



**NPTEL ONLINE CERTIFICATION COURSES**

# **DIGITAL CONTROL IN SMPCs AND FPGA-BASED PROTOTYPING**

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**Module 02: Fixed and Variable Frequency Digital Control Architectures**

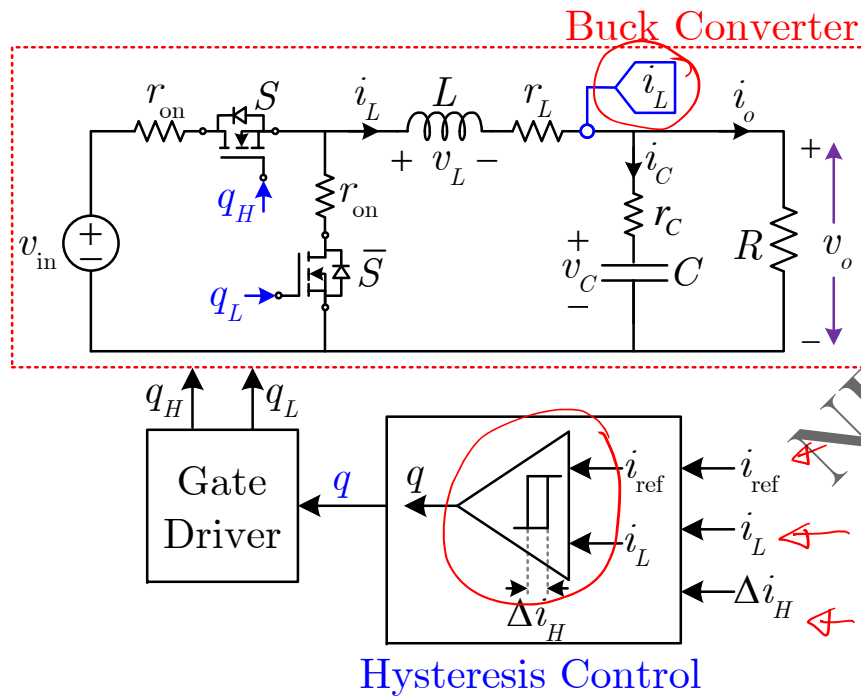
**Lecture 18: Sampling Methods under Digital Hysteresis Control Methods**



## CONCEPTS COVERED

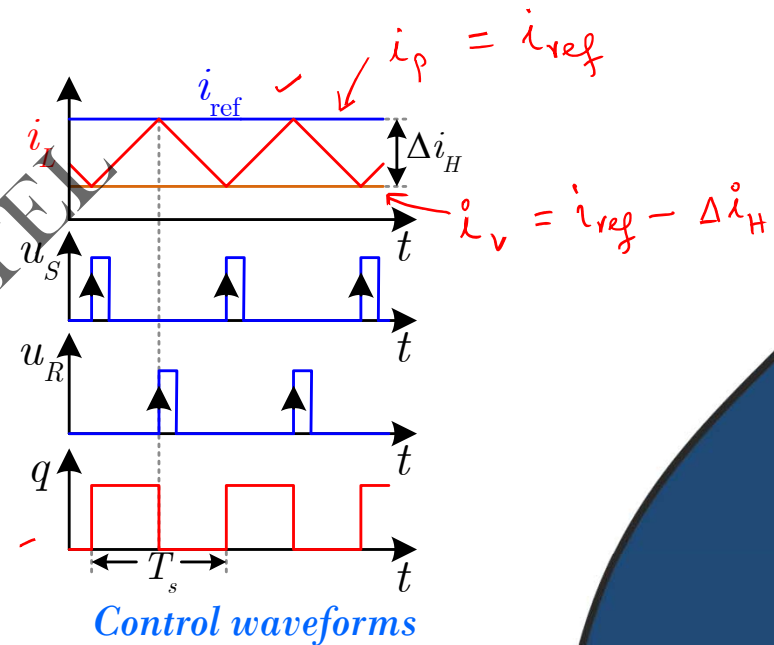
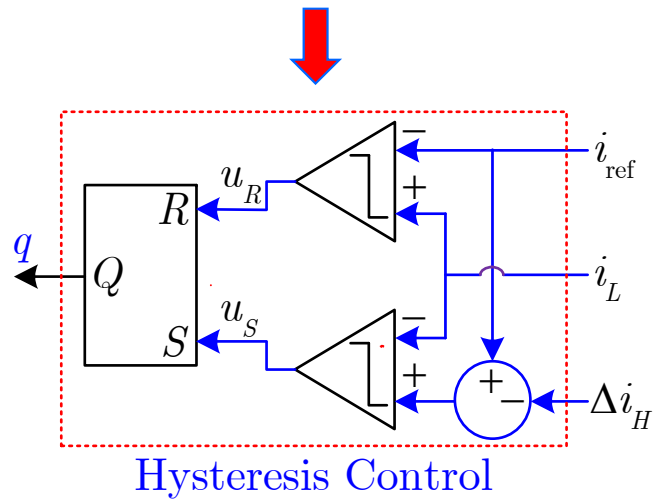
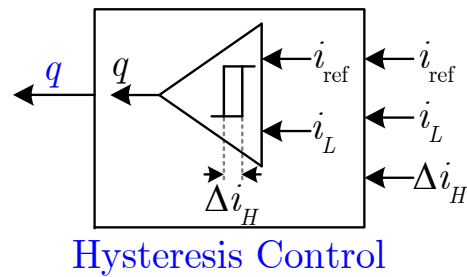
- Recap of analog current hysteresis control
- Sampling method in hysteresis current control
- Mixed-signal hysteresis current control

## Hysteresis CMC in a Buck Converter

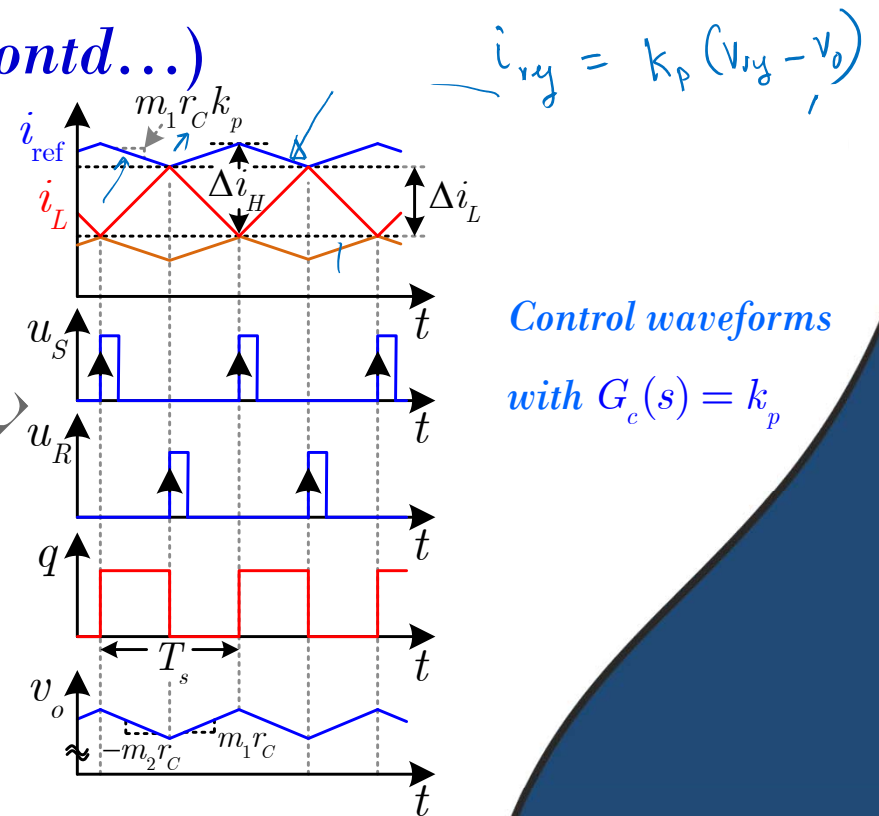
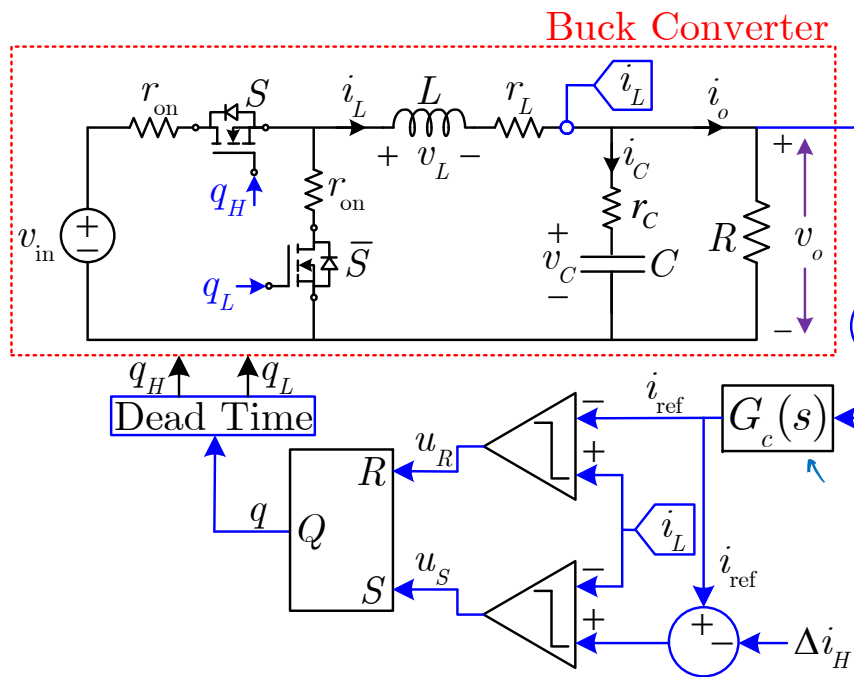


[ For details, refer to [Lecture~22, NPTEL “Control and Tuning Methods ...” course](#) ([Link](#))

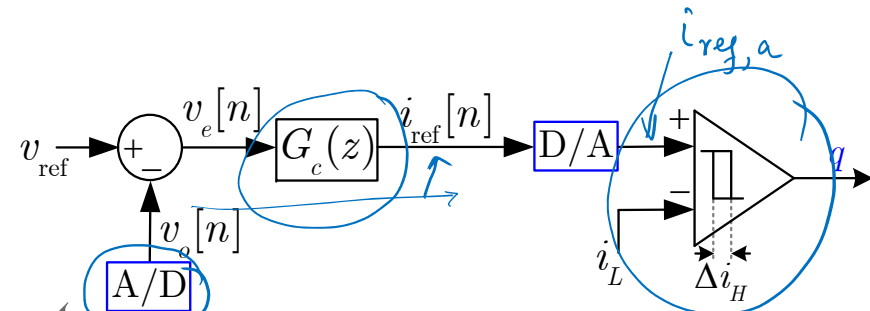
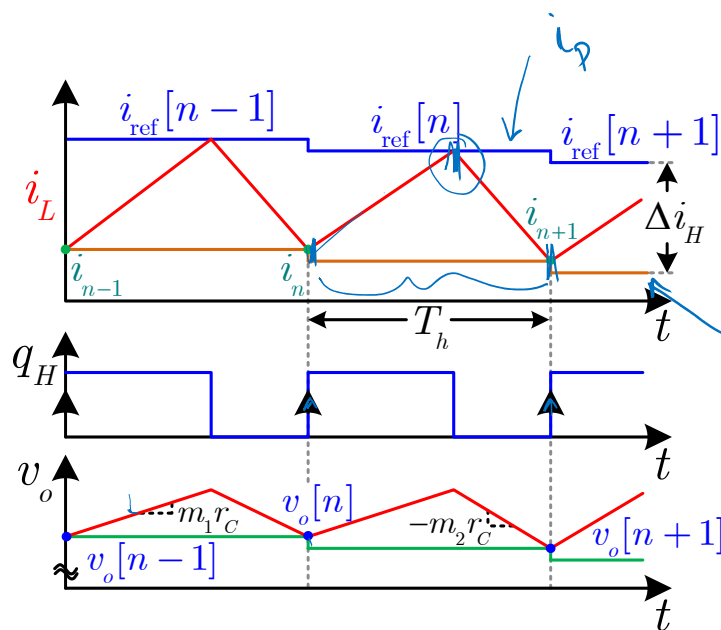
## Hysteresis CMC in a Buck Converter (contd...)



## Hysteresis CMC in a Buck Converter (contd...)



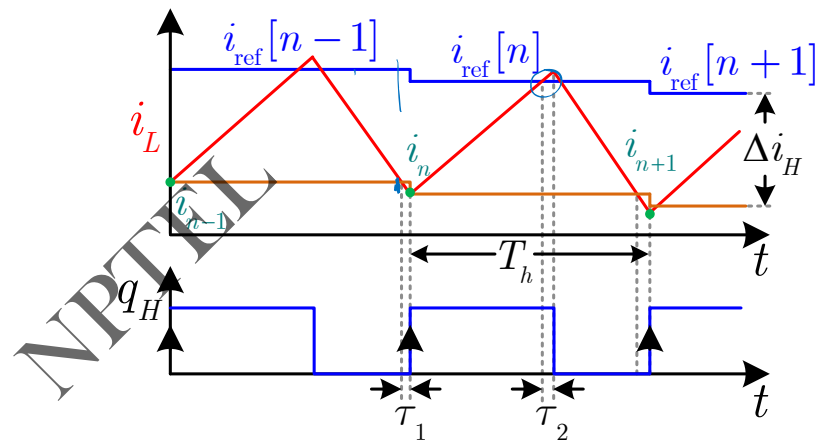
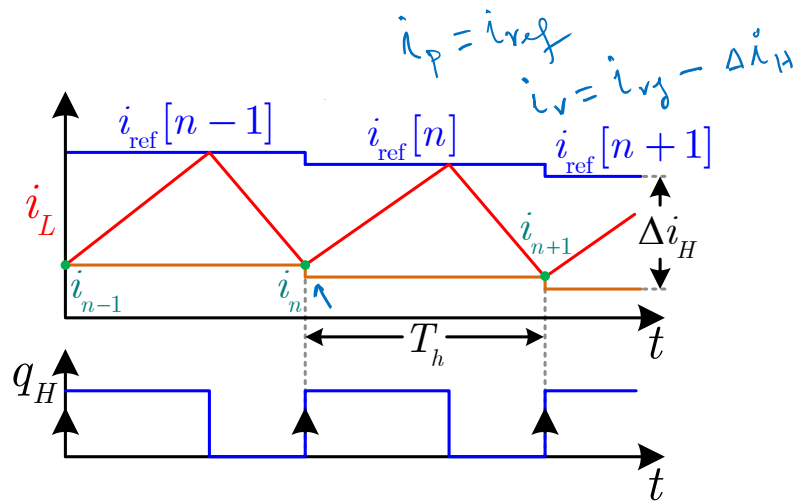
# Control Waveforms of Peak Current-mode MSHCC



Mixed signal hysteresis current controller block

[ S. Kapat, "Parameter-Insensitive Mixed-Signal Hysteresis-Band ... ", *IEEE TPEL*, 2017]

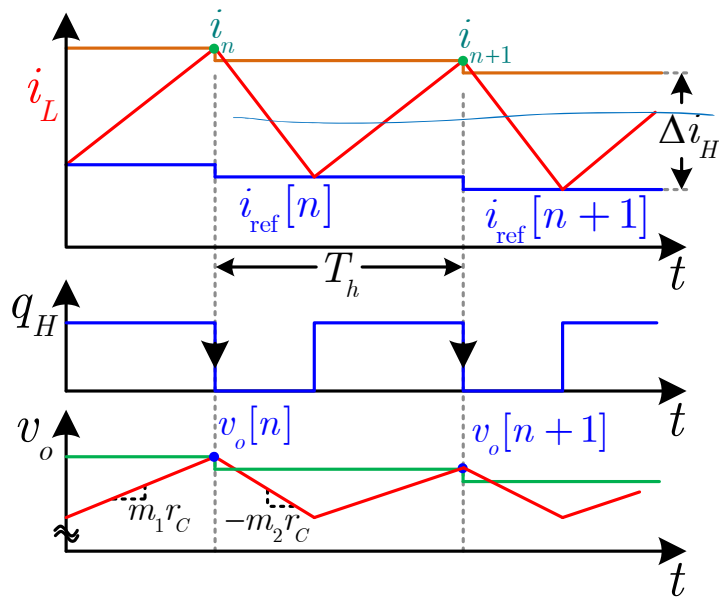
## Control Waveforms of Peak Current-mode MSHCC (contd...)



Control waveforms with comparator turn-on and turn-off delay

[ S. Kapat, "Parameter-Insensitive Mixed-Signal Hysteresis-Band ... ", *IEEE TPEL*, 2017 ]

## Control Waveforms of Valley Current-mode MSHCC



$$\begin{aligned} i_v &= i_{ref} \\ i_p &= i_{ref} + \Delta i_H \end{aligned}$$

Average HCC

$$i_p = i_{ref} + \frac{\Delta i_H}{2}$$

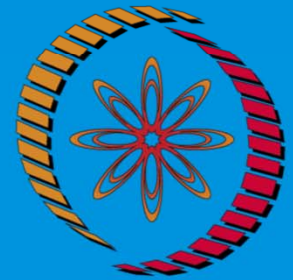
$$i_v = i_{ref} - \frac{\Delta i_H}{2}$$

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## CONCLUSION

- Recap of analog current hysteresis control
- Sampling method in hysteresis current control
- Mixed-signal hysteresis current control



**THANK  
YOU !**