

Smooth network inference from neural tracing data

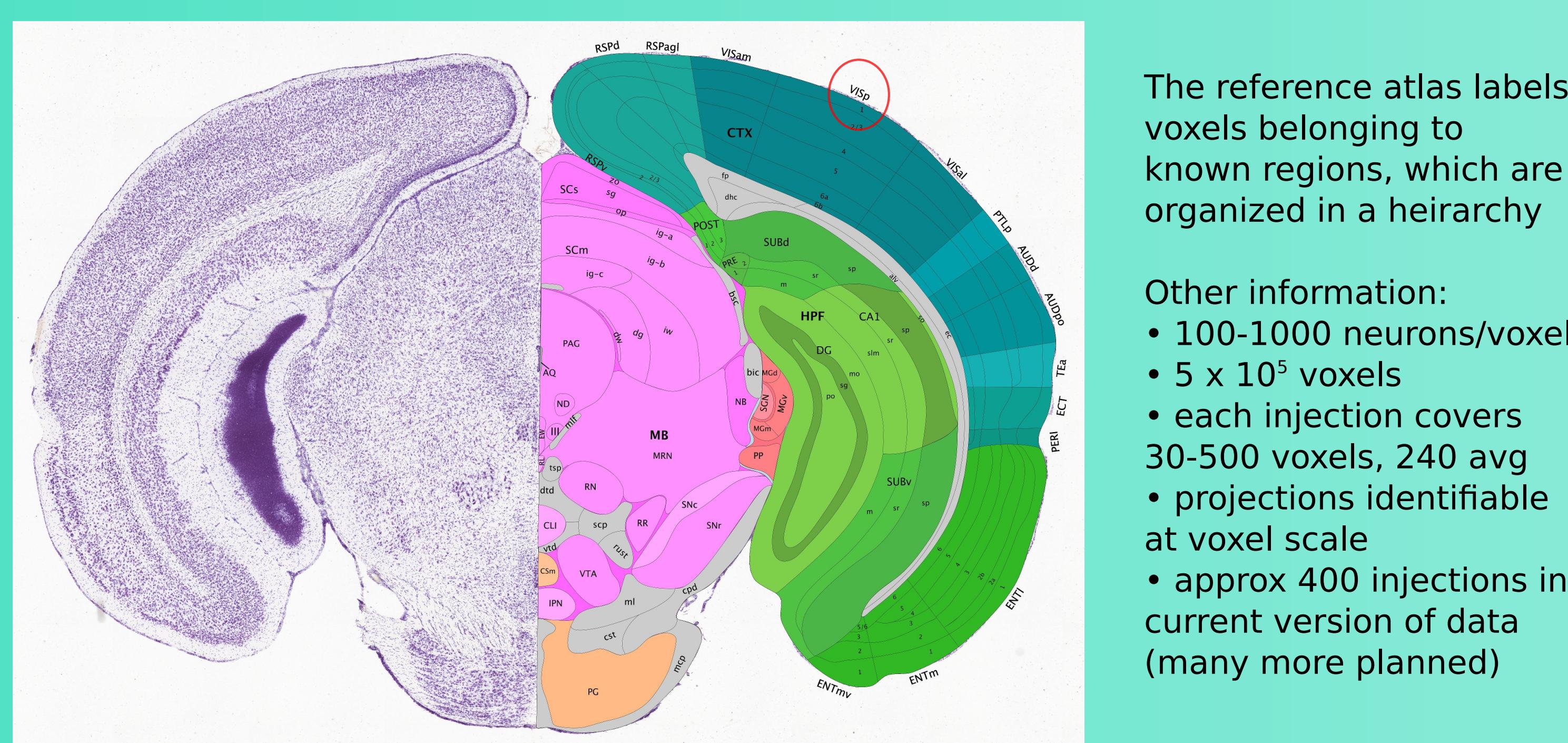
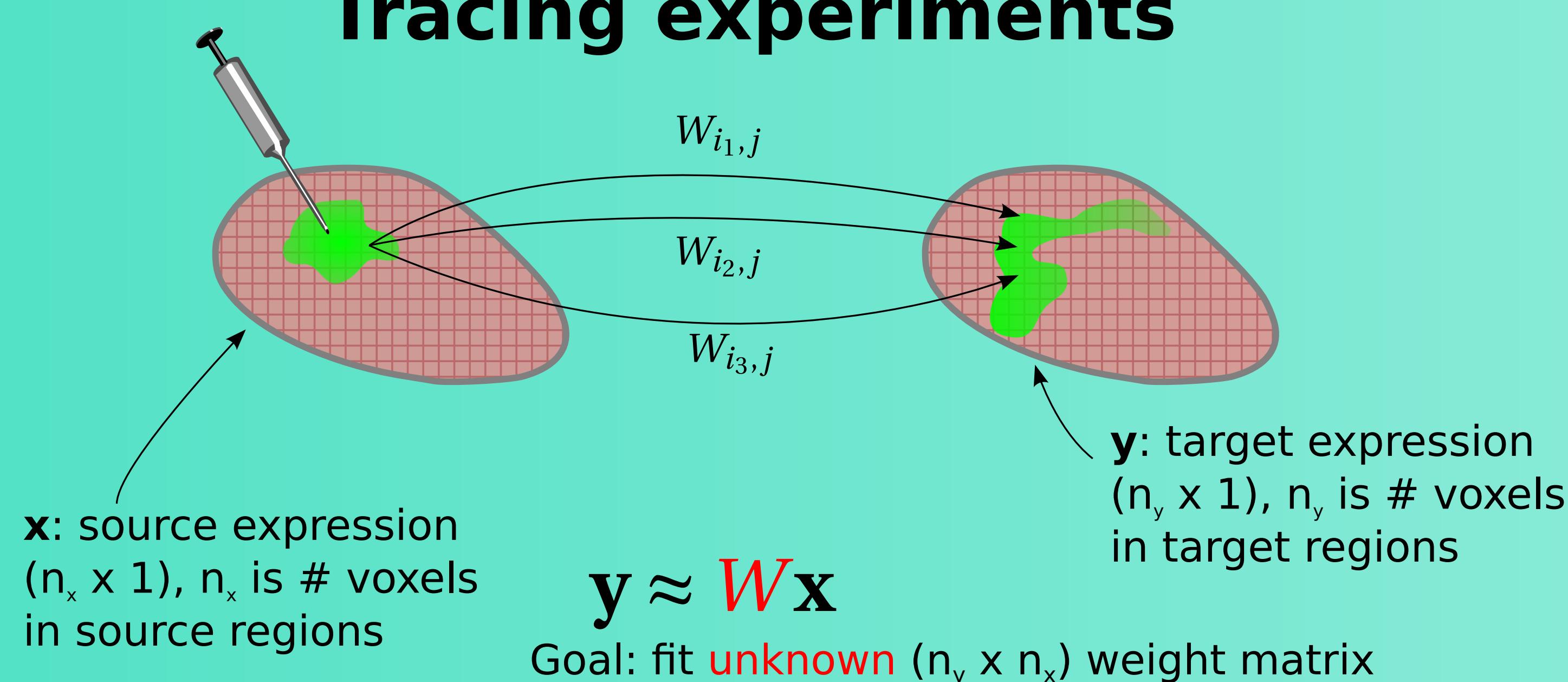
Kameron Decker Harris¹ (kamdh@uw.edu), Nicholas Cain², Stefan Mihalas^{1,2}, Eric Shea-Brown¹
¹Applied Mathematics, University of Washington, Seattle, WA USA; ²Allen Institute for Brain Science, Seattle, WA USA

Motivation

Broadly, understand interplay of brain **structure** and **information representation**

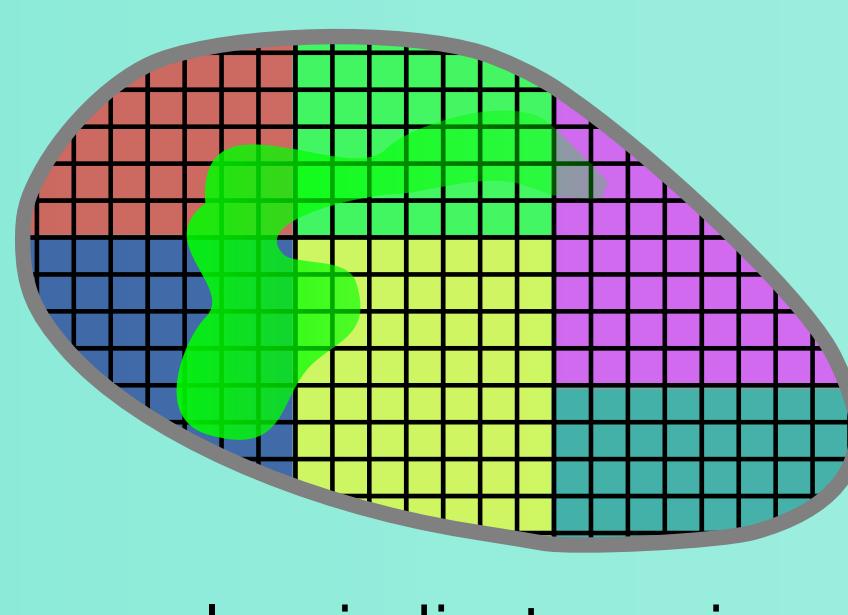
Improve the resolution of the connectivity weight matrix to voxel scale: underconstrained w/o regularization

Tracing experiments



Acknowledgements: ESB and KDH acknowledge support from NSF Grant #1122106 and a Simons Fellowship in Mathematics. KDH was also supported by a Boeing fellowship. We wish to thank the Allen Institute founders, Paul G. Allen and Jody Allen, for their vision, encouragement and support. Thanks also to the computational neuroscience community at UW, including Joel Zylberberg, for suggestions and discussions.

Previous work: regional model



Oh et al., 2014, Nature 508(7495):207-214

Integrate source and target expression over regions to produce regional vectors of expression $\mathbf{x}^{(r)}$ and $\mathbf{y}^{(r)}$

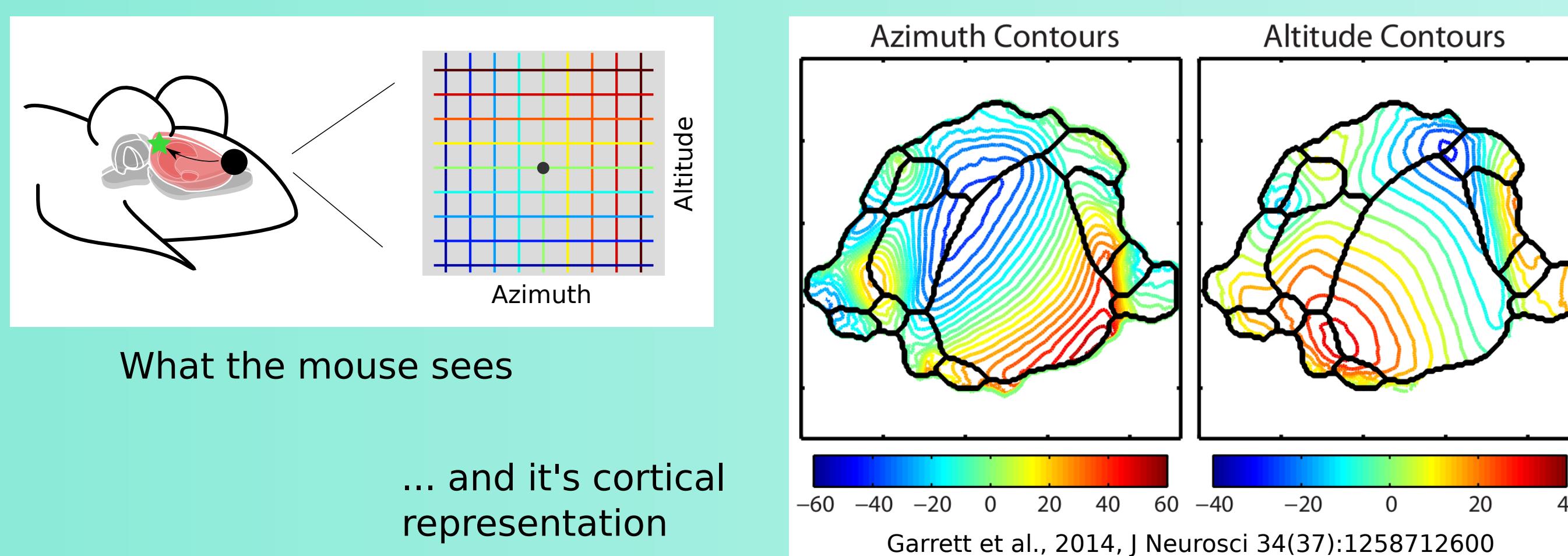
$(n_r \times 1) \quad (n_r \times 1)$

Then fit the $(n_r \times n_r)$ weight matrix $W^{(r)}$ via least squares by solving

$$\min_W \|Y^{(r)} - W^{(r)} X^{(r)}\|_F^2$$

This is the same as choosing a voxel scale W where W_{ij} is constant for all voxels i in region A and j in region B, for all regions A and B

Evidence for smoothness

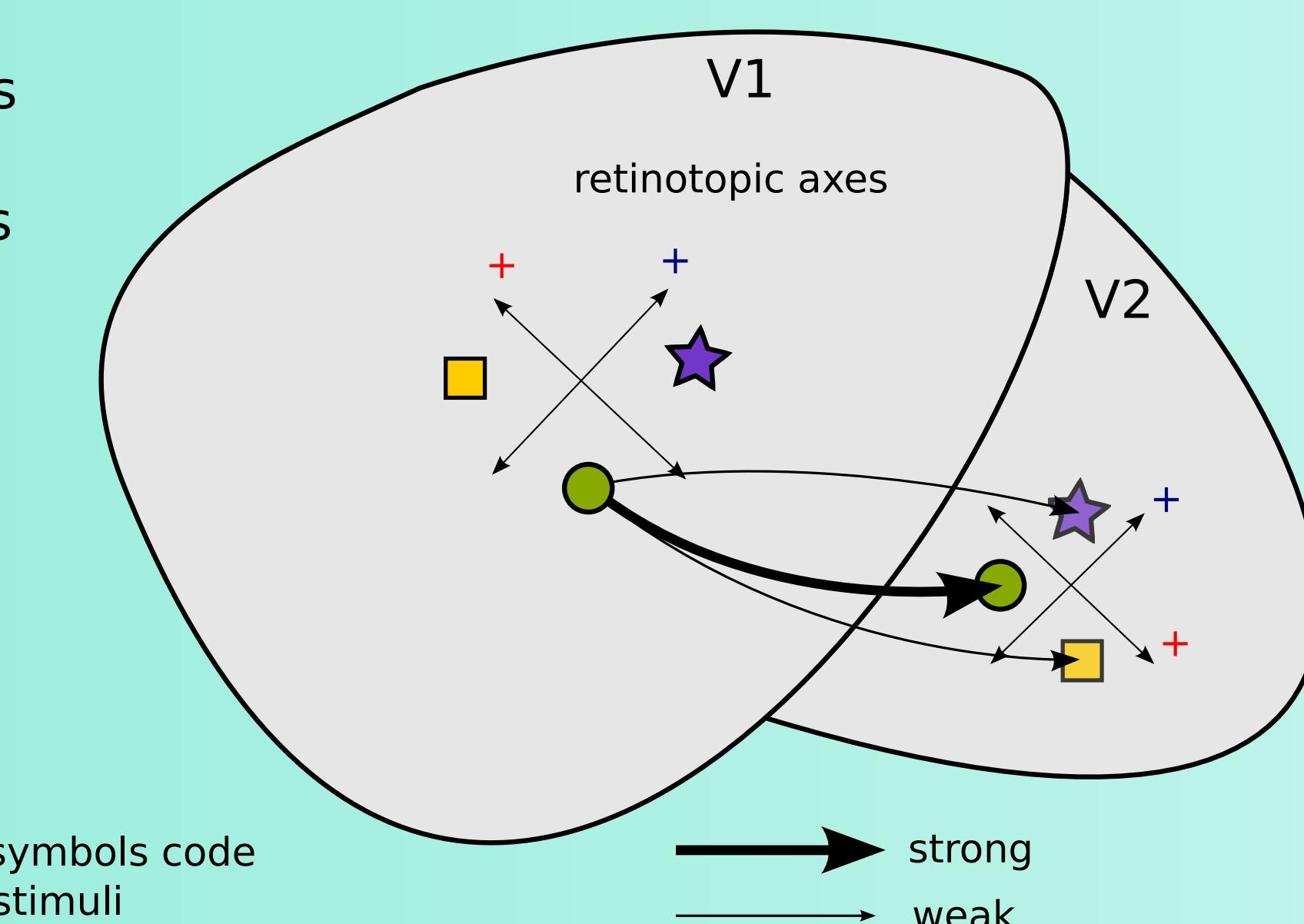


Retinotopy (map representation of visual field) in primary visual cortex is maintained from V1 into deeper areas analogous to V2, etc.

Hypothesis:

- like connects strongest to like
- connection strength decreases as similarity decreases
- each injection covers 30-500 voxels, 240 avg
- projections identifiable at voxel scale
- approx 400 injections in current version of data (many more planned)

Above items taken together suggest connections will vary smoothly in space



Smoothness regularized model

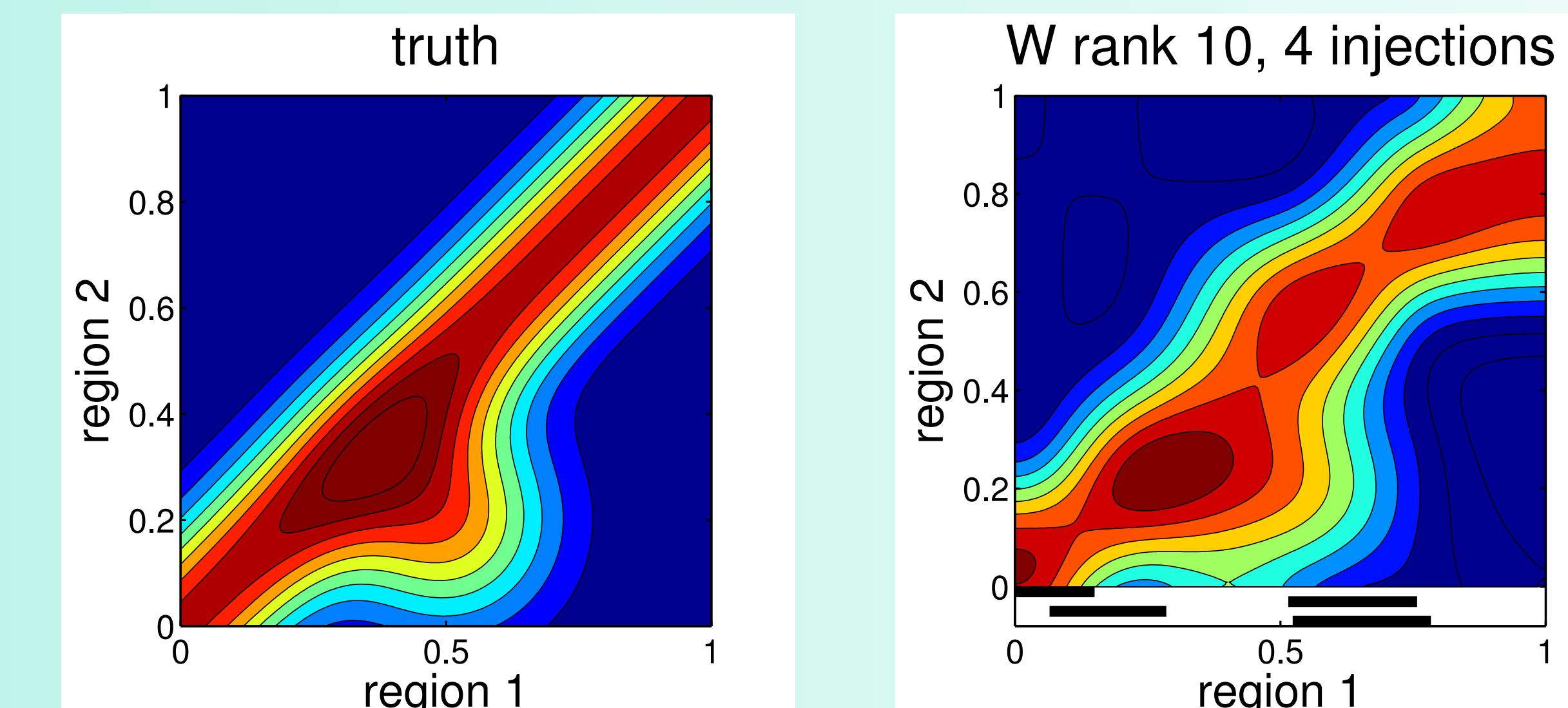
Find the voxel-resolution connection matrix W that balances goodness of fit and smoothness:

$$\min_W \|Y - WX\|_F^2 + \lambda \|WL_x^T + L_y W\|_F^2 *$$

data matrices: $Y = [y_1, \dots, y_{n_{inj}}]$
 $X = [x_1, \dots, x_{n_{inj}}]$

Laplacian matrices (smoothness terms), Neumann boundary conditions

The choice of a Laplacian penalty in this regression is analogous to so-called "thin-plate splines" for curve fitting or interpolation



Reconstruction of a smooth matrix in a test problem, $\lambda=2$

Method must be scalable to work with $O(10^5)$ voxels in dataset

Result: With n_{inj} small (relative to n_x, n_y) a low rank ($\approx 3 \times n_{inj}$) solution $W=UV^T$ works well in our 1-dimensional test problem

Require: $U_0 \in \mathbb{R}^{n_y \times r}, \epsilon > 0$ (and X, Y, L_x, L_y, λ to evaluate J)

Ensure: $W = USV^T$ rank r solution to the regularized problem

```

k ← 0
repeat
  k ← k + 1
   $\tilde{V}_k = \arg \min_V J(U_{k-1}, V)$ 
   $[V_k, S_k] = \text{svd}(\tilde{V}_k)$ 
   $\hat{U}_k = \arg \min_U J(U, V_k)$ 
   $U_k = \text{orth}(\hat{U}_k)$ 
until  $\|U_k - U_{k-1}\|_F < \epsilon$  and  $\|V_k - V_{k-1}\|_F < \epsilon$ 
return  $W = U_k S_k V_k^T$ 

```

Solve a generalized Sylvester equation of the form $AXB + CXD + XE + FX = G$ for X (J is cost function *)

Algorithm: Alternating least-squares low-rank solution

Challenges and future work

- Algorithmic bottleneck is Sylvester equation solve
- Regularization parameter & goodness of fit w/ cross-validation
- Does this work equally well in higher dimensions?
- How much injection coverage is needed?
- Hope to recover **retinotopy correlation from connectivity**
- Fit entire mouse visual system... fit entire mouse brain