

# Lecture Summary: Discrete Random Variables and Distributions

Scribe Notes

## 1 Random Variables: Concept and Definitions

**Definition of Random Variable (RV):** A random variable  $X$  on a sample space  $\Omega$  is a function  $X : \Omega \rightarrow R$  that assigns a real number  $X(\omega)$  to each sample point  $\omega \in \Omega$ .

- **Discrete Random Variables:** These variables take values in a range that is either finite or countably infinite.
- **Discrete Subset:** While  $X$  maps to the set of real numbers ( $R$ ), the actual set of values  $\{X(\omega) : \omega \in \Omega\}$  that  $X$  takes is a discrete subset of  $R$ .

## 2 Probability Mass Function (PMF)

**Definition:** The PMF of a discrete random variable gives the probability of each outcome.

- **Visualization:** The distribution can be visualized as a bar diagram where the  $x$ -axis represents the possible values of the RV and the height of the bar at value  $a$  is the probability  $Pr[X = a]$ .
- **Legitimacy Condition:** For a discrete random variable, the sum of all probabilities in the PMF must equal 1:

$$\sum_i P\{X = i\} = 1$$

### Worked Example: Tossing 3 Fair Coins

**Experiment:** Tossing 3 fair coins.

**Random Variable ( $Y$ ):** Let  $Y$  denote the number of heads that appear.

**Possible Values and Probabilities:**

- $P\{Y = 0\} = P\{(t, t, t)\} = 1/8$
- $P\{Y = 1\} = P\{(t, t, h), (t, h, t), (h, t, t)\} = 3/8$

- $P\{Y = 2\} = P\{(t, h, h), (h, t, h), (h, h, t)\} = 3/8$

- $P\{Y = 3\} = P\{(h, h, h)\} = 1/8$

**Verification:**  $\sum_{i=0}^3 P\{Y = i\} = \frac{1}{8} + \frac{3}{8} + \frac{3}{8} + \frac{1}{8} = 1.$

### 3 Guide to Selecting a Discrete Probability Distribution

The following table provides conditions to identify the appropriate distribution:

Distribution	Description of $x$	Necessary Conditions
Binomial	Number of successes in $n$ trials	1. Identical trials 2. Two outcomes: Success (S) and Failure (F) 3. $P(S)$ and $P(F)$ remain constant 4. Trials are independent
Poisson	Successes for a rare event per unit	1. $P(S)$ remains constant across units 2. Unit $x$ values are independent
Hypergeometric	Number of successes in $n$ trials	1. Drawn <b>without replacement</b> from $N$ elements 2. Two outcomes: Success (S) and Failure (F)

### 4 Expectation and Moments

- **Expectation ( $\mu$ ):** Defined as  $E[X]$ .
- **Function of RV:** The expectation of a function of a random variable,  $E[g(X)]$ .
- **Linearity:** Linear operations with expectation, e.g.,  $E[aX+b] = aE[X] + b$ .
- **Moments:**  $n^{th}$  moments and central moments including **Variance**, **Skewness**, and **Kurtosis**.

### 5 CDF and PDF Properties

- **Cumulative Density Function (CDF):** Defined with specific properties and examples for discrete variables.
- **Probability Density Function (PDF):** Used for continuous variables to give the relative likelihood of outcomes in a range.
- **Legitimacy for Continuous RVs:** A PDF  $f_x(x)$  is legitimate if:

$$\int_{-\infty}^{\infty} f_x(x)dx = 1$$