

Chap 5. Trees (4)

Contents

5.1 Introduction

5.2 Binary Trees

5.3 Binary Trees Traversals

5.4 Additional Binary Tree Operations

5.5 Threaded Binary Trees

5.6 Heaps

5.7 Binary Search Trees

5.8 Selection Trees

5.6 Heaps

5.6.1 Priority Queues

- *Priority queues*
 - *deletion*: deletes the element with the highest(or the lowest) priority
 - *insertion* : insert an element with arbitrary priority
(ex: job scheduling in OS)
- We use *max(min) heap* to implement the priority queues

ADT *MaxPriorityQueue* is

objects: a collection of $n > 0$ elements, each element has a key

functions:

for all $q \in \text{MaxPriorityQueue}$, $item \in \text{Element}$, $n \in \text{integer}$

MaxPriorityQueue $\text{create}(\text{max_size}) \quad ::= \quad \text{create an empty priority queue.}$

Boolean $\text{isEmpty}(q, n) \quad ::= \quad \text{if } (n > 0) \text{ return } \textit{FALSE}$
else return *TRUE*

Element $\text{top}(q, n) \quad ::= \quad \text{if } (!\text{isEmpty}(q, n)) \text{ return an instance}$
of the largest element in q
else return error.

Element $\text{pop}(q, n) \quad ::= \quad \text{if } (!\text{isEmpty}(q, n)) \text{ return an instance}$
of the largest element in q and
remove it from the heap **else return** error.

MaxPriorityQueue $\text{push}(q, \text{item}, n) \quad ::= \quad \text{insert } \textit{item} \text{ into } q \text{ and return the}$
resulting priority queue.

ADT 5.2: Abstract data type *MaxPriorityQueue*

5.6.2 Definition of a Max Heap

- **Definition :**
 - A *max tree* is a tree in which the key value in each node is no smaller than the key values in its children (if any). *parent's key \geq children's keys*
 - A *max heap* is a complete binary tree that is also a max tree
- **Definition :**
 - A *min tree* is a tree in which the key value in each node is no larger than the key values in its children (if any). *parent's key \leq children's keys*
 - A *min heap* is a complete binary tree that is also a min tree.

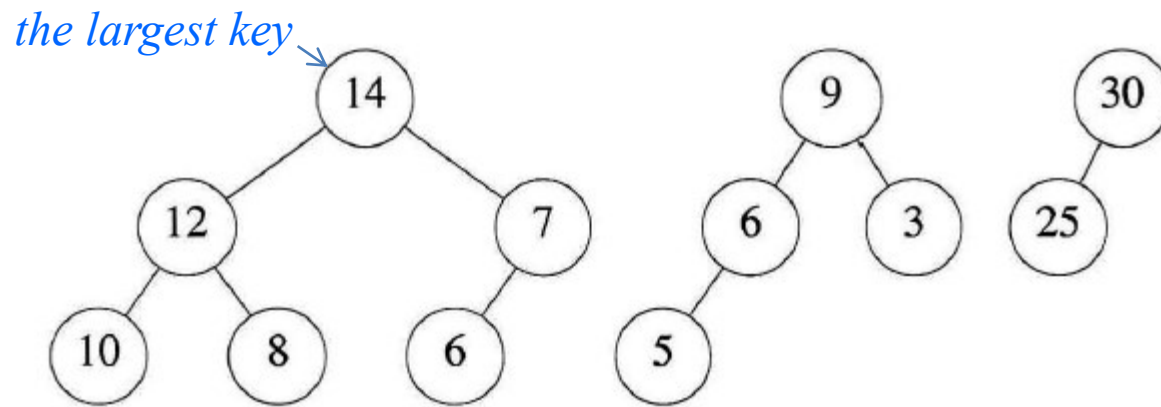


Figure 5.25: Max heaps

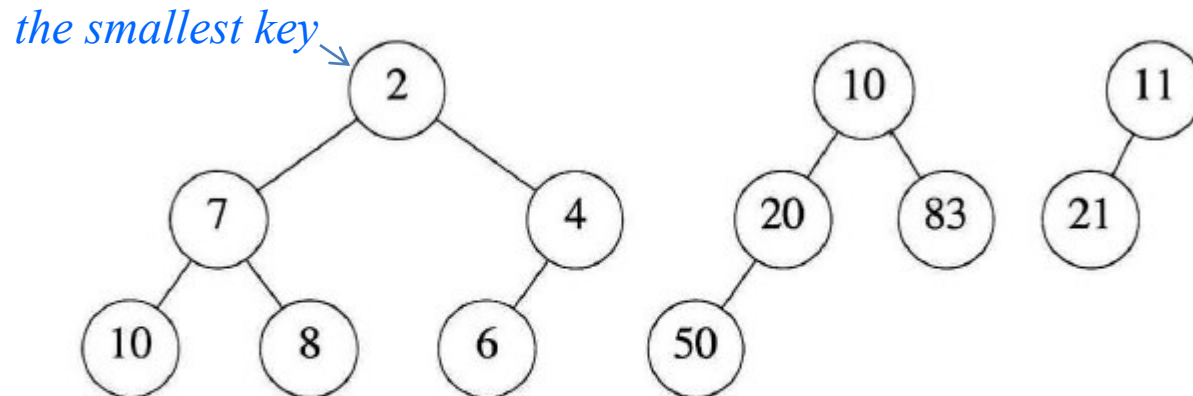
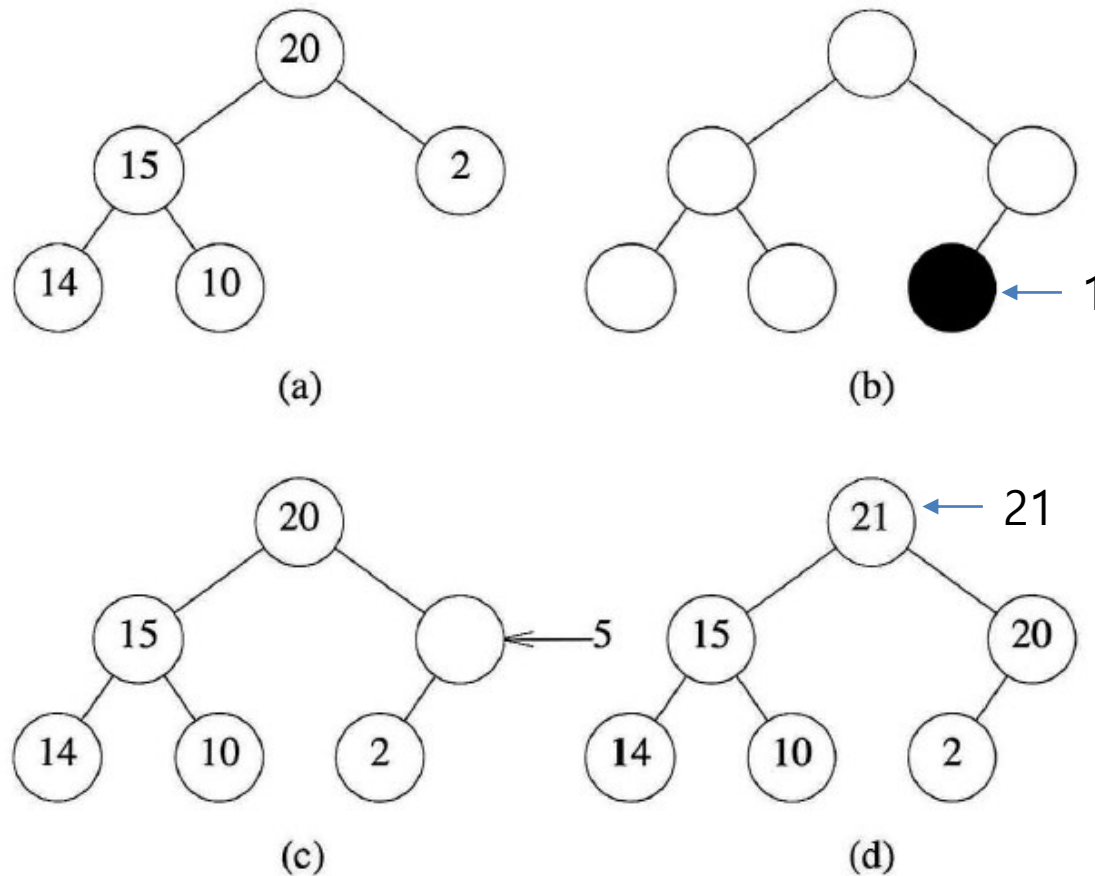


Figure 5.26: Min heaps

5.6.3 Insertion into a Max Heap




(a)
Insert(1)/
Insert(5)/
Insert(21)
↓
?

Figure 5.27: Insertion into a max heap

```
#define MAX_ELEMENTS 200 /* maximum heap size+1 */
#define HEAP_FULL(n) (n == MAX_ELEMENTS-1)
#define HEAP_EMPTY(n) (!n)
typedef struct {
    int key;
    /* other fields */
} element;
element heap[MAX_ELEMENTS];
int n = 0;
```

```
void push(element item, int *n)
{/* insert item into a max heap of current size *n */
    int i;
    if (HEAP_FULL(*n)) {
        fprintf(stderr, "The heap is full. \n");
        exit(EXIT_FAILURE);
    }
    i = ++(*n);
    while ((i != 1) && (item.key > heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    }
    heap[i] = item;
}
```



heap size
199


```

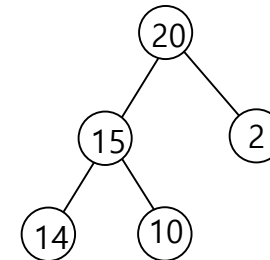
void push(element item, int *n)
{
    ...
    i = ++(*n);
    while ((i != 1) && (item.key > heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    }
    heap[i] = item;
}

```

current size

n 5

| | [0] | [1] | [2] | [3] | [4] | [5] | [6] | [7] |
|------|-----|-----|-----|-----|-----|-----|-----|-----|
| heap | - | 20 | 15 | 2 | 14 | 10 | | ... |

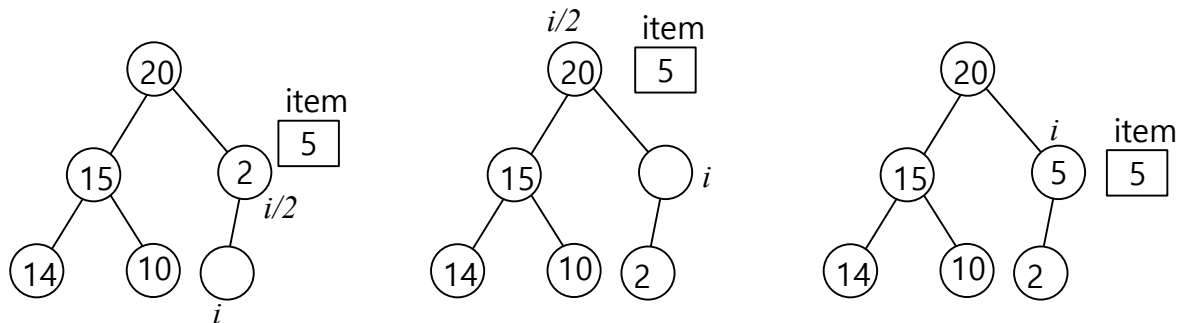


push(5, &n)



current size

n 6



```

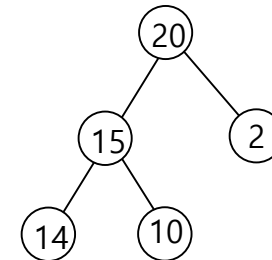
void push(element item, int *n)
{
    ...
    i = ++(*n);
    while ((i != 1) && (item.key > heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    }
    heap[i] = item;
}

```

current size

n 5

| | [0] | [1] | [2] | [3] | [4] | [5] | [6] | [7] |
|------|-----|-----|-----|-----|-----|-----|-----|-----|
| heap | - | 20 | 15 | 2 | 14 | 10 | | ... |

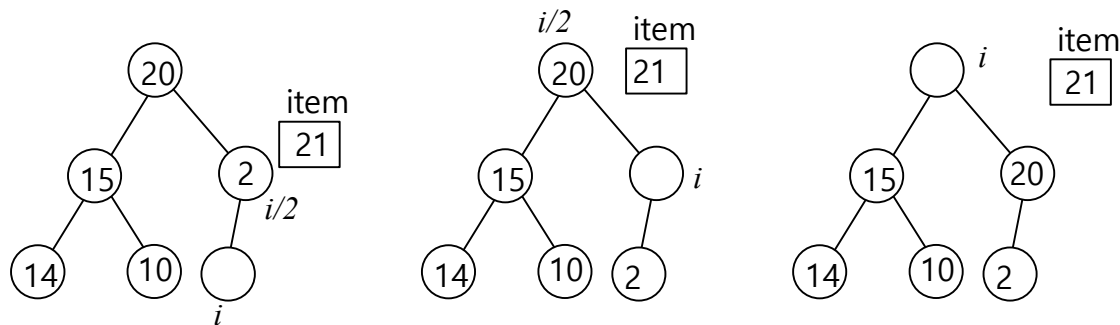


push(21, &n)



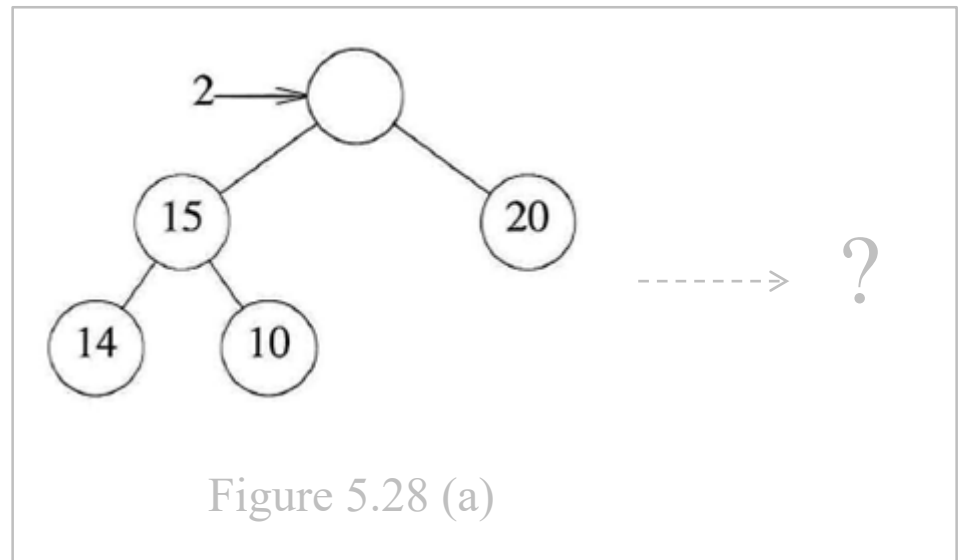
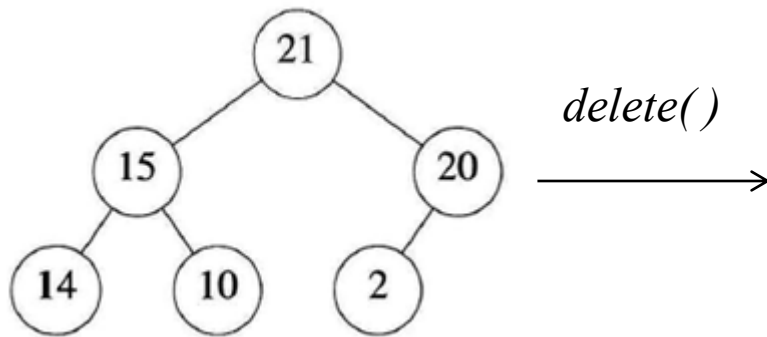
current size

n 6



- Analysis of *push*
 - the height of heap with n elements : $\lceil \log_2(n+1) \rceil$
 - while loop is iterated $O(\log_2 n)$ times
 - time complexity: $O(\log_2 n)$

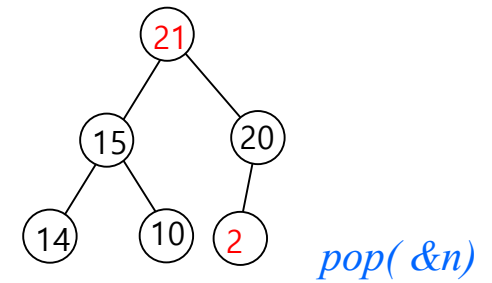
5.6.4 Deletion from a Max heap



current size

n 6

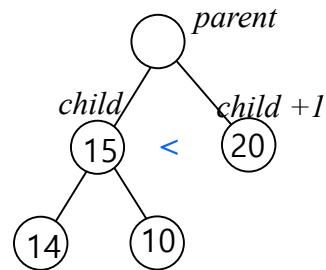
| | [0] | [1] | [2] | [3] | [4] | [5] | [6] | [7] |
|------|-----|-----|-----|-----|-----|-----|-----|-----|
| heap | - | 21 | 15 | 20 | 14 | 10 | 2 | ... |



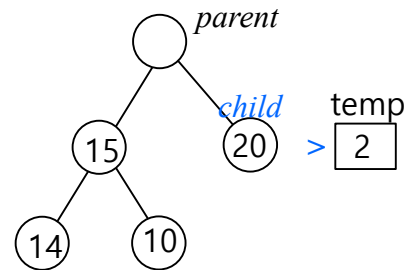
current size

n 5

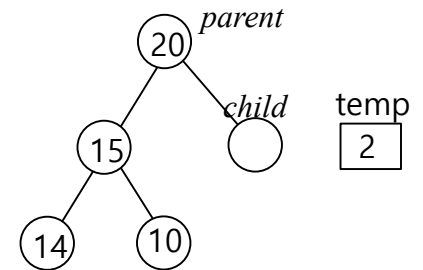
item 21 temp 2



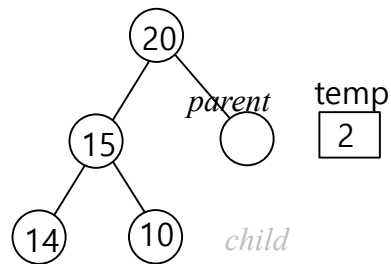
item 21



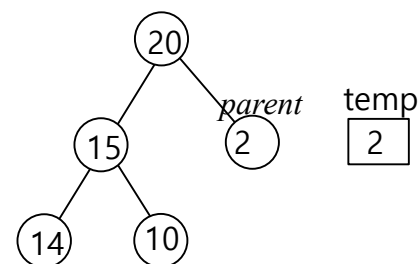
item 21



item 21



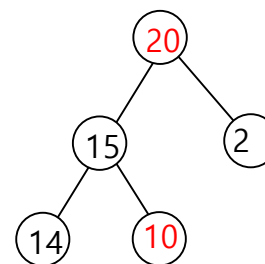
item 21



current size

n 5

| | [0] | [1] | [2] | [3] | [4] | [5] | [6] | [7] |
|------|-----|-----|-----|-----|-----|-----|-----|-----|
| heap | - | 20 | 15 | 2 | 14 | 10 | ... | |

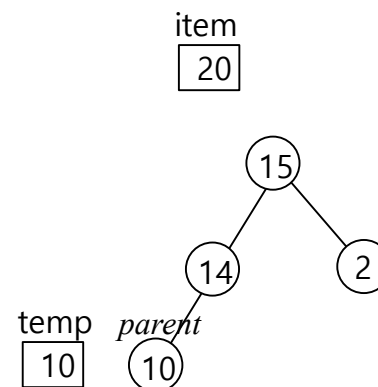
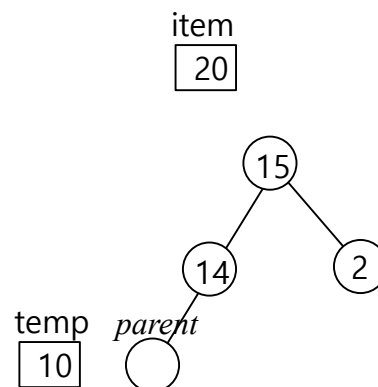
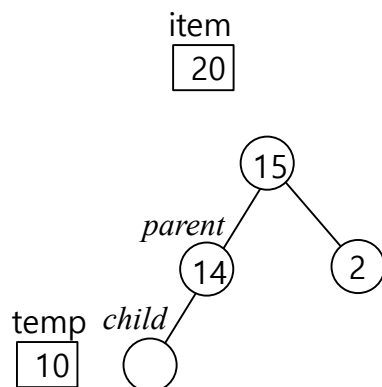
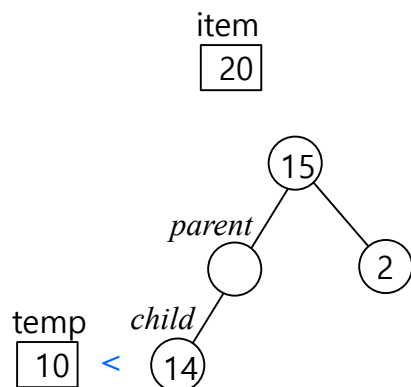
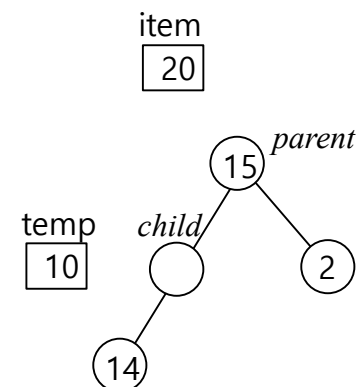
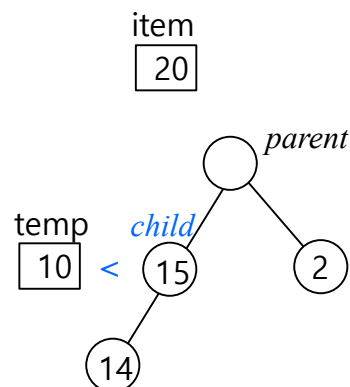
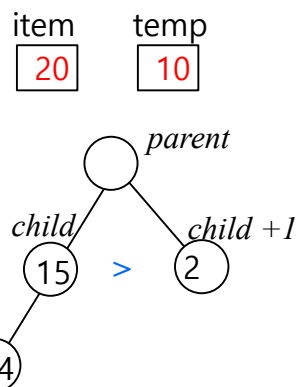


pop(&n)



current size

n 4



child

```

element pop(int *n)
{
    /* delete element with the highest key from the heap */
    int parent, child;
    element item, temp;
    if (HEAP_EMPTY(*n)) {
        fprintf(stderr, "The heap is empty\n");
        exit(EXIT_FAILURE);
    }
    /* save value of the element with the highest key */
    item = heap[1];
    /* use last element in heap to adjust heap */
    temp = heap[(*n)--];
    parent = 1;
    child = 2;
    while (child <= *n) {
        /* find the larger child of the current parent */
        if ((child < *n) && (heap[child].key < heap[child+1].key))
            child++;
        if (temp.key >= heap[child].key) break;
        /* move to the next lower level */
        heap[parent] = heap[child];
        parent = child;
        child *= 2;
    }
    heap[parent] = temp;
    return item;
}

```

- Analysis of *pop*
 - the height of heap with n elements : $\lceil \log_2(n+1) \rceil$
 - while loop is iterated $O(\log_2 n)$ times
 - time complexity: $O(\log_2 n)$