# Due: Wednesday, July 17th at 11:59 pm

## EE 263 Homework 3

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### Memory of a linear dynamical, time-invariant system

#### **Solution:**

(a) Let us first consider how we might check if a valid impose response of fixed size *M* exists. The first thing to note is that the covolution operator given in the problem statent can actually be written as a linear system:

$$\bar{y} = Ah$$

where  $\bar{y} \in \mathbb{R}^{T-M}$ ,  $h \in \mathbb{R}^M$  and  $A \in \mathbb{R}^{(T-M)\times M}$ . Note that we remove the first  $\{y_1, \dots, y_M\}$ . In fact, we can use the matrix A as defined below:

$$A = \begin{bmatrix} u_{M} & u_{M-1} & u_{M-2} & \cdots & u_{1} \\ u_{M+1} & u_{M} & u_{M-1} & \cdots & u_{2} \\ u_{M+2} & u_{M+1} & u_{M} & \cdots & u_{2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ u_{T-2} & u_{T-3} & u_{T-4} & \cdots & u_{T-M-1} \\ u_{T-1} & u_{T-2} & u_{T-3} & \cdots & u_{T-M} \end{bmatrix}$$

$$y_{-1} = \begin{bmatrix} y_{M+1} \\ \vdots \\ y_{T} \end{bmatrix}$$

$$h = \begin{bmatrix} h_{1} \\ \vdots \\ h_{M} \end{bmatrix}$$

We can see by inspection above that Ah performs the needed convolutions betweens u and h to obtain  $\bar{y}$ , by the properties of matrix multiplication (eg, to obtain  $y_i$ , we compute the dot product of the i-M-th row of A with h, which is exactly what our convolution dictates, and for  $i \leq M$ , the convolution is not fully defined so we ignore them).

In the problem statement, we're given the fact that T > 2M, so this means that there will always be at least T - M > 2M - M = M rows in A, meaning it will always be a tall and skinny matrix.

As such, we can use the pseudo inverse to find the closests solution for h, computing:

$$\bar{h} = (A^T A)^{-1} A^T \bar{y}$$

Finally, once we've computed this h, we can re-compute that  $\bar{y}$  given our inputs forming A, and see if this equals our what we started with. In other words, we have that:

$$||A\bar{h} - \bar{y}|| \le \epsilon \implies M$$
 is a valid value

( $\epsilon$  is needed to deal with floating point imprecision)

The above gives us a way to check if M is sufficient. To finallize our method, we simply iterate over the possible values of M from  $M = 1, \dots, \frac{T}{2} - 1$  in order until we find a valid value.

(b) Applying the process we described above, we find that M=7 is the smallest value that works. We also have:

$$h = \begin{bmatrix} 0.63 \\ 0.27 \\ 0.02 \\ 0.37 \\ 0.96 \\ 0.95 \\ 0.46 \end{bmatrix}$$