# AVR: Timers, Counters, Interrupts

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## What is a timer/counter?

- All microcontrollers have clocks in them (or use one that resides outside of a microcontroller).
- The timer and counter functions in the microcontroller count in sync with the microcontroller clock.
- The microcontroller provides a very useful feature called prescaling. **Prescaling** is a way for the counter to skip a certain number of microcontroller clock ticks. The AVR microcontrollers allow prescaling numbers of: 8, 64, 256 and 1024.

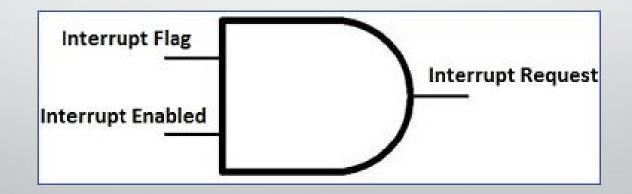
#### Code to make an LED blink 7 times

```
#include <avr/io.h>
int main(void) {
    DDRB = 0b00000001;
    PORTB = 0b00000000;
   TCCR1B |= 1<<CS10 | 1<<CS11; //set prescalar
   while(1) {
       if (TCNT1 > 2232) {
           TCNT1 = 0;
           PORTB ^= 1<<PINBO; //toggle LED
```

### Interrupts

- Interrupts are basically events that require immediate attention by the microcontroller.
- When an interrupt event occurs the microcontroller pause its current task and attend to the interrupt by executing an Interrupt Service Routine (ISR); at the end of the ISR the microcontroller returns to the task it had paused and continues its normal operations.

- An Interrupt Service Routine (ISR) or Interrupt Handler is a piece of code that should be execute when an interrupt is triggered.
- Apart from the enabled bits for the specific interrupts the global interrupt enabled bit MUST be enabled for interrupts to be activated in the microcontroller. This is done via the sei() method.



## How are interrupts triggered?

- ADC
- Serial communication
- Timer matching given count
- Pin high/low

```
#include <avr/io.h>
#include <avr/interrupt.h>
int main(void) {
    sei(); //enable global interrupt
    DDRB |= 1<<PINBO;
    TCCR1B |= 1<<CS10 | 1<<CS11 | 1<<WGM12; //prescalar , enable CTC
    TIMSK1 |= 1<<OCIE1A; //Timer1 Output Compare A Match interrupt is enabled
    OCR1A = 15624; //Value at which CTC
    while(1) { }
ISR(TIMER1_COMPA_vect) { //CHECK arg
    PORTB ^= 1<<PINBO;
```

