Graph Data Structure

Graph

A graph **G** is defined by two sets

• **V**: set of vertices

• *E*: set of edges

Notation:

A graph G consisting of vertices V and edges E is denoted by

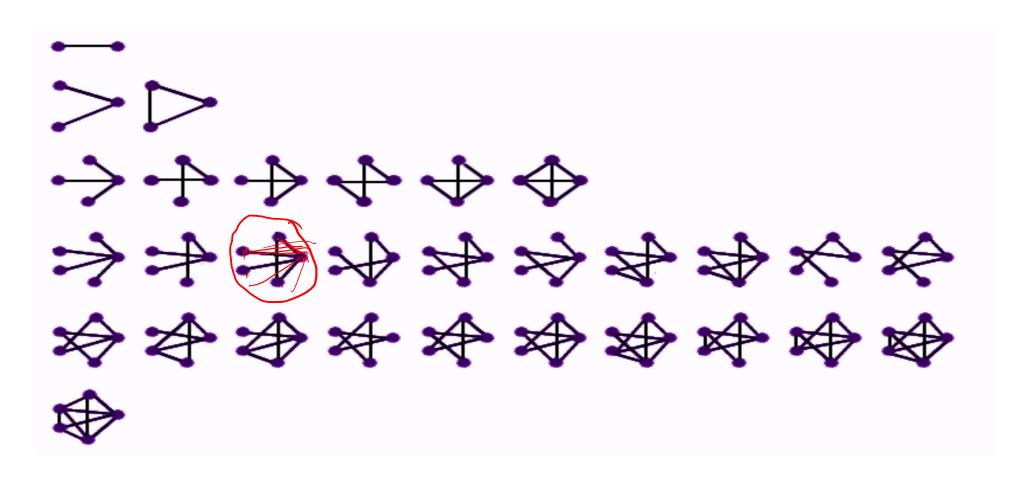


Order of a graph

• The order of a graph is number of vertices in the graph.

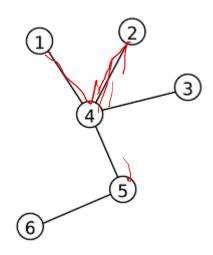
Connected graph

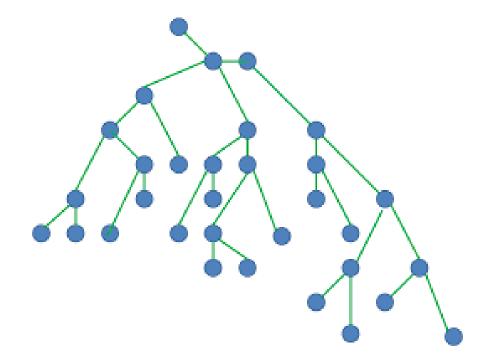
• A graph is a connected graph if, for each pair of vertices, there exists at least one single path which joins them.



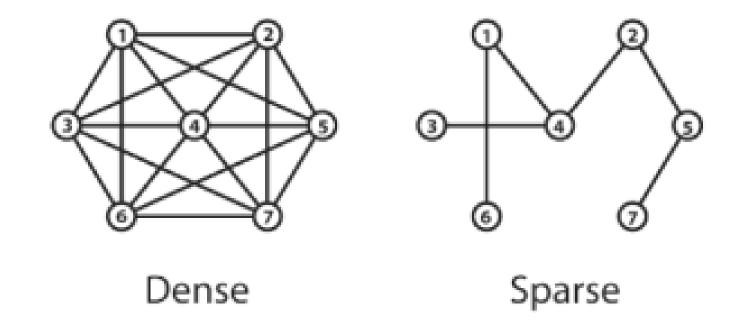
Tree graph

- A connected acyclic **graph** is called a **tree**. In other words, a connected **graph** with no cycles is called a **tree**.
- A **tree** is an undirected **graph** in which any two vertices are connected by exactly one path.





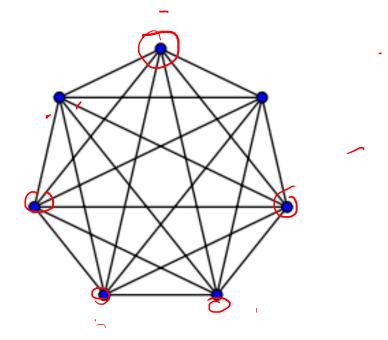
Sparsely connected graph

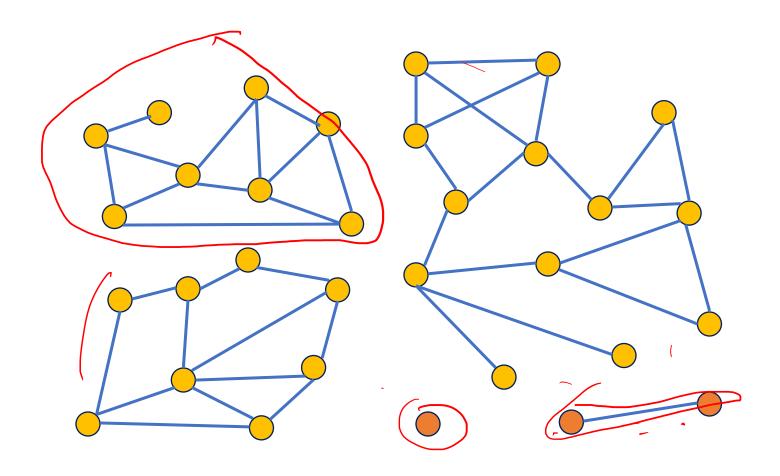


Fully connected graph

Complete Graph:

Every vertex is having an edge to all other vertices





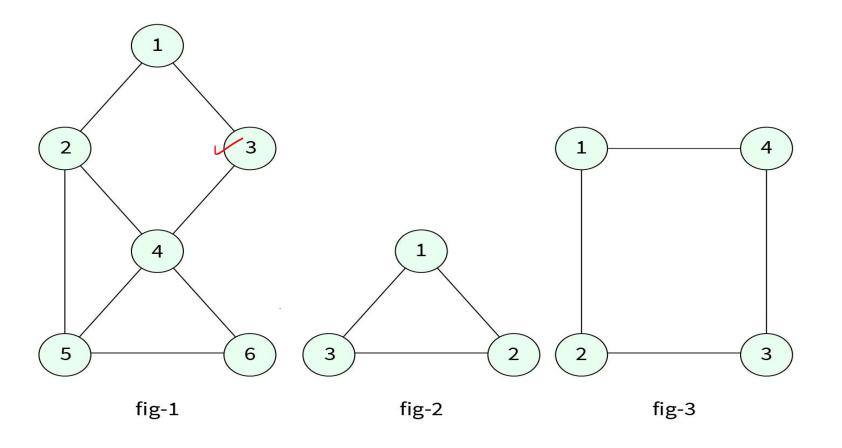
Graph with 5 Connected components

Bi-connected Graph

A graph is said to be Biconnected if:

1. It is connected, i.e. it is possible to reach every vertex from every other vertex,

2. Even after removing any vertex the graph remains connected.





Biconnected component

 A bioconnected component of a graph is a connected subgraph that cannot be broken into disconnected pieces

by deleting any single node (and its incident links)

Biconnected Graph

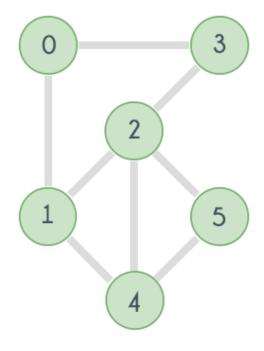


Fig. 1

• Removing any vertex from this graph does not increase the number of connected components.

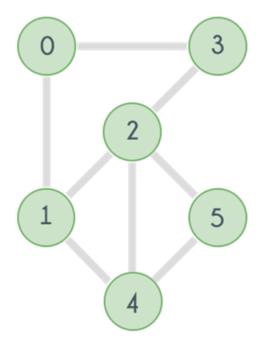
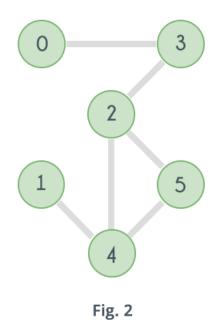
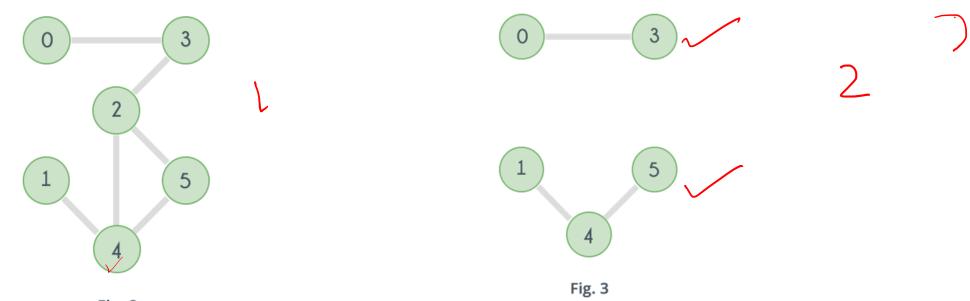


Fig. 1

Check if this graph is a Biconnected graph



Removing vertex 2 increases number of connected components

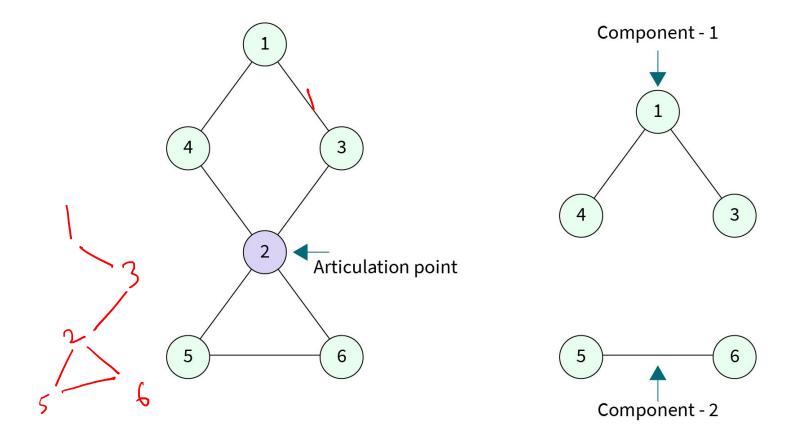


• so it is not a Biconnected graph

Articulation Point

• If removal of a vertex increases the number of connected components in the graph, then it is not Biconnected.

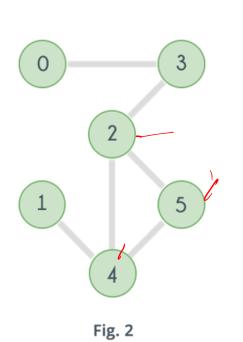
 A vertex is called an Articulation Point whose removal increases the number of connected components in the graph





Biconnected Component?

- It is one of the subgraphs which is Biconnected.
- Four biconnected components of the given graph



2 3 2 4 5 1 4

Fig. 6

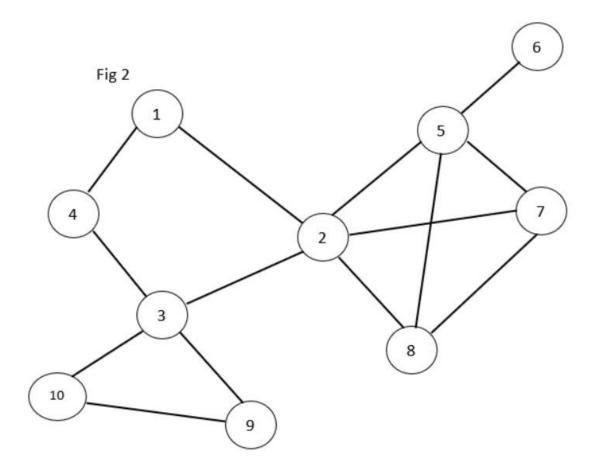
• For a given graph, a Biconnected Component is one of its subgraphs that is Biconnected.

• This means there is always a path between any two nodes in the component, even after removing any node from the component.

Biconnected Component

• A *biconnected component* is a group of vertices and edges that are all connected to each other in a way

 that you can always get from one vertex to another using two different paths.



How to discover biconnected components?

• https://www.hackerearth.com/practice/algorithms/graphs/biconnected-components/tutorial/

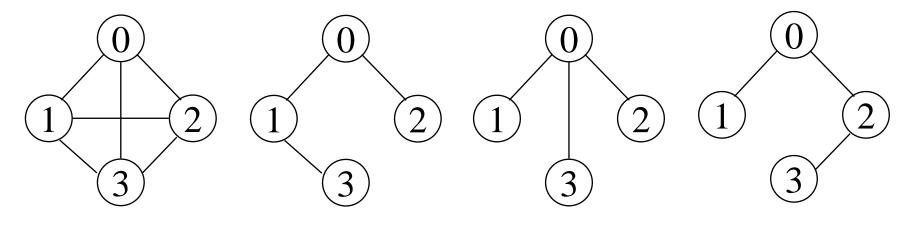
Spanning Trees

Spanning Tree: Tree Graph

Tree formed of graph edges which connect all the vertices of the graph.

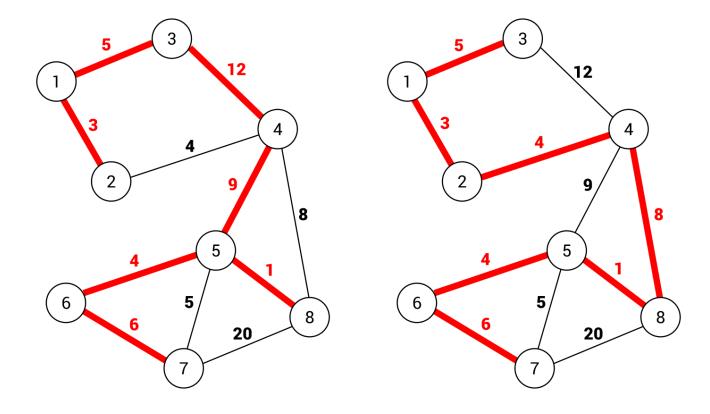
Spanning tree does not have a cycle

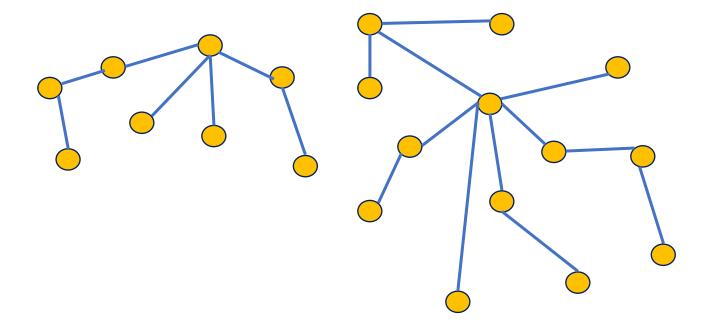
Spanning Tree examples



G₁ Possible spanning trees

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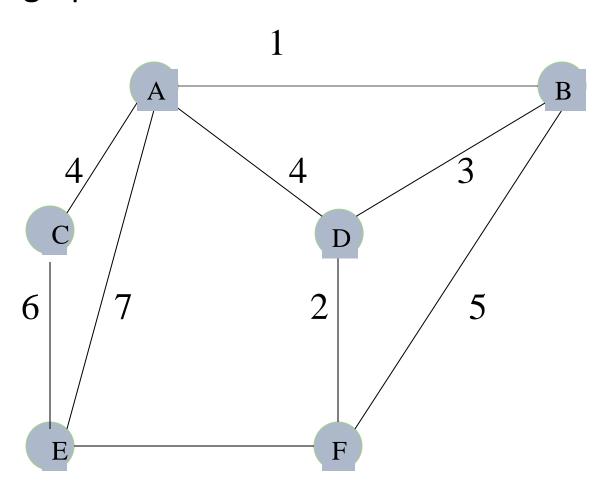


Spanning Trees

Spanning Tree

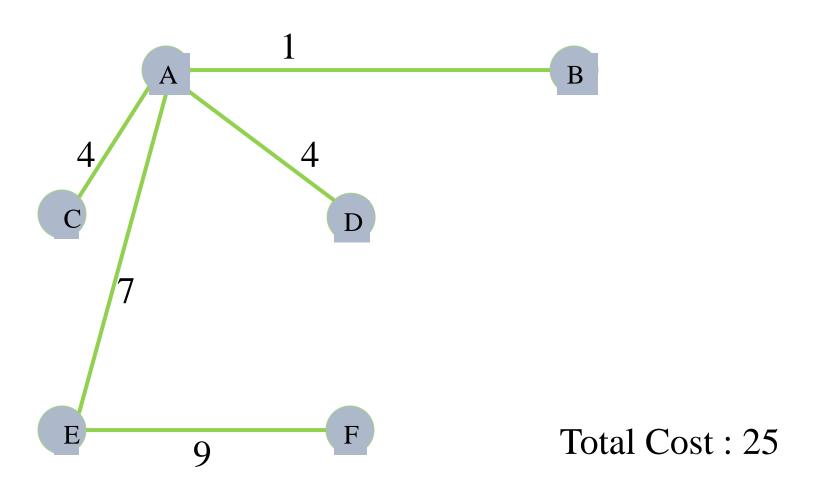
- Spanning Tree (ST) of an undirected graph
 - includes all its nodes,
 - is connected,
 - (you can go from any node to any other node)
 - is acyclic

Consider the spanning trees for the following graph with 5 vertices.

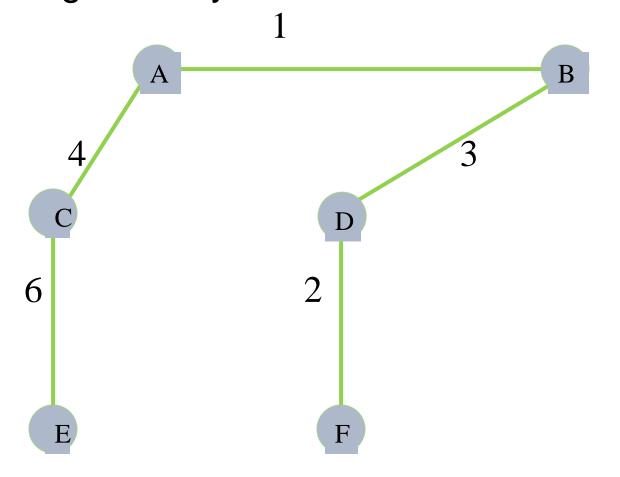


There can be number of possible Spanning Trees. Here is one. All nodes are connected. No cycles.

We are interested in Cost of Spanning Tree



Another spanning tree of same graph. All 5 nodes are connected. But its weight is only 16.



Smallest cost network

- Each edge of a real world graph will have some weight, such as path length, cost to travel, time to travel etc.
- The problem is to select subset of all edges, such that the network has smallest cost
- This is done by creating a spanning tree of the graph which has smallest cost

MST

- Which spanning tree is most interesting or useful?
- All spanning trees provide connectivity between various nodes
- However, the edges have different costs (path lengths).

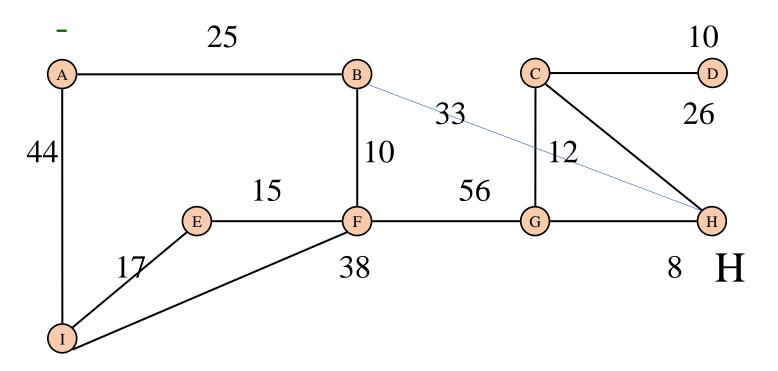
- The useful spanning tree would be the one for which total cost of the edges is minimum.
- Such a tree is called the Minimum Spanning Tree (MST)

MST of a Graph

Applications of MST in real world Graphs

- Design of minimum cost network while providing connections to all points
 - Road network
 - cable network
 - electrical network
 - telephone network
 - wire routing in printed circuit board
 - Supply chain network

Select minimum cost road network which connects all cities



MST

- A Minimum Spanning Tree (MST) of an undirected graph
 - includes all its nodes,
 - is connected,
 - is acyclic, and
 - has minimum total edge weight

Greedy Strategy for MST

MST Algorithms

- Two algos for MST
 - Kruskal's algorithm
 - Prim's algorithm

Kruskal's Algorithm

• It builds the spanning tree by adding edges one by one into a growing spanning tree.

- It follows the greedy strategy to build the MST
- Since objective is to build smallest cost tree, the greedy approach would be to locate an edge which has least weight
- and add it to the growing spanning tree.
- Repeat this for all iterations.

Kruskal's Algorithm

Algorithm Steps:

- Each edge has a weight.
- Sort the edges with respect to their weights.
- Add edges to the MST, starting with the smallest weight, until the edge with the largest weight.
- Take care not to add an edge if it forms a cycle

- This could be implemented using DFS which starts from the first vertex, then check if the second vertex is visited or not.
- But DFS will make time complexity large as it has an order of O(V+E)
- where V is the number of vertices, E is the number of edges.

• A better way is to make use of "Disjoint Sets".

Kruskal's method for MST

- Kruskal's algorithm
- starts with an empty spanning tree, and
- creates a tree by progressively adding edges with lowest cost in the graph
- Let there be n vertices and m edges in a graph

- Sort the edge list in increasing order.
- Make a set of n disjoint sets.
- Pick up the edges one by one from the list.
- Add the edge to MST if it does not form a cycle

Consider a graph with edge weights 1,2,...,7

Edge 1: OK

Edge 2: OK

Edge 3: OK

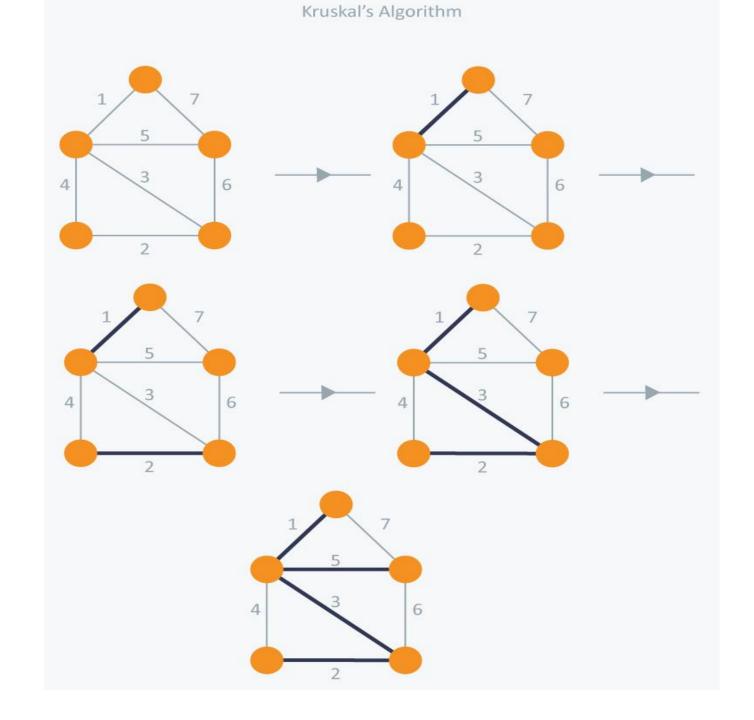
Edge 4: forms cycle

Edge 5: OK

Edge 6: forms cycle

Edge 7: forms cycle

Total cost: 11

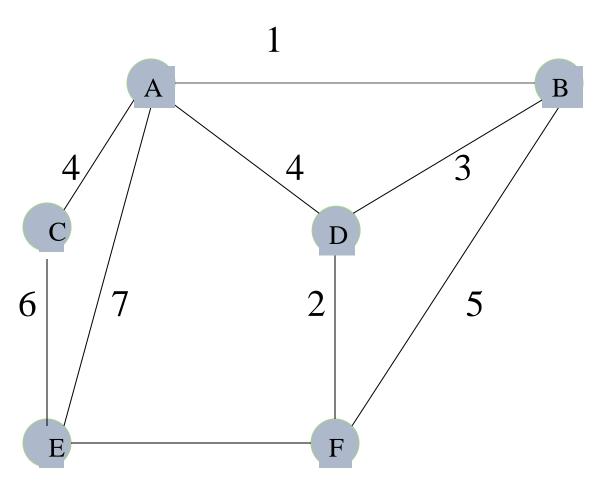


```
//Kruskal algorithm using Disjoint Sets
Kruskal( edgelist, v) {
       sort(edgelist)
       for i = 1 to n
               makeset(i)
       count = 0;
                       i=1
       while (count < m - 1) {
           if (find(edgelist[i].v != find(edgelist[i].w)) { // check if edges have
                                                          //common root
              println ( edge )
              count = count + 1
              union(edgelist[i].v , edgelist[i].w) }
           i = i + 1
```

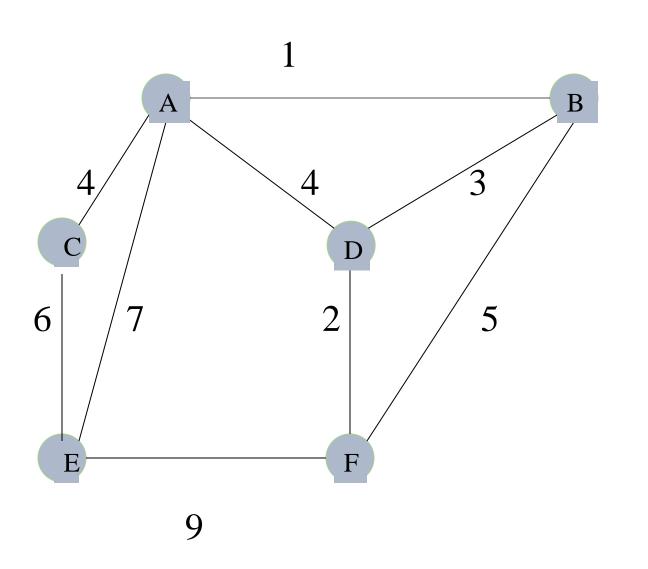
Complexity of Kruskal Implementation

- There are m makeset operations, atmost 2m find operations and n-1 union operations.
- because graph is connected, m >= n-1
- Disjoint set graph is of height at most log m
- number of union and find operations is O(m log m)
- sorting edges would also take atmost Θ(m log m)
- Thus worst time for Kruskal's algorithm is Θ(m log m)

Create the MST for the following graph with 6 vertices.



Sort the edges.



Sort the edges

AB 1

DF 2

BD 3

AC 4

AD 4

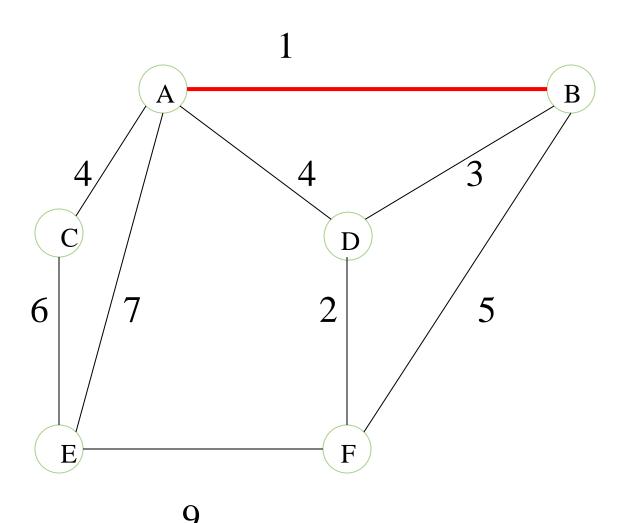
BF 5

CE 6

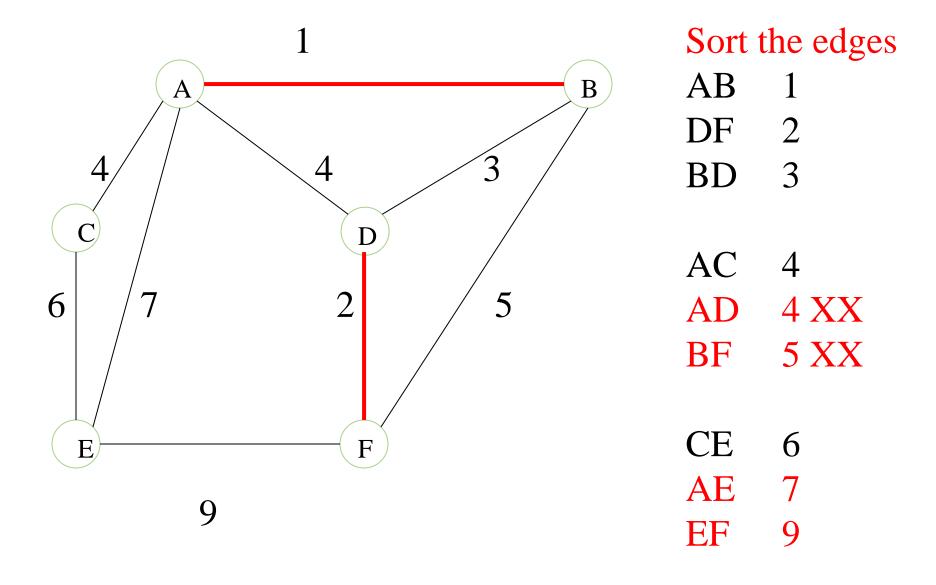
AE 7

EF 9

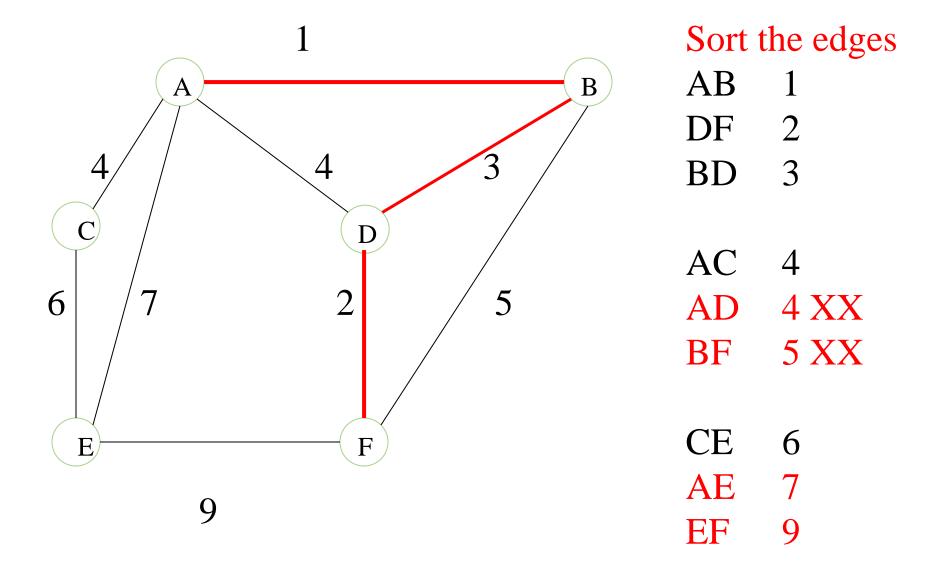
Select edge with smallest cost -- AB



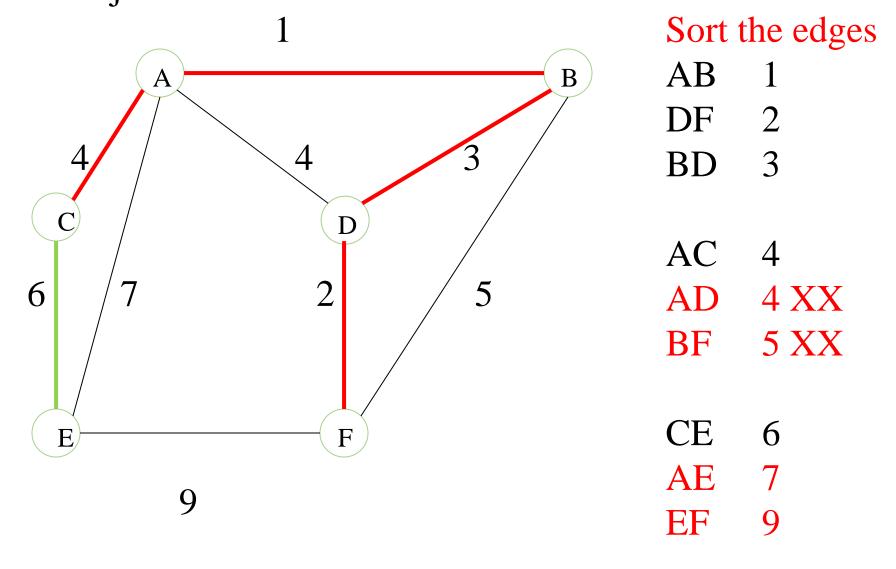
Next select DF.



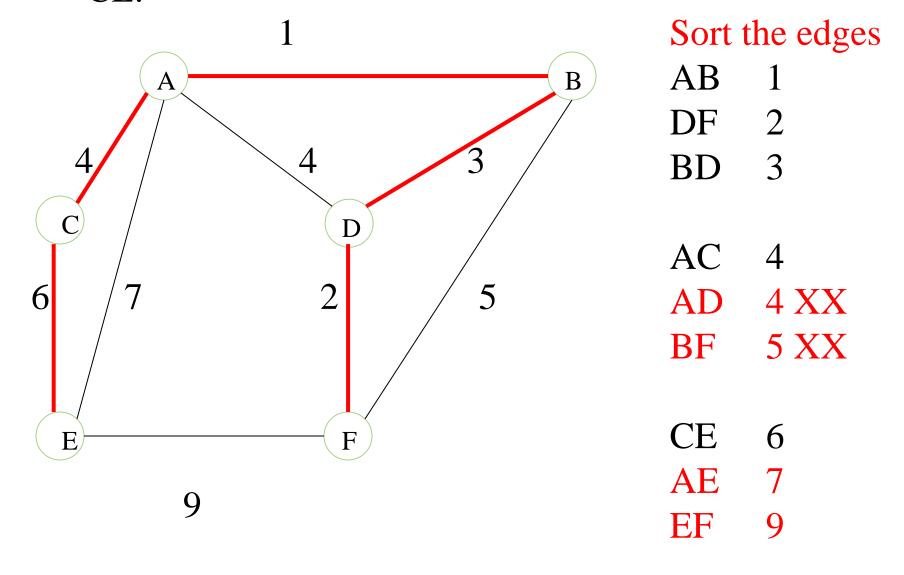
Next select BD.



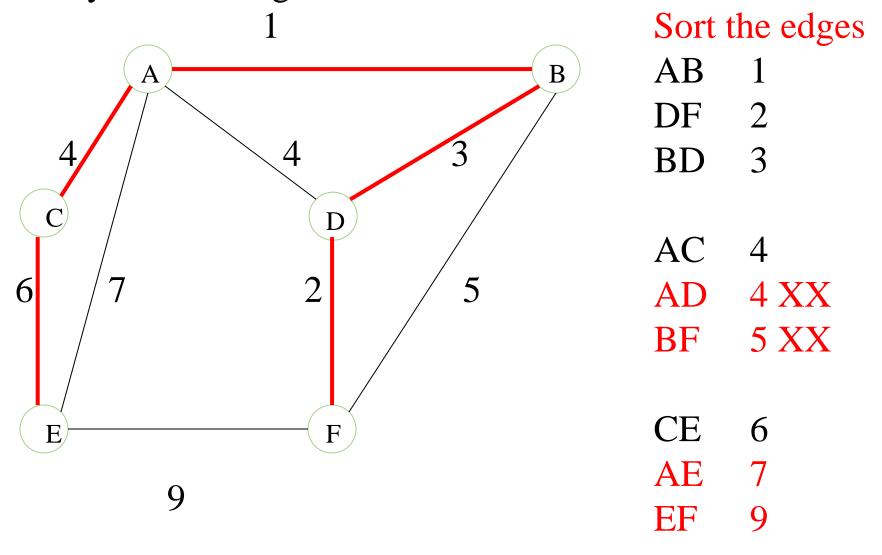
Next select AC, as AD creates a cycle and is rejected.



BF is rejected as it creates a cycle. Next select CE.



Both AE and EF are rejected as they create cycles. All edges have been considered.



We got (6-1) edges on the tree. This is the MST. Total weight: 16 which is minimum cost

