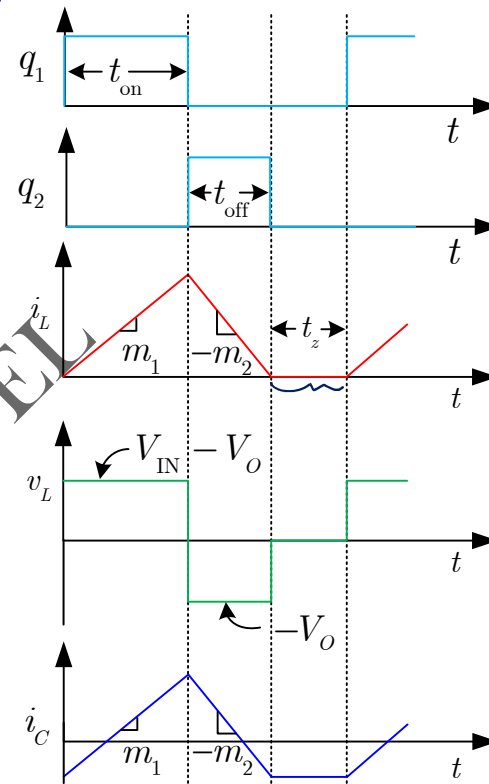
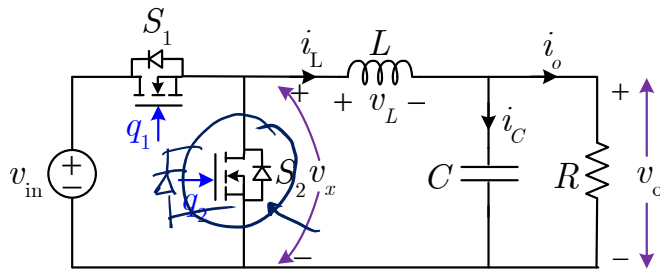
[ For details, refer to Lecture~23, NPTEL “Stability and Performance ...” course ([link](#))]

## Switching Frequency – Buck Converter in CCM

Modulation Technique	Switching frequency ( $f_{sw}$ )	Worst case scenario
Pulse width modulation	$f_{sw} = f_{ext}$	Insensitive to system and operating conditions
Constant on-time modulation	$f_{sw} = \frac{1}{T_{on}} \times \left( \frac{V_o}{V_{in}} \right)$	Highest switching frequency at lowest input voltage
Constant off-time modulation	$f_{sw} = \frac{1}{T_{off}} \times \left( 1 - \frac{V_o}{V_{in}} \right)$	Highest switching frequency at highest input voltage

[ For details, refer to [Lecture~23, NPTEL “Stability and Performance ...” course \(link\)](#)]

# Synchronous Buck Converter (DCM)



Steady-state waveforms

## Steady State Characterization of a Buck Converter in DCM

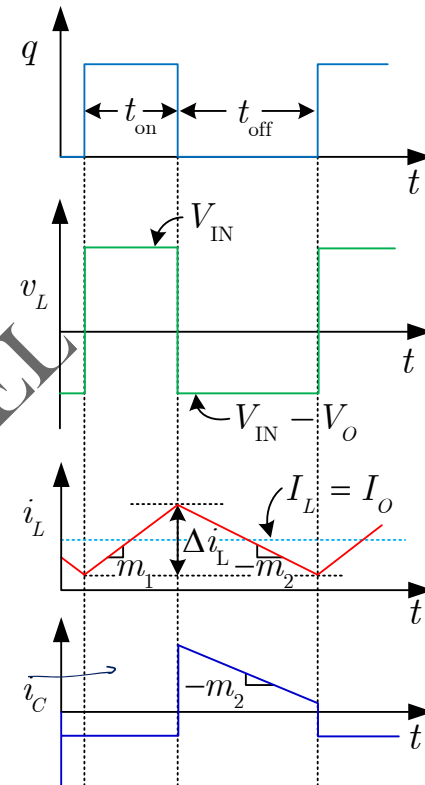
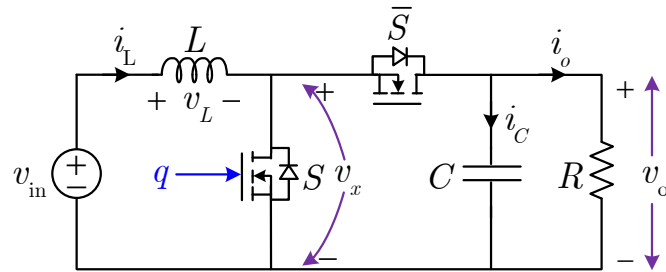
Modulation Technique	Voltage ripple ( $\Delta v_o$ )	Switching frequency ( $f_{sw}$ )
<u>Pulse width modulation</u>	$\Delta v_o \approx \frac{1}{C} \times \left( \frac{V_{in}}{V_o} \right) \times \frac{i_o}{f_{sw}}$	Fixed $f_{sw}$ , but varying duty ratio $D = \sqrt{\frac{2V_o i_o}{(V_{in} - V_o)V_{in}}} \times \frac{L}{T}$
<u>Constant on-time modulation</u>	$\Delta v_o \approx \left[ \frac{(V_{in} - V_o)V_{in}}{V_o} \right] \times \frac{T_{on}^2}{2LC}$	$f_{sw} = \left[ \frac{V_o}{V_{in}(V_{in} - V_o)} \right] \times \left( \frac{2L}{T_{on}^2} \right) \times i_o$

Ripple voltage increases with increasing input voltage

[ For details, refer to Lecture~24, NPTEL “Light Load Control...” course ([link](#))]

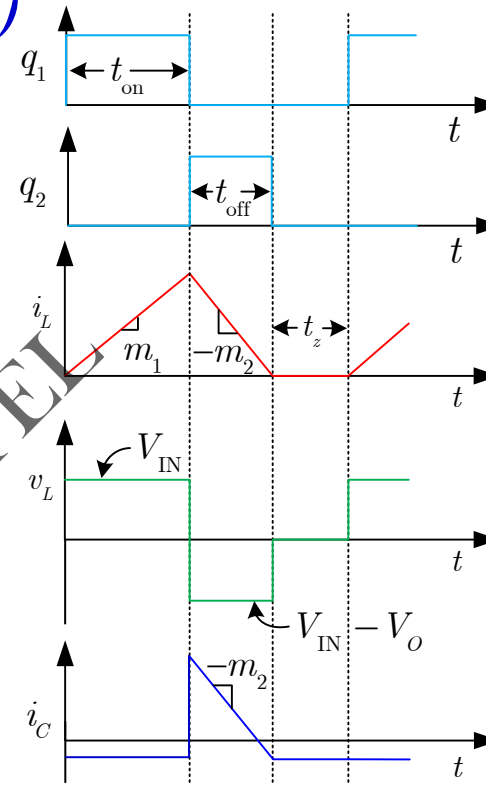
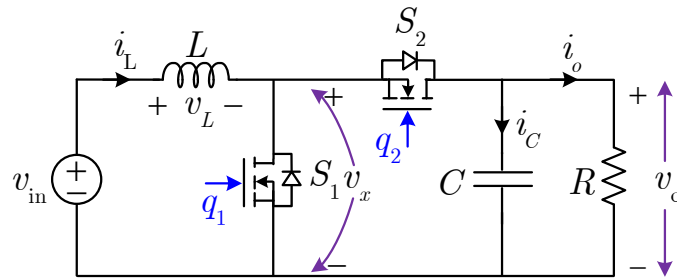


# Synchronous Boost Converter (CCM)



Steady-state waveforms

# Synchronous Boost Converter (DCM)

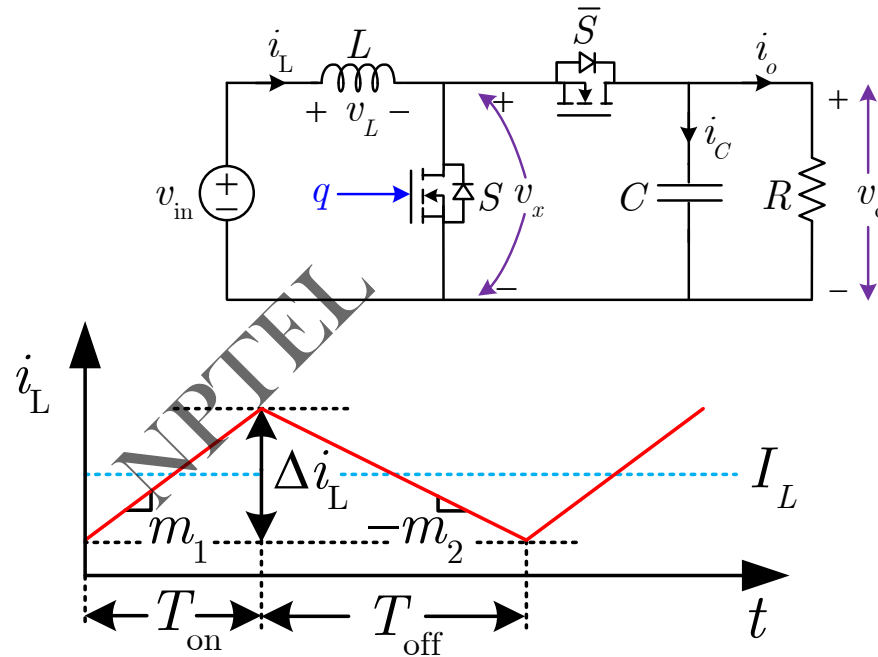


Steady-state waveforms

## Ripple Inductor Current- Boost Converter

$$\Delta i_L = m_1 \times T_{\text{on}} = \frac{V_{\text{IN}}}{L} \times T_{\text{on}}$$

Express  $V_{\text{IN}}$  in terms of  $V_o$   
 since  $V_o$  is constant for a VR



*Inductor current waveform*

[ For details, refer to [Lecture~7, NPTEL “Power Stage Design of ...” course \(link\)](#)]

## For a Boost Converter

$$V_o = \frac{T_{\text{on}} + T_{\text{off}}}{T_{\text{off}}} V_{\text{IN}} \Rightarrow V_{\text{IN}} = \frac{T_{\text{off}}}{T_{\text{on}} + T_{\text{off}}} V_o$$

$$\Delta i_L = \frac{V_{\text{IN}}}{L} \times T_{\text{on}} \Rightarrow \Delta i_L = \frac{V_o}{L} \times \left( \frac{T_{\text{on}} T_{\text{off}}}{T_{\text{on}} + T_{\text{off}}} \right)$$

$$\therefore \Delta i_L = \frac{V_o}{L f_{\text{sw}}} \times [D(1 - D)]$$

$\Delta i_L$  is maximum at  $D=0.5$

### Under PWM

$$T_{\text{on}} + T_{\text{off}} = T_{\text{sw}} = \frac{1}{f_{\text{sw}}}$$

$$T_{\text{on}} = D T_{\text{sw}}$$

$$T_{\text{off}} = (1 - D) T_{\text{sw}}$$

[ For details, refer to [Lecture~7, NPTEL “Power Stage Design of ...” course \(link\)](#)]

## Ripple Output Voltage – Boost Converter

$$\Delta v_o \times C = I_o T_{\text{on}}$$

$$\Delta v_o = \frac{I_o}{C} \times T_{\text{on}}$$

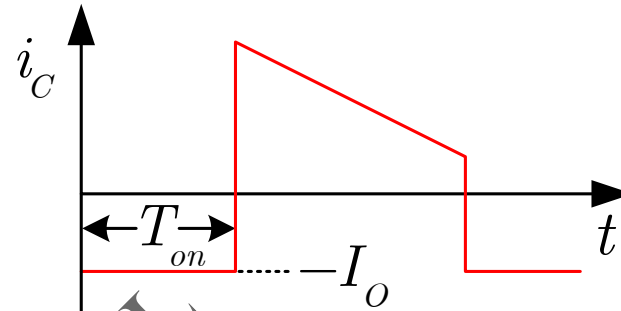
Under PWM  $T_{\text{on}} = DT_{\text{sw}}$

$$\therefore \Delta v_o = \frac{I_o}{C f_{\text{sw}}} \times D$$

Worst-case voltage ripple at

**lowest input voltage and highest load current**

[ For details, refer to [Lecture~7, NPTEL “Power Stage Design of ...” course \(link\)](#)]



*Capacitor current waveform*

- Voltage ripple is maximum when
  - Load current is maximum and
  - Duty ratio is maximum

## *Worst Case Inductor Current Ripple – Boost Converter in CCM*

Modulation Technique	Current Ripple ( $\Delta i_L$ )	Worst case scenario
Pulse width modulation	$\frac{T}{L} \times \left[ \frac{V_{in}}{V_o} (V_o - V_{in}) \right]$	Input voltage equals to half of the output voltage
Constant on-time modulation	$\frac{T_{on}}{L} \times V_{in}$	<u>Highest input voltage</u>
Constant off-time modulation	$\frac{T_{off}}{L} \times (V_o - V_{in})$	<u>Lowest input voltage</u>

[ For details, refer to [Lecture~23](#), NPTEL “Stability and Performance ...” course ([link](#))]

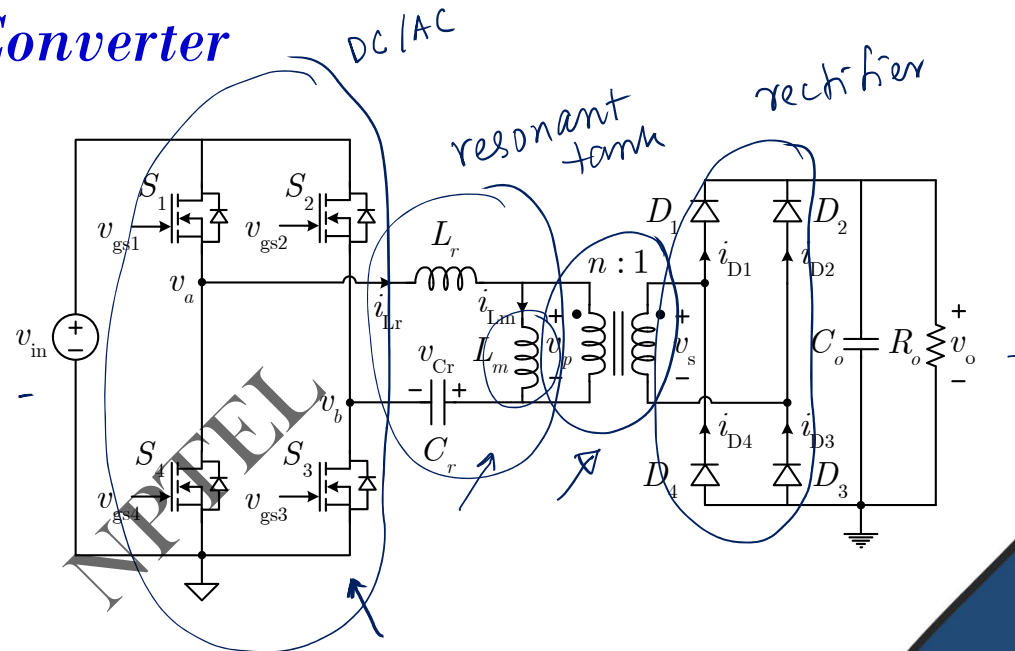
## Switching Frequency – Boost Converter in CCM

Modulation Technique	Switching frequency ( $f_{sw}$ )	Worst case scenario
Pulse width modulation	$f_{sw} = f_{ext}$	Insensitive to system and operating conditions
Constant on-time modulation	$f_{sw} = \frac{1}{T_{on}} \times \left(1 - \frac{V_{in}}{V_o}\right)$	Highest switching frequency at lowest input voltage
Constant off-time modulation	$f_{sw} = \frac{1}{T_{off}} \times \frac{V_{in}}{V_o}$	Highest switching frequency at highest input voltage

[ For details, refer to [Lecture~23](#), NPTEL “Stability and Performance ...” course ([link](#))]

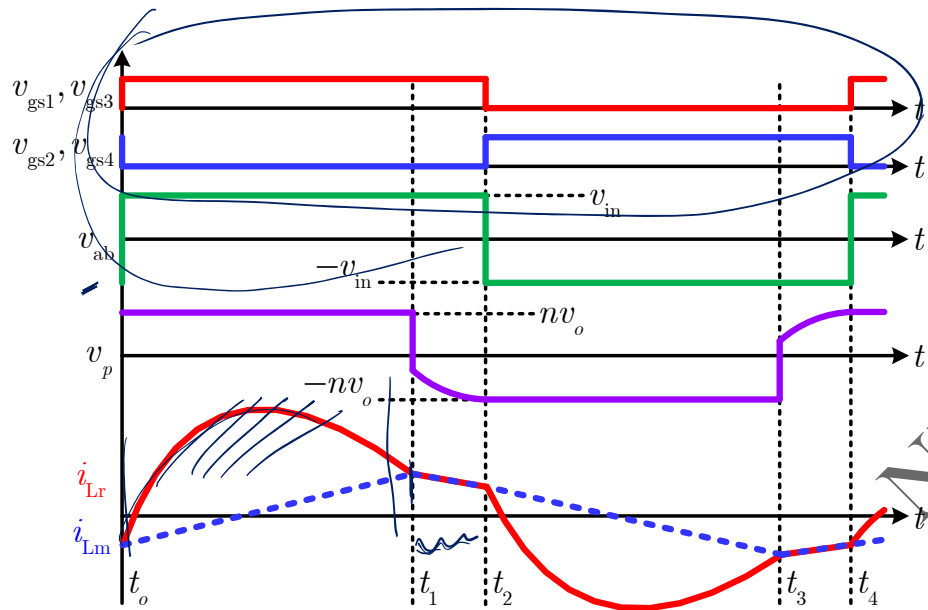
## Full-Bridge LLC Resonant Converter

- High efficiency
- High power density
- Magnetic integration
- Low EMI
- High operation frequency
- Regulation of output over wide line and load variations  
with a relatively smaller variation of switching frequency

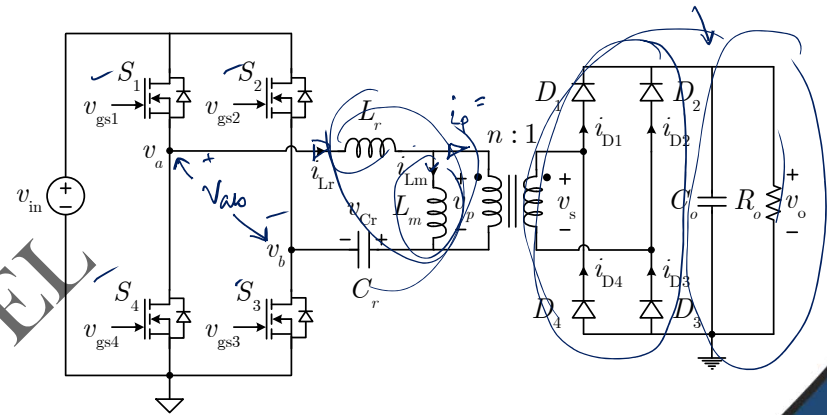




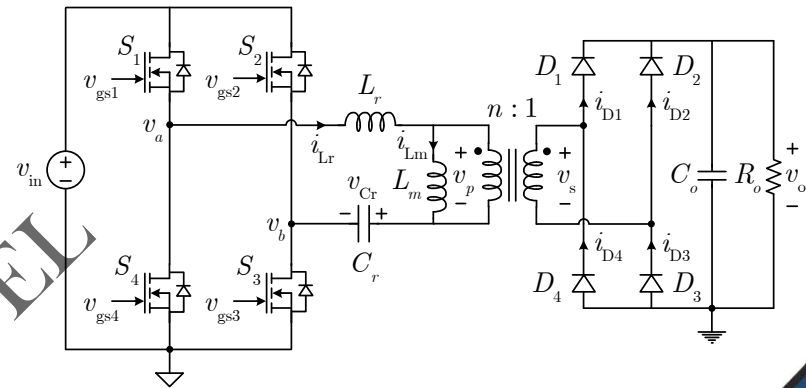
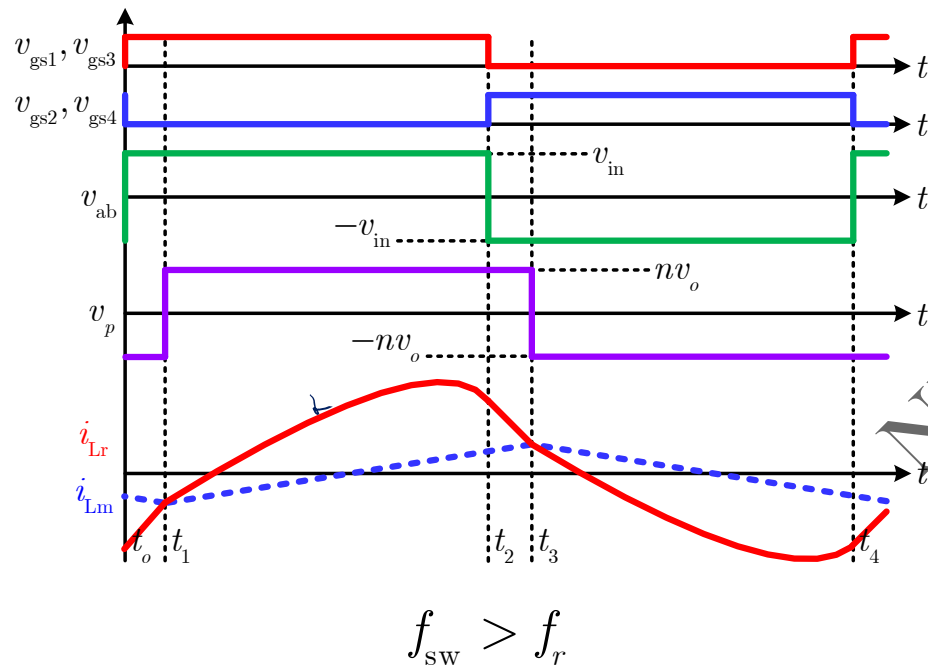
### *Switching Frequency Below Resonant Frequency (DCM)*



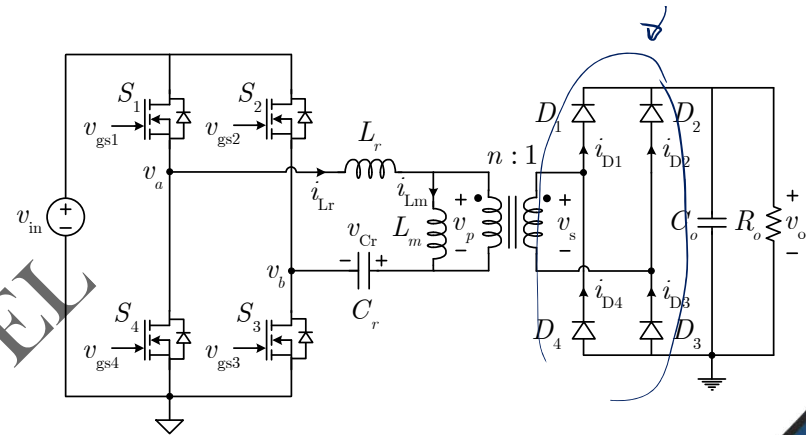
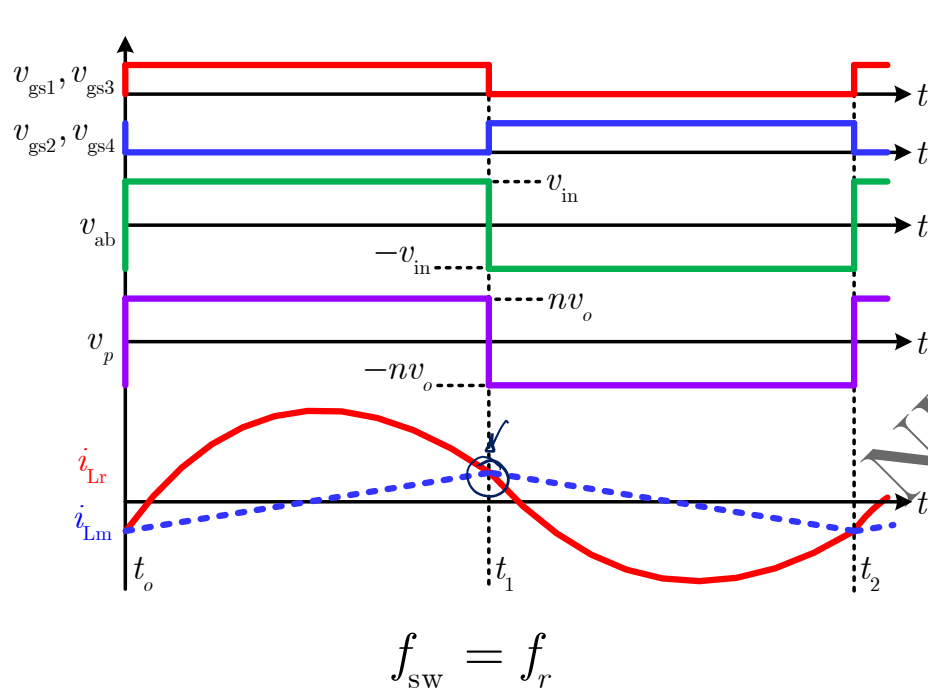
$$f_{\text{SW}} < f_r$$



## Switching Frequency Above Resonant Frequency (CCM)



## Switching Frequency Equals Resonant Frequency (CCM)



Single phase AC

230 V rms

$v_{ac}$

$D_1$ ,  $D_2$ ,  $D_3$ ,  $D_4$

$C_{hf}$

$S$

$L$

$i_L$

$D_5$

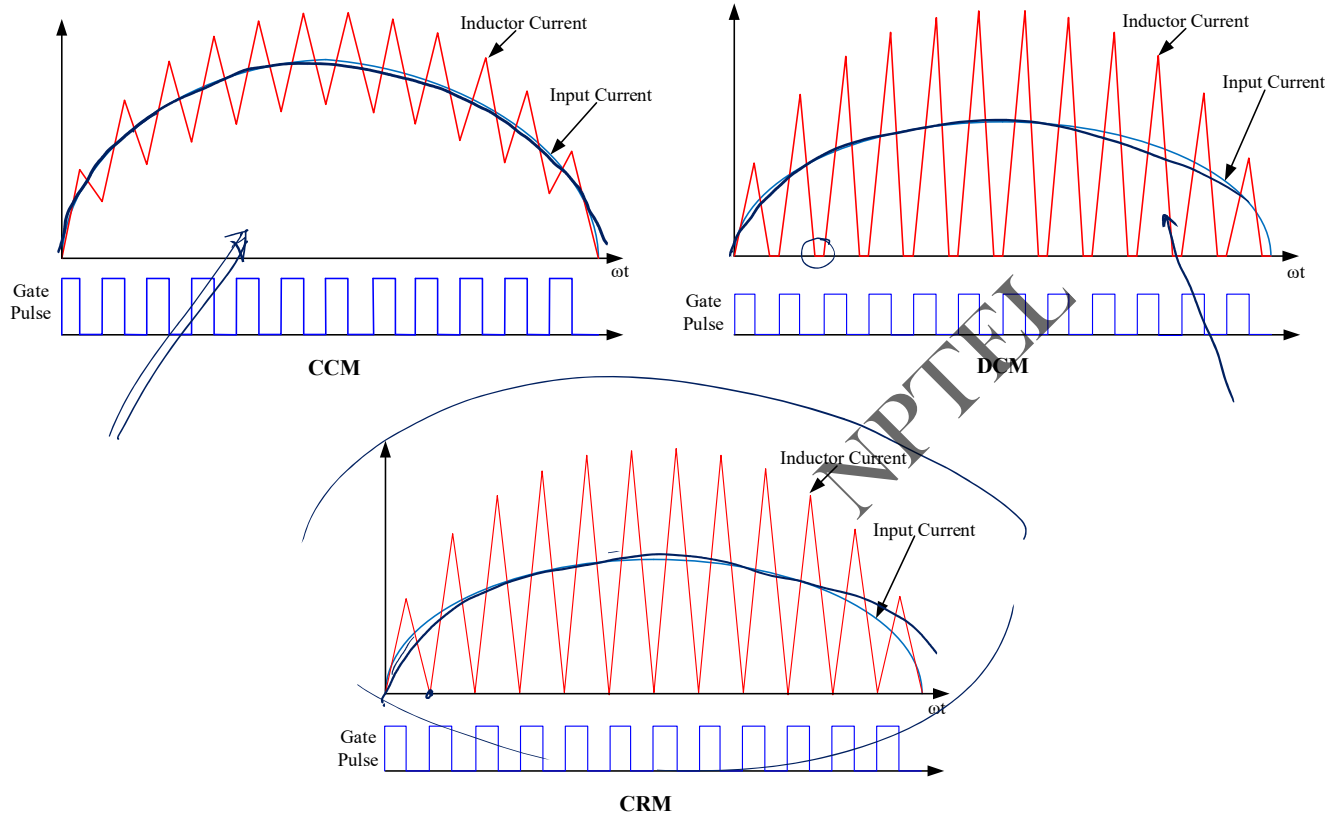
$C_{dc}$

$v_o$

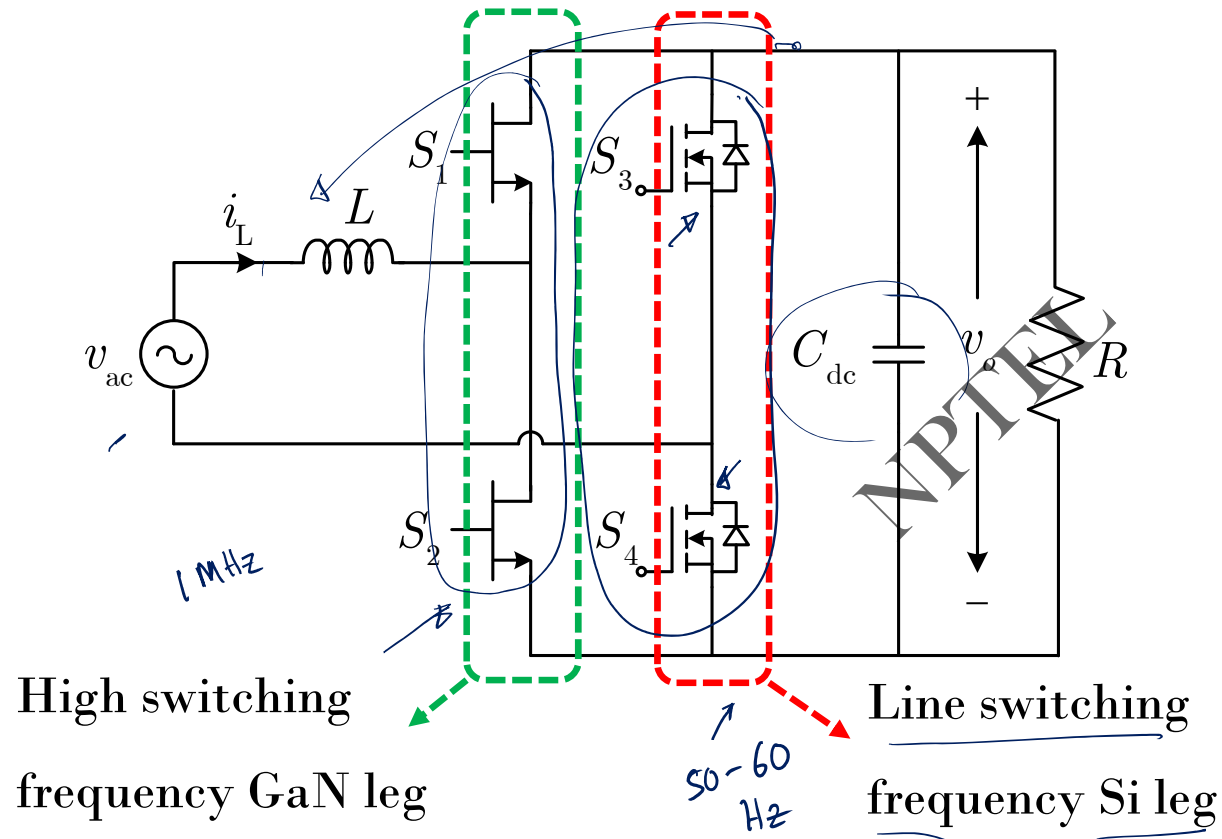
$R$

380 to 400V

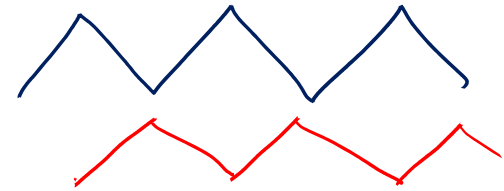
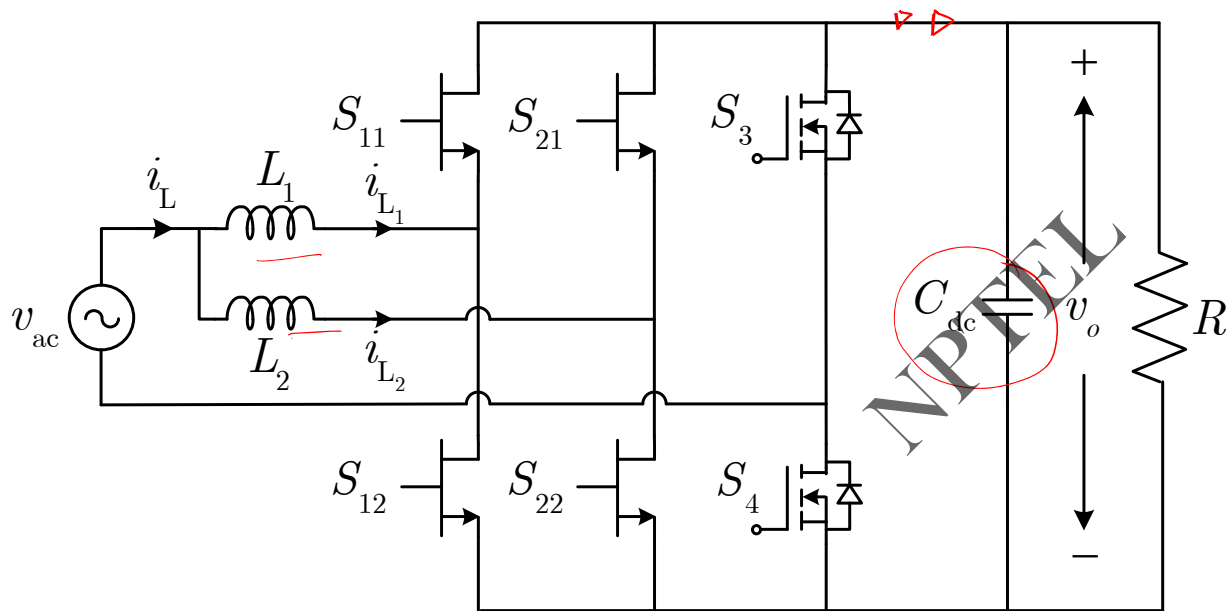
# Modes of Operation



## Single-Phase Totem-pole PFC



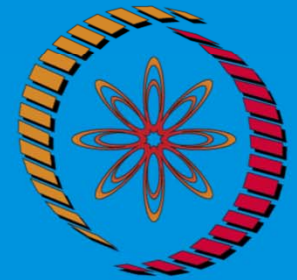
## Single-Phase Interleaved Totem-pole PFC



## CONCLUSION

- Power stage design aspects of buck and boost converters
- Buck and boost converters under steady-state in CCM and DCM
- Full-bridge LLC converter – basic operations for varying frequency
- Conventional boost PFC and totem-pole PFC for AC/DC conversion





**THANK  
YOU !**