

Andre Milzarek · Fall Semester 2020/21

MDS 6106 – Introduction to Optimization								
Exercise Sheet Nr.:								
Na	me:	Kan	g Havyi	🕽 Student I	d: <u>22</u>	,004	1025	
In the creation of this solution sheet, I worked together with:								
Name:			_ Student I	D:				
Name:			_ Student I	D:				
Name:			_ Student I	D:				
For corre	ection:							
	Exercise						Σ	
	Grading							

A Z. I
a) If
$$f(x)$$
 is coercive. we should show that $f(x) = +\infty$
as $x = \frac{1}{3}x^3 - \frac{3}{2}x = x(\frac{1}{3}x^3 - \frac{3}{2}) \rightarrow -\infty$ thus, f is not coercive x_{13} - ∞

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$x_1 \Rightarrow \infty$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$x_1 \Rightarrow \infty$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$f(x) = \frac{1}{3}x_1^3 - \frac{3}{2}x_1 = x_1(\frac{1}{3}x_1^3 - \frac{3}{2}) \longrightarrow \infty \text{ thus, } f \text{ is not coercive}$$

$$\nabla f(x) = \begin{pmatrix} x_{1}^{2} - \frac{3}{2} - x_{2}^{2} \\ -2x_{1}x_{2} + 4x_{2}^{3} \end{pmatrix} \qquad \nabla f(x) = \begin{pmatrix} 2x_{1} - 2x_{2} \\ -2x_{2} - 2x_{1} + 12x_{2}^{2} \end{pmatrix}$$

$$X^{*} \text{ are stationary points, when } x f(x^{*}) = 0$$

$$\begin{pmatrix} x_{1} - \frac{3}{2} - x_{2}^{2} \\ -2x_{1}x_{2} + 4x_{2}^{3} \end{pmatrix} = 0 \Rightarrow x_{1}^{*} = (\frac{16}{2}, 0)x_{2}^{*} = (-\frac{3}{2}, 0)x_{3}^{*} = (\frac{3}{2}, \frac{12}{2})x_{4}^{*} = (\frac{3}{2}, -\frac{12}{2})$$

(-2x1x2+4x3) = 0 - 1 x, (2, 1)
$$\frac{1}{2}$$
 (2, 1) $\frac{1}{2}$ (3, 1) $\frac{1}{2}$ (3, 1) $\frac{1}{2}$ (3, 1) $\frac{1}{2}$ (4, 1) $\frac{1}{2}$ (5, 1) $\frac{1}{2}$ (5, 1) $\frac{1}{2}$ (6, 1) $\frac{1}{2}$ (7, 1) $\frac{1}{2}$ (8, 1) $\frac{1}{2}$

2° put the $\chi_2^* = (-\frac{16}{2}, \circ)$ into the $\nabla^2 f(x_2^*) = (-\frac{16}{0}, \circ) = > \lambda_1 = \sqrt{6}$, $\lambda_2 = \sqrt{6}$ thus, $\nabla^2 f(x)$ is indefinite that means χ_2^* is saddle point 3° put the $x_3^* = (\frac{3}{2}, \frac{13}{2})$ into the $\nabla^2 f(x_3^*) = (\frac{3}{\sqrt{3}}, \frac{13}{6}) = \frac{1}{3} \lambda_1 \lambda_2 = \frac{1}{5} \lambda_1 + \lambda_2 = \frac{9}{5}$ 50 A, Az 70, positive definite which means x3 is local minimizer 4° put the $\chi_4^* = (\frac{2}{2}, -\frac{15}{2})$ into the $\nabla^2 f(\chi_4^*) = (\frac{3}{13}, \frac{13}{6}) = \lambda_1 + \lambda_2 = 9$ So, >1,>270 and \$3 f(x) is positive definite which means x4 is local minimizer

According to the results from c), \$\frac{1}{2}f(x_3*) and \$\frac{1}{2}f(x_4*)\$ both are positive definite lhus, x3* and x4* must be strict local minimizer.

In addition, we know that f is not coercive since x equal to $(-\infty, 0)$ $f \to -\infty$, which means that f doesn't have global minimizer

So, f just possess strict local minimizer.

A 7. 2

a) If
$$f(x)$$
 is coercive. we should show that $f(x) = +\infty$
 $\lim_{|x| \to \infty} f(x) = x^4 - 2x_1^2 + x_2^2 + 2x_2x_3 + 2x_2^2$
 $f(x) = x^4 (x_1^3 - 3) + x^3 + \frac{1}{3}x_2^2 + \frac{16}{3}x_3 + \frac{16}{2}x_3)^3 + \frac{1}{2}x_3^3$
 $= x_1^3(x_1^3 - 3) + x^3 + \frac{1}{3}x_2^3 + \frac{16}{3}x_2 + \frac{16}{3}x_3)^3 + \frac{1}{2}x_3^3$
 $= x_1^3(x_1^3 - 3) + x^3 + \frac{1}{3}x_2^3 + \frac{16}{3}x_2 + \frac{16}{3}x_3 + \frac{1}{3}x_3^3 + \frac{1}{3}x_3^3$

C) according +0 (b) $\nabla f(x) = \begin{pmatrix} 4x_1^3 - 4x_1 \\ 2x_2 + 2x_3 \end{pmatrix}$ If we want to find stationary points $2x_2 + 4x_3$ $2x_2 + 4x_3$ Thus, x_1^* , x_2^* , x_3^* are stationary points

1° put x_1^* into the $\nabla^2 f(x) = \nabla^2 f(x_1^*) = \begin{pmatrix} 0 & 2 & 2 \\ 0 & 2 & 4 \end{pmatrix} = \lambda^* = 3 + \sqrt{5} \lambda^2 = 3 - \sqrt{5} \lambda^2 = 4$ So $\nabla^2 f(x_1^*)$ is indefinite $= \nabla x_1^* = (0,0,0)$ is paddle point $\nabla^2 f(x_1^*) = (0,0,0)$ is paddle point $\nabla^2 f(x_1^*) = (0,0,0)$ is $\nabla^2 f(x_1^*) = (0,0,0$ So $\nabla^2 f(x_2^*)$ is positive definite => $x_2^* = (1,0,0)$ is strict 10 cal minimum point St \= \(\(\tau_3^4 \) is positive definite => \(\tau_3^* = (-1,0,0) \) is strict local minimum point points are generated from 10 cal minimum points and $f(x_2^*) = f(x_3^*)$.

Thus, $x_2^* = (1,0,0)$ and $x_1^* = (-1,0,0)$ both are non-strict ghobal minimum point

a) >1 is not convex set. Because we can verify it by 11st a counter-example We can assume that X, is in one-dims, ion Sor Q=1, B=4 Q=1=5 X1={xER: 15x3=4] Let X=-1 EXI, Y=1 EXI, X E[0,1] So $\left[\chi + (1-\chi) \lambda \right]_{0}^{2} = \left(1-2\chi \right)_{0}^{2} + \left(1-\chi \right)_{0}^{2} = 0 \neq \chi$ Thus X, is not a coarex set $Z^{n} \cdot X_{z} = \begin{cases} x \in \mathbb{R}^{n} : \|x - \alpha\|_{z} \in \|x - b\|_{z} \end{cases}$, $\alpha, b \in \mathbb{R}^{n}$, $\alpha \neq b$ => $||x-a||^2 - ||x-b||^2 \le 0 => (x-a)^T (x-a) - (x-b)^T (x-b) \le 0$ $= 2x^{7}(b-a) + a^{7}a - b^{7}b = 0 = 7x^{2} - x^{2}x + ix^{n} : 2x^{7}b-a) + a^{7}a - b^{7}b = 0$ Thus set x e x 2 y e x 2 => 2[>x+(-))y] (b-a) + a Tor - b Tb $= 2 \times \sqrt{(b-a)} + 2(-x) \sqrt{(b-a)} + a^{7}a - b^{7}b$ = 0 $= x(b^{7}b - a^{7}a) = (-x)(b^{7}b - a^{7}a)$ Thus Xz is a convex set

AZ.3

 $\frac{\partial T_b d}{\partial t} = \frac{\partial T_b \left(\left(\frac{1}{h} + \left(\frac{1}{h} \right) \right) + \left(\frac{1}{h} \right) +$ Thus $b = x_3 + (1-x)y \in \text{set} X = x_1 \times x_2 \times x_3 = x_4 \times x_4 \times$ (C) 1° False Set $Y = X_1 \cup X_2$ if $x \in Y$ and $y \in Y = > X \in X$, or $X \in X_2$ when $X_1 + (I-X)y \in Y$, it means that $X_1 + (I-X)y \in X_1$ ($X \in Y_1$, $Y \in X_2$)

when $\lambda x + (-\lambda)y \in Y$, it means that $\lambda x + (-\lambda)y \in X$, $(x \in X_1, y \in X_1)$ or $\lambda x + (-\lambda)y \in X_2(x \in X_2, y \in X_2)$ or $\lambda x + (-\lambda)y \in X_2(x \in X_2, y \in X_2)$ So, if $\lambda x \in X_2$ or $\lambda x \in X_2$, the union of two convex is also a convex set

Since $f: R^n \rightarrow R$ be a concare, we can get that $\lambda f(x) + (1-\lambda)f(y) \leq f(\lambda x + (1-\lambda)y) \qquad \lambda \in [0,1]$ if we limit $f(x) \neq 0$ and $f(y) \neq 0$ $f(\lambda x + (1-\lambda)y) \neq \lambda f(x) + (1-\lambda)f(y) \neq 0$ $= > f(\lambda x + (1-\lambda)y) > 0$

Thus set $X := \int x \in \mathbb{R}^n : f(x) = \int x \in \mathbb{R}^n : f(x) = \int x \in \mathbb{R}^n : f(x) = \int x \cdot \int$

a) , we can compute the
$$\nabla^2 f(x)$$
 to verify

Since $x \in R$, $f(x) = \sqrt{1 + x^{-2}}$
 $f'(x) = \sqrt{1 + x^{-2}}$

For any $x \in R+t$, $f'(x) > 0$, thus $f(x) = \sqrt{1 + x^{-2}}$ is convex

 z° we can use definition of General composition-epsolve

Let $h(x) = Ax - b$ $g(x) = ||X||^{0}$, $Since h(x)$ is thear function and $g(x)$

is convex function

So $f(x) = g(h(x))$ is convex and $f_{2}(x) = \mu ||X||^{0}$ is also a convex function $f(x) = \frac{1}{2}f(x) + \mu ||f_{2}(x)|| = \frac{1}{2}f(x) + \mu ||f_{2}(x)|| = \frac{1}{2}f(x) + \frac{1}{2}f(x) \frac{1}$

fixip is convex function

A 2.4

(b) Function g is not convex, according to definition of convex function $\lambda g(x) + (1-\lambda)g(y) = \lambda (f(x))^{\theta} + (1-\lambda)(f(y))^{\theta}$ g()x+(1-))y) = (f[xx+(1-x)y]) => Since f is convex $= (xf(x)+(1-x)f(y))^{2}(1x+(1-x)y)(-1x+(1-x)f(y))$ => $g(x+(1-x)y) = (f[xx+(1-x)y])^{2}(xf(x)+(1-x)f(y))^{2}, (f[x+(1-x)y]>|xf(x)+(1-x)f(y)|$ = xf(x)+(1-x)f(y)=> (f[xx+(1-x)y]) = x (f(x)) + (1+x2-2x) (f(y)) + 2x(1-x) f(x) f(y) = >2(f(x)) + (x-x2)f(x)) + (1+x0-2)(54(x-2))(f(xp)) -x(xx)[f(x)-f(y)]2 $= \lambda(f(x))^{\delta} + (-\lambda)[f(y)]^{\delta} - \lambda(-\lambda)[f(x) - f(y)]^{2}$ 7 > g(x) + (1-2)g(y) when ≤ 0 Thus, it exists the situation that g[xx+ (1-x)y] > xcg(x)+ (1-x)g(y) $h(x) = x^2$ $g(x) = \frac{1}{2} h(f(x))^2$, and we've verified that $g(x) = (f(x))^2$ above is not convex, so & 1= 1 (11×112-1) is not convex yet

A 2.f

(a)
$$f_{\beta}(x) = \frac{1}{2}(x-b)^{7}(x-b) + \frac{1}{2}(\frac{1}{2})^{7}x$$

$$\nabla f_{\beta}(x) = x-b+\beta-(\frac{1}{2})(\frac{1}{2})^{7}x$$

$$\nabla^{2}f_{\beta}(x) = I+\beta(\frac{1}{2})(\frac{1}{2})^{7}$$

(b) If f_{β} is strongly convex - $\int_{-\infty}^{\infty} z^{2}f_{\beta}(x)h > M \|h\|^{2}$, $n > 0$

According to (b), we know that fig is strongly convex, that is to say of ix) >0, so of(x) is a positive definite which means fix(x) only has one stationary point Through the result of (a), we know $\nabla f(x) = X - b + \beta(\frac{1}{2})(\frac{1}{2})^T X$ If we want to find stationary point of (x) \$ 0) So $\nabla f(x) = x - b + \beta \left(\frac{1}{2} \right) \left(\frac{1}{2} \right)^{7} x = \left(\frac{0}{2} \right)^{8}$ $= > \left(I + \beta \left(\frac{1}{2} \right) \left(\frac{1}{2} \right)^T \right) \times = b$ $\begin{pmatrix} x_1 + \beta \stackrel{\wedge}{\geqslant} x_0 \\ x_2 + \beta \stackrel{\wedge}{\geqslant} x_0 \\ \vdots \\ y_n + \beta \stackrel{\wedge}{\geqslant} x_0 \end{pmatrix} = b = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$ $x + \beta(\frac{1}{2}) \stackrel{N}{\underset{i \to i}{\sum}} x_i = b = >$ => (1+mb) = = = = = |bi $\sum_{i=1}^{n} x_{i} = \sum_{i=1}^{n} b_{i}$ $= > \lambda_{i} = b_{i} - \underbrace{\beta_{i=1}^{n} b_{i}}_{NB}$ $=>\chi_{\beta}^{*}\begin{pmatrix}b_{1}-\beta_{1}^{\frac{N}{2}}b_{1}/1+n\beta\\b_{1}-\beta_{1}^{\frac{N}{2}}b_{1}/1+n\beta\end{pmatrix}=b-\frac{1}{1+n\beta}\left(\frac{1}{2}\right)\begin{pmatrix}\beta_{1}/2\\b_{1}/2\end{pmatrix}b$ and $f_{\beta}(x)$ is a strict convex function.

So, xpx is a strict rocal minimizer

(d) According to the result of
$$x_{p}^{*}$$

$$x_{p}^{*} = \begin{pmatrix} b_{1} - \beta \sum_{i=1}^{N} b_{i} / 1 + m_{p} \\ b_{n} - \beta \sum_{i=1}^{N} b_{i} / 1 + m_{p} \end{pmatrix} \qquad x_{oz}^{*} = b_{1} - \beta \sum_{i=1}^{N} b_{i} / 1 + m_{p}$$

$$= > \lim_{n \to \infty} x_{i}^{*} = \lim_{n \to \infty} x_{oz}^{*} = \lim_{n \to \infty} b_{1} - \frac{\sum_{i=1}^{N} b_{i}}{n} = b_{1} - \frac{\sum_{i=1}^{N} b_{i}}{n}$$

$$= b_{1} - \frac{\sum_{i=1}^{N} b_{i}}{n}$$

 $= \left(\frac{1}{2}\right)^{7}b - \left(\frac{1}{2}\right)^{7}b = 0$ $= \left(\frac{1}{2}\right)^{7}b - \left(\frac{1}{2}\right)^{7}b = 0$ $= \left(\frac{1}{2}\right)^{7}b - \left(\frac{1}{2}\right)^{7}b = 0$

$$[Owthen X^*] \text{ into the constraint.}$$

$$I^* = (I)^T (b - h(I)(I)^T b) = (I)^T (I)^T (I)^T (I)^T (I)^T b$$