

Explanation of Algorithm

- ▶ DFS numbers of all vertices initialized to 0.
 - It serves as vertices marked "unvisited"
 - Assigning DFS number to a vertex implies it is marked "visited"
- ▶ It then selects an arbitrary vertex $v = x$, builds a DFST, and computes $LOW[v]$ in one single pass.
- ▶ An edge leading to a new vertex is a tree edge.
- ▶ The tree edge is pushed on to the stack before making the recursive call.

Explanation of Algorithm

- ▶ On return from call $\text{LOW}[v]$ is computed.
- ▶ If v is an articulation point then its DFS number must be greater than or equal to LOW point of the child.
- ▶ At this point, all the edges up to and including v, w are output as a biconnected component.
- ▶ If w is a old vertex (DFS number is nonzero) then it is a back edge.
- ▶ Only back edge to a proper ancestor of the parent ($w \neq u$) would lower the LOW point.

Correctness of Algorithm

Lemma (*Correctness of LOW point computation*)

When $\text{Search}(w)$ procedure completes, the edges in the stack above (v, w) are the edges in the same biconnected components as (v, w) .

- ▶ To prove it, we use induction on the number of biconnected components, b .
- ▶ If there is just one biconnected components, i.e., $b = 1$, it is trivial.
 - In this case, there is no articulation point.
 - So all the edges of G will be on the stack.

Correctness of Algorithm

- ▶ Induction hypothesis: assume this to be true for all graphs having b biconnected components.
- ▶ Let G have $b + 1$ biconnected components.
- ▶ Consider the first $\text{Bicon}(w, v)$ call that ends with $\text{LOW}[w] \geq \text{dfn}[v]$ for a tree edge (v, w) .
- ▶ No edge has been removed yet from the STACK.
- ▶ Since $\text{LOW}[w] \geq \text{dfn}[v]$, all the set of edges above (v, w) are incident on the descendants of w and first block B_1 has been detected.
- ▶ So the edges on the STACK above (v, w) are exactly the edges in the same biconnected component as (v, w) .

Correctness of Algorithm

- ▶ Now after removing edges of B_1 , the algorithm works on induced graph $G' = G - B_1$, in exactly the same way as it had worked on graph G .
- ▶ But G' has b biconnected components.
- ▶ By induction, algorithm should correctly obtain all b biconnected components of G' .

Notion of Connectedness in Directed Graphs

- ▶ For every pair of vertices u, v there exists a path.
- ▶ But path here means directed path.
- ▶ Connectivity in directed graph implies both $u \rightsquigarrow v$ and $v \rightsquigarrow u$.
- ▶ In general, it is possible that path $u \rightsquigarrow v$ may exist but $v \not\rightsquigarrow u$.
- ▶ Or even u and v are not reachable from each other.
- ▶ There is also a notion of weak connectivity: it possible to reach any vertex from any other vertex by traversing edges in some direction (ignoring direction).
- ▶ It essentially means every vertex has either indegree or outdegree of at least 1.

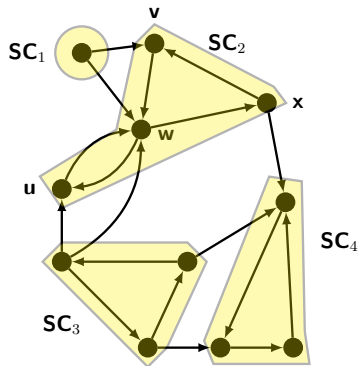
Strong Connected Components (SCC)

Definition (SCC)

Let $G = (V, E)$ be directed graph. G is strongly connected iff for every pair of vertices v, w , there is a directed path from v to w and also a directed path from w to v .

- ▶ SCC is an equivalence relation.
- ▶ If u, v are in same SCC then uRv and vRu where R : there exists a directed path.
- ▶ If uRv and vRw then obviously, uRw .
- ▶ Collapsing each SCC to a vertex we get a condensation graph which is a DAG.

Strong Connected Components



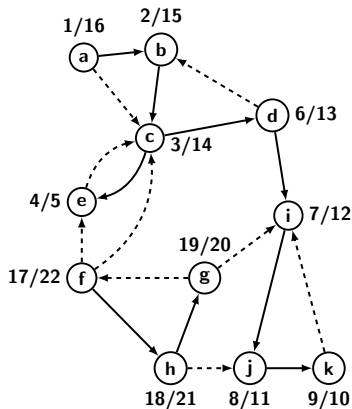
- ▶ There are four SCCs.
- ▶ One SCC has just one vertex.
- ▶ Consider $u, v \in SC_2$.
- ▶ There exists pair of paths:
 $u \rightarrow w \rightarrow x \rightarrow v$ and
 $v \rightarrow w \rightarrow u$.

Strong Connected Components

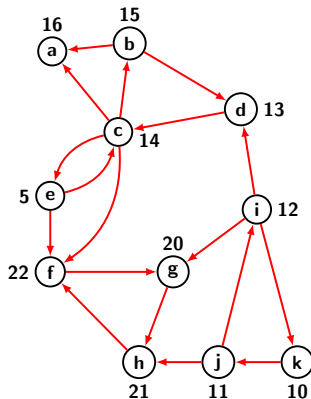
- ▶ Compute Finish time $f[u]$ for $u \in V$.
- ▶ Reverse each edge of G to obtain G^T .
- ▶ Call DFS on G^T but apply it decreasing order of finish time $f[u]$ as computed in first DFS.
- ▶ Output the vertices of each tree in DFS forest of G^T as a separate SCC.

Strong Connected Components

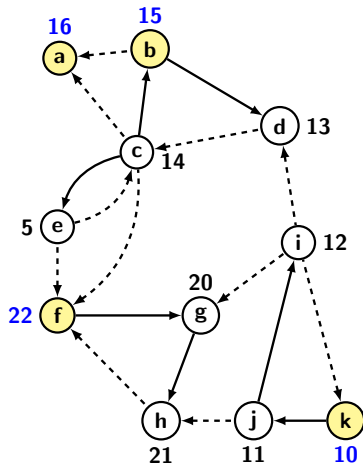
Original Graph G



Transformed Graph G^T (by reversing edge directions).



Strong Connected Components



- ▶ Start vertices in decreasing order of finish time: f , a , b , and k .
- ▶ DFS from these vertices discover SCCs:
 - f : $\{f, g, h\}$
 - a : $\{a\}$
 - b : $\{b, c, d, e\}$
 - k : $\{i, j, k\}$

Correctness of SCC Algorithm

- ▶ Let $d[v]$: DFS discovery time, and
- ▶ Let $f[v]$: DFS finish time.
- ▶ Let S be subset of V .

$$d[S] = \min_{u \in S} d[u], \text{ and } f[S] = \max_{u \in S} f[u]$$

Lemma

Let S_1 and S_2 be two distinct SCCs. If \exists an edge $(u, v) \in E$, where $u \in S_1$ and $v \in S_2$ then $f[S_1] > f[S_2]$

Correctness of SCC Algorithm

Proof.

- ▶ Case 1 ($d[S_1] < d[S_2]$): Let x be first vertex in S_1 to be discovered.
- ▶ At this time none of the vertices in S_1 and S_2 have been marked "visited"
- ▶ For any vertex $w \in S_2$, \exists a path from x to w .
- ▶ So, all vertices in S_2 are descendants of x
- ▶ Therefore, $f[x] = f[S_2] < f[S_1]$



Correctness of SCC Algorithm

Proof continues.

- ▶ Case 2 ($d[S_1] > d[S_2]$): Let y be the first vertex discovered in S_2 .
- ▶ All vertices in S_2 are descendant of y .
- ▶ Therefore, by definition $f[y] = f[S_2]$.
- ▶ Since, S_1 and S_2 are distinct SCC there cannot be path from any vertex of S_2 to a vertex of S_1 .
- ▶ So all vertices in S_1 are "unvisited" when DFS of S_2 is complete.
- ▶ Therefore, $f[S_2] < f[S_1]$.



Correctness of SCC Algorithm

A corollary of the above lemma is on G^T where the inequalities are reversed is as follows:

Lemma (Corollary I)

Let S_1 and S_2 be two distinct SCCs. If \exists an edge $(u, v) \in E^T$ where $u \in S_1$ and $v \in S_2$ then $f[S_2] < f[S_1]$.

Proof.

- ▶ Since every edge is reversed in E^T , it implies $(v, u) \in E$.
- ▶ Therefore, $f[S_1] > f[S_2]$ from the previous lemma.



Correctness of SCC Algorithm

Another corollary that follows from the above result is:

Lemma (*Corollary II*)

If $f[S_2] > f[S_1]$, then there cannot be any edge (u, v) , where $u \in S_2$ to $v \in S_1$ in G^T .

- Use of decreasing finish time in exploring G^T is the intuition behind the algorithm's correctness.

Correctness of SCC Algorithm

- ▶ Consider a pair of vertices v and w .
- ▶ Let finish time of w is smaller than v : $f[w] < f[v]$.
- ▶ Now we consider three cases:
 - Case 1: $w \not\rightarrow v$ (v is not reachable from w) then v and w are in different SCCs, and correctness of algorithm is not affected.
 - Case 2: $w \rightsquigarrow v$ (v is reachable from w) and w is not in DFS subtree of v in G^T .
 - Case 3: w is in DFS subtree of v .
- ▶ Therefore, we consider last two cases in more details.

Correctness of SCC Algorithm

► Consider case 2:

- Since $d[w] < d[v]$ in DFS of G , w cannot be an ancestor of v .
- Furthermore, there cannot be of a cross link on $w \rightsquigarrow v$ path, because the finish time of a cross link's source vertex is greater than the finish time of its end vertex.
- So, case 2 is not possible, leaving case 3 as the only one possibility.

Correctness of SCC Algorithm

- ▶ Consider case 3:
 - When DFS enters a vertex v in G^T , all the vertices in SCCs with lower finish times remain unvisited.
 - And if there is a path $w \rightsquigarrow v$, it only means $w \in T_v$.
- ▶ So, proof is complete by noticing that for every two distinct components S_1 and S_2 , if $f[S_1] > f[S_2]$ there cannot be an edge from S_1 to S_2 in G^T .
- ▶ The above fact follows directly from the Corollary II proved earlier.
- ▶ This implies w and v both belong to same SCC.

Summary of Graph Algorithms

- ▶ Graph terminology and representation were introduced.
- ▶ BFS, and DFS search were explained.
- ▶ We learnt about a number of applications of DFS, particularly in computing:
 - Connected components, biconnected components of a undirected graphs, and
 - Strong connected components of directed graph and topological sorting of a DAG

Summary of Graph Algorithms

- ▶ With reference to weighted graphs we talked about the problems of determining shortest paths, namely,
 - Dijkstra and Bellman-Ford algorithms using edge relaxation operation.
 - Prim and Kruskal's algorithms for finding MSTs.
- ▶ We also looked at almost linear time UNION and FIND operations on disjoint sets in the context of Kruskal's algorithm.
- ▶ However, a detailed analysis of UNION-FIND algorithms was not discussed recognizing involved mathematical complications.