view_frames Result Recorded at time: 1600945323.897 world Broadcaster: /robot_state_publisher Broadcaster: /tf_interactive_marker_7086_1600944317799 Average rate: 10000.000 Hz Average rate: 20.385 Hz Most recent transform: 0.000 (1600945323.897 sec old) Most recent transform: 1600945323.702 (0.195 sec old) Buffer length: 0.000 sec Buffer length: 2.600 sec base_link HV8 Broadcaster: /robot_state_publisher Broadcaster: /tf_interactive_marker_7086_1600944317799 Broadcaster: /robot_state_publisher Broadcaster: /work_point_broadcaster Average rate: 10000.000 Hz Average rate: 42.049 Hz Average rate: 20.384 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1600945323.897 sec old) Most recent transform: 1600945323.690 (0.207 sec old) | Most recent transform: 1600945323.702 (0.195 sec old) Most recent transform: 1600945322.720 (1.177 sec old) Buffer length: 2.600 sec Buffer length: 0.000 sec Buffer length: 2.616 sec Buffer length: 0.000 sec open_orientation J1 HV8_optical_frame photoneo_center Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /work_point_broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 42.049 Hz Most recent transform: 0.000 (1600945323.897 sec old) | Most recent transform: 0.000 (1600945323.897 sec old) Most recent transform: 1600945322.720 (1.177 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.616 sec Buffer length: 0.000 sec grasp_work_point photoneo_center_optical_frame photoneo_center_camera_frame photoneo_center_sensor_frame Broadcaster: /robot_state_publisher Broadcaster: /work_point_broadcaster Average rate: 42.049 Hz Average rate: 10000.000 Hz Most recent transform: 1600945323.690 (0.207 sec old) Most recent transform: 1600945319.721 (4.176 sec old) Buffer length: 2.616 sec Buffer length: 0.000 sec J3 fixed_real_work Broadcaster: /robot_state_publisher Average rate: 42.049 Hz Most recent transform: 1600945323.690 (0.207 sec old) Buffer length: 2.616 sec Broadcaster: /robot_state_publisher Average rate: 42.049 Hz Most recent transform: 1600945323.690 (0.207 sec old) Buffer length: 2.616 sec J5 Broadcaster: /robot_state_publisher Average rate: 42.049 Hz Most recent transform: 1600945323.690 (0.207 sec old) Buffer length: 2.616 sec Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1600945323.897 sec old) Buffer length: 0.000 sec hand_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1600945323.897 sec old) Buffer length: 0.000 sec hand_body_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 42.049 Hz Average rate: 42.049 Hz Average rate: 42.049 Hz Most recent transform: 1600945323.690 (0.207 sec old) Most recent transform: 1600945323.690 (0.207 sec old) Most recent transform: 1600945323.690 (0.207 sec old) Buffer length: 2.616 sec Buffer length: 2.616 sec Buffer length: 2.616 sec finger_3rd finger_L finger_R