

thegrill::BoxCollider  
::get\_collisionResponse

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::get\_collisionResponse

thegrill::Transform  
::set\_position

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graph LR; A[thegrill::BoxCollider::get_collisionResponse] --> C[thegrill::Transform::set_position]; B[thegrill::BoxCollider::get_collisionResponse] --> C;
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The diagram illustrates a sequence of operations. On the left, there are two identical boxes, each containing the text 'thegrill::BoxCollider::get\_collisionResponse'. Blue arrows originate from the right side of each of these boxes and point towards a single box on the right. This box contains the text 'thegrill::Transform::set\_position' and has a gray background, distinguishing it from the white boxes on the left.