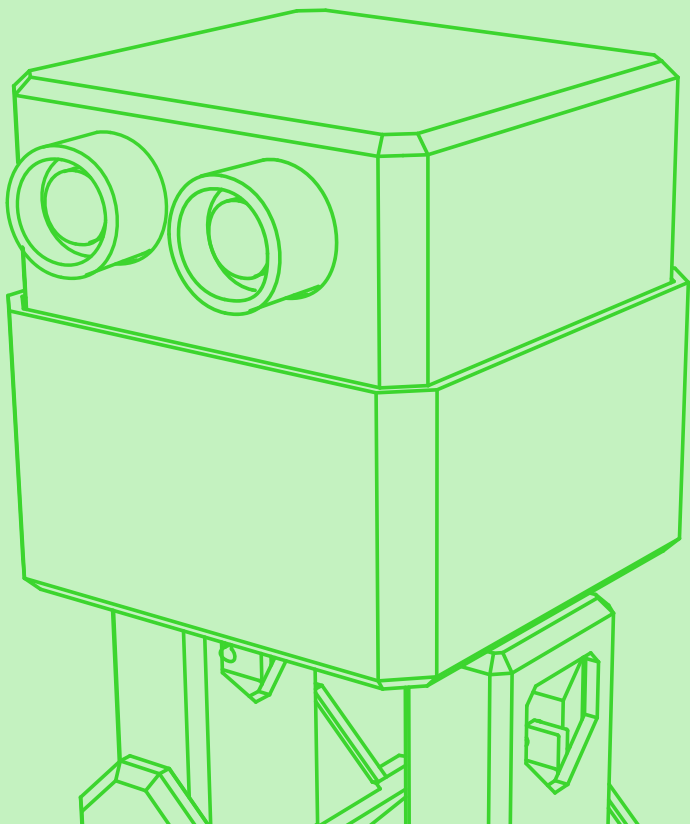


# DIY

INSTRUCTION MANUAL

说明书



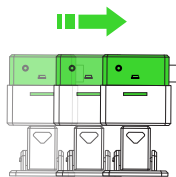
# build your own robot

## 打造你自己的机器人



### Otto is an interactive robot that anyone can make!

you will be able to build your own Otto in as little as two hours!  
easy to build and disassemble with a simple screwdriver.



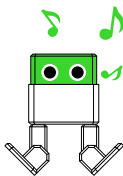
walk &  
dance



detect &  
avoid  
obstacles



easy to  
program

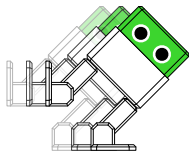


beeps &  
8bit music



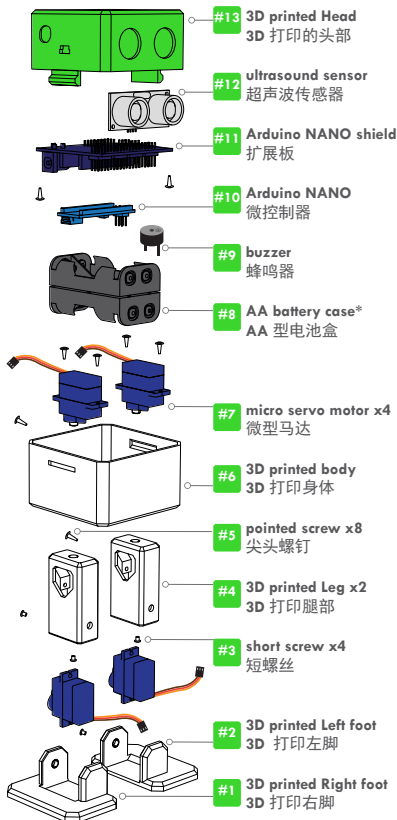
#OttoDIY

follow us!



# PARTS

## 部分



#16 F/F connector cable x6  
母对母杜邦线



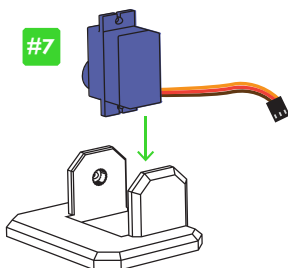
#15 mini cross screwdriver  
螺丝刀十字刀小一字



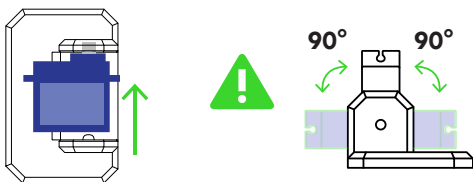
#14 mini usb cable  
延长线

\*AA batteries not included

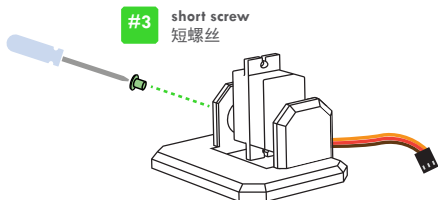
a



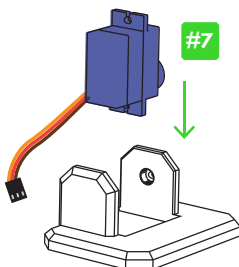
b



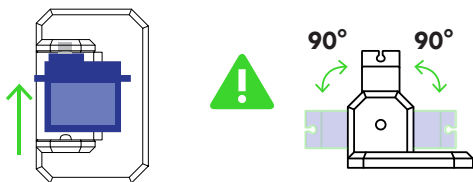
c



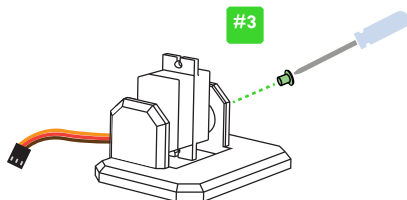
a



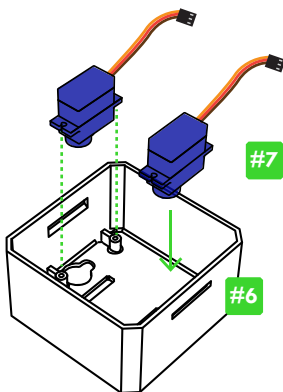
b



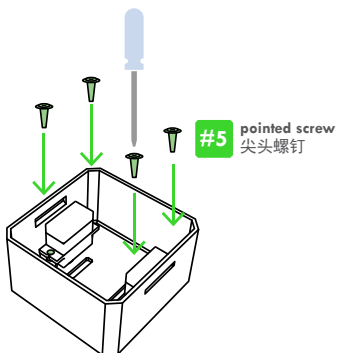
c



a



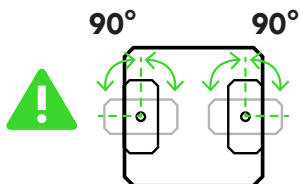
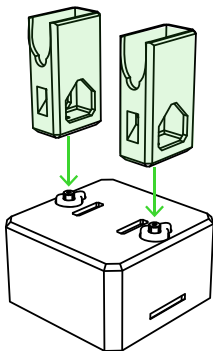
b



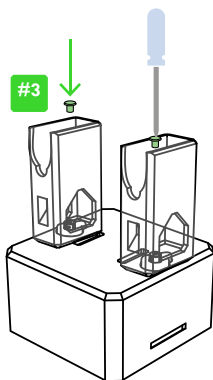
# 4



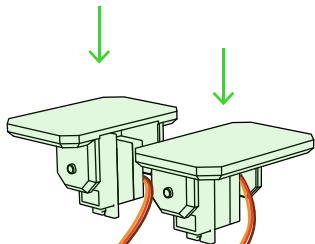
a



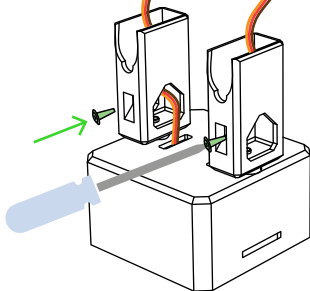
b



a

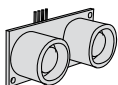


b

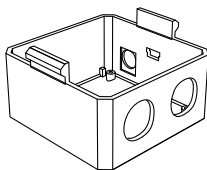




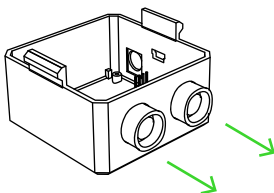
a



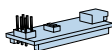
#12



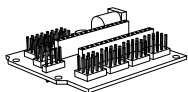
b



a

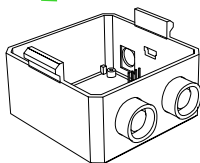
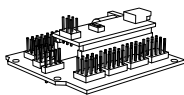


#10

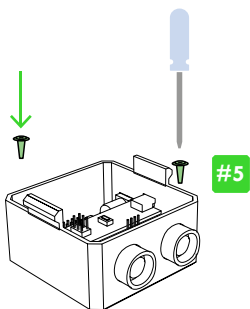


#11

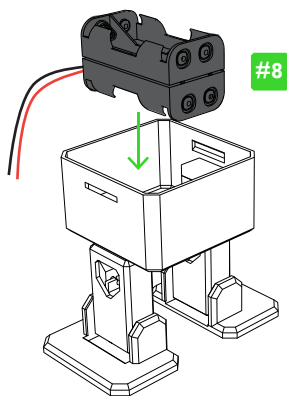
b



a



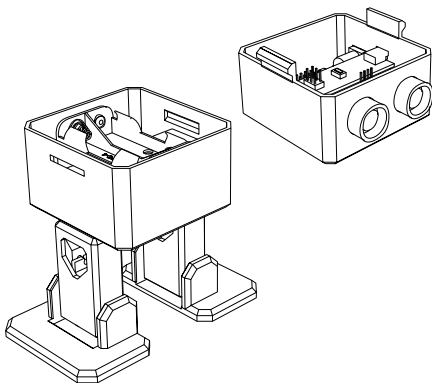
b



# 9

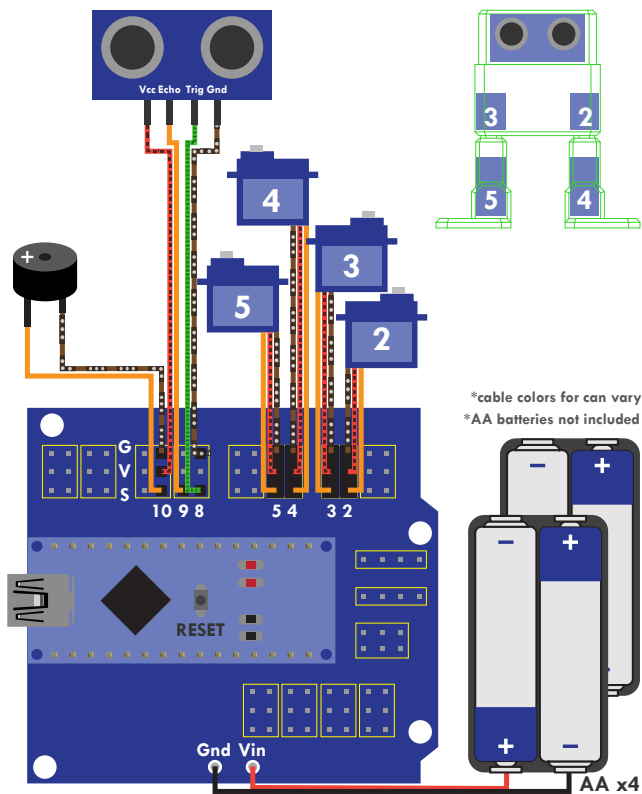


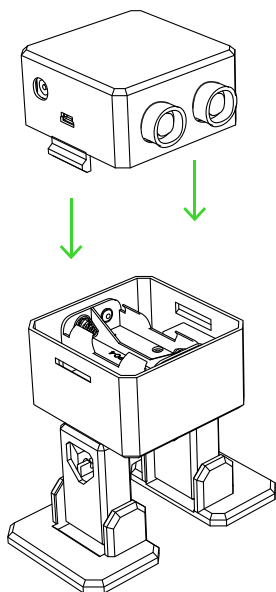
#9



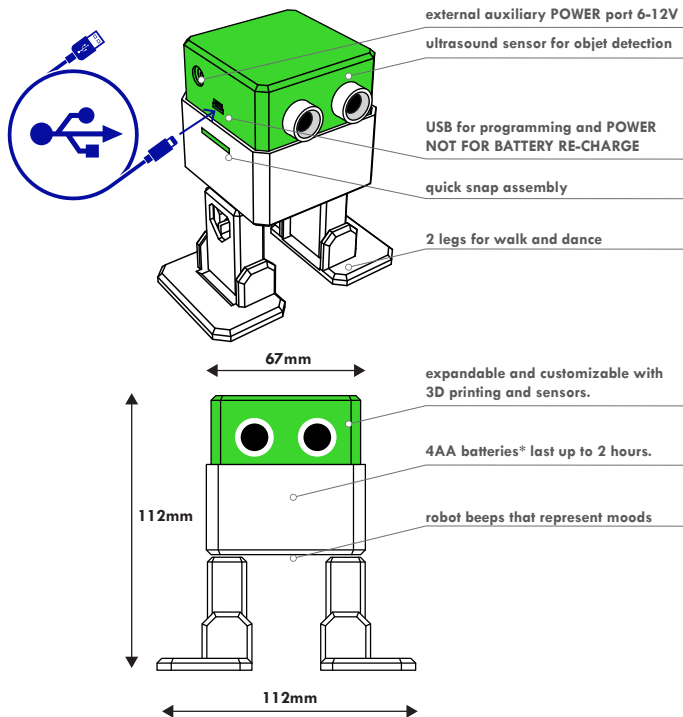
\*cable colors may vary

# 10



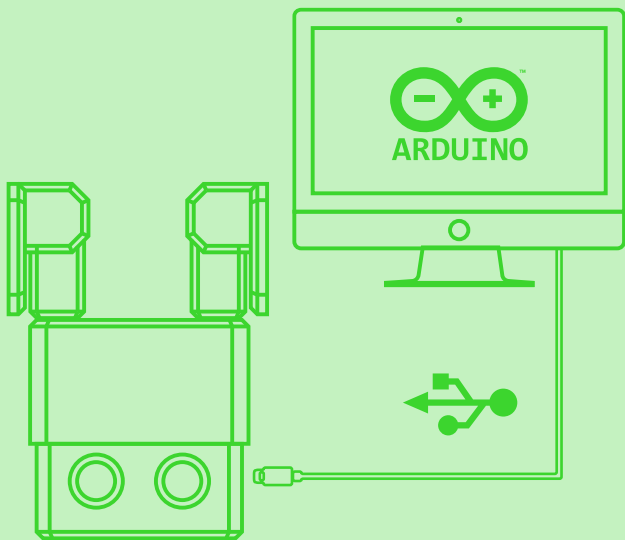


# 12



# DIY

## ARDUINO PROGRAMMING 编程





# 1



a

download Arduino for FREE to your computer  
from [www.arduino.cc](http://www.arduino.cc)




choose the appropriate Operating System  
installation package for your computer.



b

install Arduino in your computer...

- a** go to [ottodiy.com](http://ottodiy.com) in the build it! section  
download and unzip [OTTO\\_DIY\\_all.zip](#)
- b** from the “driver” folder install [CH341SER](#)
-  choose the appropriate Operating System  
installation package for your computer.
- c** copy or move all “[libraries](#)” folders to:  
  
C:\Documents\Arduino\libraries\  
(or wherever your Arduino library folder is)
- d** copy or move all “[OTTO\\_](#)” folders to:  
  
C:\Documents\Arduino\  
(or wherever your Arduino sketch folder is)

# 3



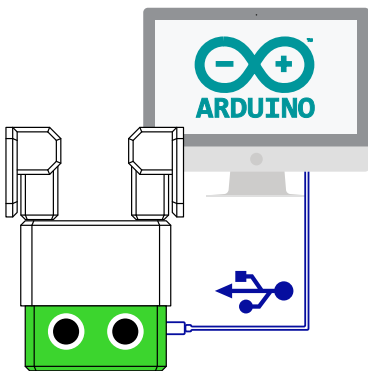
**a**

open Arduino and  
open OTTO\_avoid.ino



**b**

Connect Otto to your computer USB

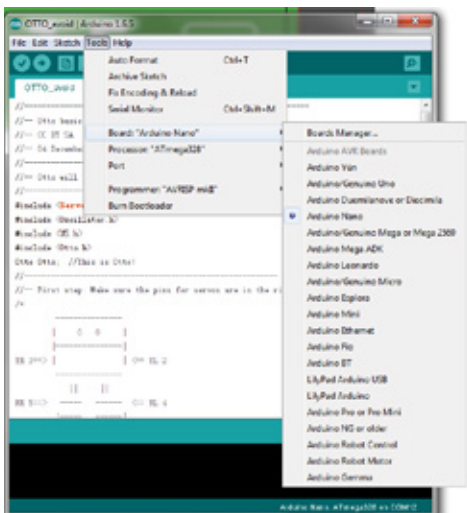


# 4



select in Arduino Tools/

- Board: “Arduino Nano”
- Processor: “ATmega328”
- Port COM# (where your Otto is connected)



# 5



**a**

verify the code



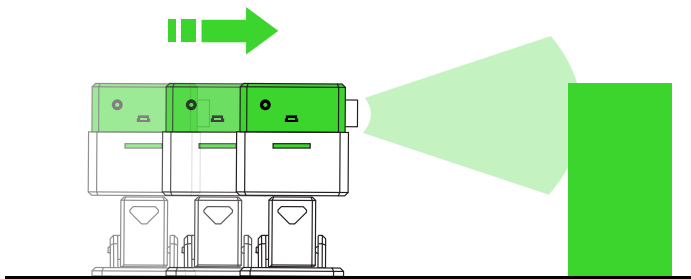
**b**

upload the code



**c**

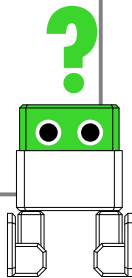
Otto will walk endless until detect obstacles to avoid



*in Arduino the principal loop code looks like this:*

OTTO\_avoid.ino

```
52 | void loop() {  
    if(obstacleDetected){  
        Otto.sing(S_surprise);  
        Otto.playGesture(OttoFretful);  
        Otto.sing(S_fart3);  
        Otto.walk(2,1300,-1);  
        Otto.turn(2,1000,-1);  
        delay(50);  
        obstacleDetector();  
    }  
    else{  
        Otto.walk(1,1000,1);  
        obstacleDetector();  
    }  
}
```



### *sing function:*

Otto.sing(S\_surprise);

└──┘  
|  
sing function

("sound to make")



### *try change sound:*

(S\_surprise);

(S\_OhOoh);

(S\_OhOoh2);

(S\_cuddly);

(S\_sleeping);

(S\_happy);

(S\_superHappy);

(S\_happy\_short);

(S\_sad);

(S\_confused);

(S\_fart1);

(S\_fart2);

(S\_fart3);

(S\_mode1);

(S\_mode2);

(S\_mode3);

(S\_connection);

(S\_disconnection);

(S\_buttonPushed);

### *play Gesture function:*

```
Otto.playGesture(OttoFretful);
```

play Gesture function

("emotion to express")

### *try change emotion:*

(OttoSuperHappy);



(OttoSad);



(OttoSleeping);



(OttoFart);



(OttoConfused);



(OttoFretful);



(OttoLove);



(OttoAngry);



(OttoMagic);



(OttoWave);



(OttoVictory);



(OttoFail);





### *move functions:*

Otto.walk(2,1300,-1);



move function    (“#steps, Time[ms], direction”)

### *try change move function to:*

Otto.walk(1,1000,1);

Otto.walk(1,1000,-1);

Otto.turn(3,1000,1);

Otto.turn(3,1000,-1);

Otto.bend(2,1000,1);

Otto.bend(2,500,-1);

Otto.shakeLeg(1,1000,1);

Otto.shakeLeg(1,500,-1);

Otto.moonwalker(1,1000,moveSize,1);    moveSize: “height of the move”

Otto.moonwalker(1,1000,30,1);

Otto.crusaito(1,1000,moveSize,1);

Otto.flapping(1,1000,moveSize,1);

Otto.swing(1,1000,moveSize);

Otto.updown(1,1000,moveSize);

Otto.tiptoeSwing(1,1000,moveSize);

Otto.jitter(1,1000,moveSize);

Otto.ascendingTurn(1,1000,moveSize);

Otto.jump(1,1000);

# 10

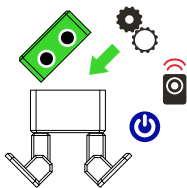


post your creations online

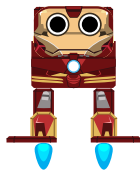


#OttoDIY share!

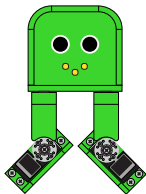
expand...



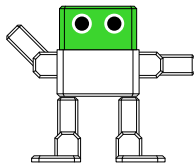
customize



modify



remix





build your own robot  
打造你自己的机器人

[ottodiy.com](http://ottodiy.com)