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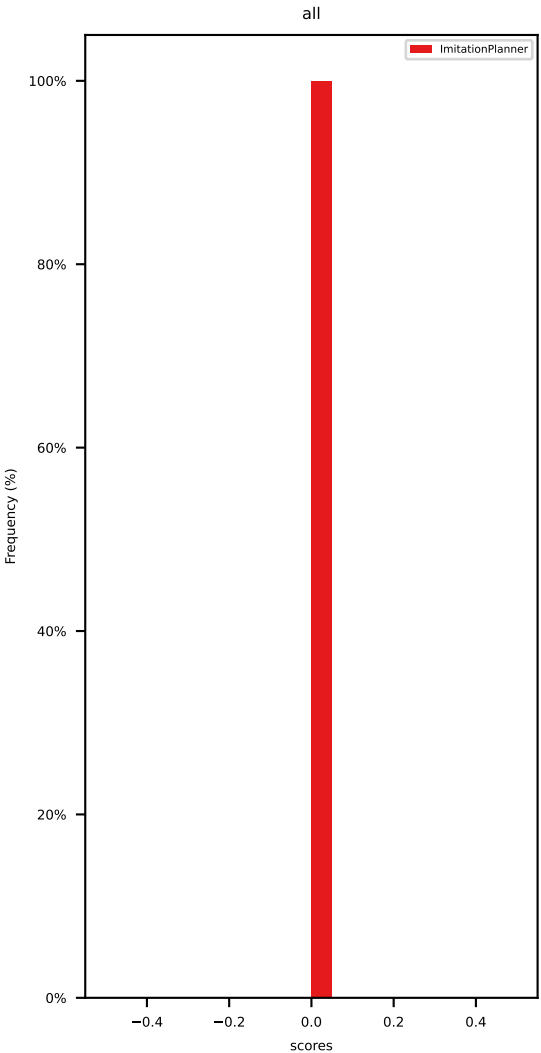
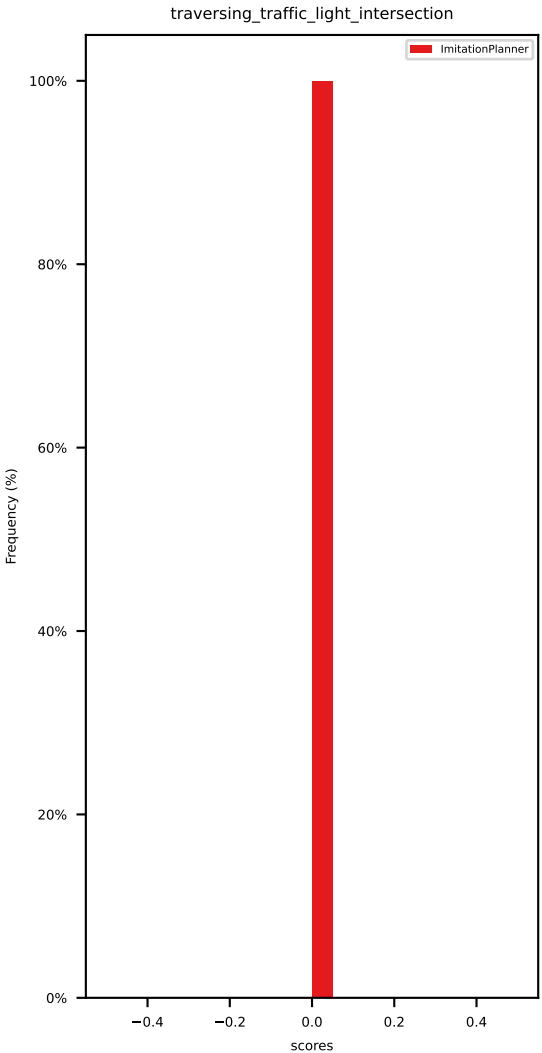
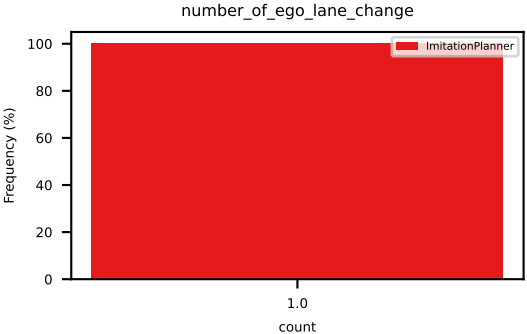
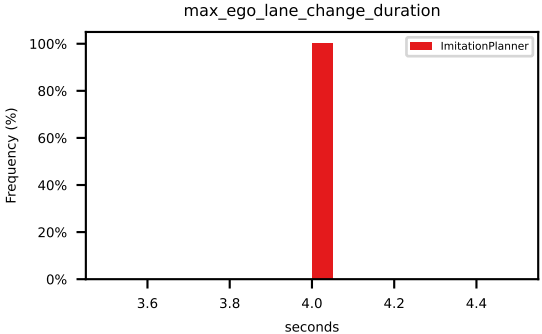
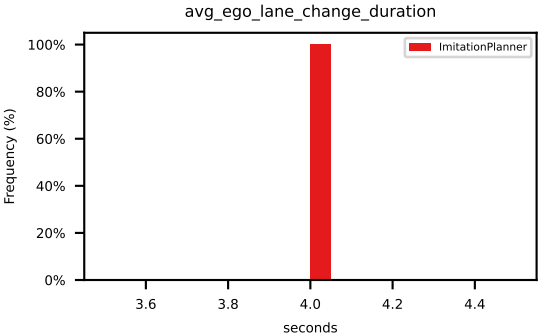


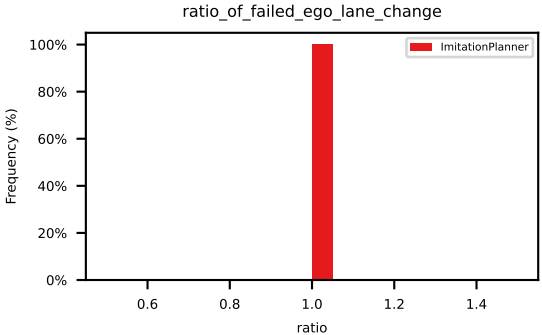



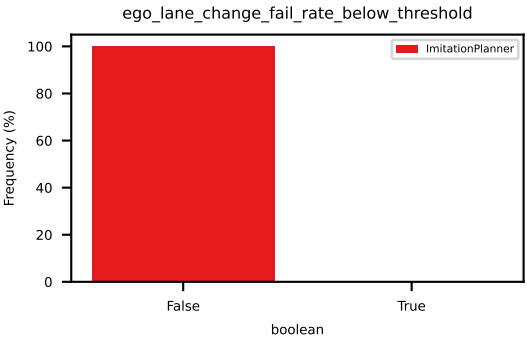
# ego_lane_change



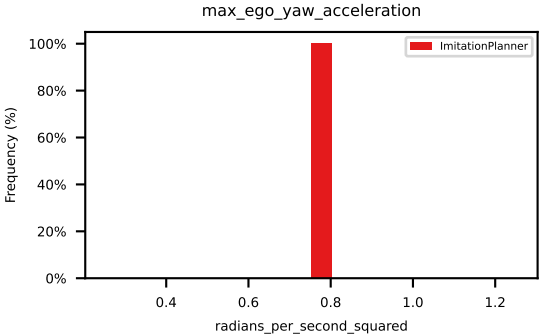



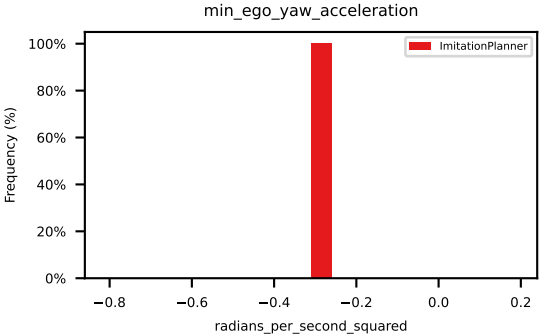



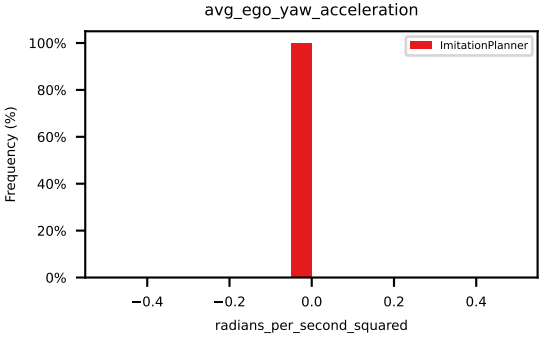



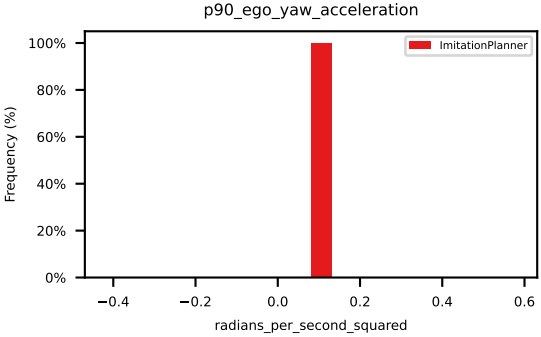



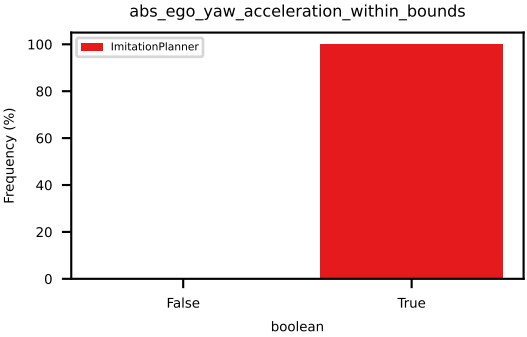
# ego_yaw_acceleration



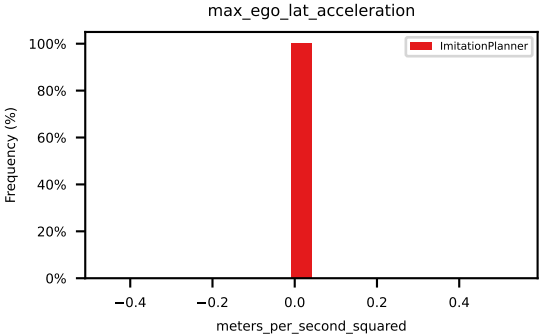



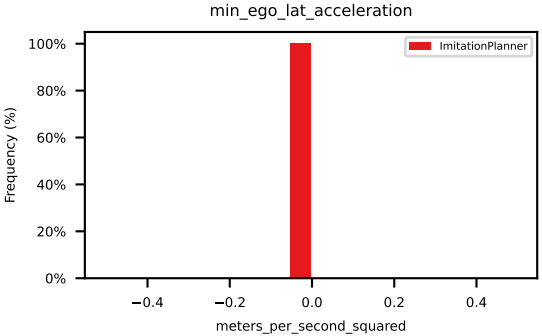



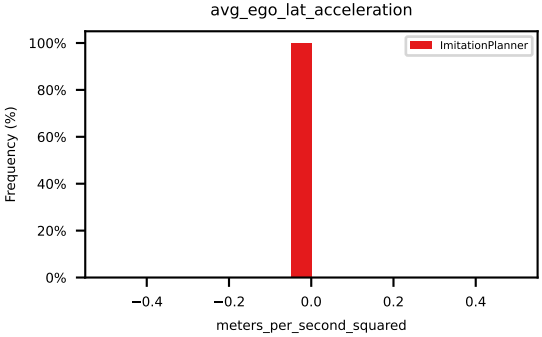



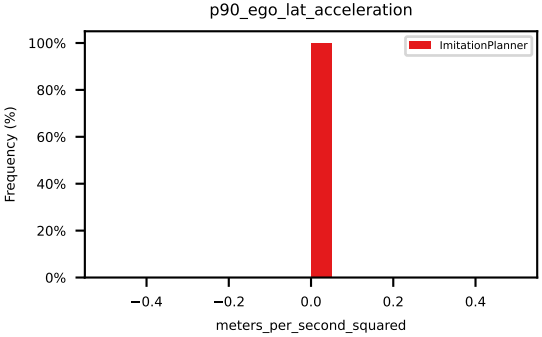



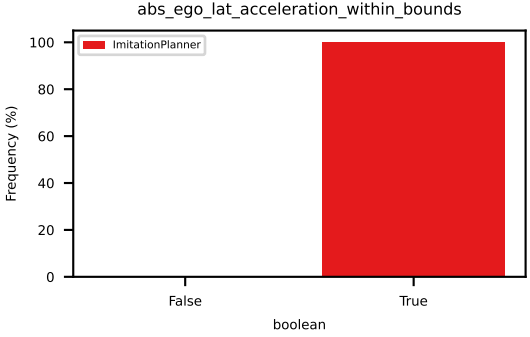
# ego_lat_acceleration



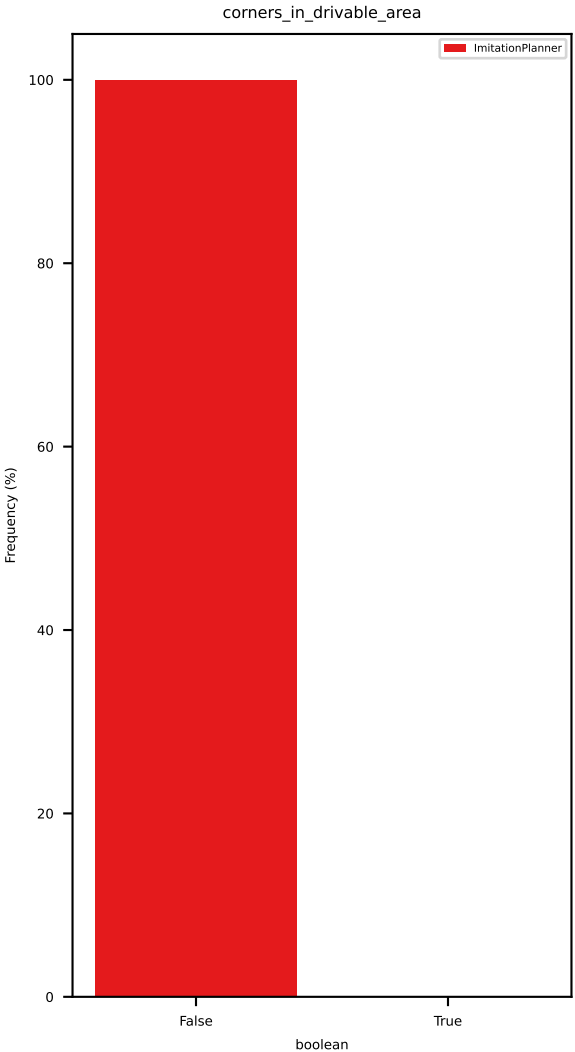



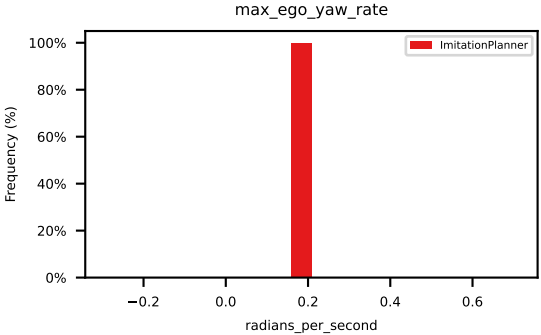



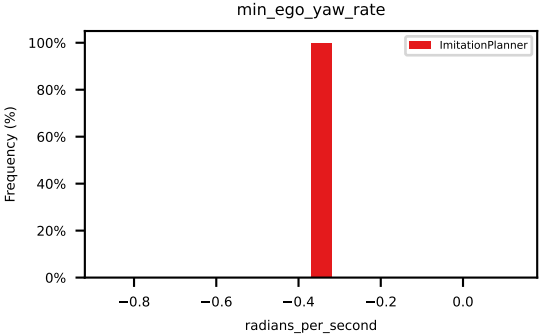



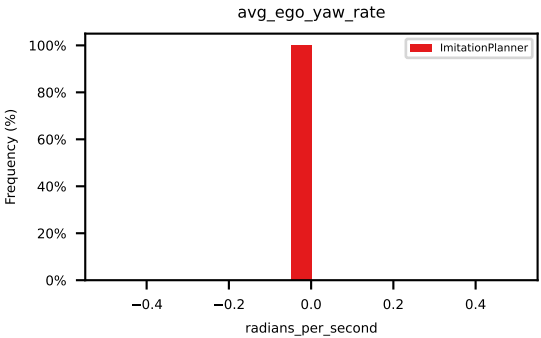
# corners_in_drivable_area

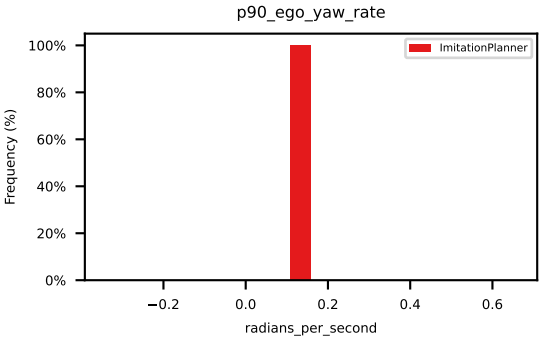


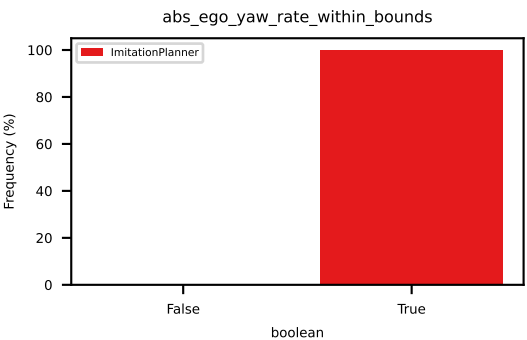
# ego_yaw_rate

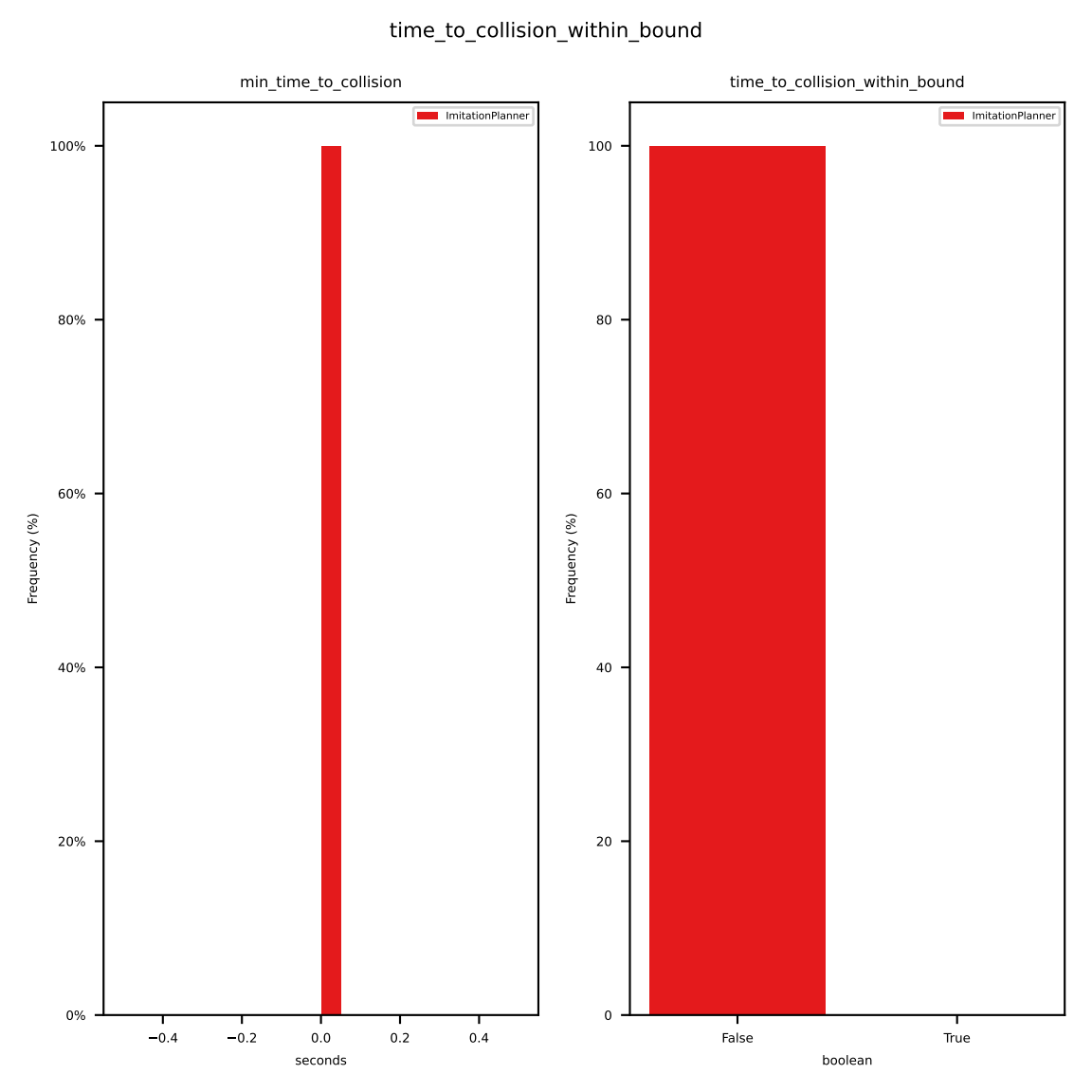

max_ego_yaw_rate
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−0.2
0.0
0.2
0.4
0.6
radians_per_second


min_ego_yaw_rate
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−0.8
−0.6
−0.4
−0.2
0.0
radians_per_second

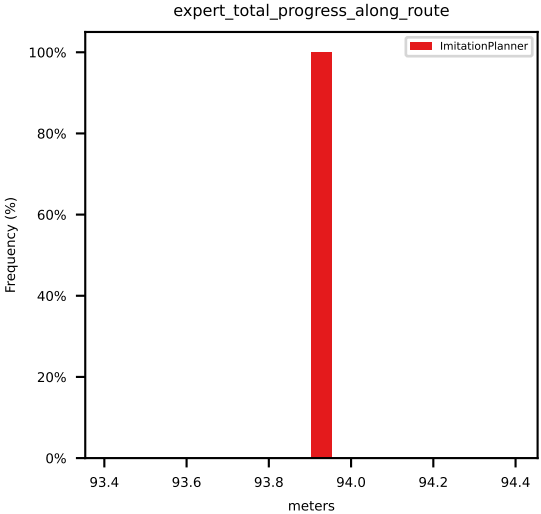

avg_ego_yaw_rate
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−0.4
−0.2
0.0
0.2
0.4
radians_per_second

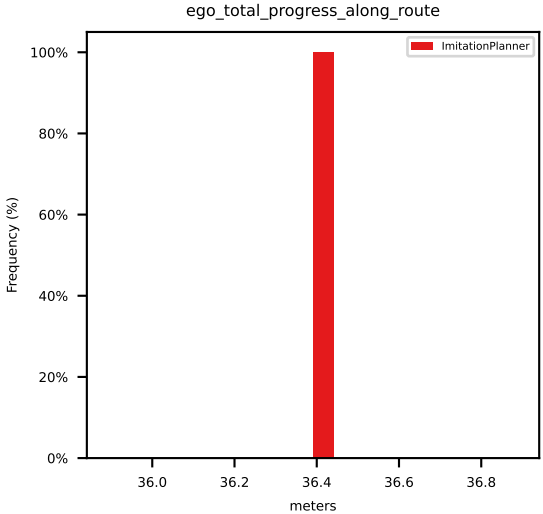

p90_ego_yaw_rate
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−0.2
0.0
0.2
0.4
0.6
radians_per_second

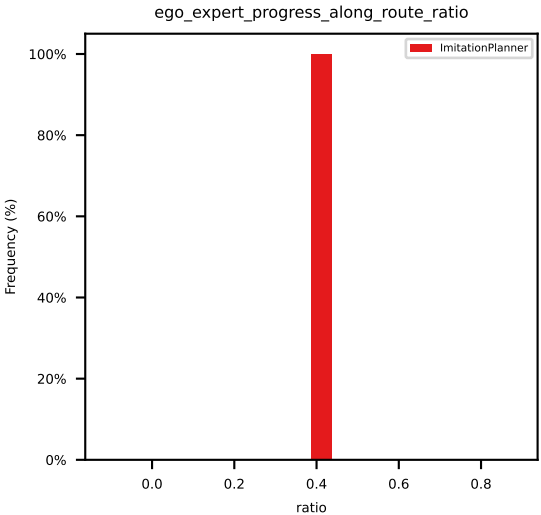

abs_ego_yaw_rate_within_bounds
ImitationPlanner
Frequency (%)
100
80
60
40
20
0
False
True
boolean


time_to_collision_within_bound
min_time_to_collision
ImitationPlanner
100%
80%
60%
40%
20%
0%
Frequency (%)
−0.4
−0.2
0.0
0.2
0.4
seconds
time_to_collision_within_bound
ImitationPlanner
100
80
60
40
20
0
Frequency (%)
False
True
boolean

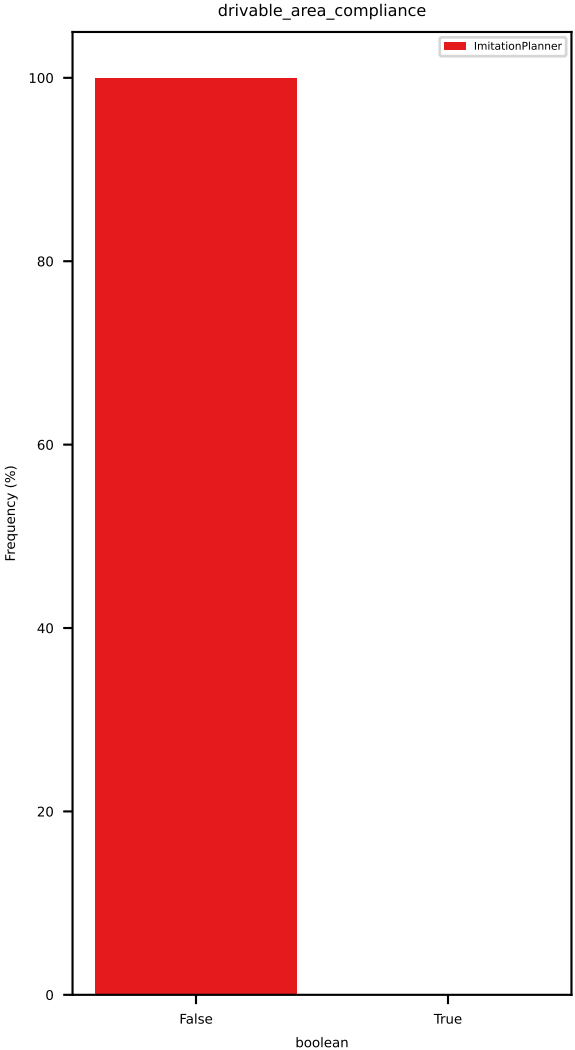
# ego_progress_along_expert_route



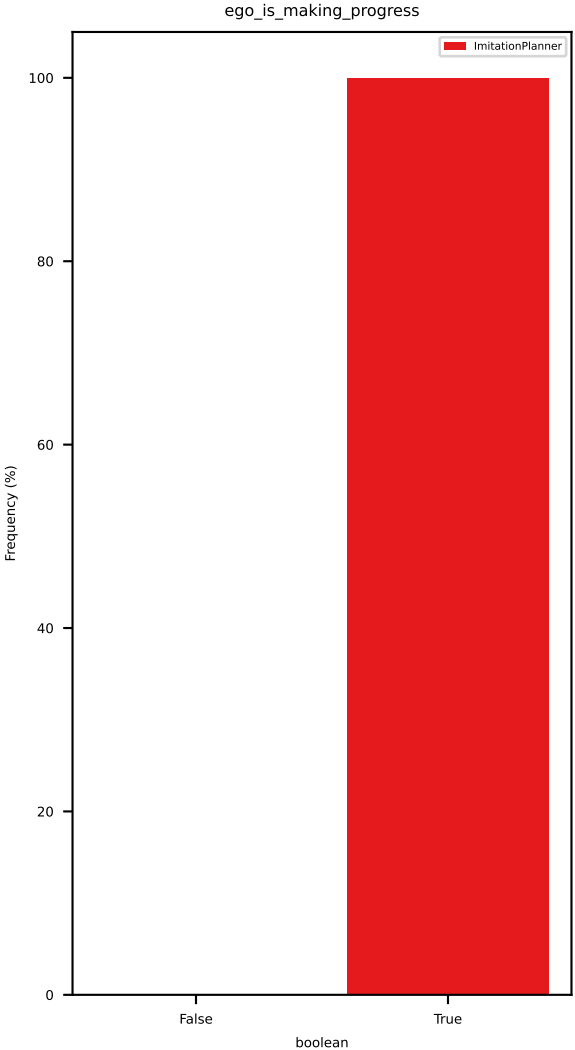



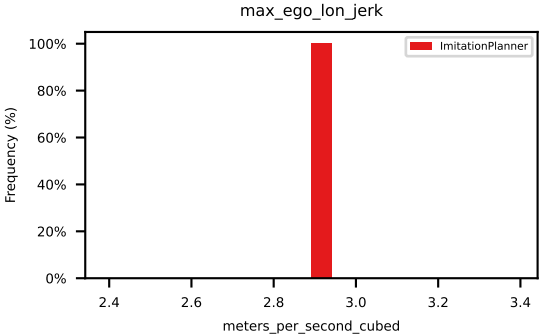
drivable_area_compliance

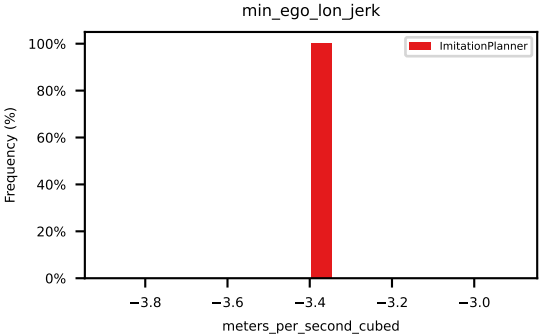


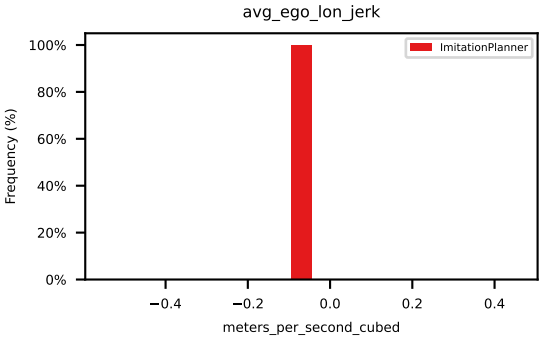
# ego_is_making_progress

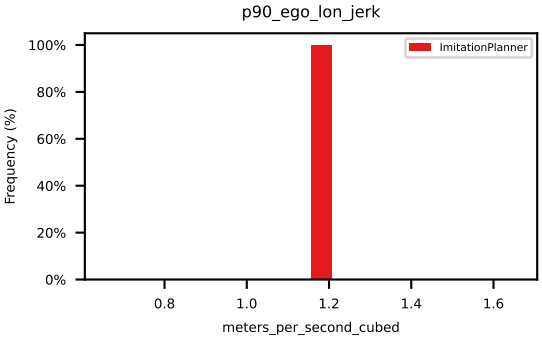


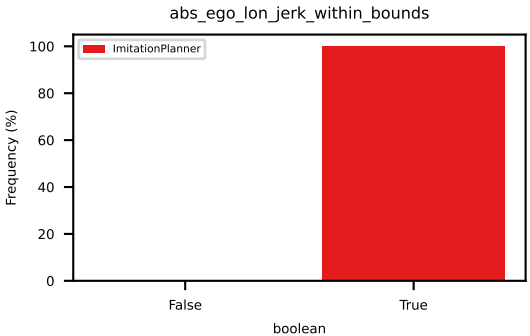
# ego_lon_jerk

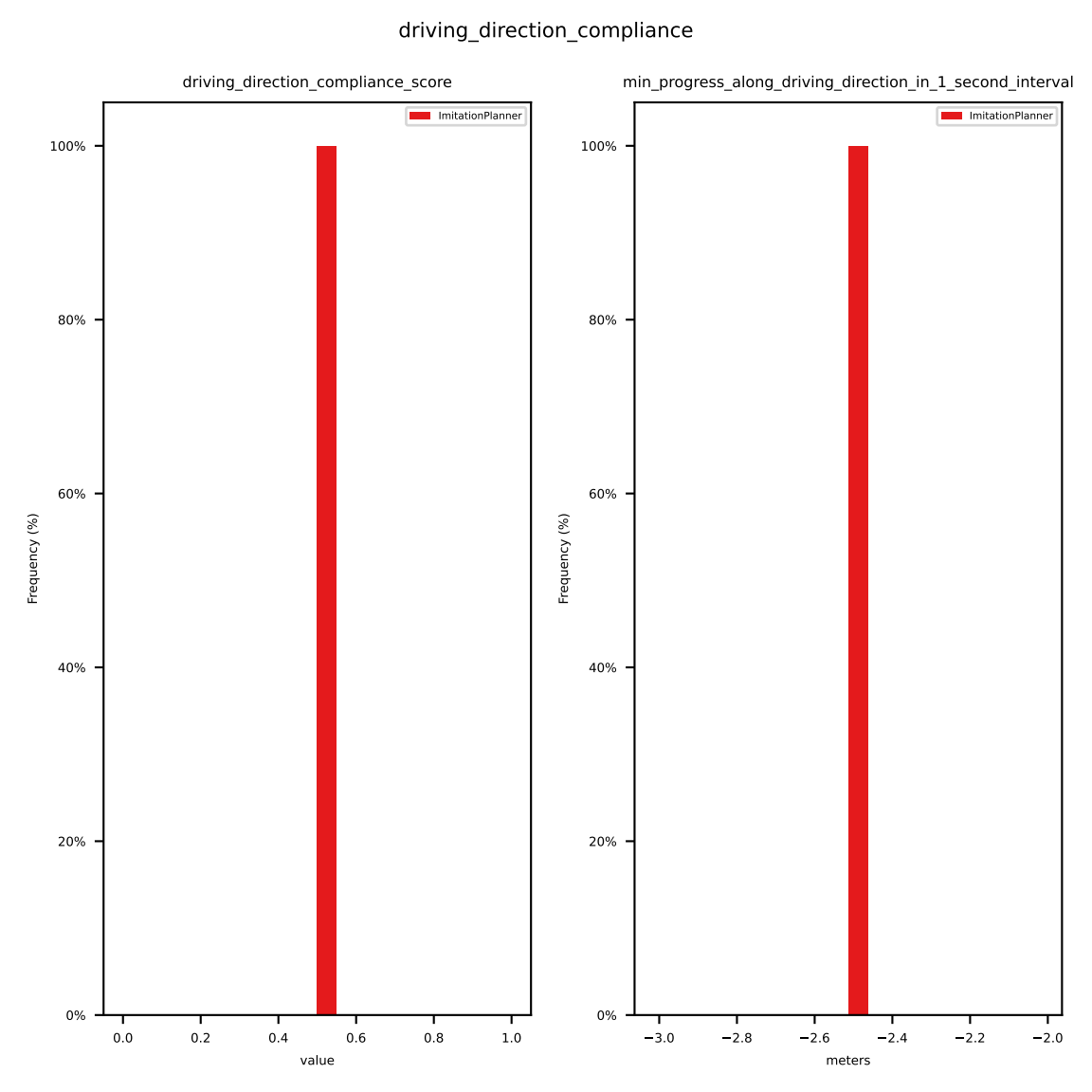

max_ego_lon_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
2.4
2.6
2.8
3.0
3.2
3.4
meters_per_second_cubed


min_ego_lon_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−3.8
−3.6
−3.4
−3.2
−3.0
meters_per_second_cubed

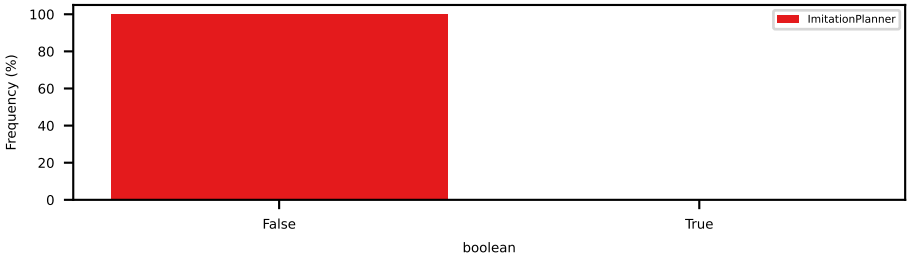

avg_ego_lon_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−0.4
−0.2
0.0
0.2
0.4
meters_per_second_cubed

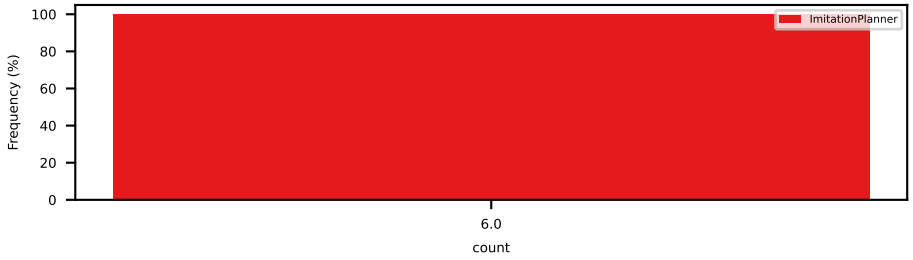

p90_ego_lon_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
0.8
1.0
1.2
1.4
1.6
meters_per_second_cubed

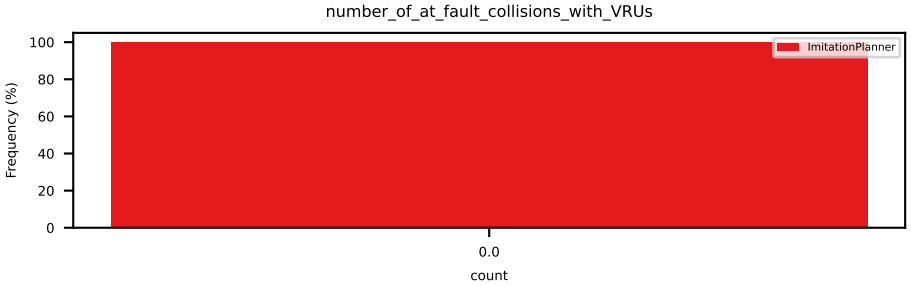

abs_ego_lon_jerk_within_bounds
ImitationPlanner
Frequency (%)
100
80
60
40
20
0
False
True
boolean

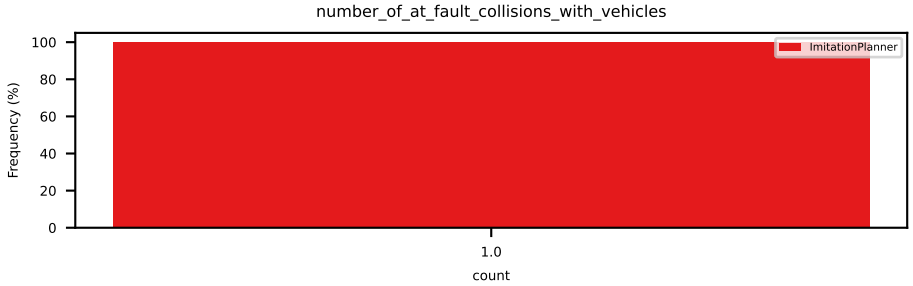

driving_direction_compliance
driving_direction_compliance_score
ImitationPlanner
100%
80%
60%
40%
20%
0%
Frequency (%)
0.0
0.2
0.4
0.6
0.8
1.0
value
min_progress_along_driving_direction_in_1_second_interval
ImitationPlanner
100%
80%
60%
40%
20%
0%
Frequency (%)
−3.0
−2.8
−2.6
−2.4
−2.2
−2.0
meters

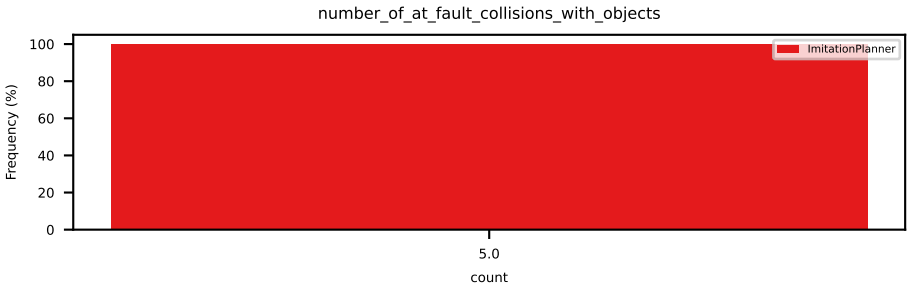
# no_ego_at_fault_collisions

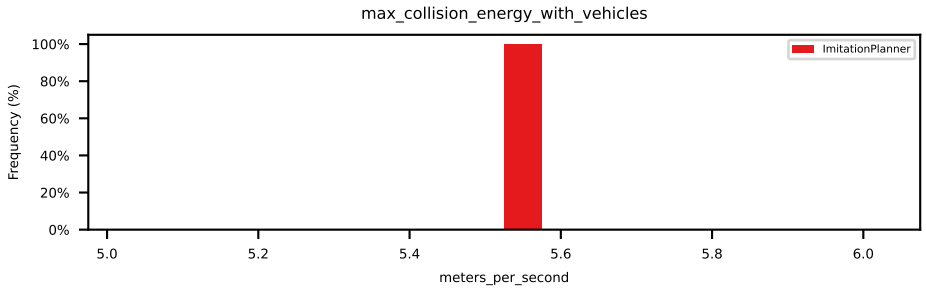


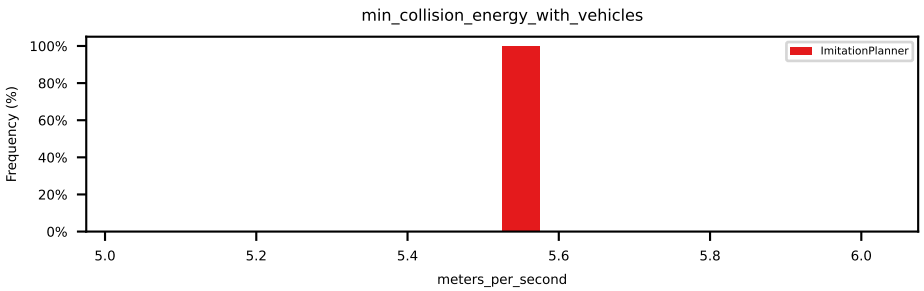



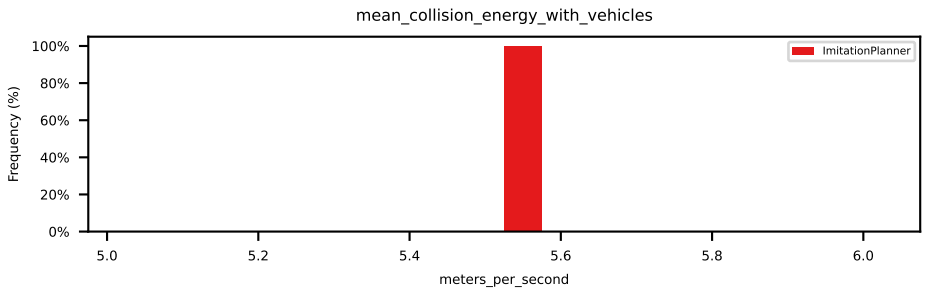



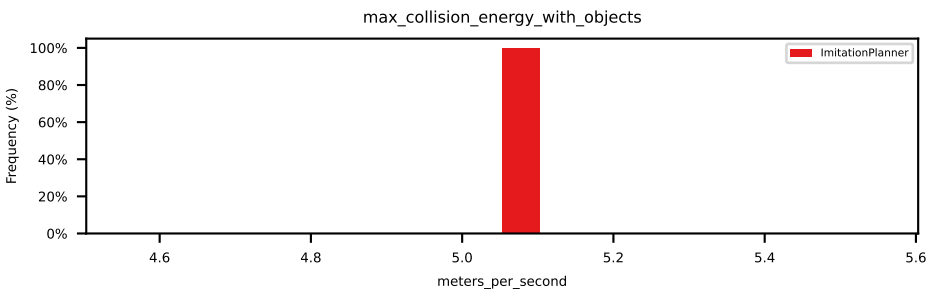



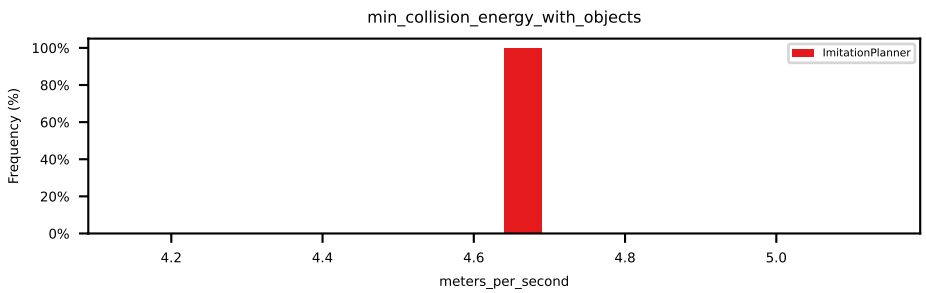



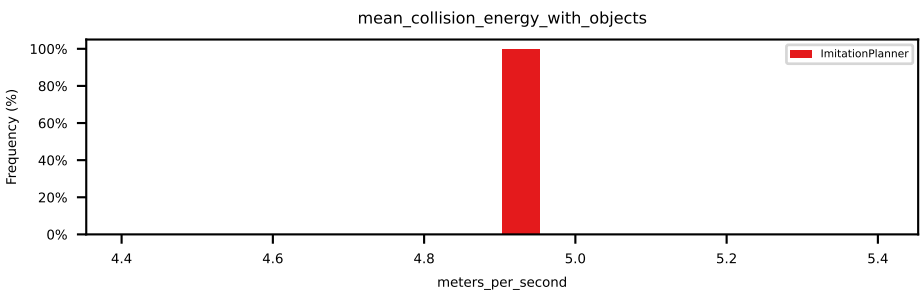



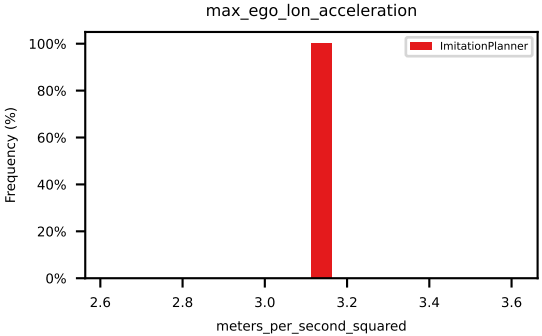



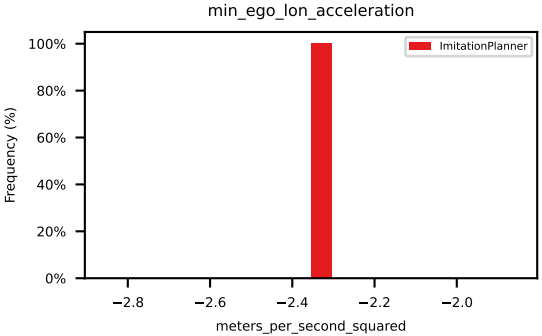



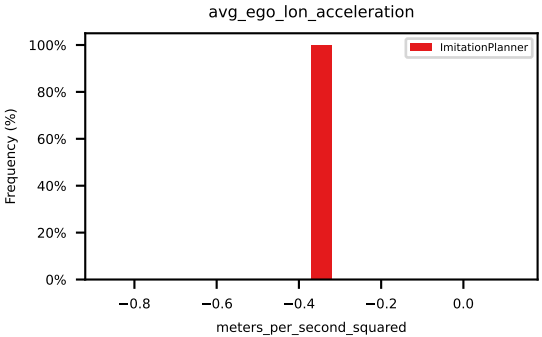



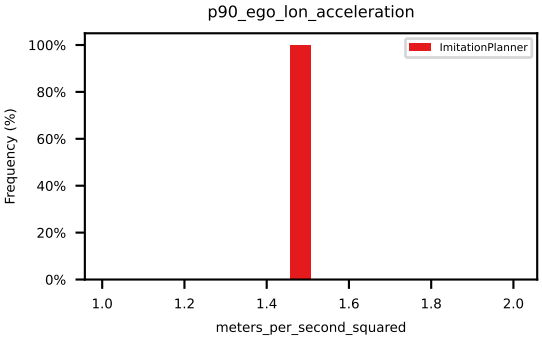



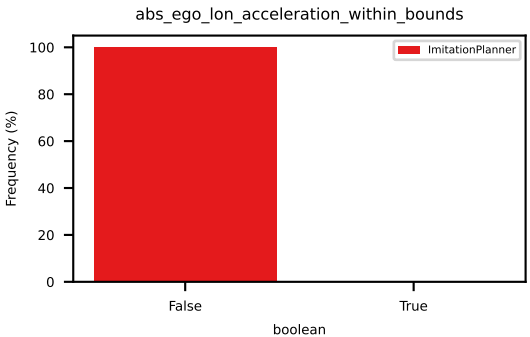
# ego_lon_acceleration



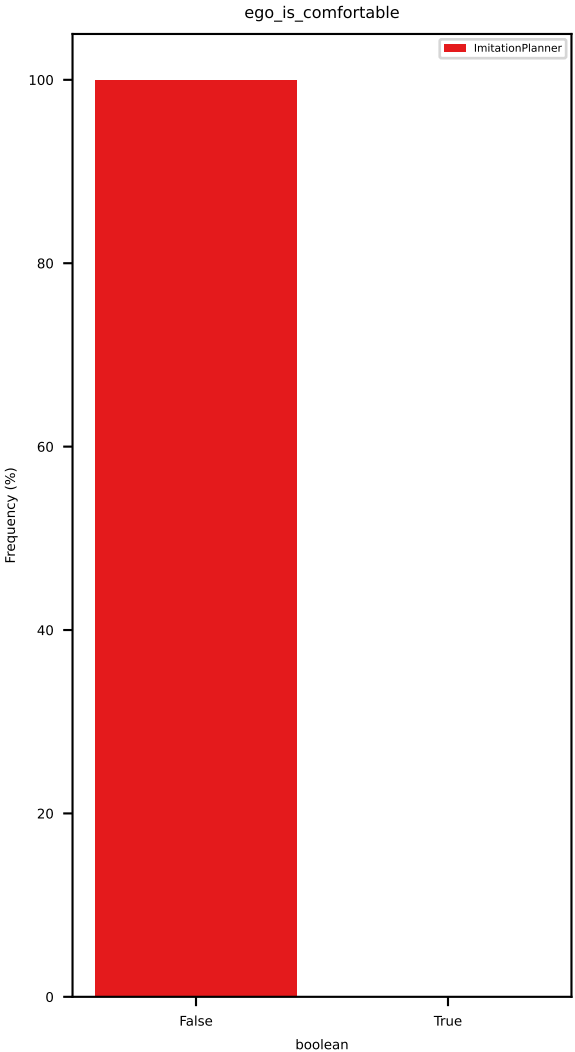



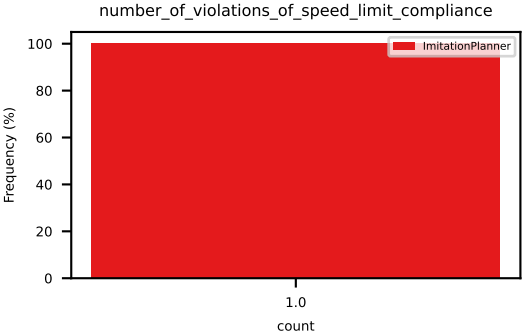



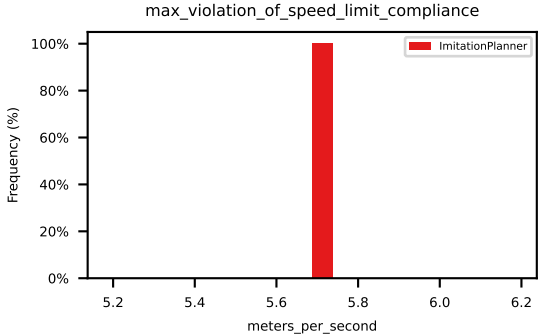



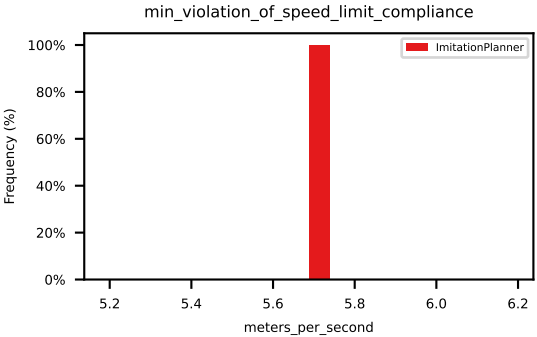
ego_is_comfortable

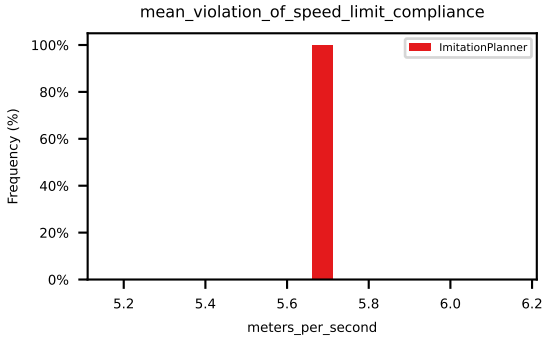


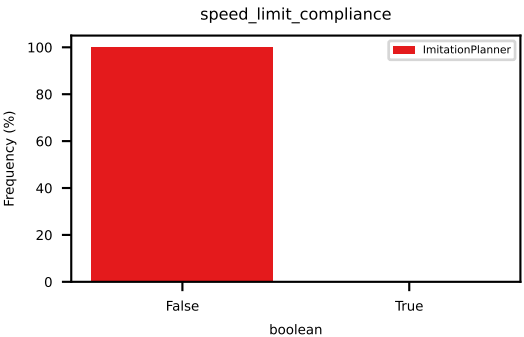
# speed_limit_compliance



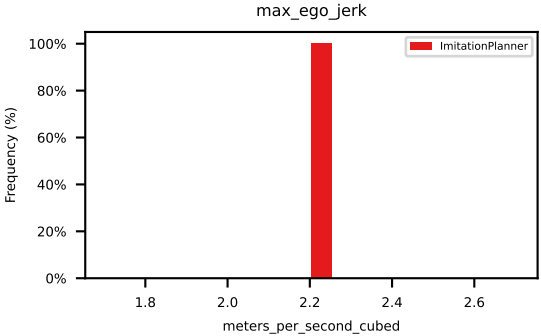



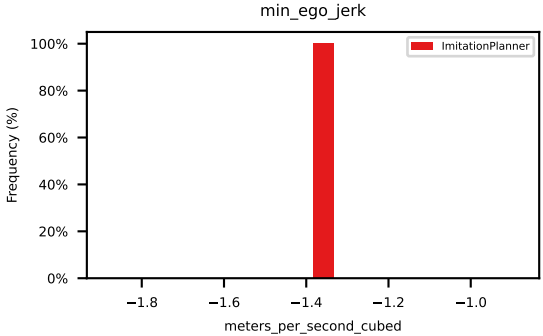



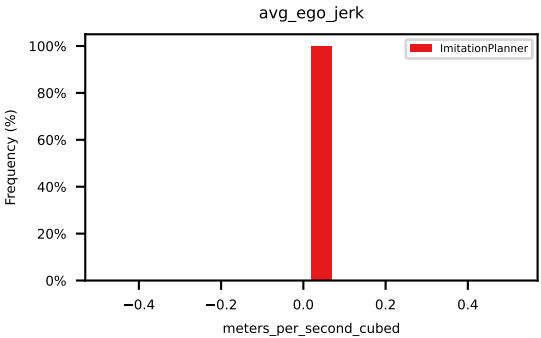



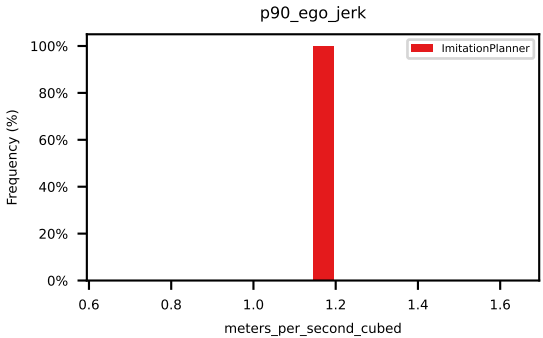



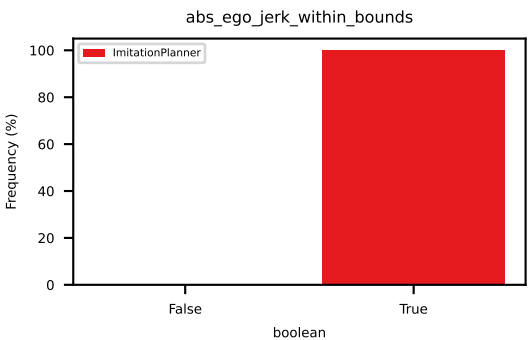
# ego_jerk


max_ego_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
1.8
2.0
2.2
2.4
2.6
meters_per_second_cubed


min_ego_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−1.8
−1.6
−1.4
−1.2
−1.0
meters_per_second_cubed


avg_ego_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
−0.4
−0.2
0.0
0.2
0.4
meters_per_second_cubed


p90_ego_jerk
ImitationPlanner
Frequency (%)
100%
80%
60%
40%
20%
0%
0.6
0.8
1.0
1.2
1.4
1.6
meters_per_second_cubed


abs_ego_jerk_within_bounds
ImitationPlanner
Frequency (%)
100
80
60
40
20
0
False
True
boolean