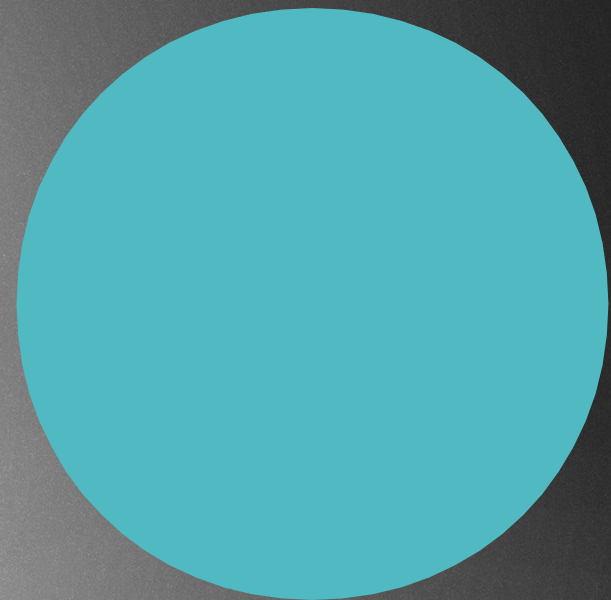


# BREADTH FIRST SEARCH

bfs





# Breadth-first search

- ▶ What is it good for?
- ▶ We have a graph and we want to visit every node → we can do it with BFS
- ▶ We visit every vertex exactly once
- ▶ We visit the neighbours then the neighbours of these new vertices and so on
- ▶ Running time complexity:  $O(V+E)$
- ▶ Memory complexity is not good: we have to store lots of references
- ▶ That's why DFS is usually preferred
- ▶ BUT it constructs a shortest path: Dijkstra algorithm does a BFS if all the edge weights are equal to 1



# Breadth-first search

*bfs(vertex)*

*Queue queue*

*vertex set visited true*

*queue.enqueue(vertex)*

*while queue not empty*

*actual = queue.dequeue()*

*for v in actual neighbours*

*if v is not visited*

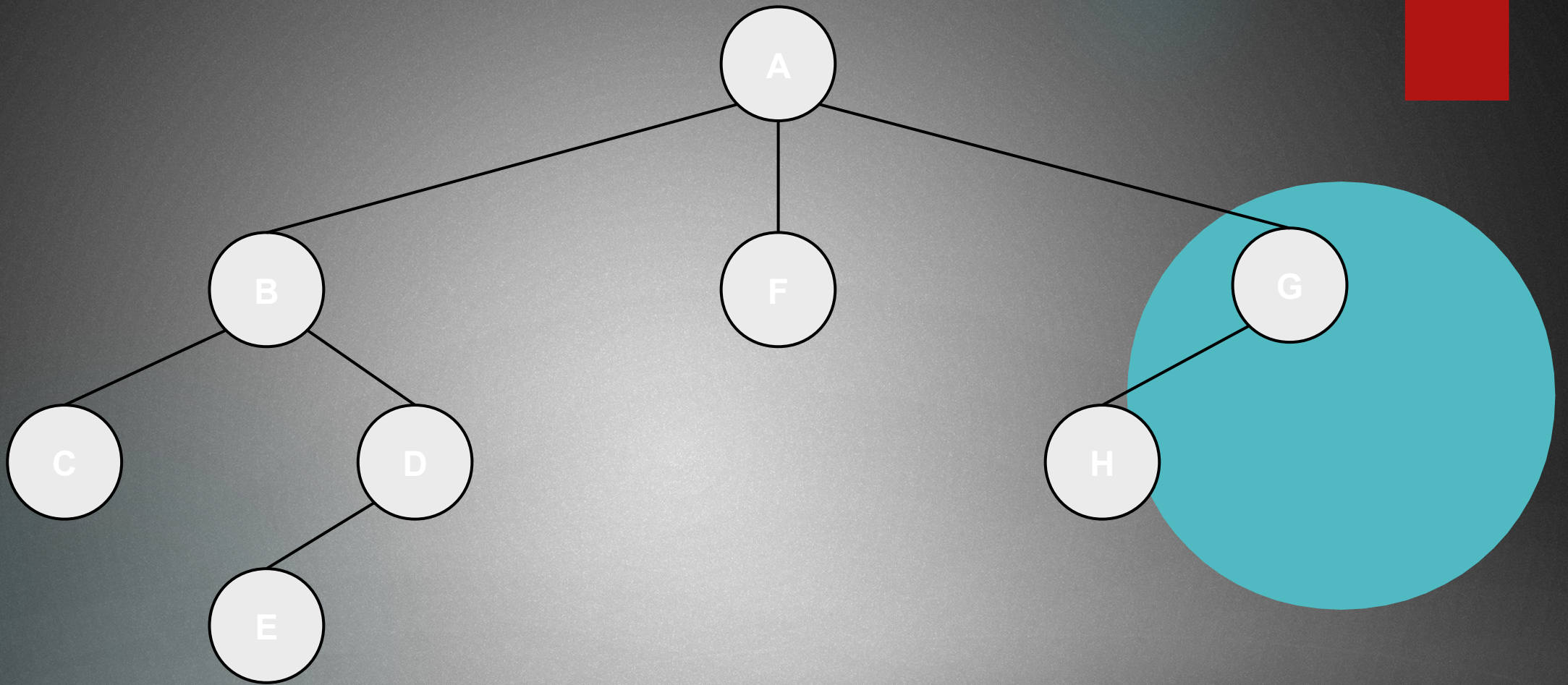
*v set visited true*

*queue.enqueue(v)*

We have an empty queue at the beginning  
and we keep checking whether we have visited  
the given node or not  
~ keep iterating until queue is not empty

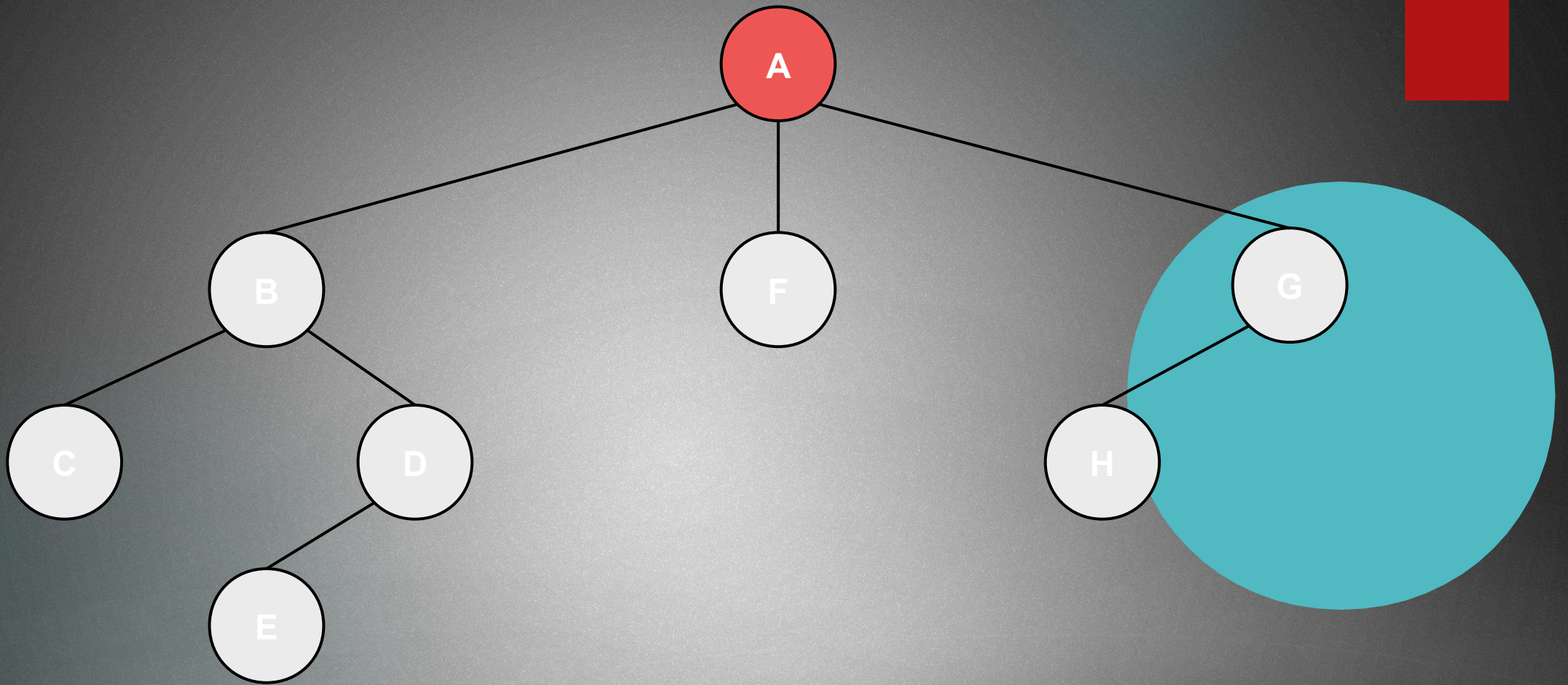
ITERATION





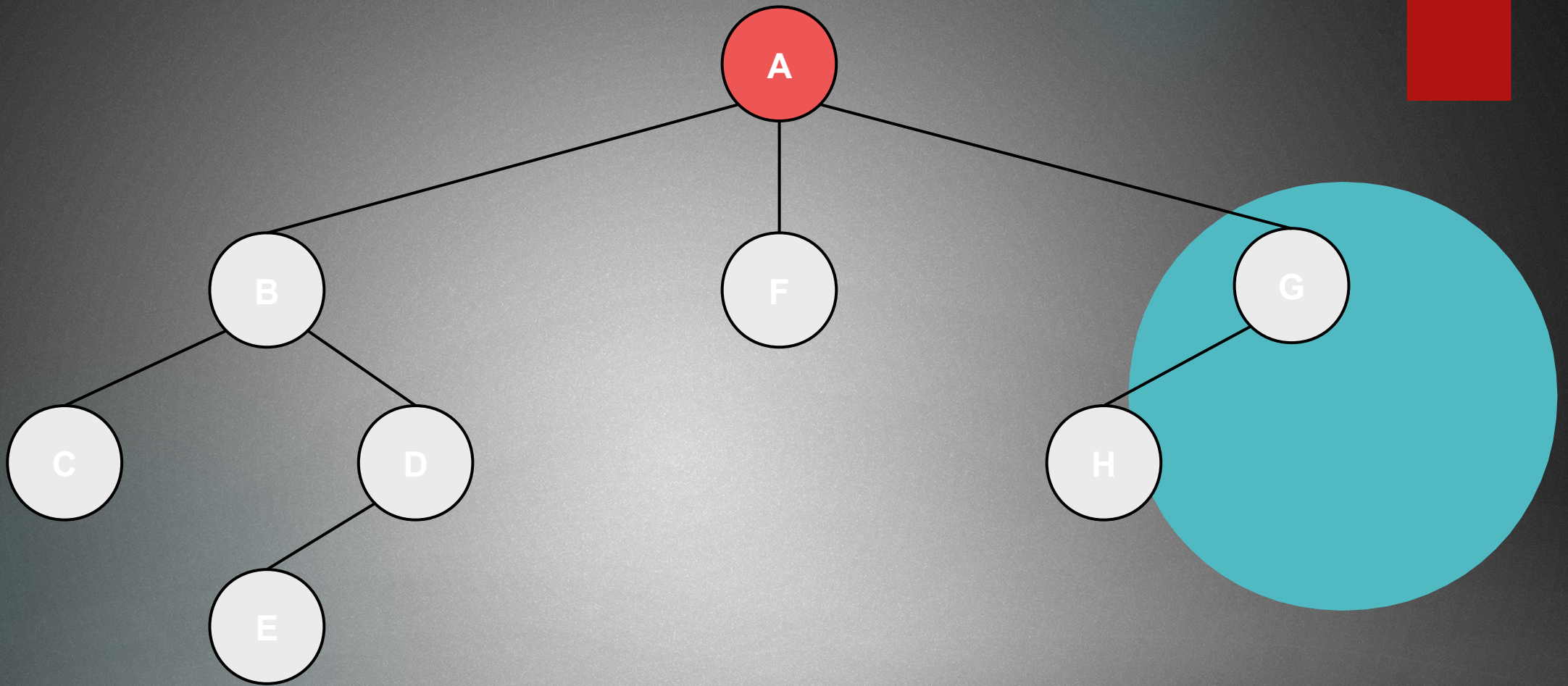
Queue: { }





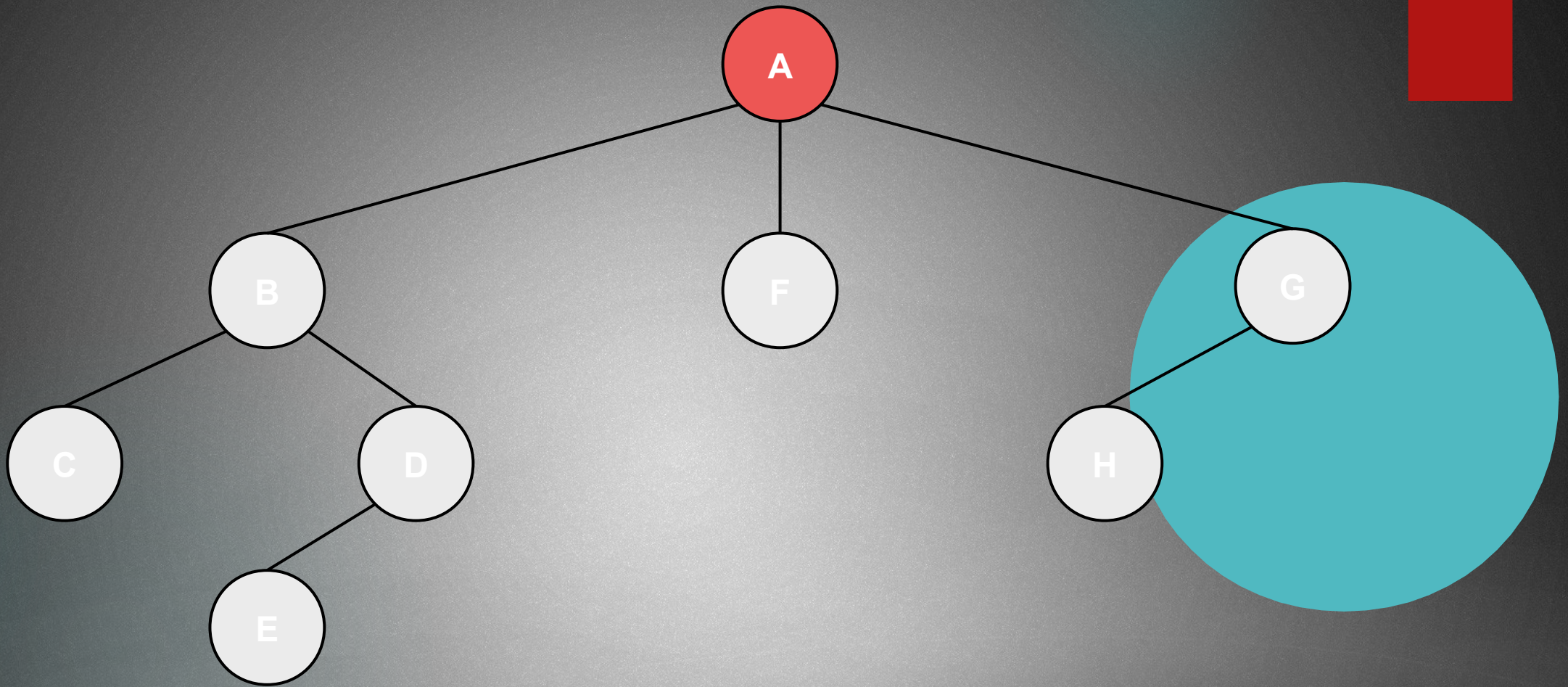
Queue: { A }





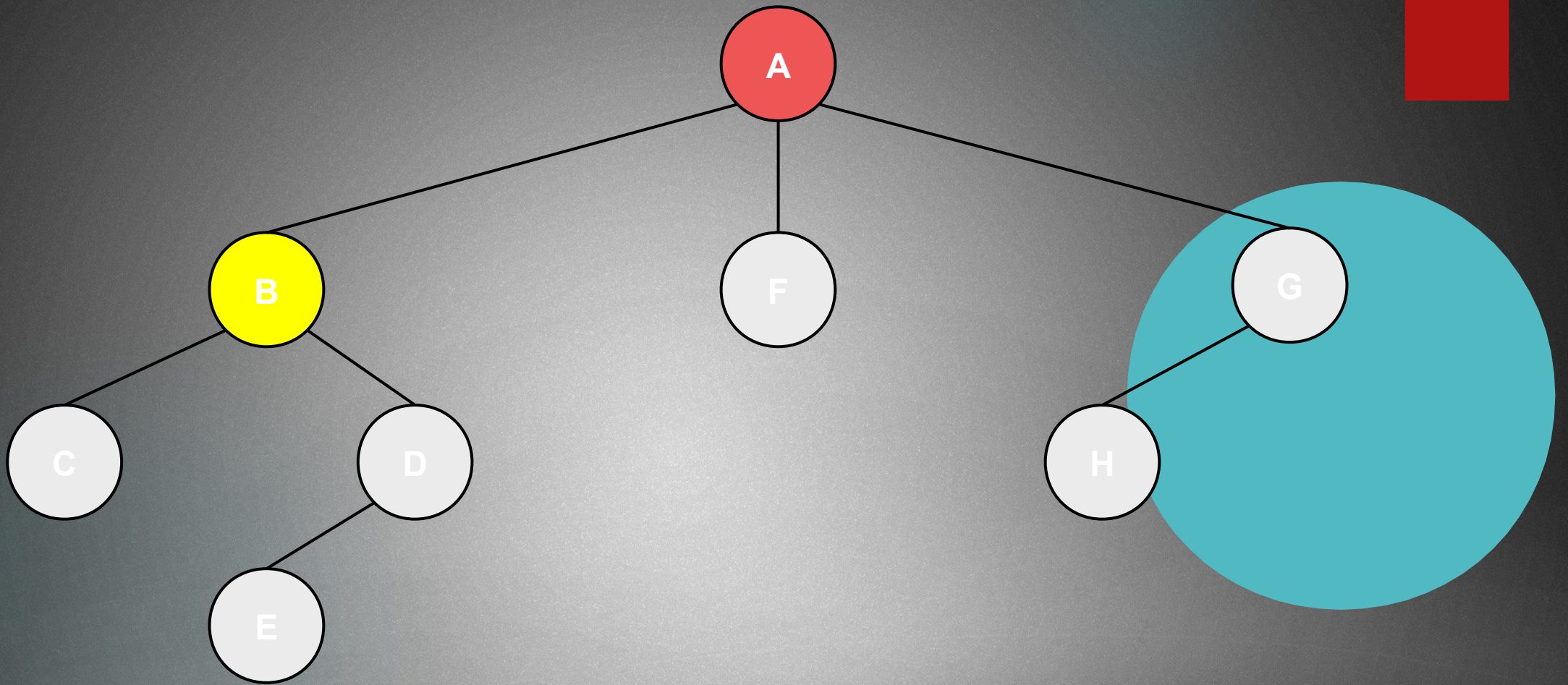
Queue: { **A** }      dequeue node A to be able to process its





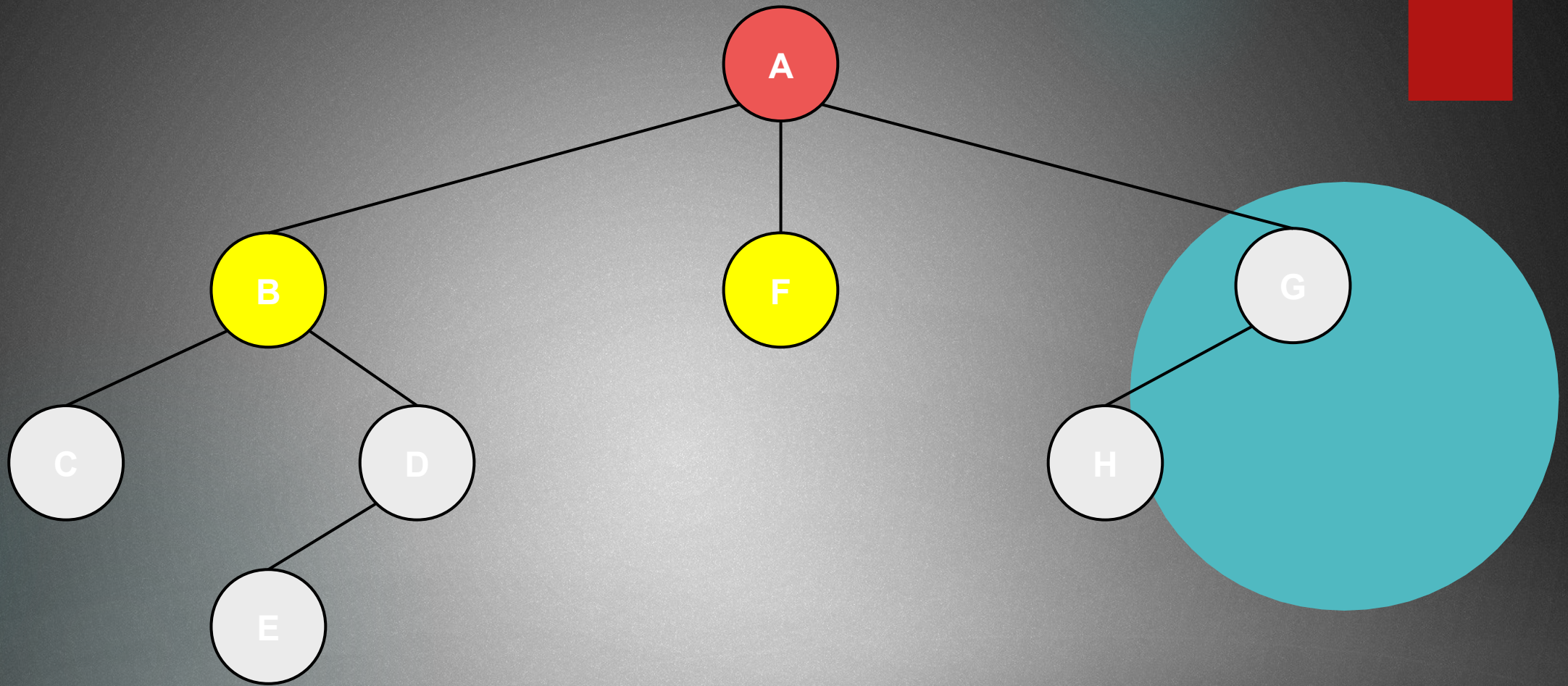
Queue: { } dequeue node A to be able to process its neighbours → visit all the children, if a node is unvisited then enqueue it !!!





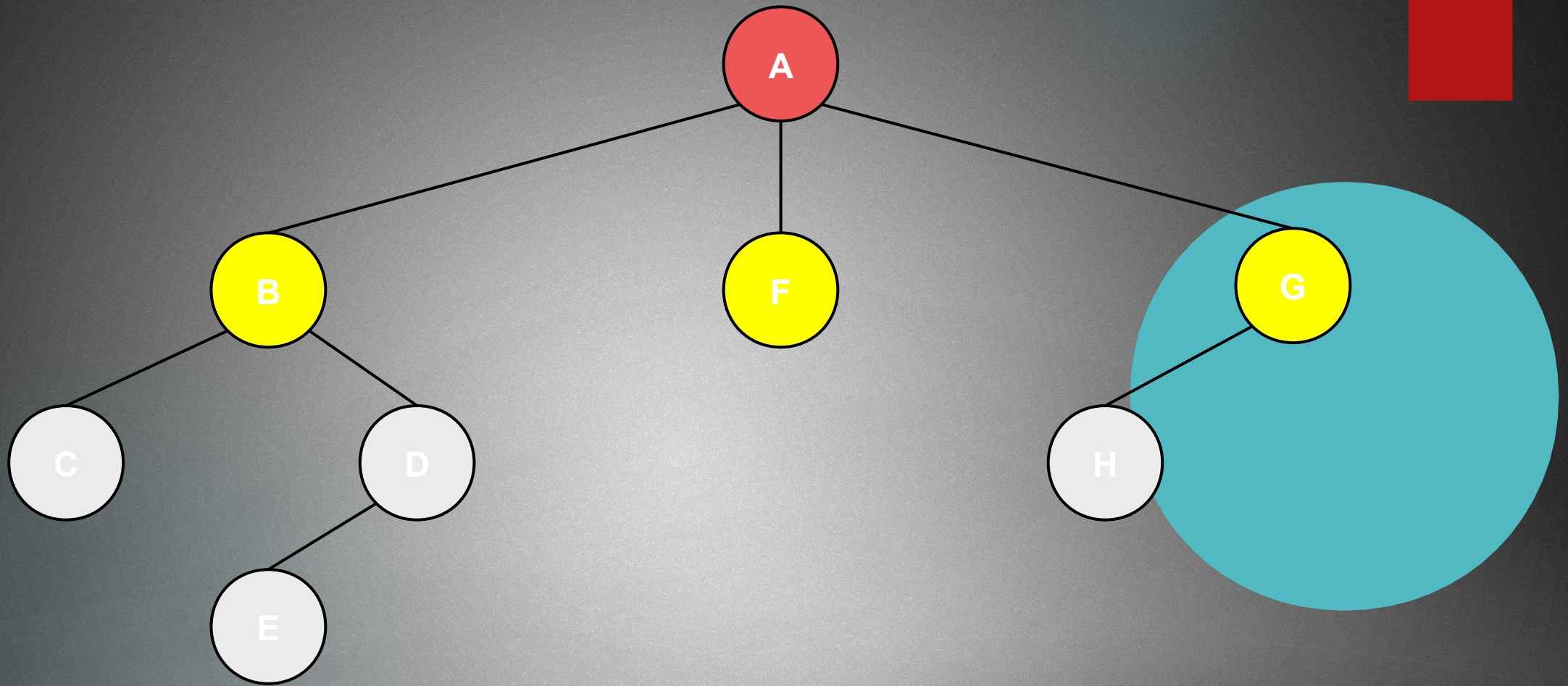
Queue: { B }    node B is not visited → put it to the queue





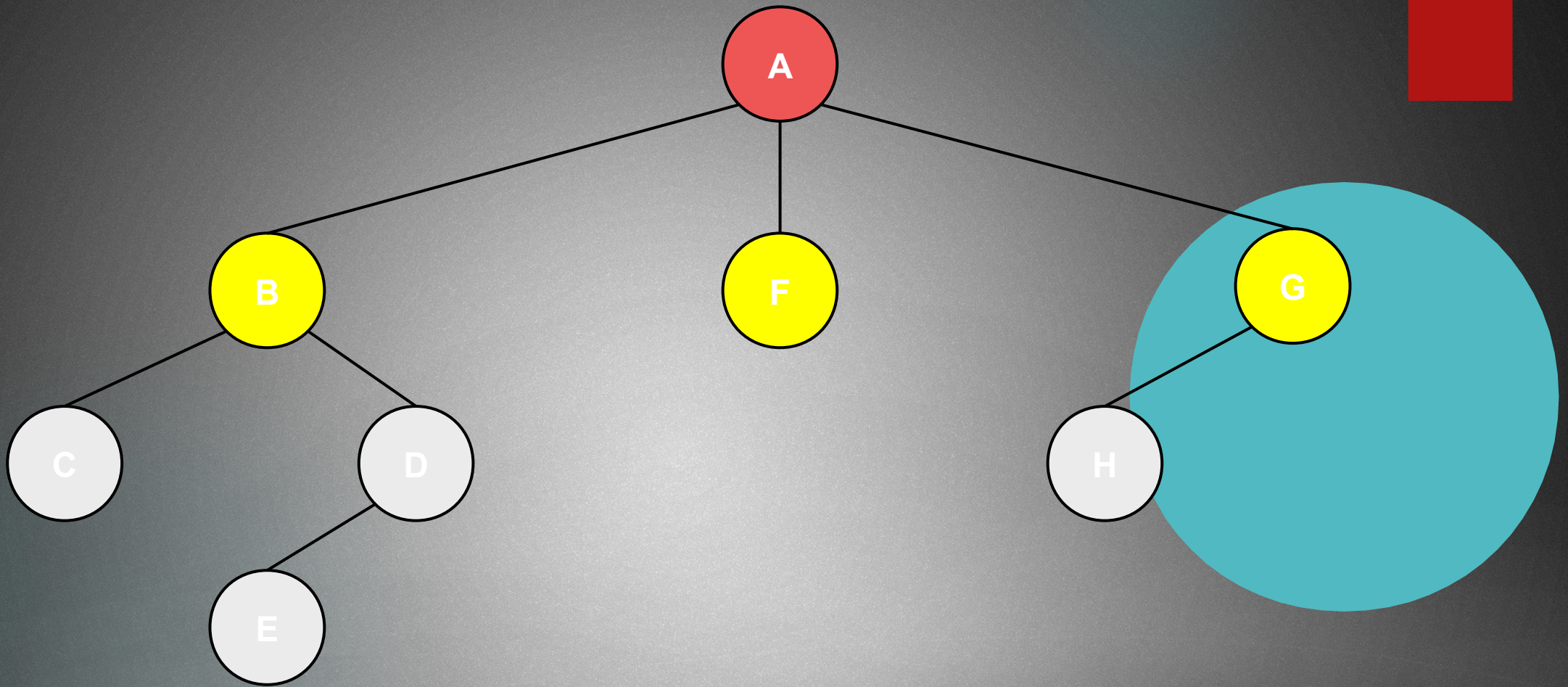
Queue: { F B }    node F is not visited → put it to the queue





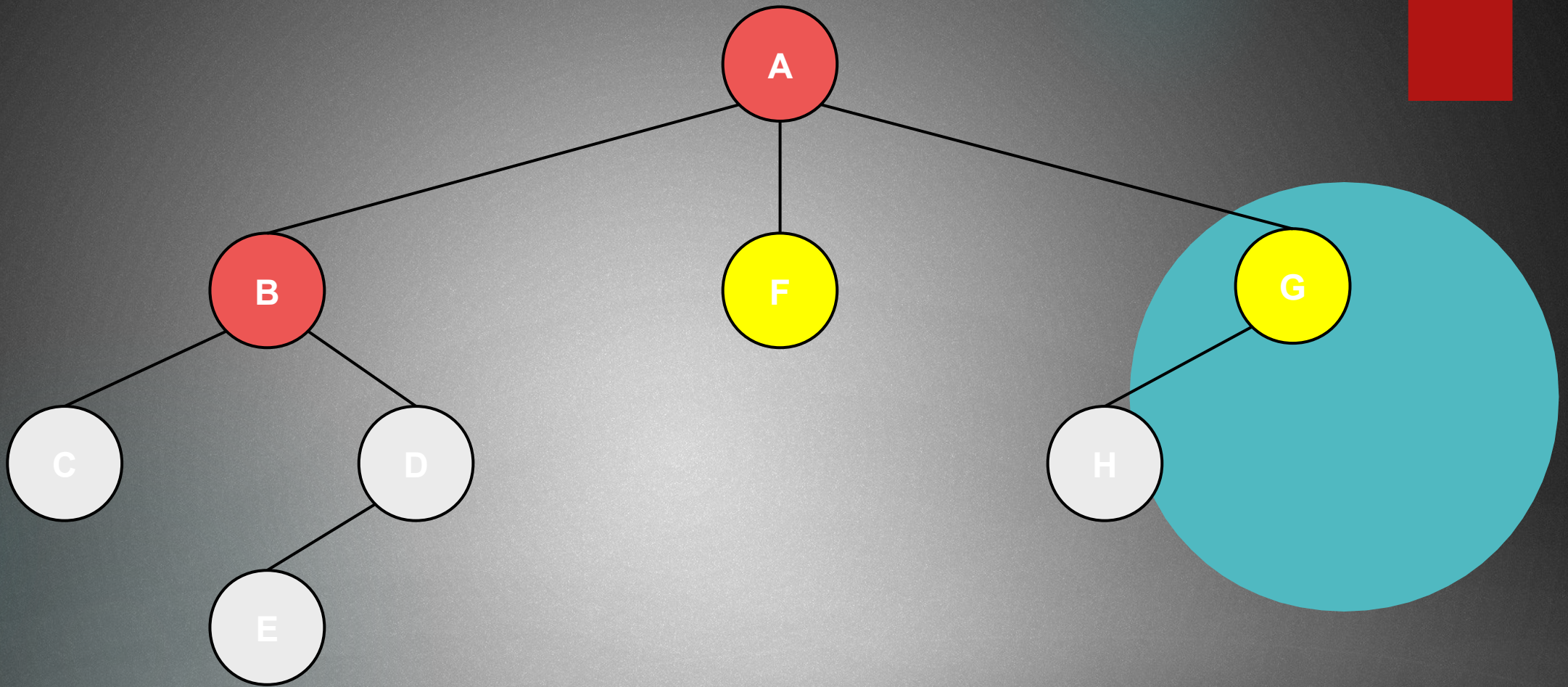
Queue: { G F B }    node G is not visited → put it to the queue





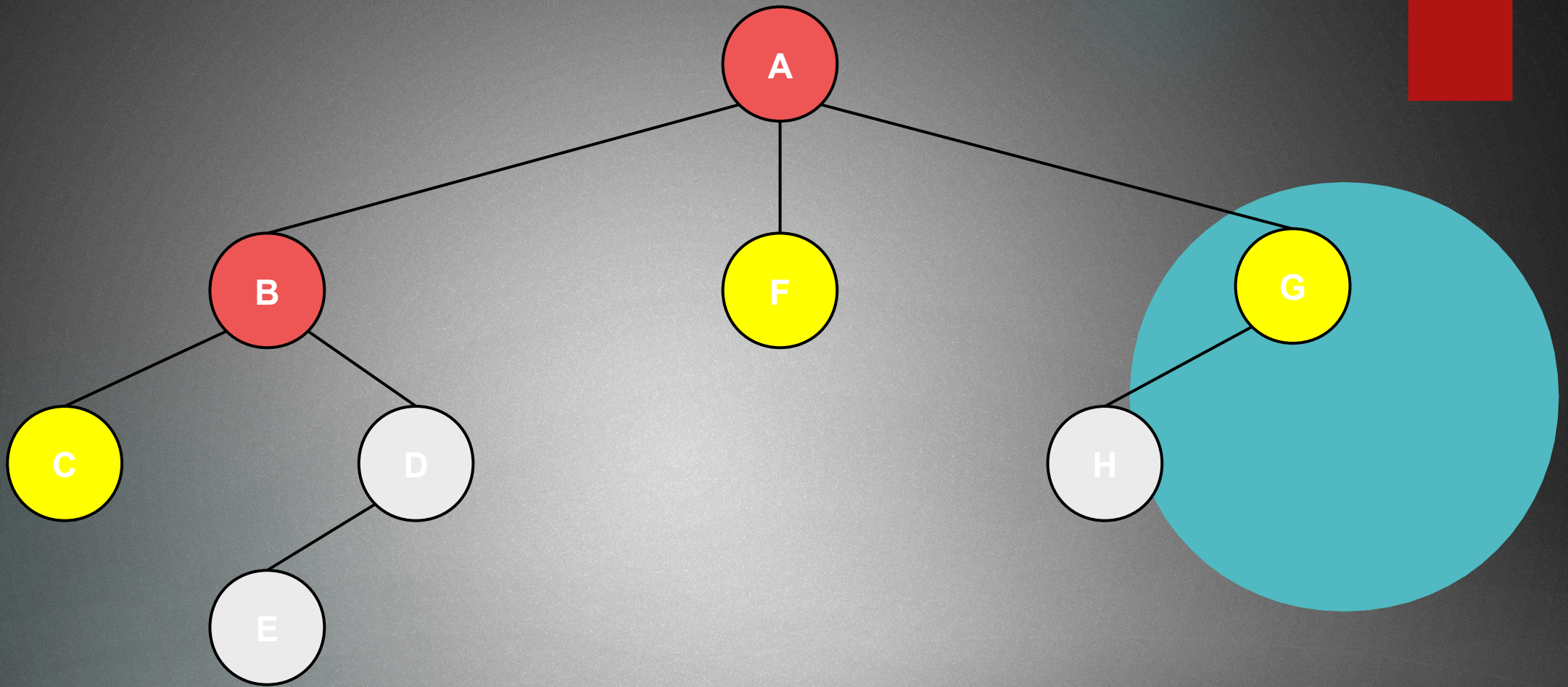
Queue: { G F **B** } dequeue the next node → it is B and visit its children + put them into the queue if necessary





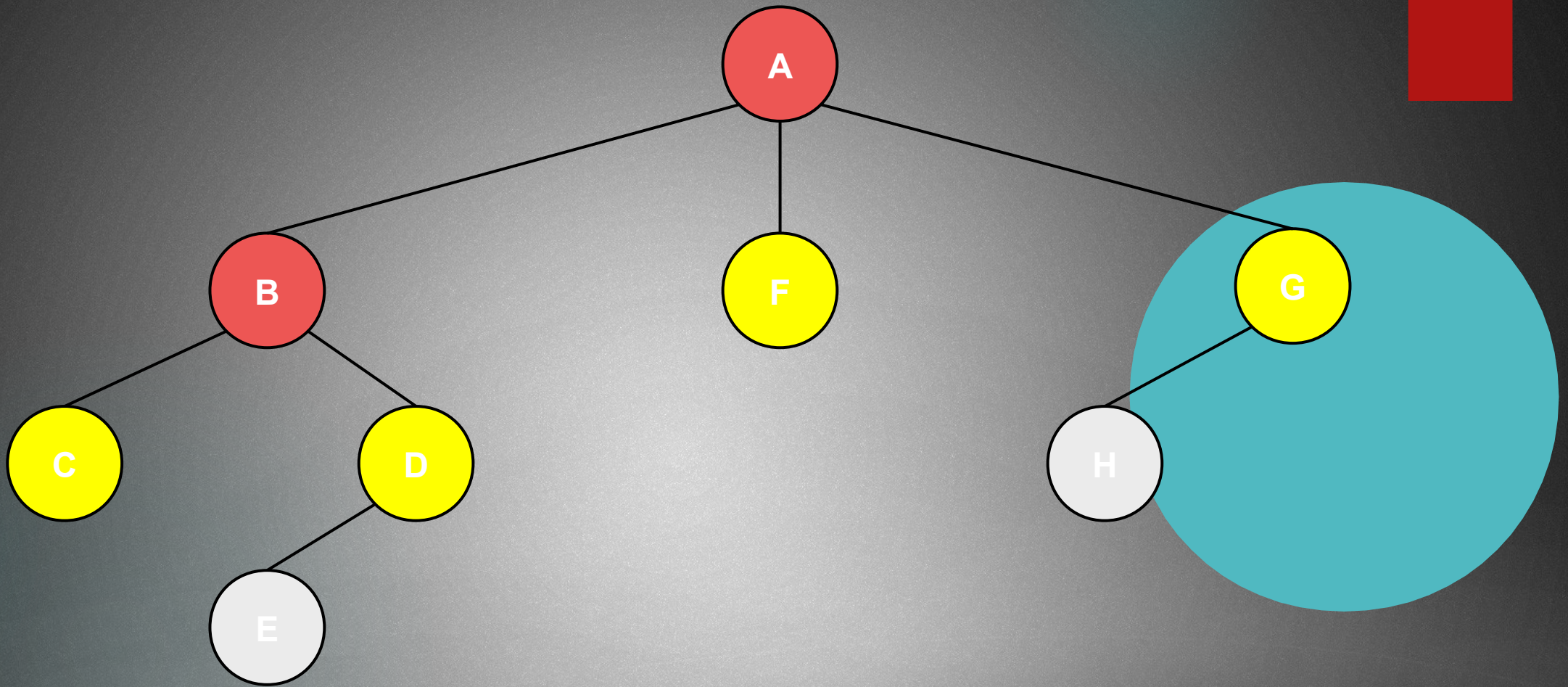
Queue: { G F } dequeue the next node → it is G and visit its children + put them into the queue if necessary





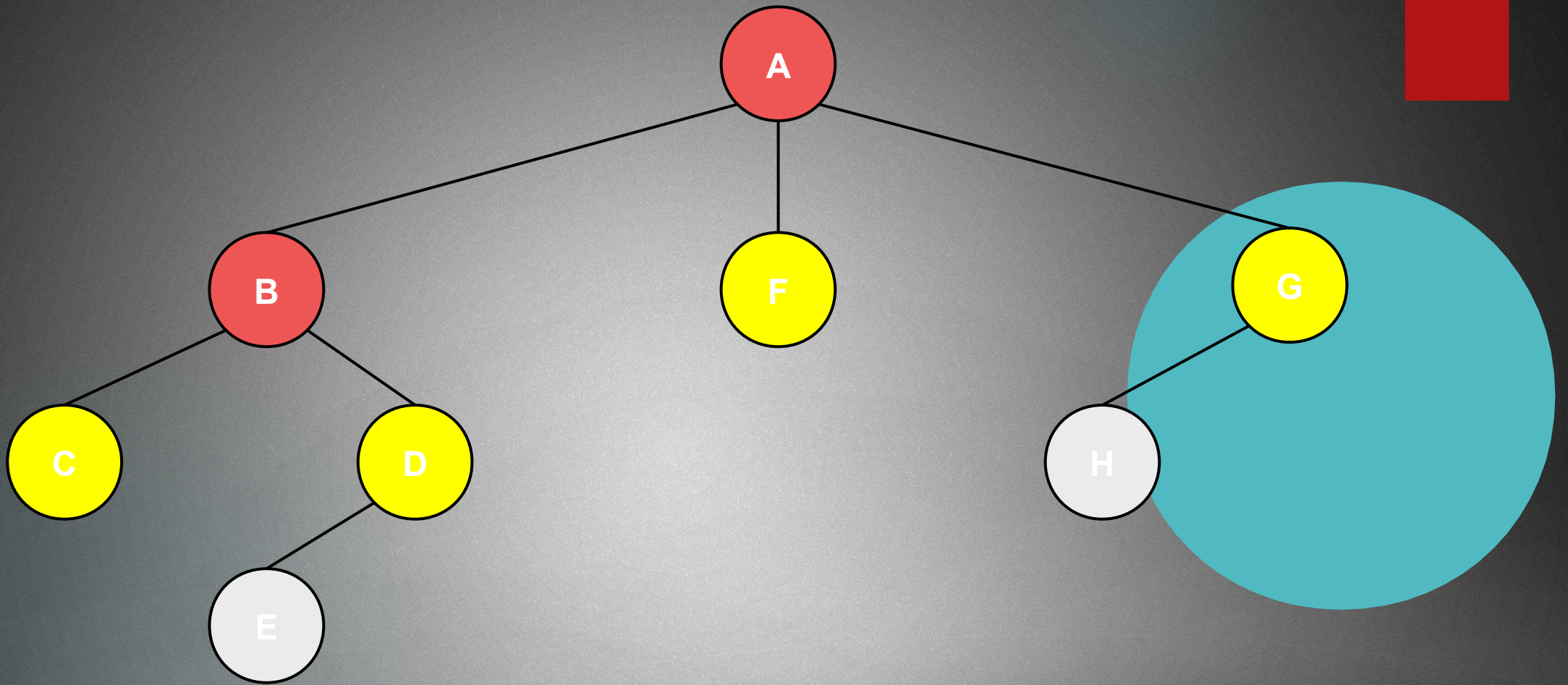
Queue: { C G F } dequeue the next node → it is G and visit its children + put them into the queue if necessary





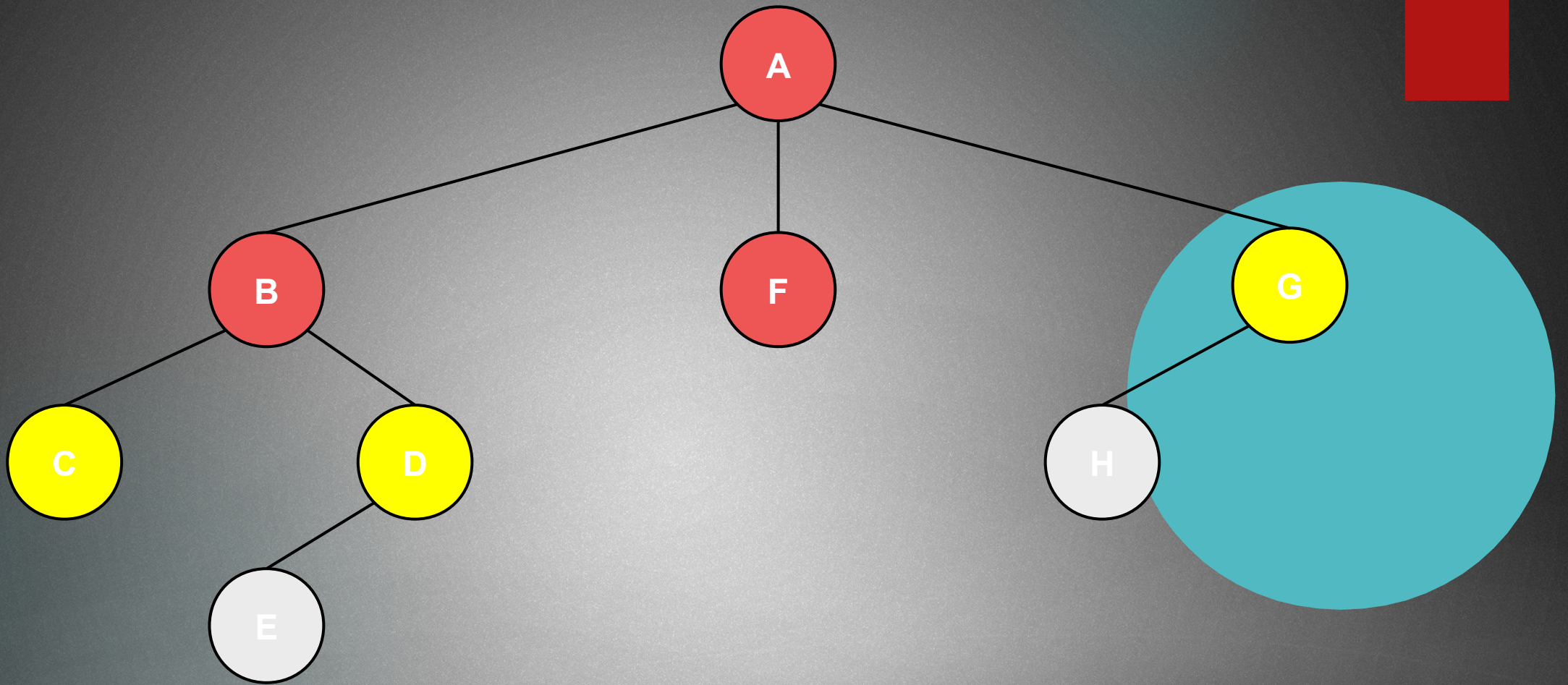
Queue: { D C G F } dequeue the next node → it is G and visit its children + put them into the queue if necessary





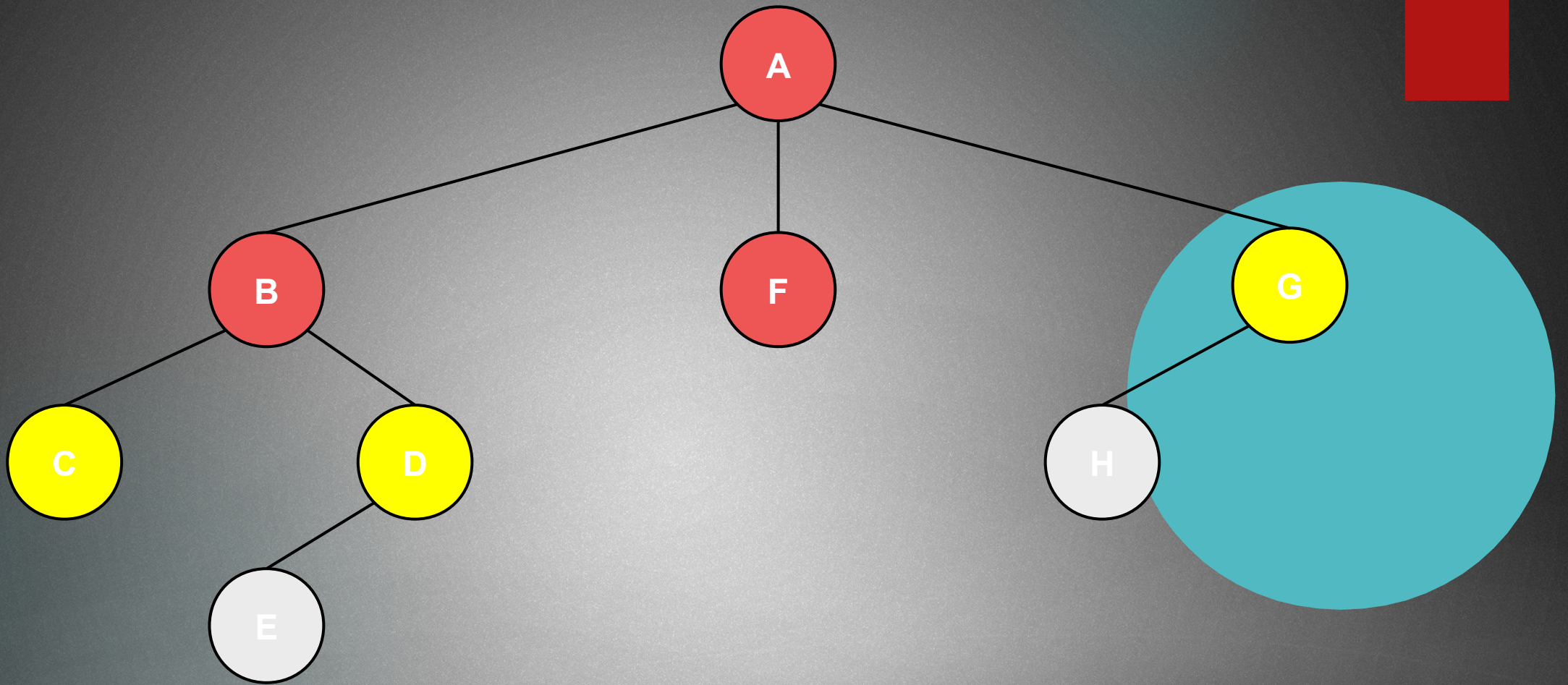
Queue: { D C G F }





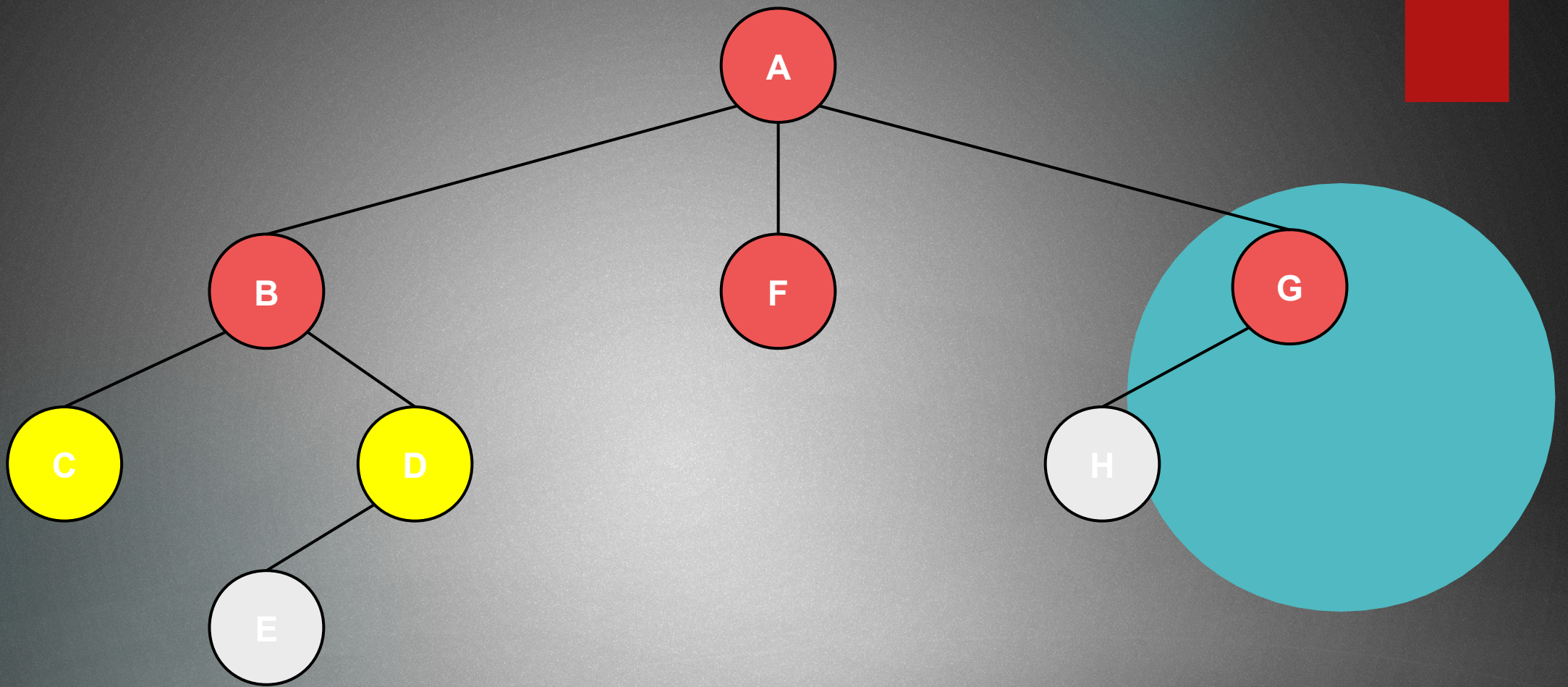
Queue: { D C G }





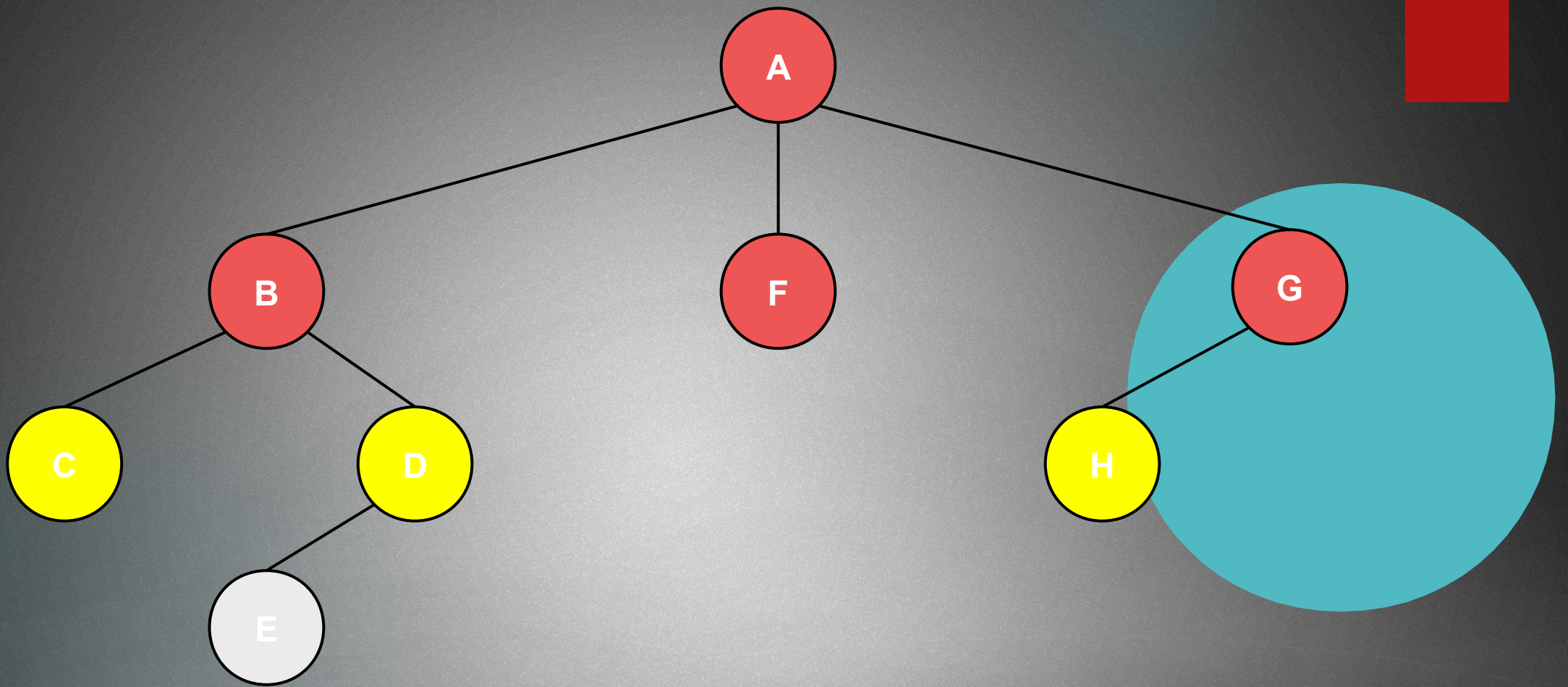
Queue: { D C G }





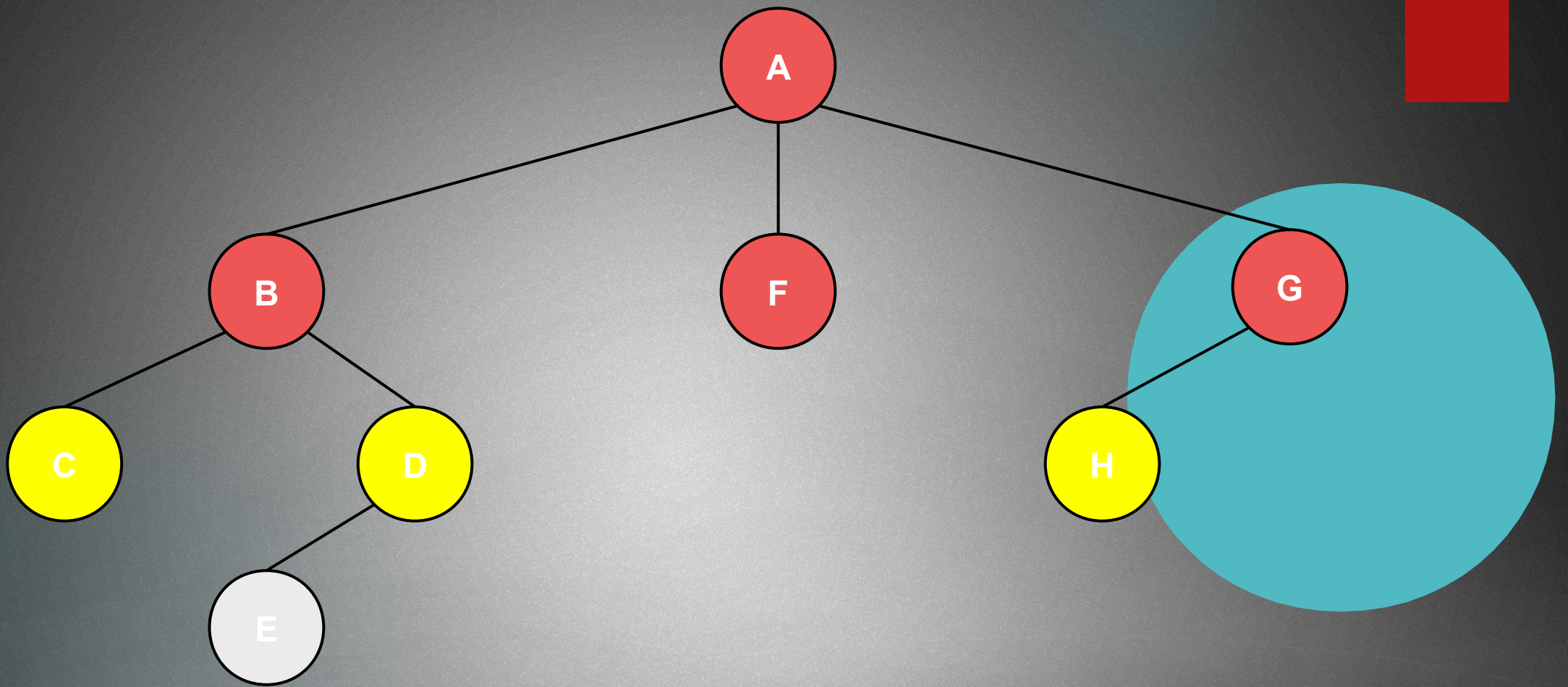
Queue: { D C }





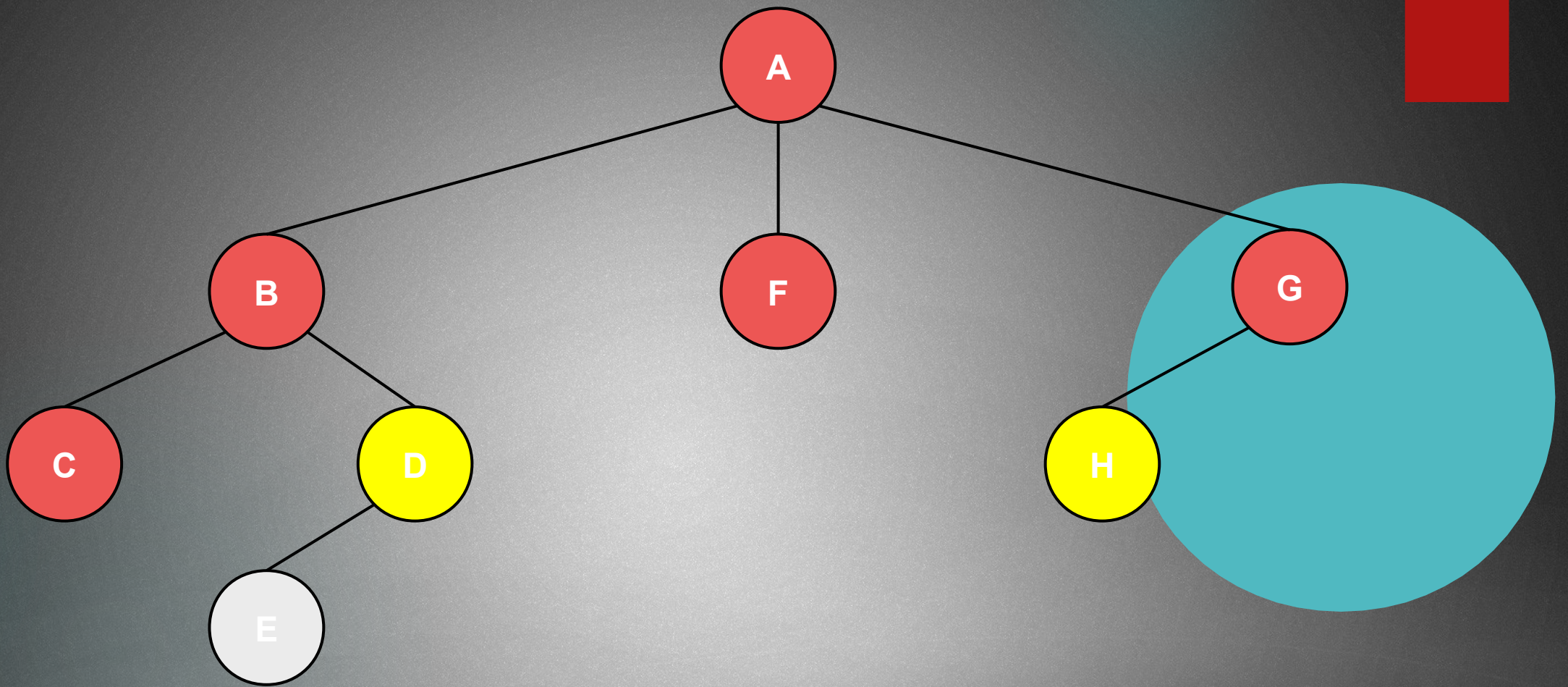
Queue: { H D C }





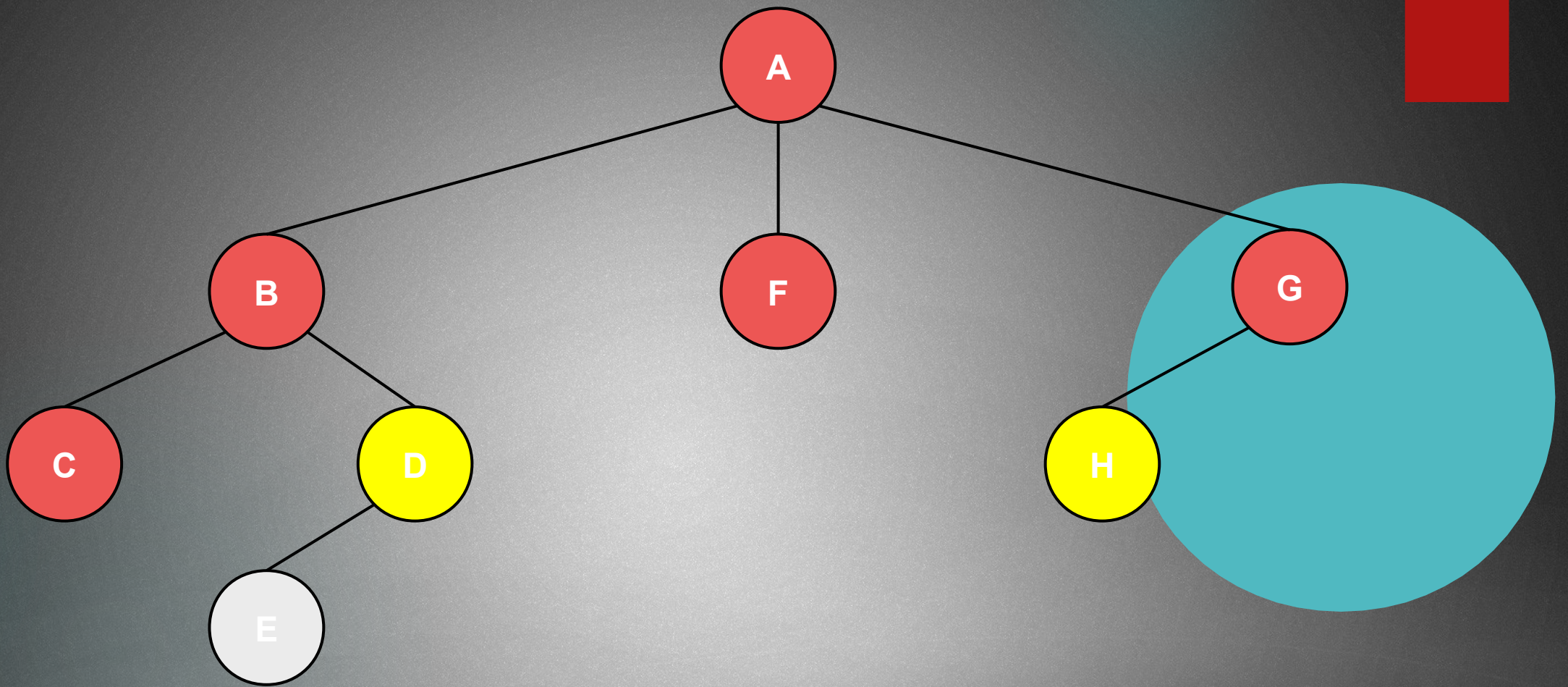
Queue: { H D C }





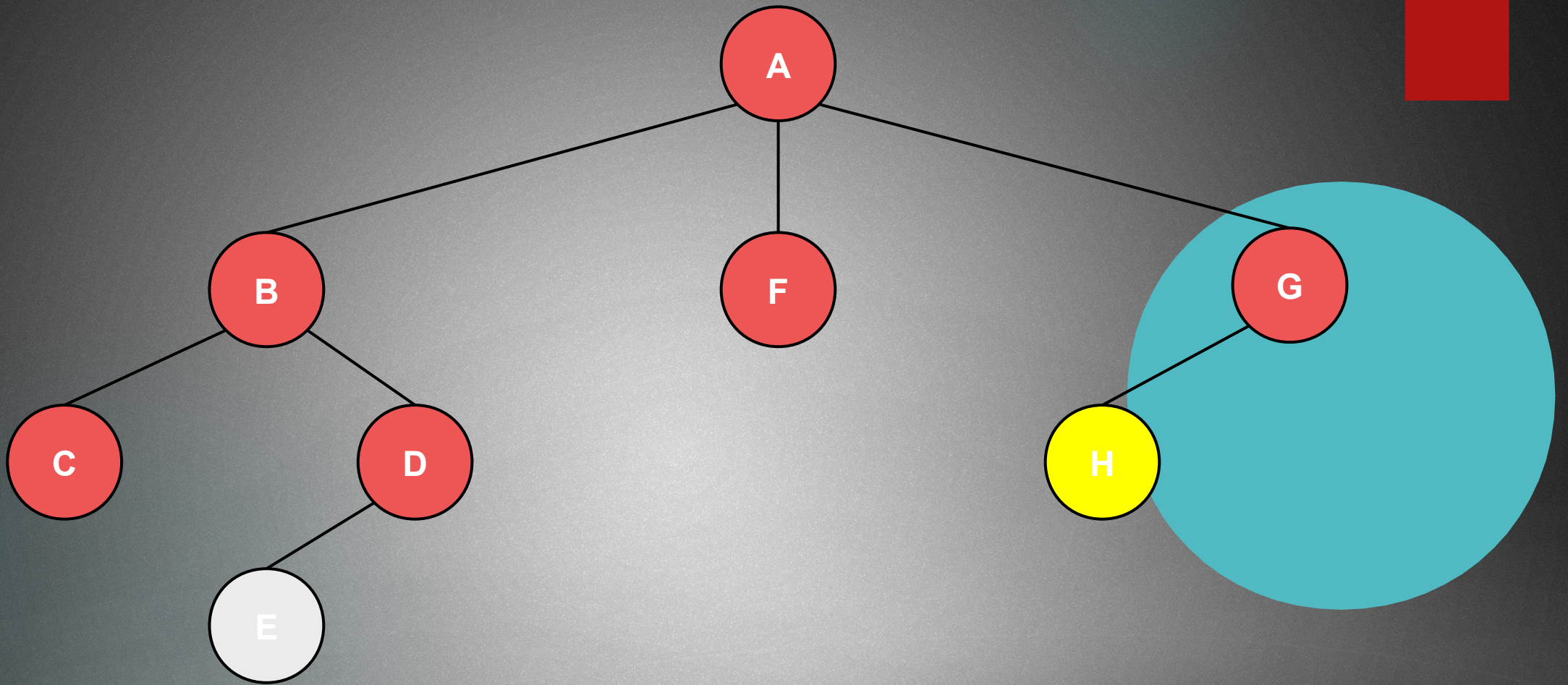
Queue: { H D }





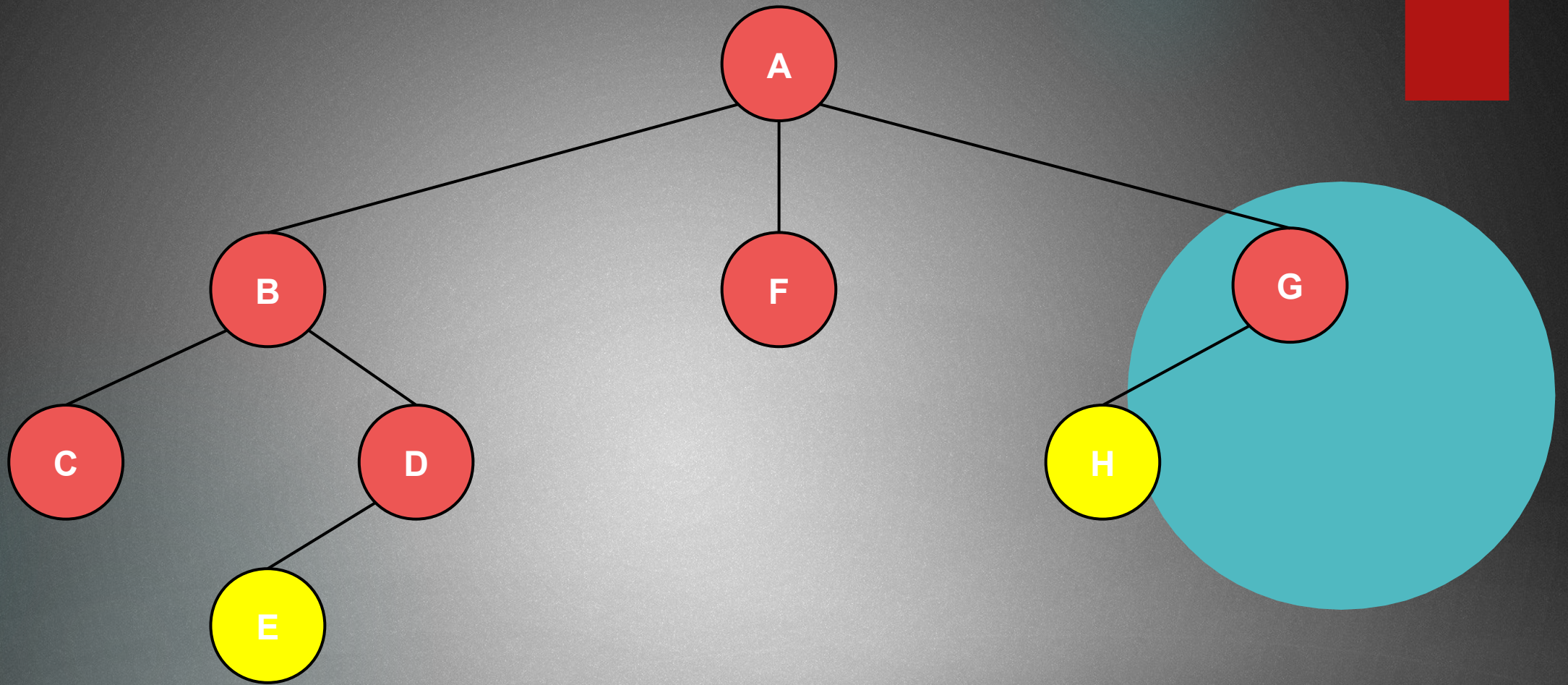
Queue: { H D }





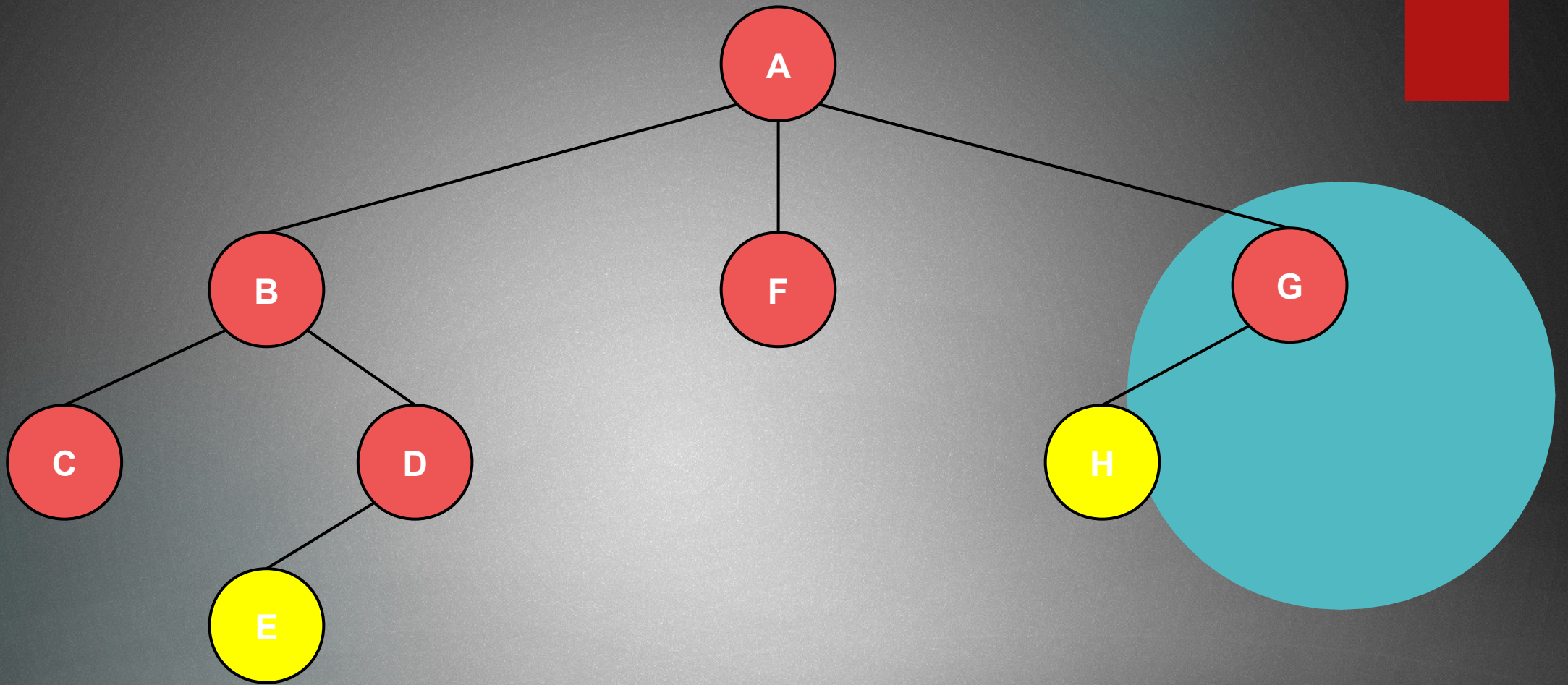
Queue: { H }





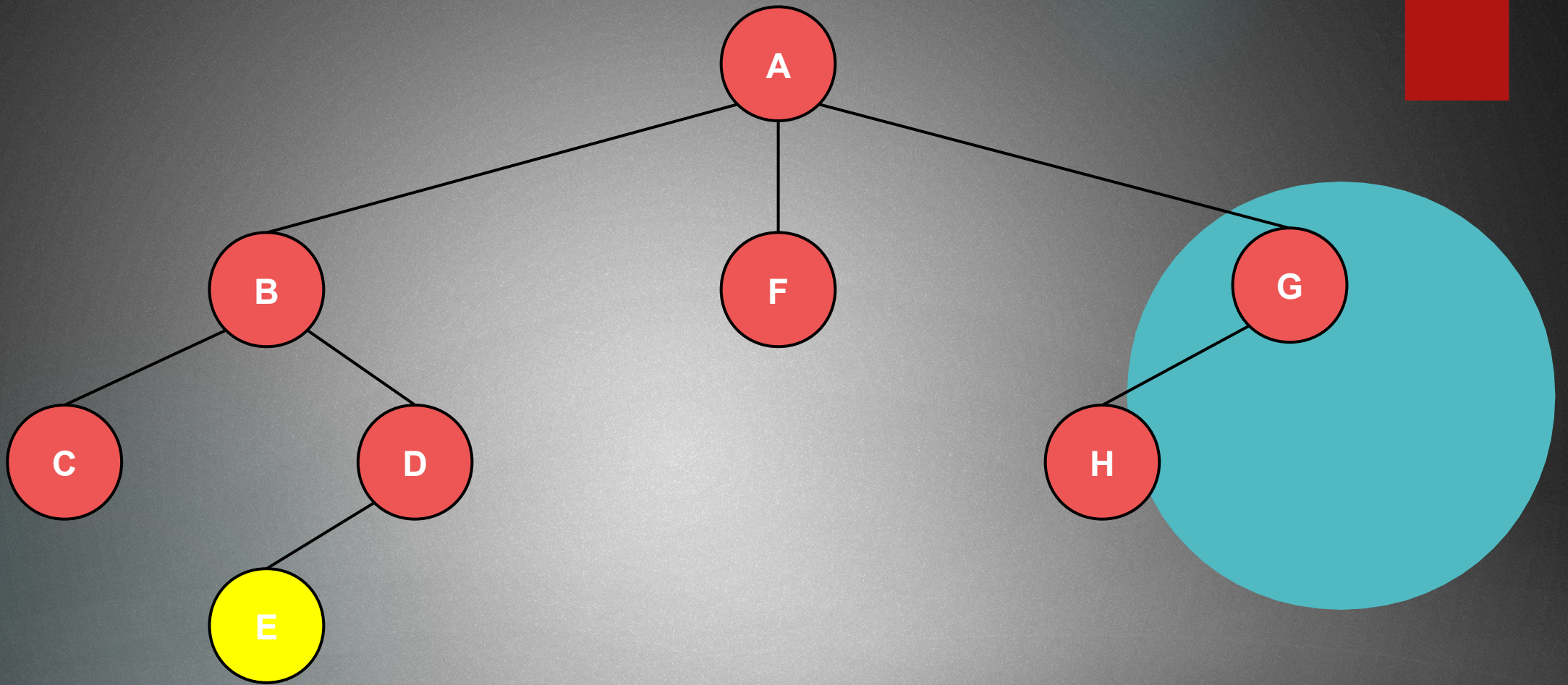
Queue: { E H }





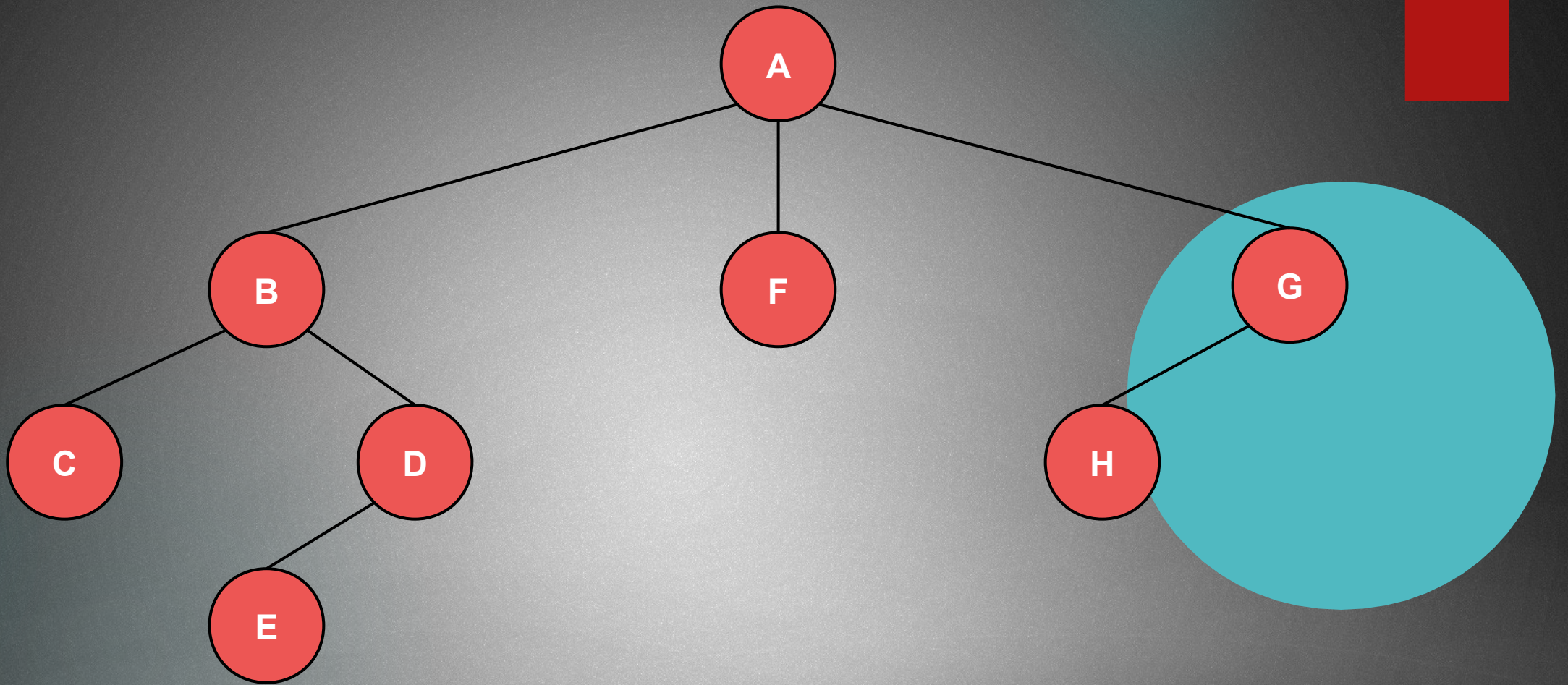
Queue: { E H }





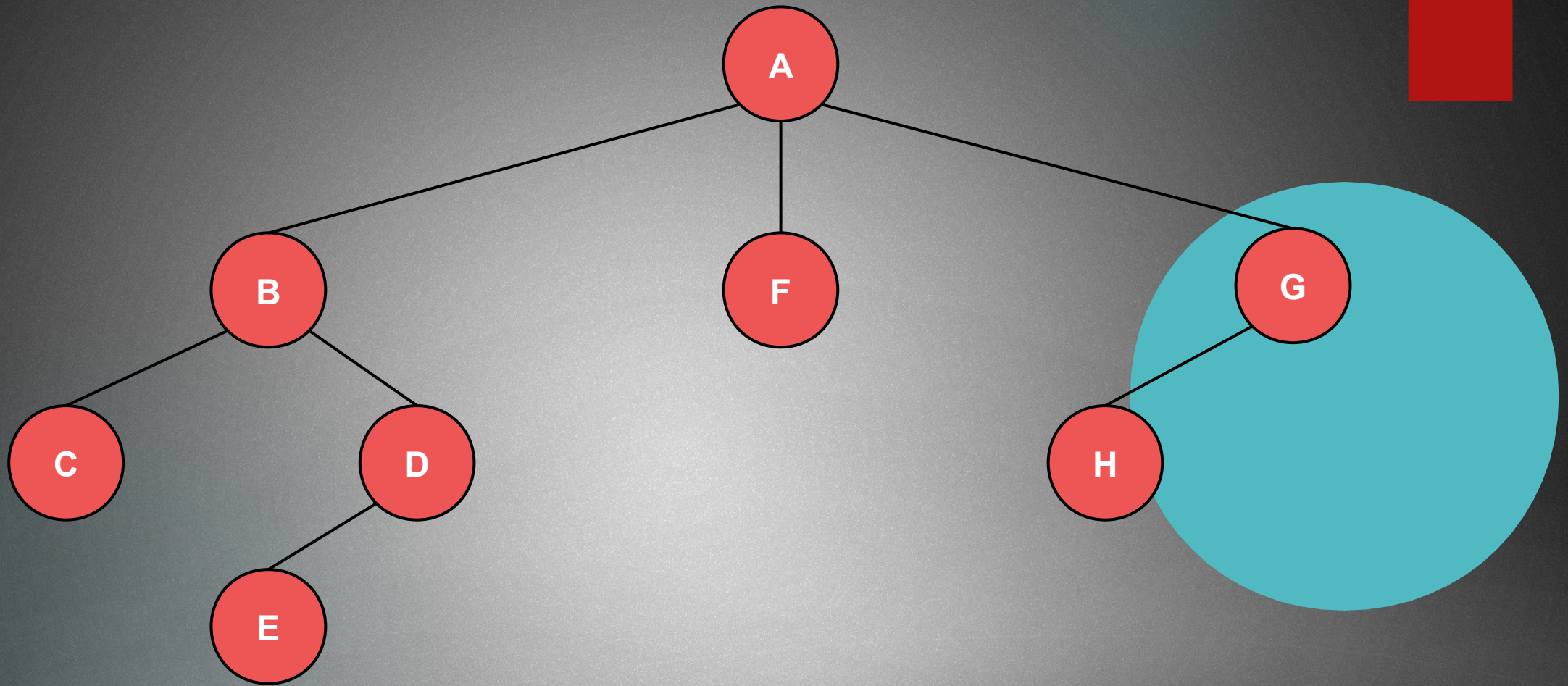
Queue: { E }





Queue: { E }

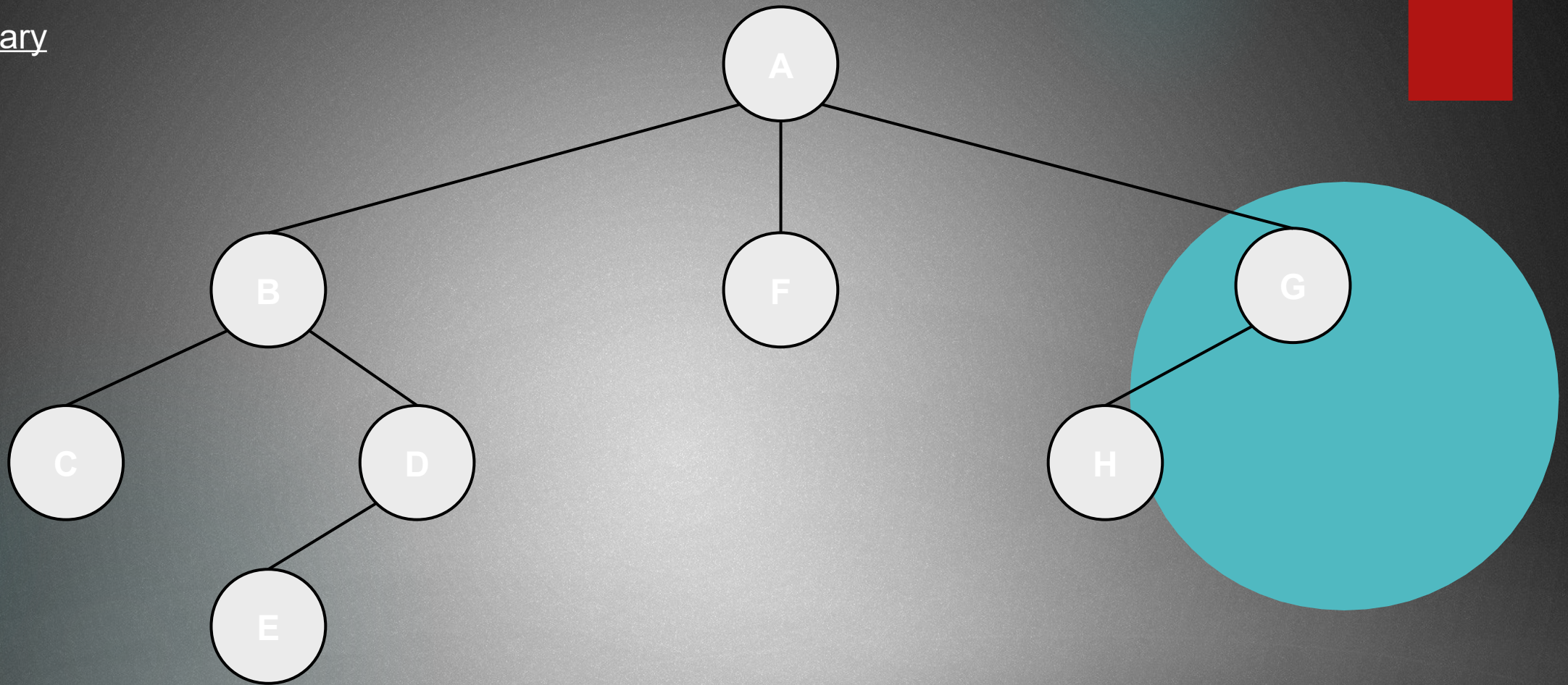




Queue: { } the queue is empty → **FINISHED !!!**

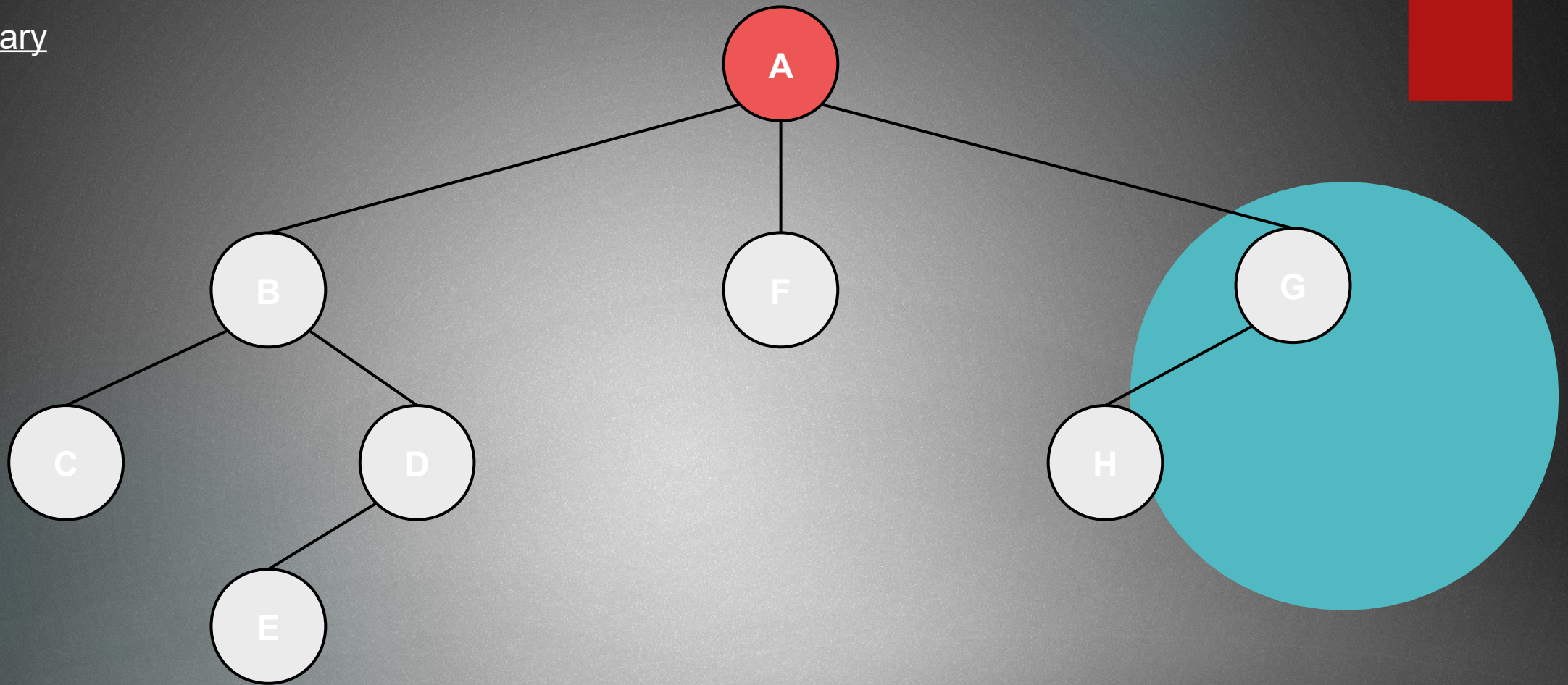


## Summary



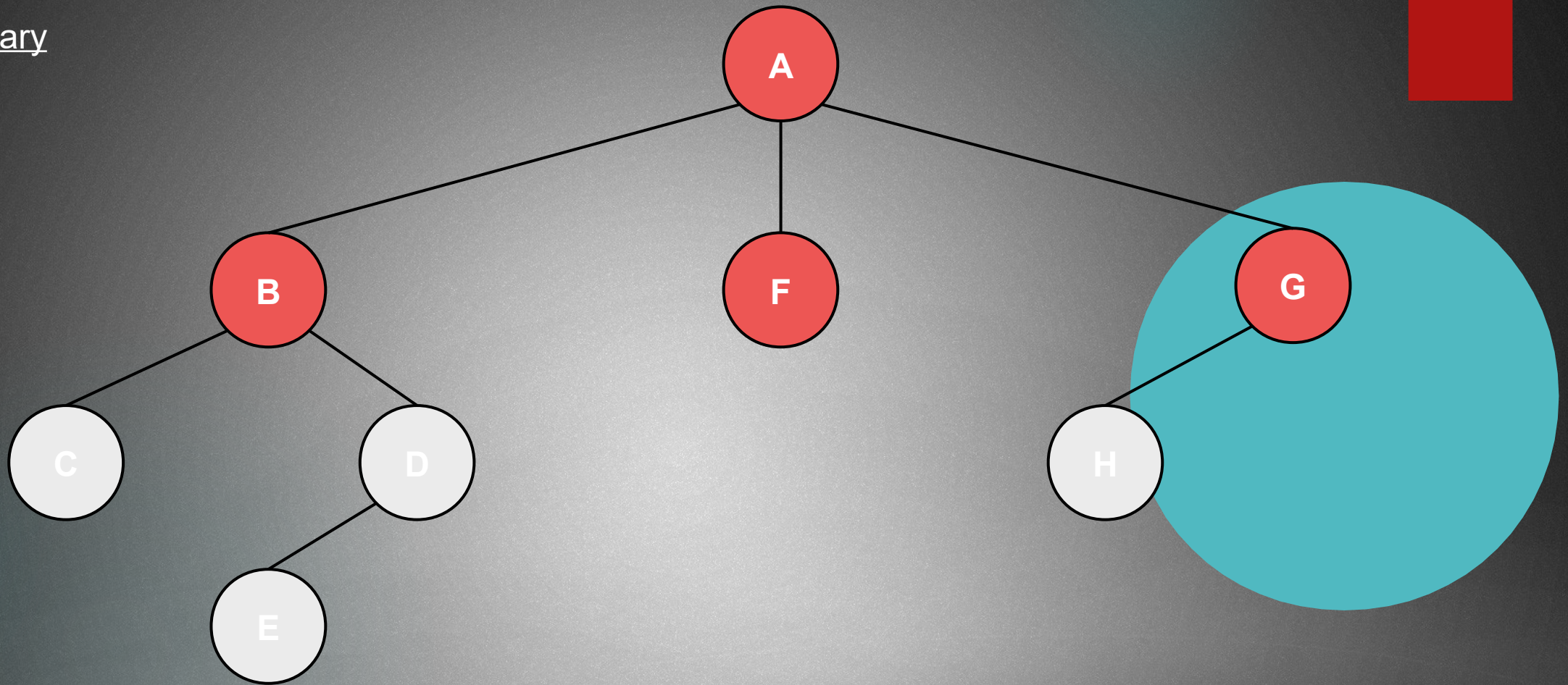


## Summary



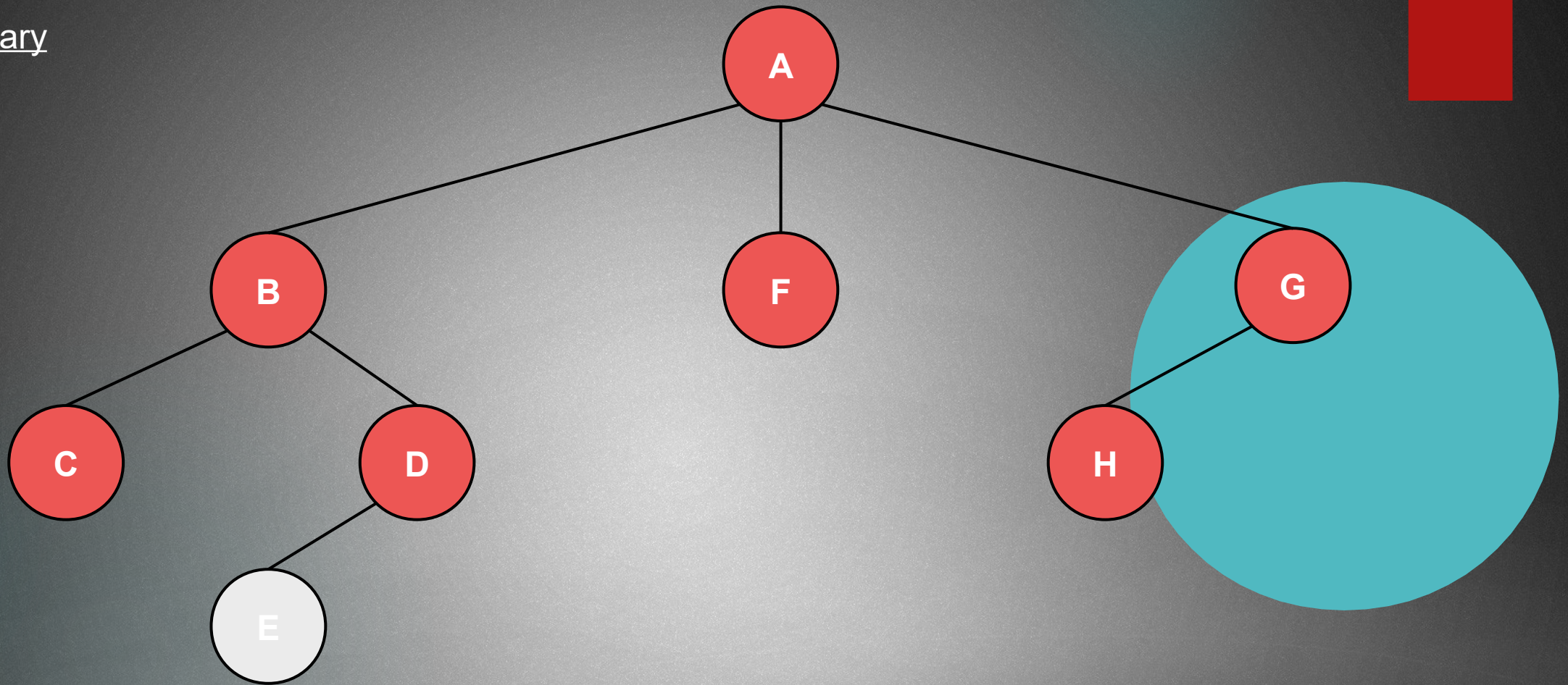


## Summary



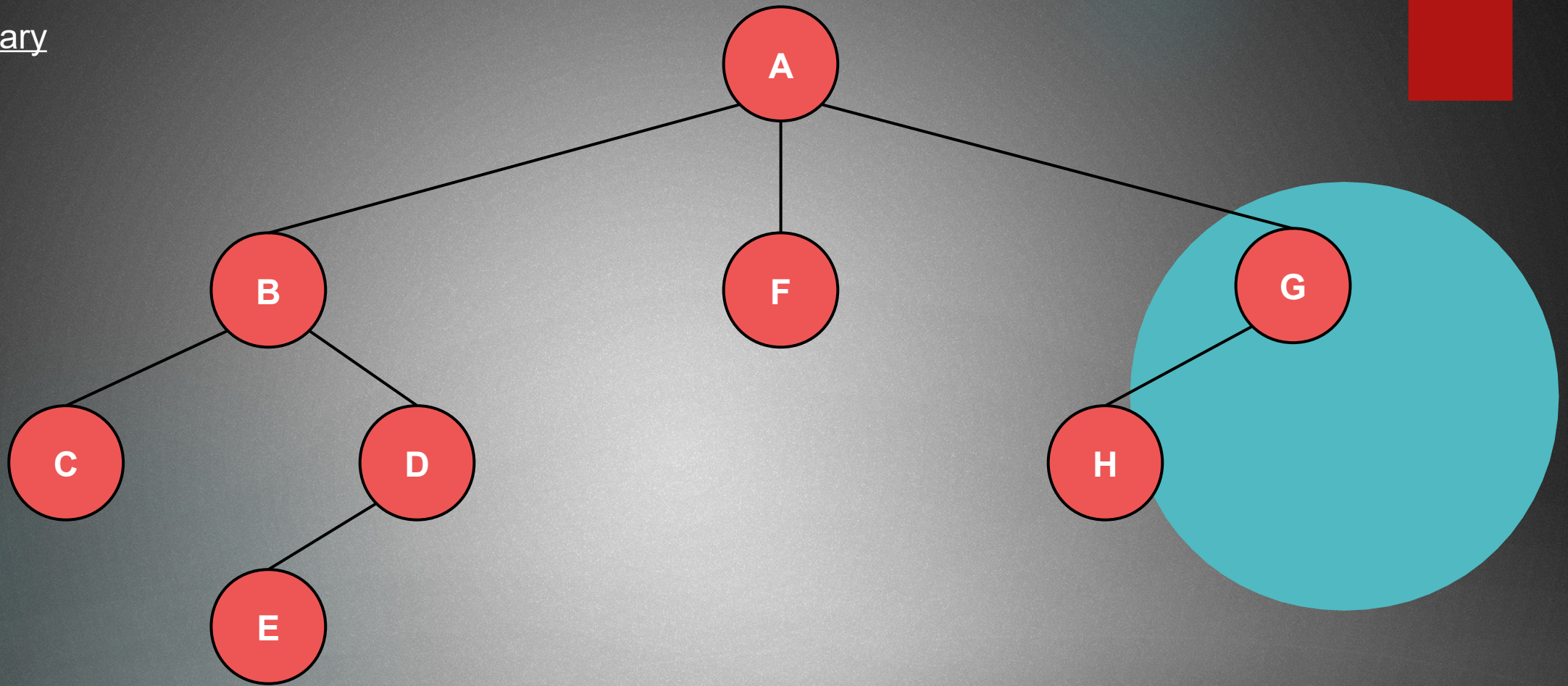


## Summary





## Summary





# Applications

- ▶ In artificial intelligence / machine learning it can prove to be very important: robots can discover the surrounding more easily with BFS than DFS
- ▶ It is also very important in maximum flow: Edmonds-Karp algorithm uses BFS for finding augmenting paths
- ▶ Cheyen's algorithm in garbage collection → it help to maintain active references on the heap memory
- ▶ It uses BFS to detect all the references on the heap
- ▶ Serialization / deserialization of a tree like structure ( for example when order does matter ) → it allows the tree to be reconstructed in an efficient manner !!!



# DEPTH FIRST SEARCH

dfs





# Depth-first search

- ▶ Depth-first search is a widely used graph traversal algorithm besides breadth-first search
- ▶ It was investigated as strategy for solving mazes by Trémaux in the 19th century
- ▶ It explores as far as possible along each branch before backtracking // BFS was a layer-by-layer algorithm
- ▶ Time complexity of traversing a graph with DFS:  $O(V+E)$
- ▶ Memory complexity: a bit better than that of BFS !!!



# Depth-first search

*dfs(vertex)*

*vertex set visited true*  
*print vertex*

*for v in vertex neighbours*  
*if v is not visited*  
*dfs(v)*

RECURSION

*dfs(vertex)*

*Stack stack*  
*vertex set visited true*  
*stack.push(vertex)*

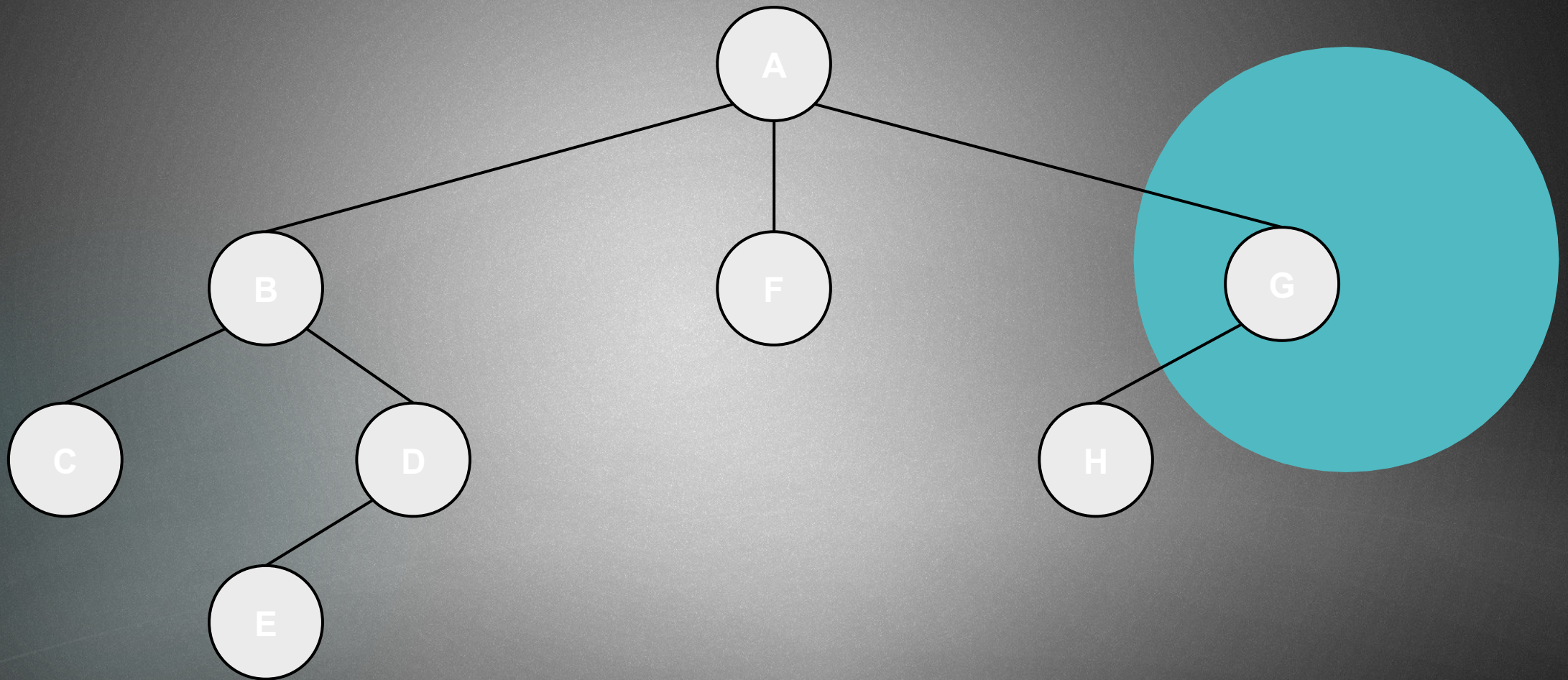
*while stack not empty*  
*actual = stack.pop()*

*for v in actual neighbours*  
*if v is not visited*  
*v set visited true*  
*stack.push(v)*

ITERATION

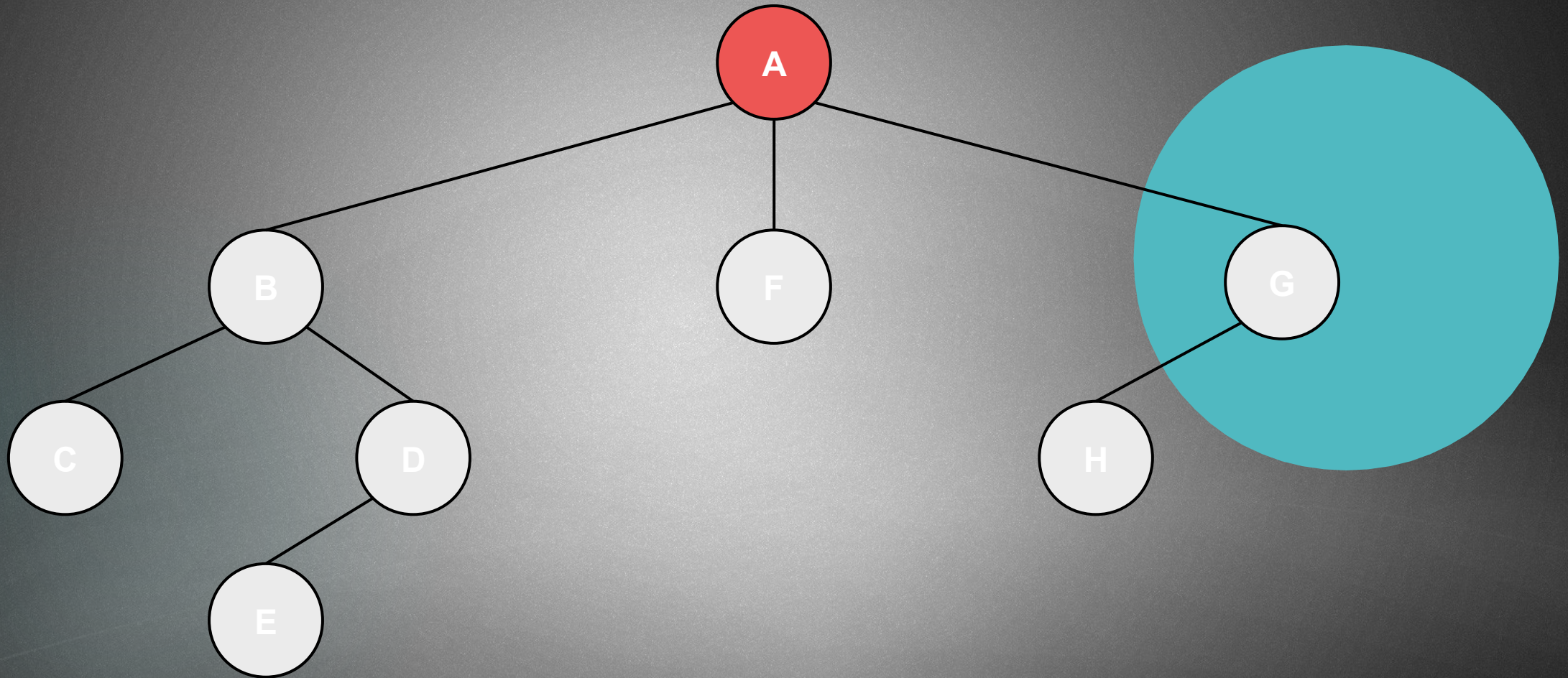


Recursively check every  
unmarked vertices!



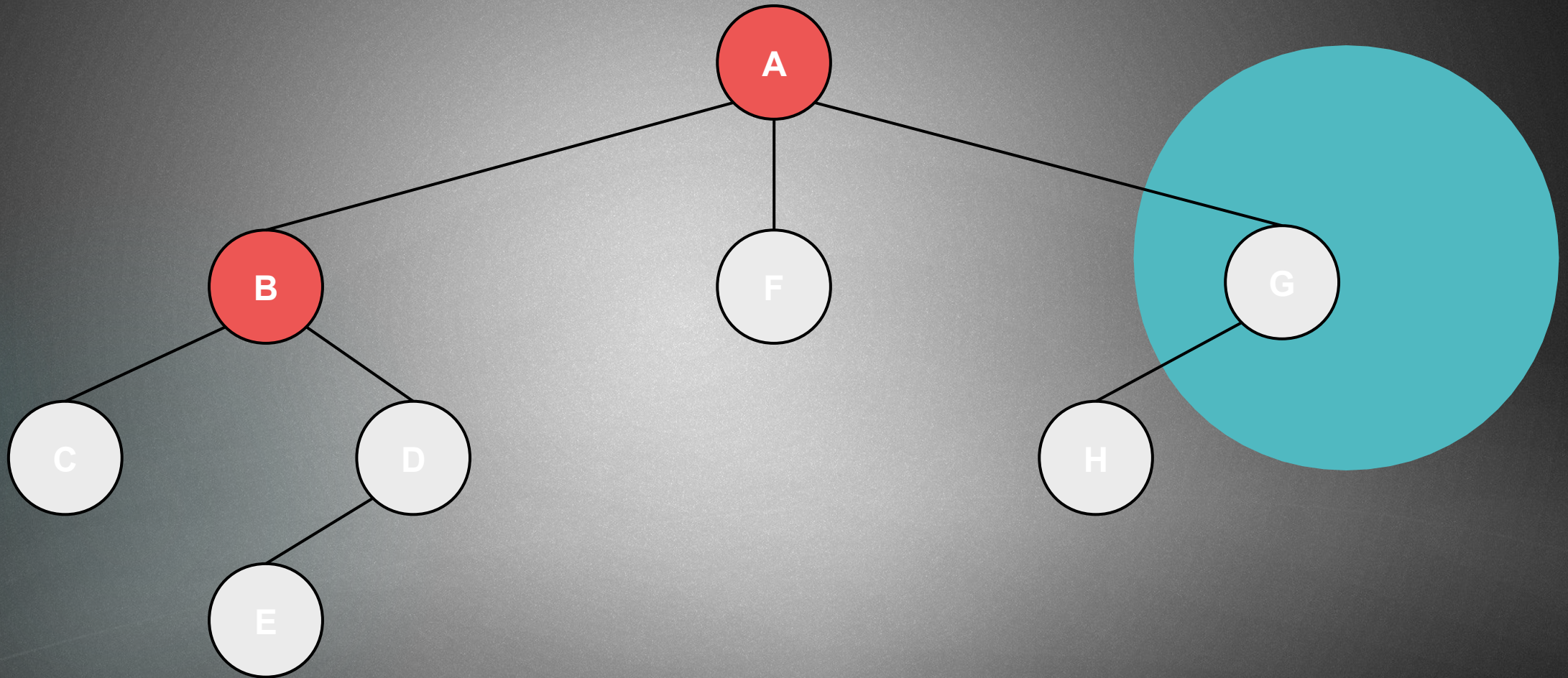


Recursively check every  
unmarked vertices!



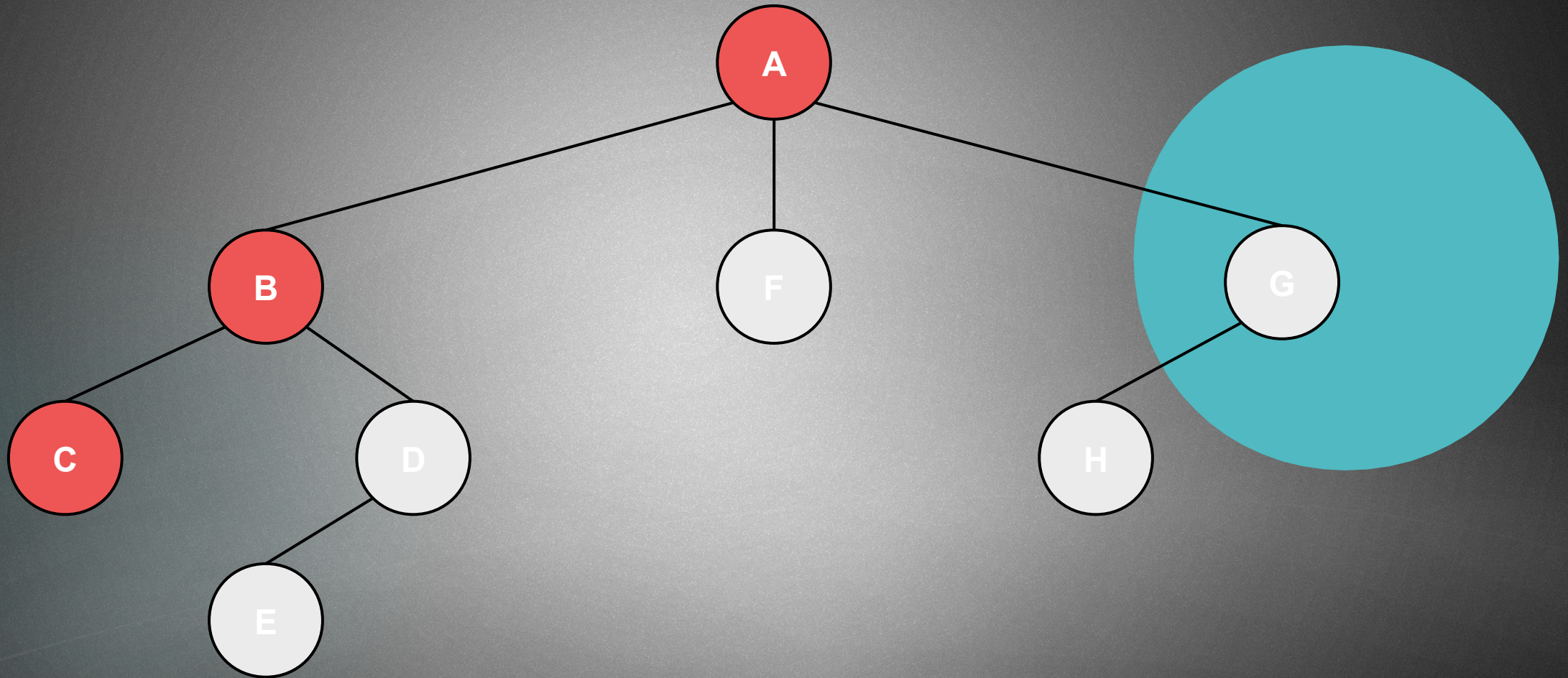


Recursively check every  
unmarked vertices!



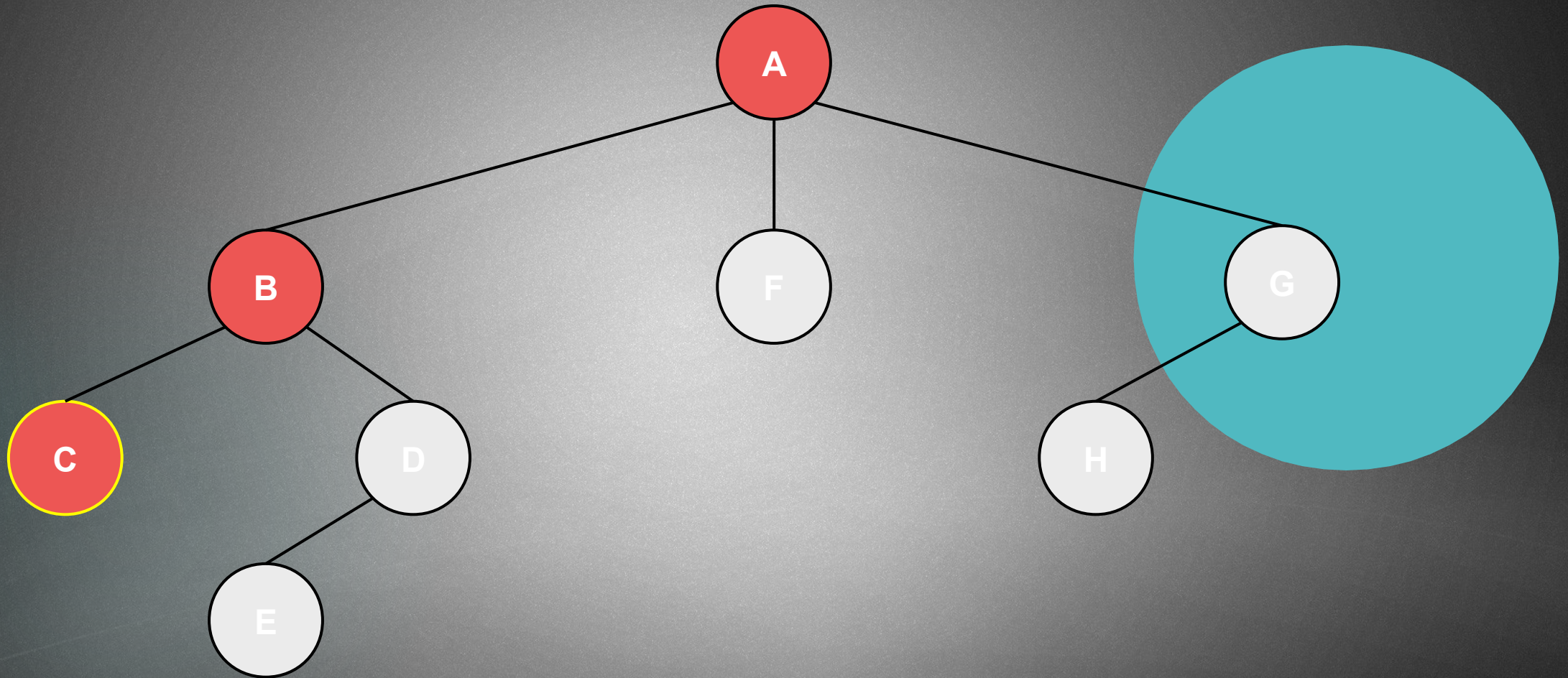


Recursively check every  
unmarked vertices!



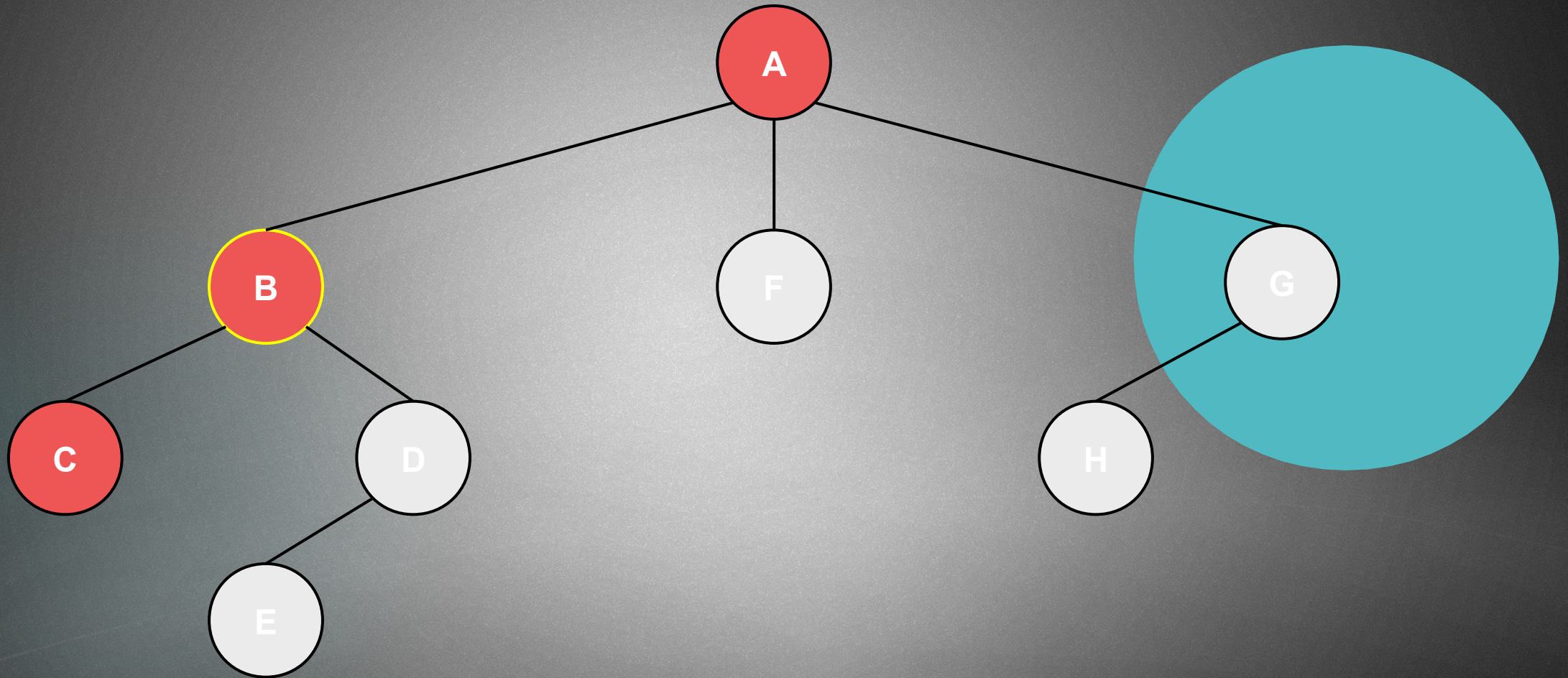


Recursively check every  
unmarked vertices!



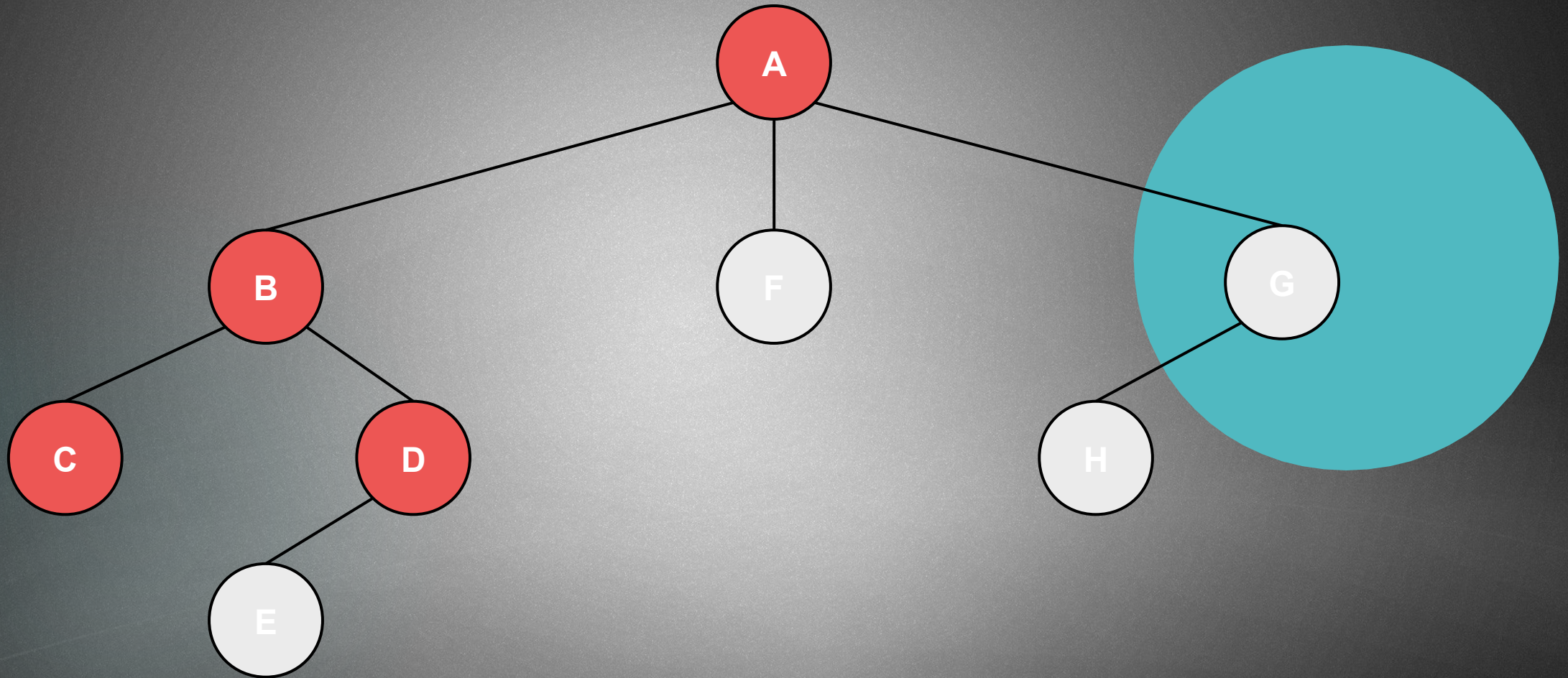


Recursively check every  
unmarked vertices!



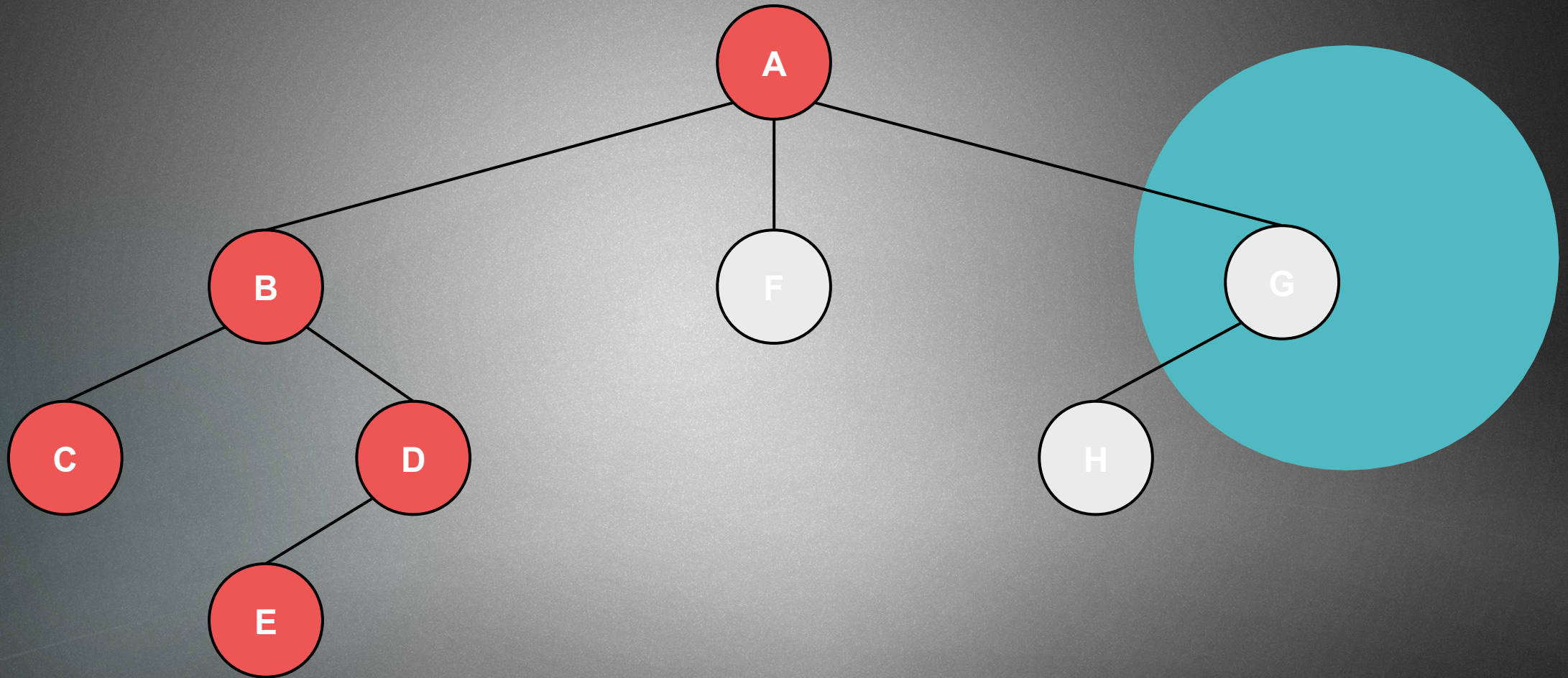


Recursively check every  
unmarked vertices!



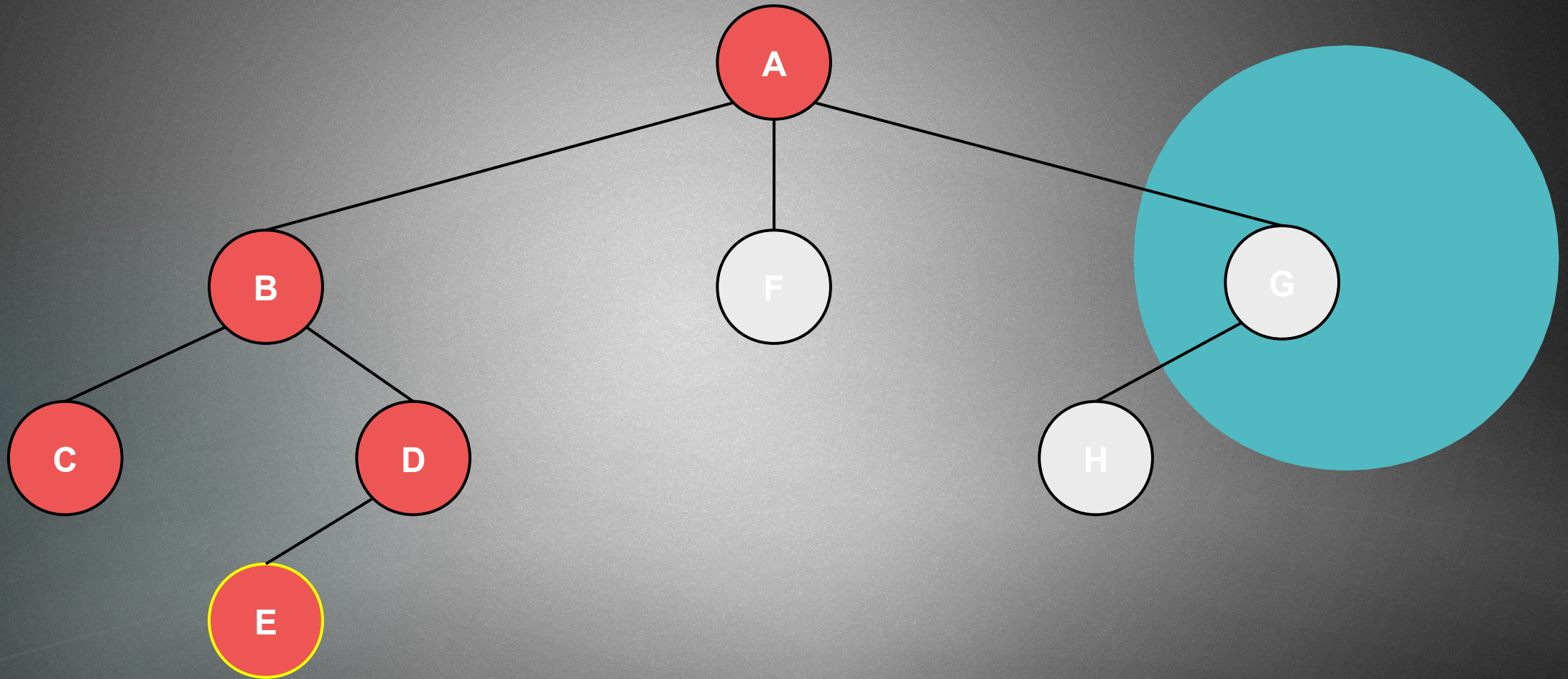


Recursively check every  
unmarked vertices!



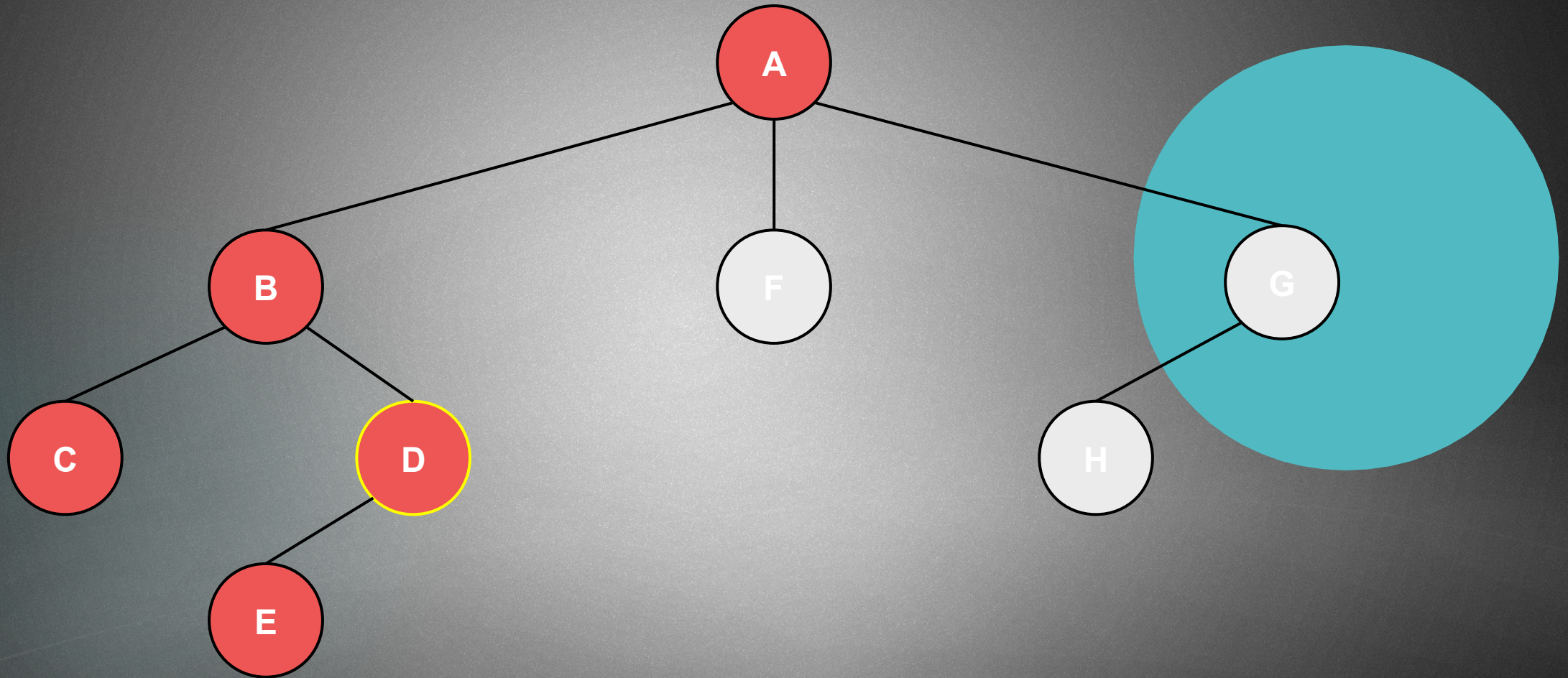


Recursively check every  
unmarked vertices!



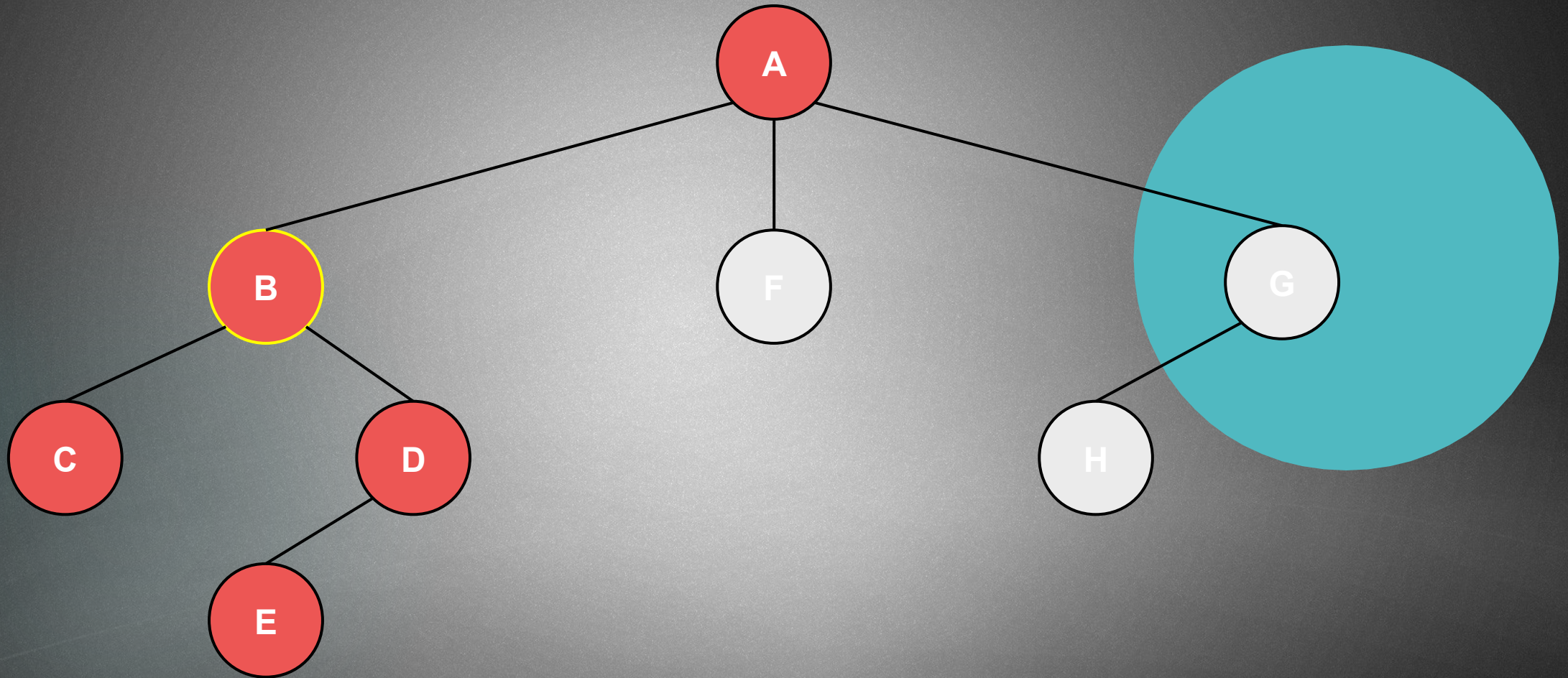


Recursively check every  
unmarked vertices!



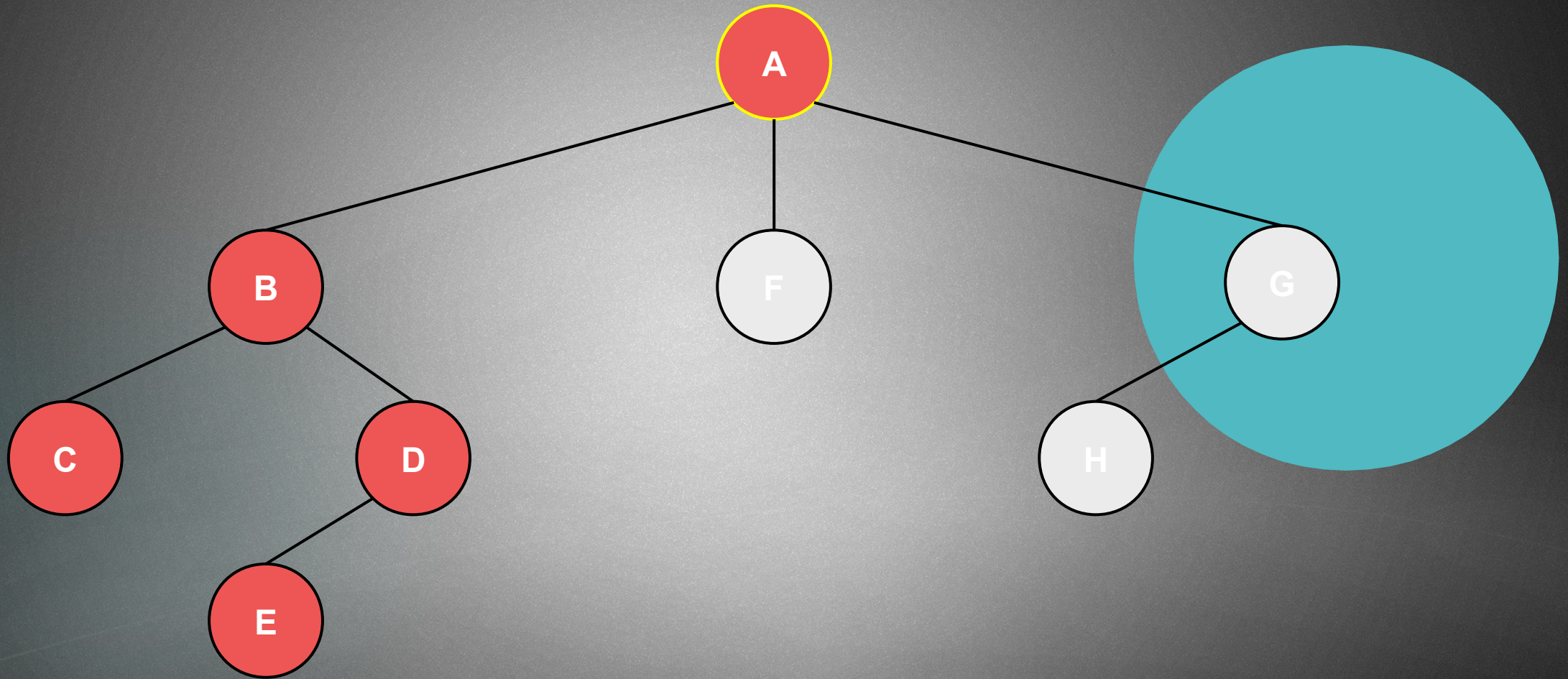


Recursively check every  
unmarked vertices!



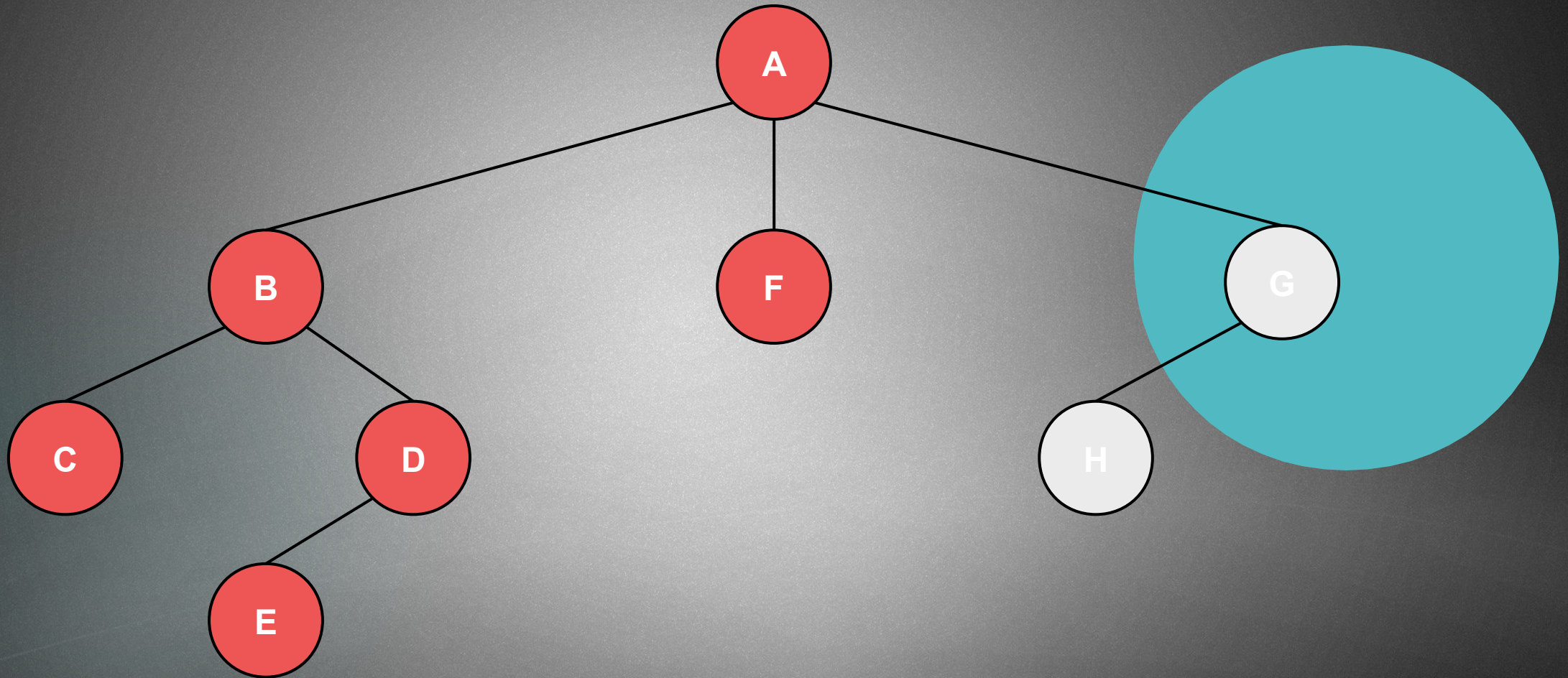


Recursively check every  
unmarked vertices!



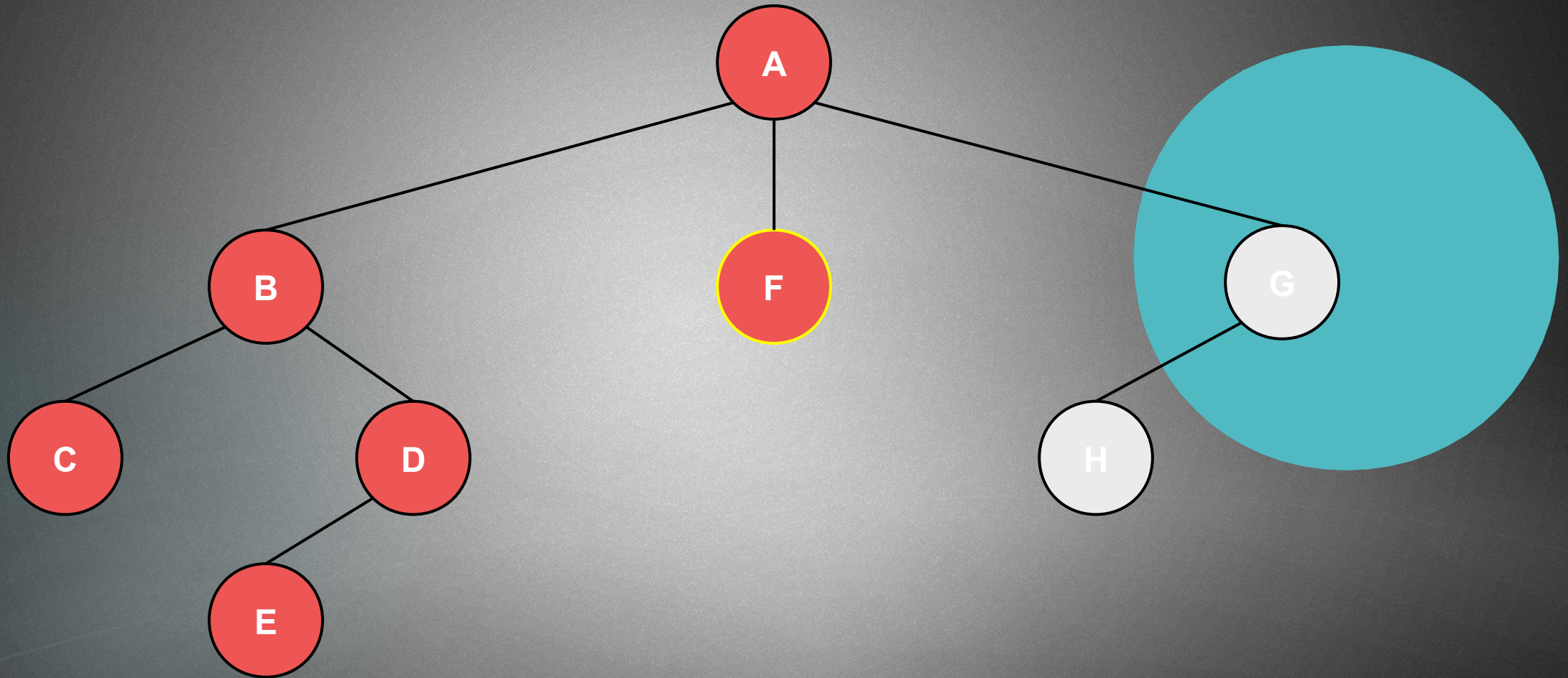


Recursively check every  
unmarked vertices!



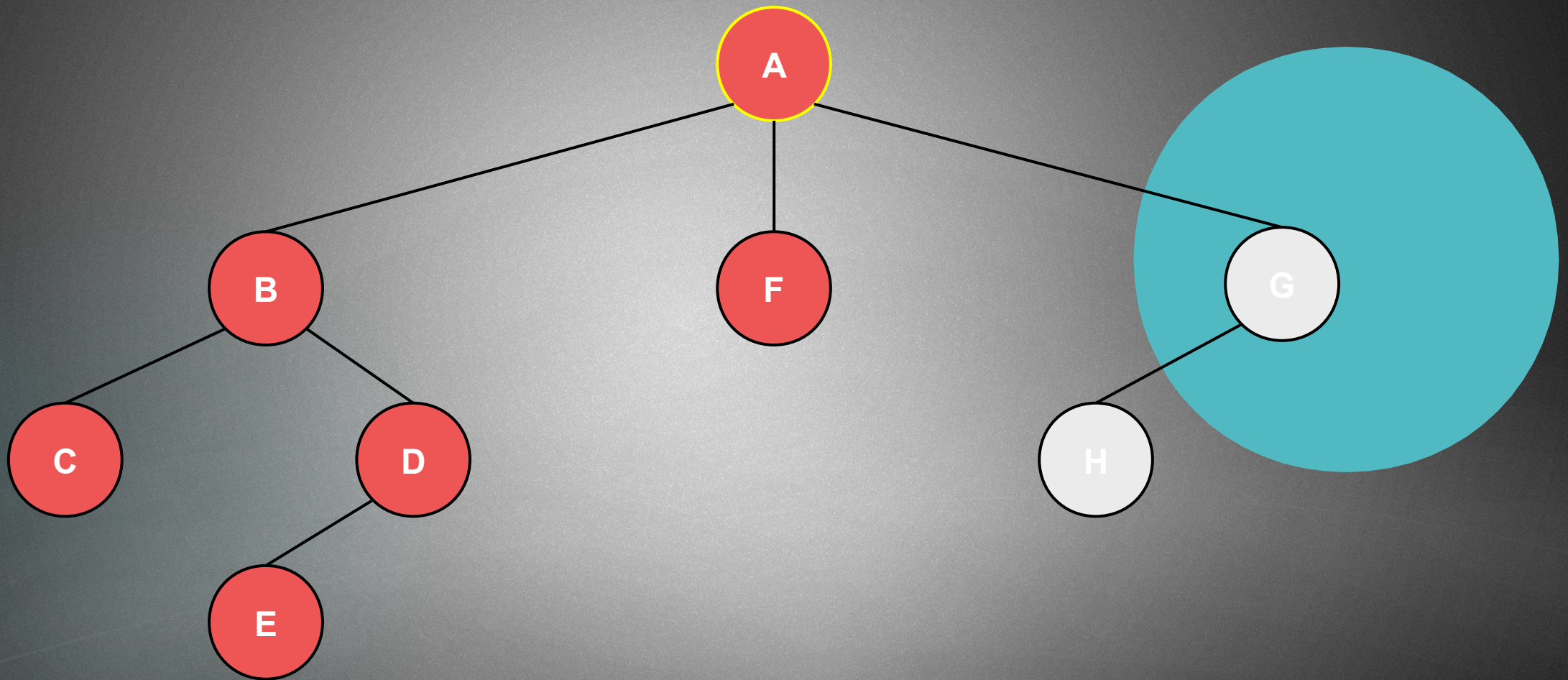


Recursively check every  
unmarked vertices!



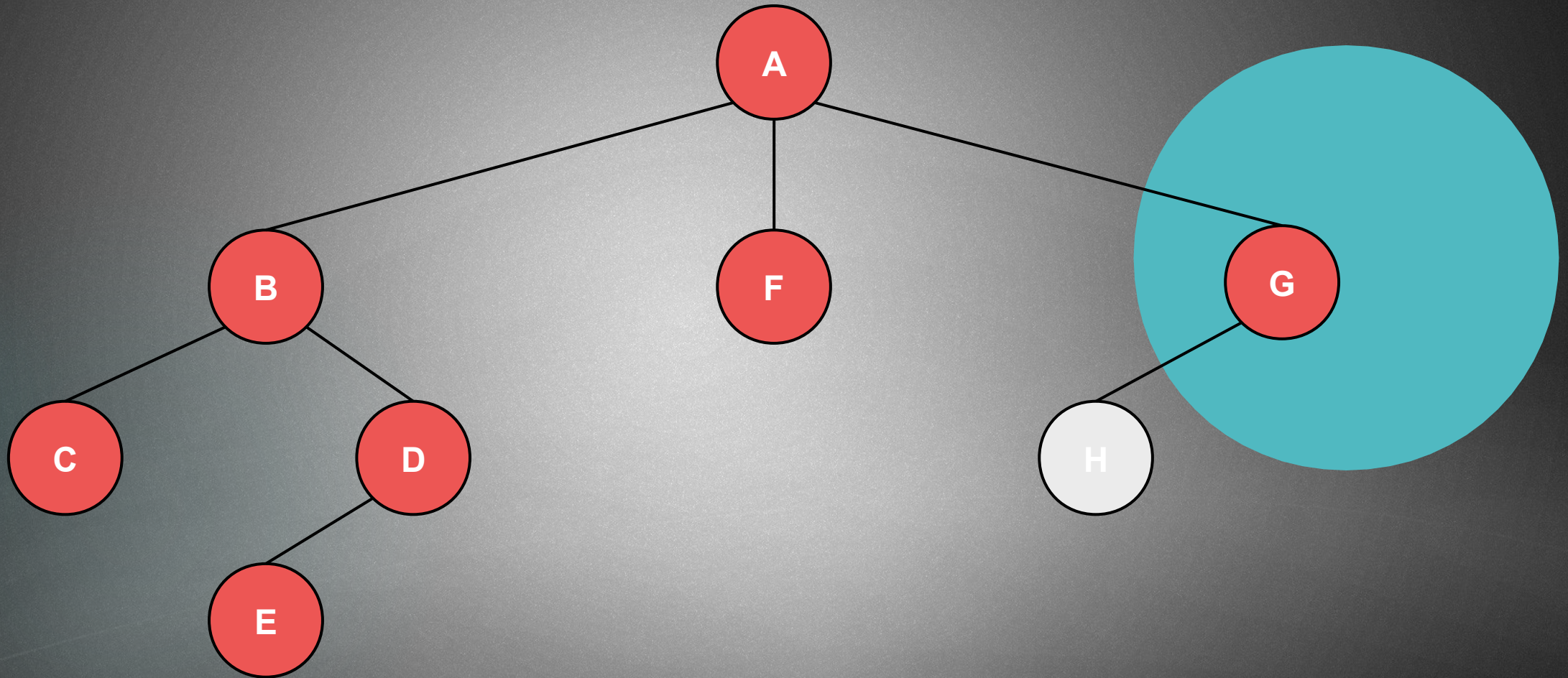


Recursively check every  
unmarked vertices!



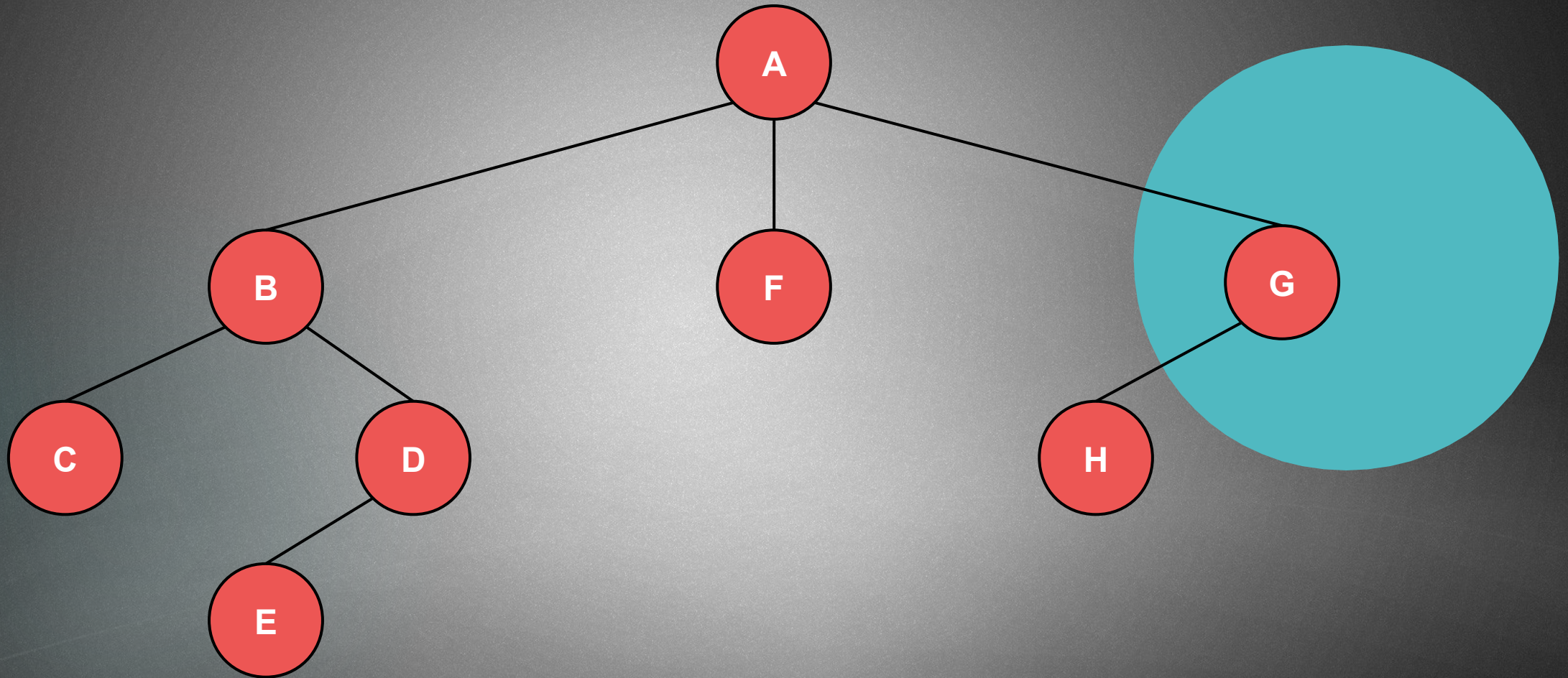


Recursively check every  
unmarked vertices!



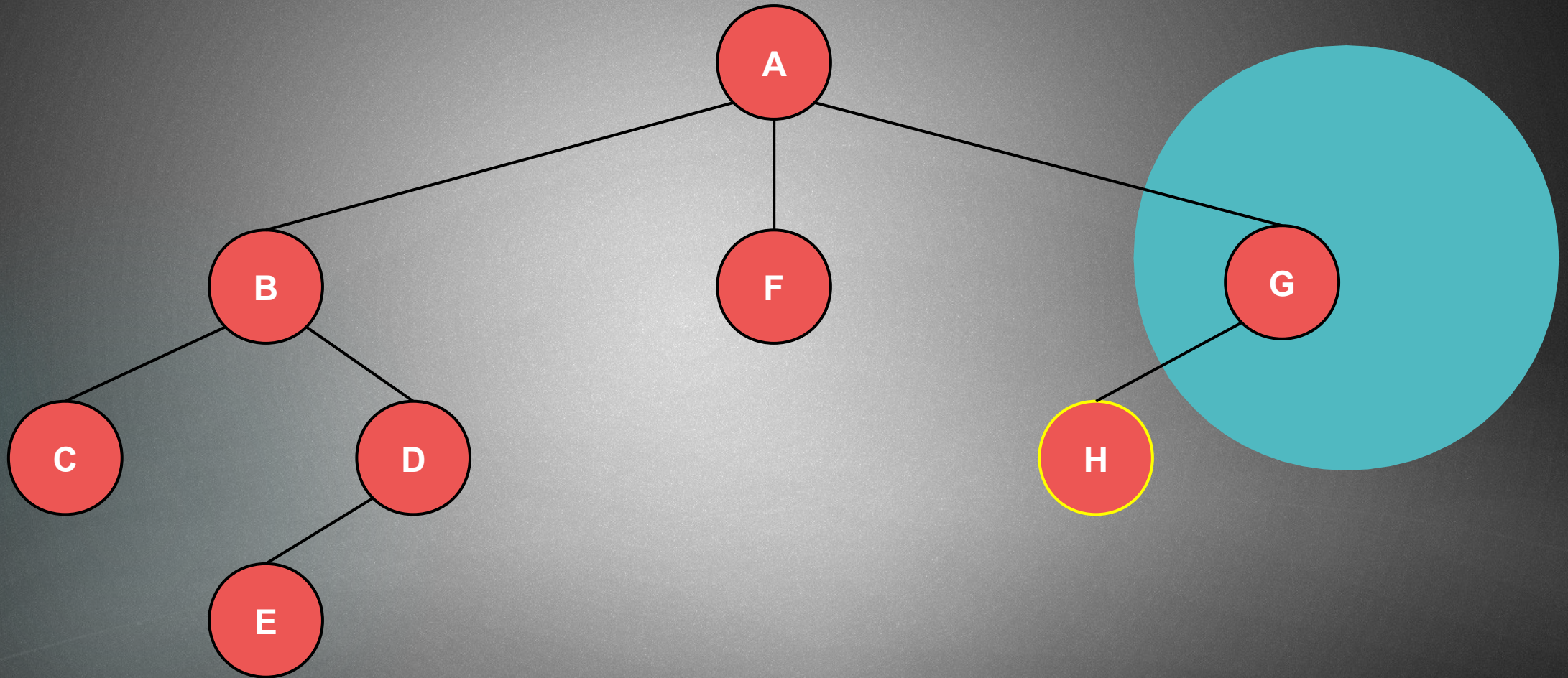


Recursively check every  
unmarked vertices!



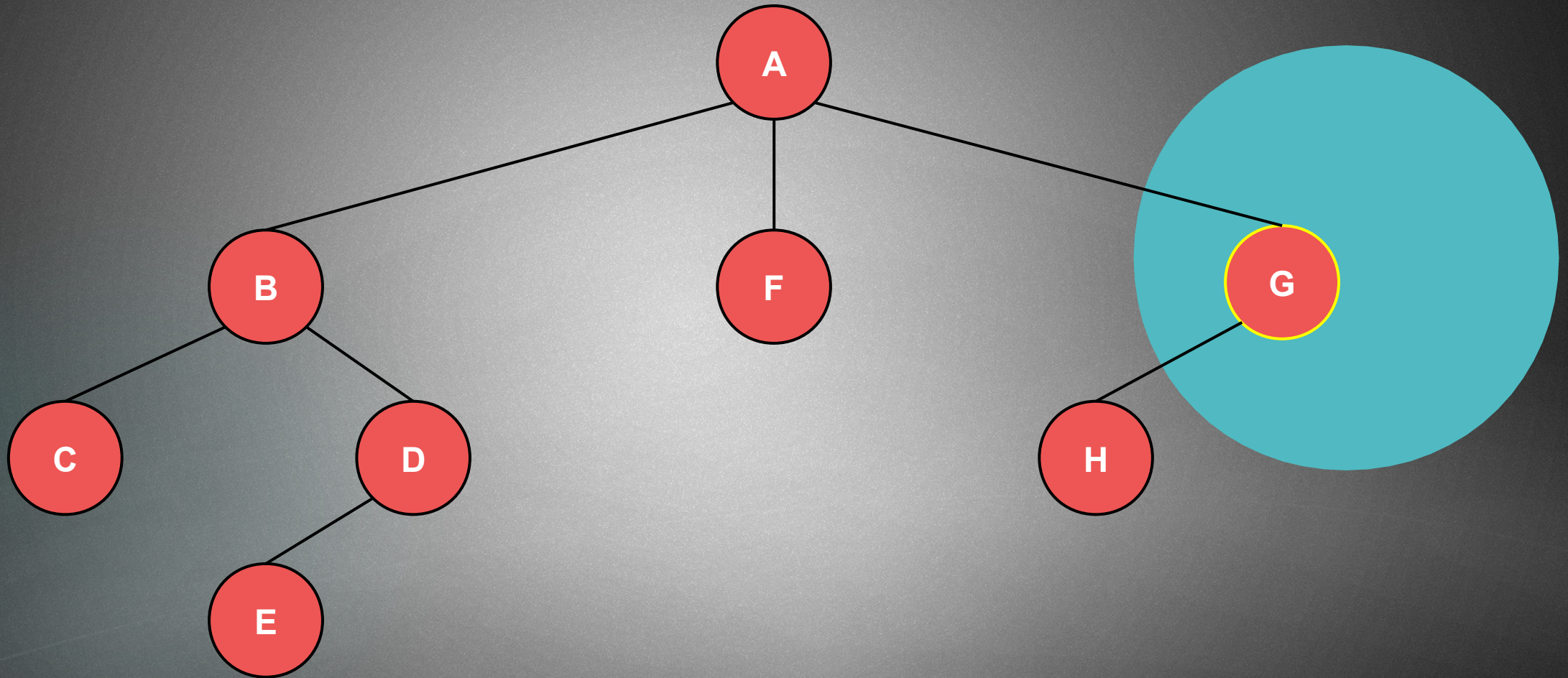


Recursively check every  
unmarked vertices!



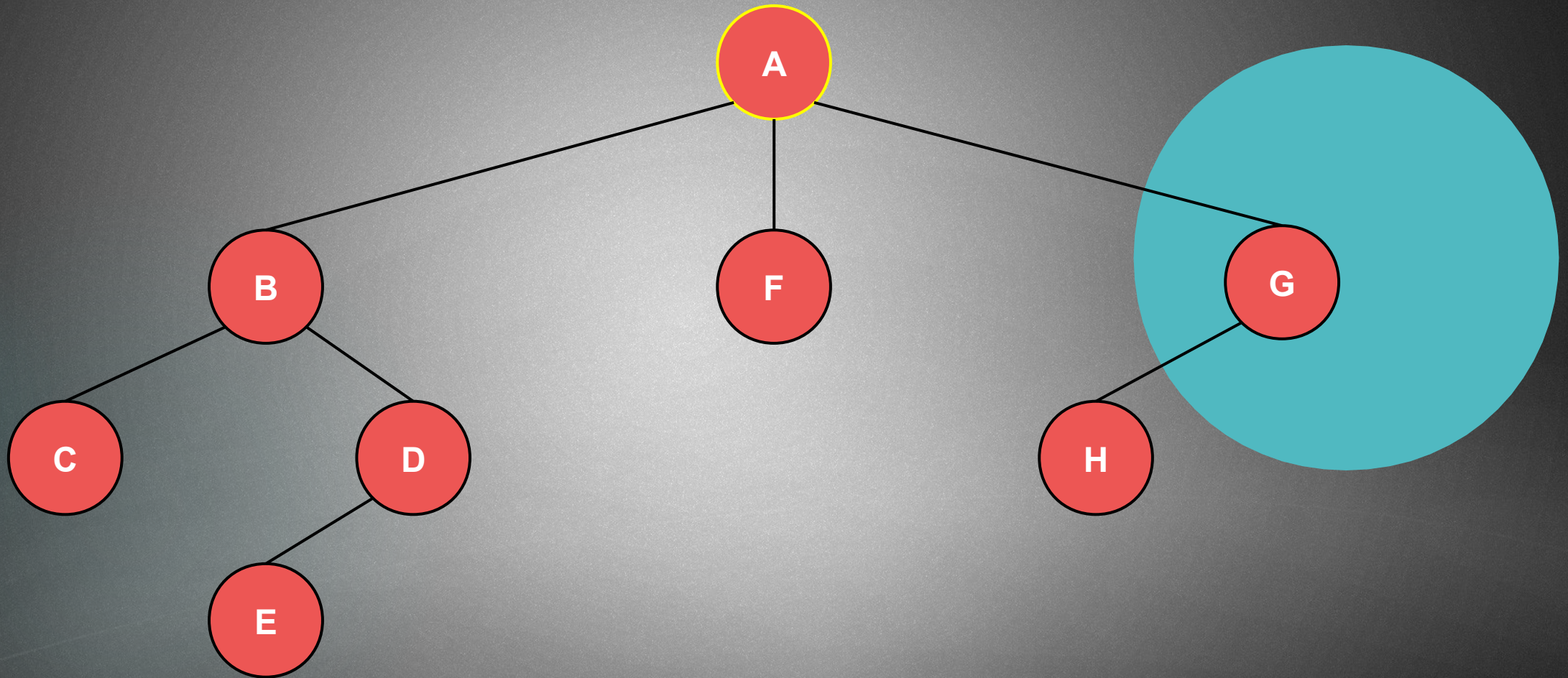


Recursively check every  
unmarked vertices!





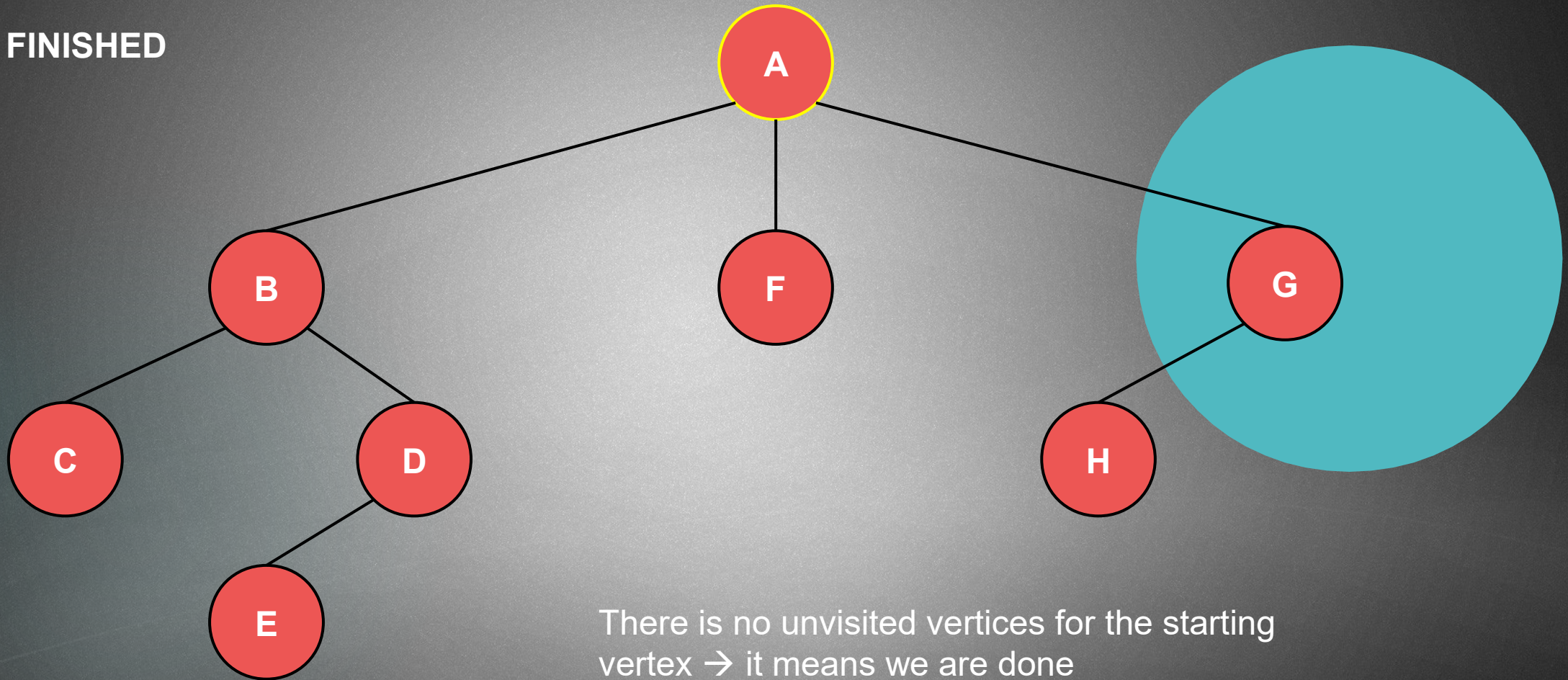
Recursively check every  
unmarked vertices!





Recursively check every  
unmarked vertices!

**FINISHED**



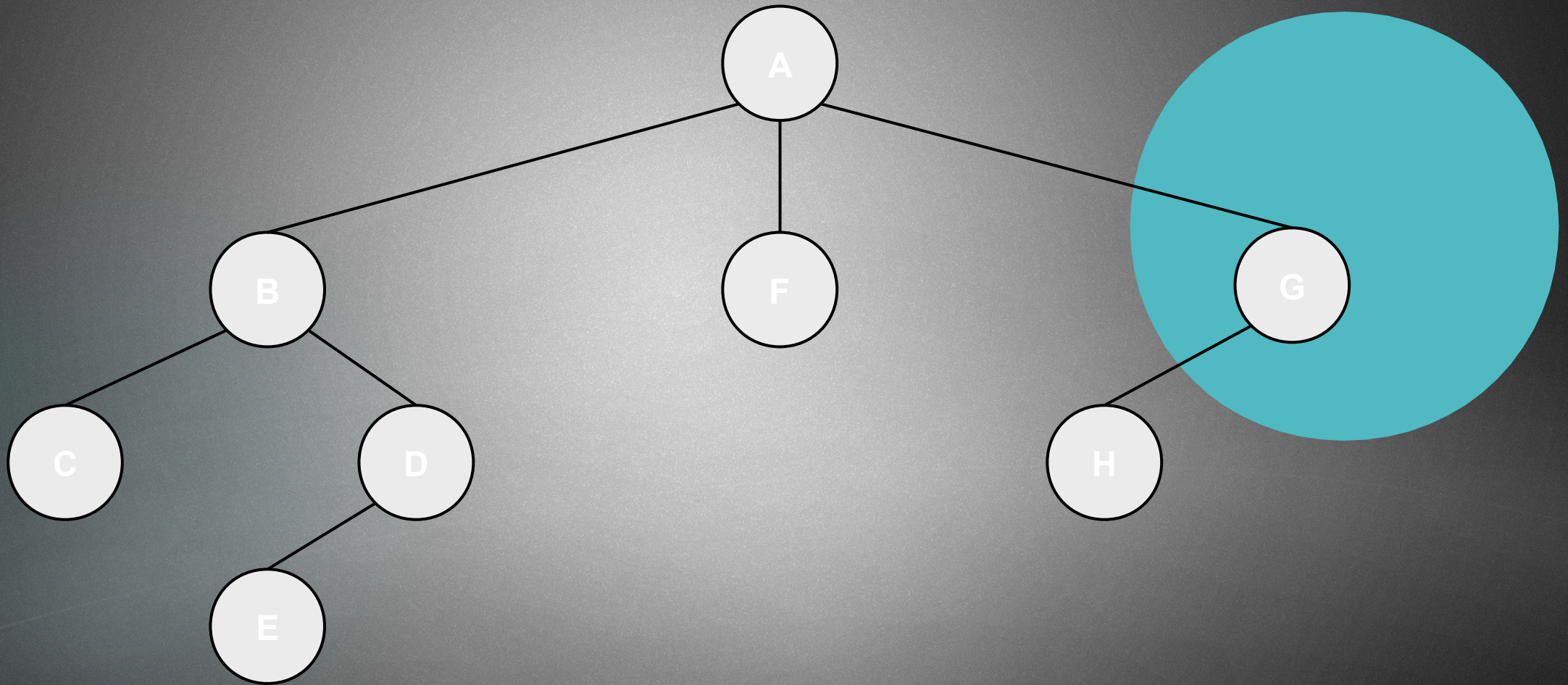


# Applications

- ▶ Topological ordering
- ▶ Kosaraju algorithm for finding strongly connected components in a graph which can be proved to be very important in recommendation systems ( youtube )
- ▶ Detecting cycles ( checking whether a graph is a DAG or not )
- ▶ Generating mazes OR finding way out of a maze

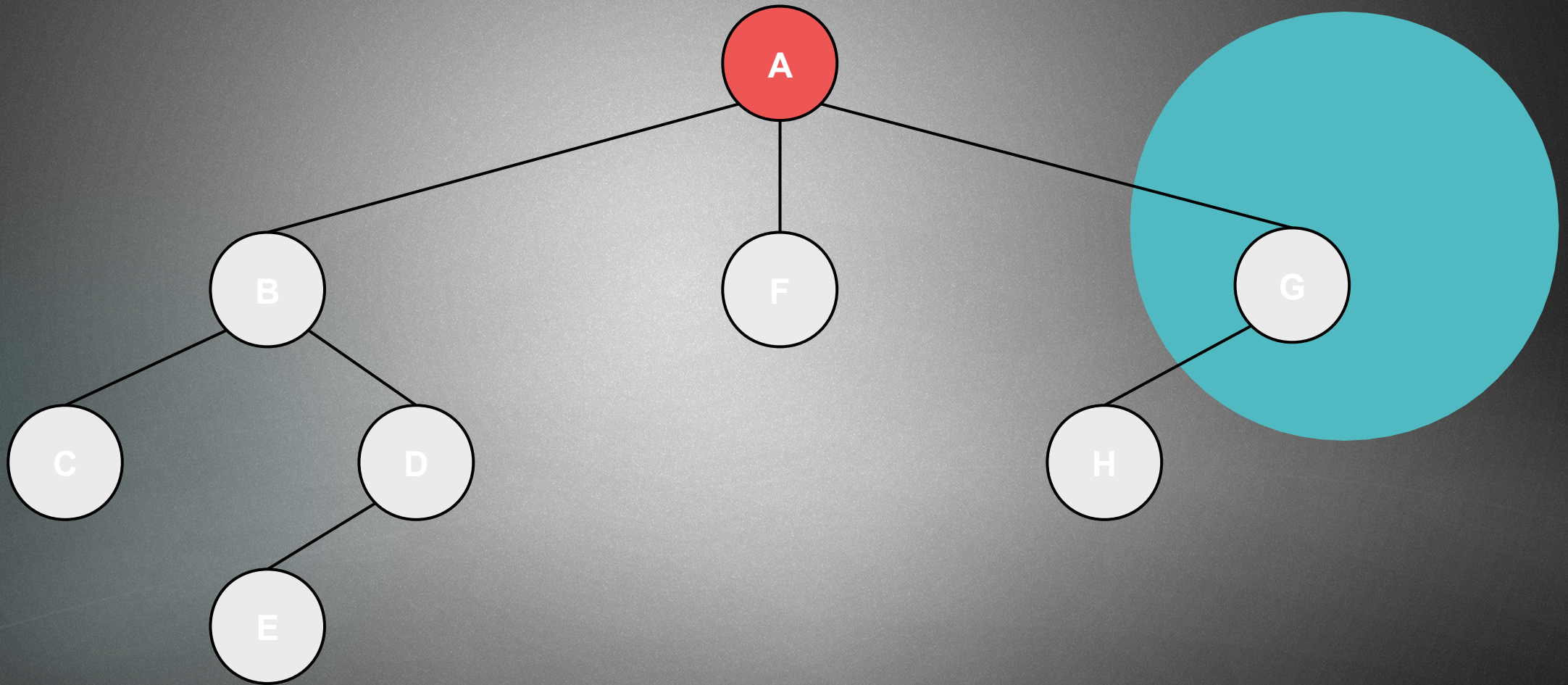


# Revisiting breadth-first search



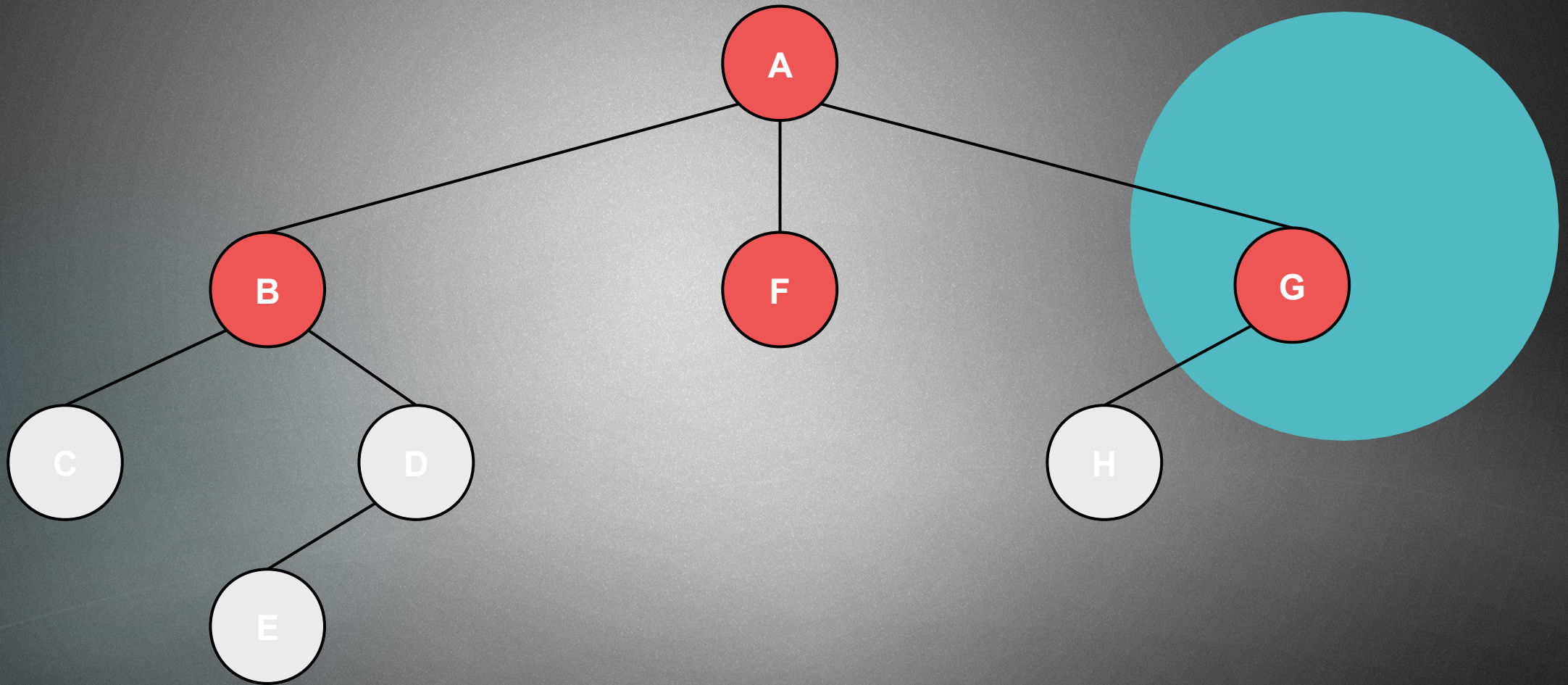


# Revisiting breadth-first search



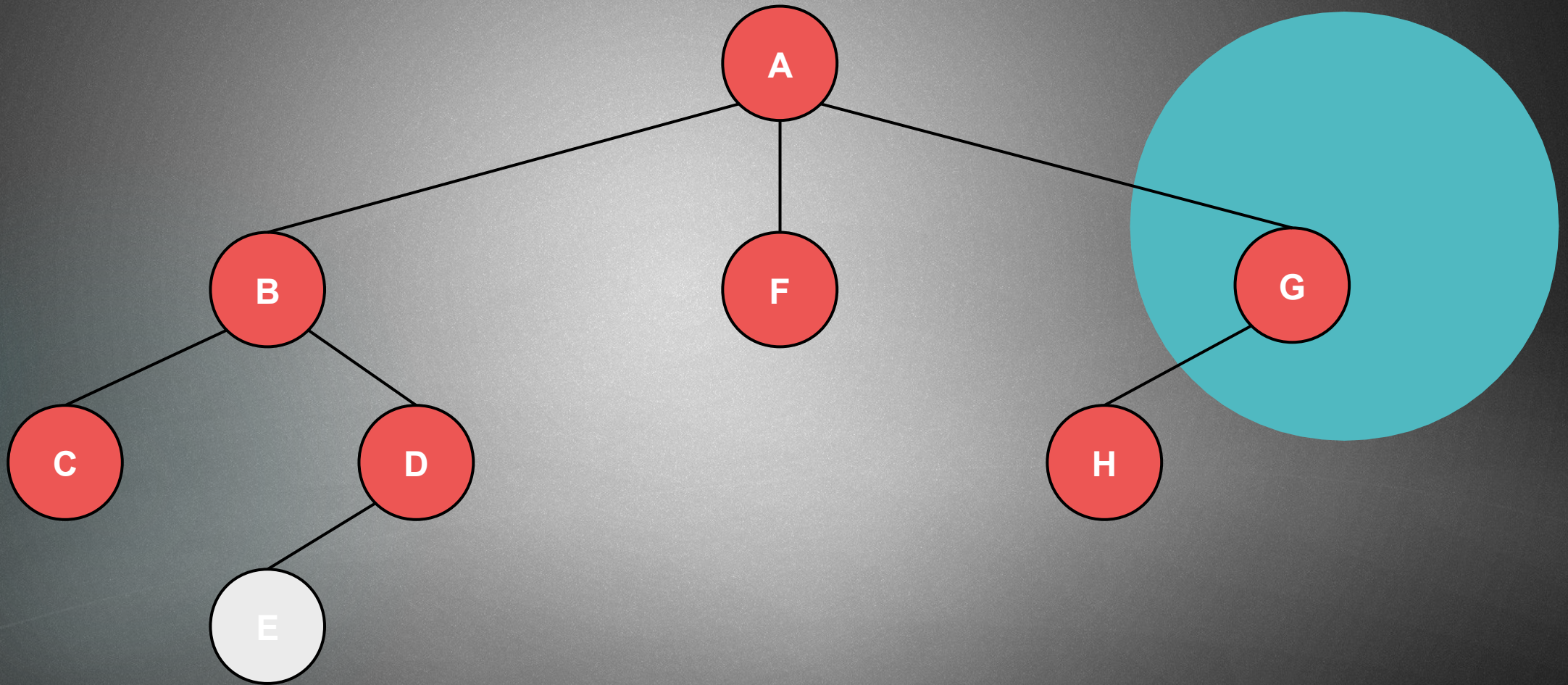


# Revisiting breadth-first search



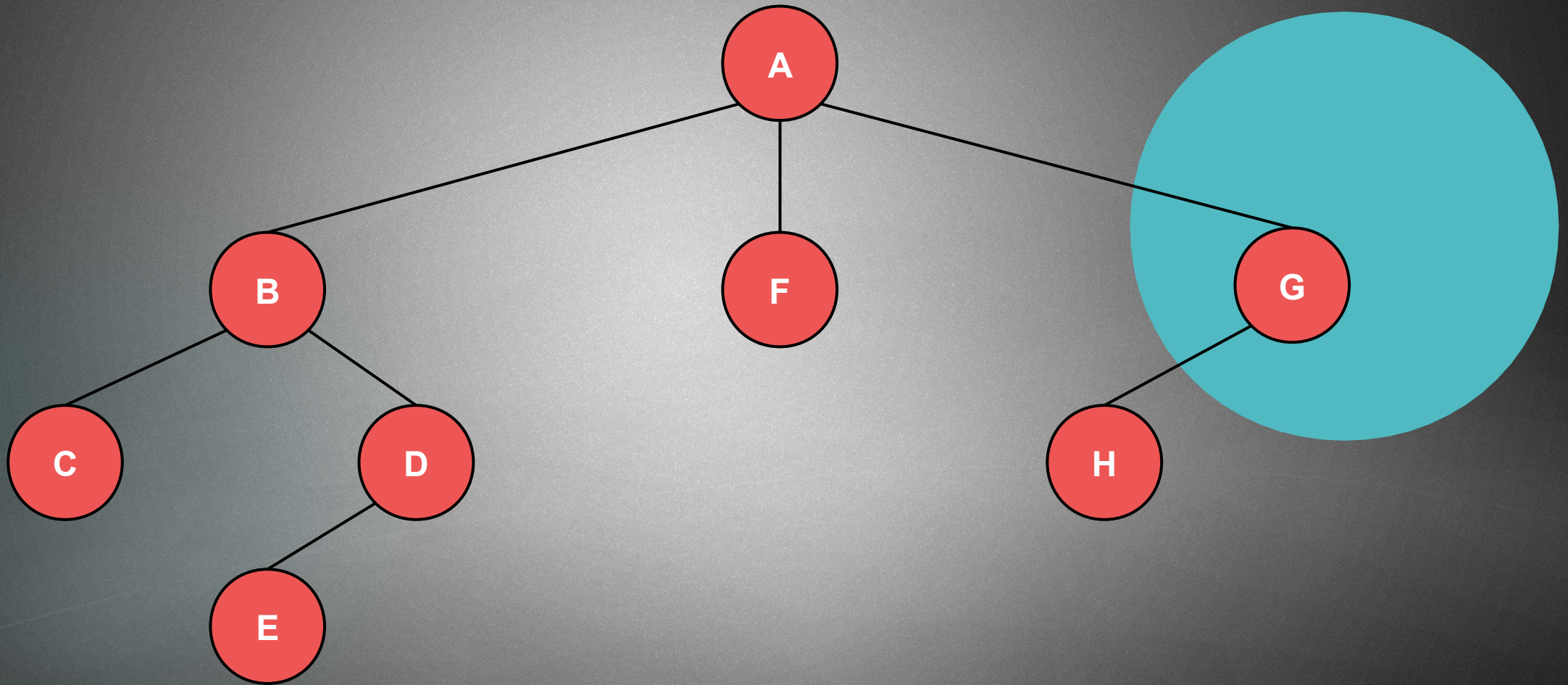


# Revisiting breadth-first search





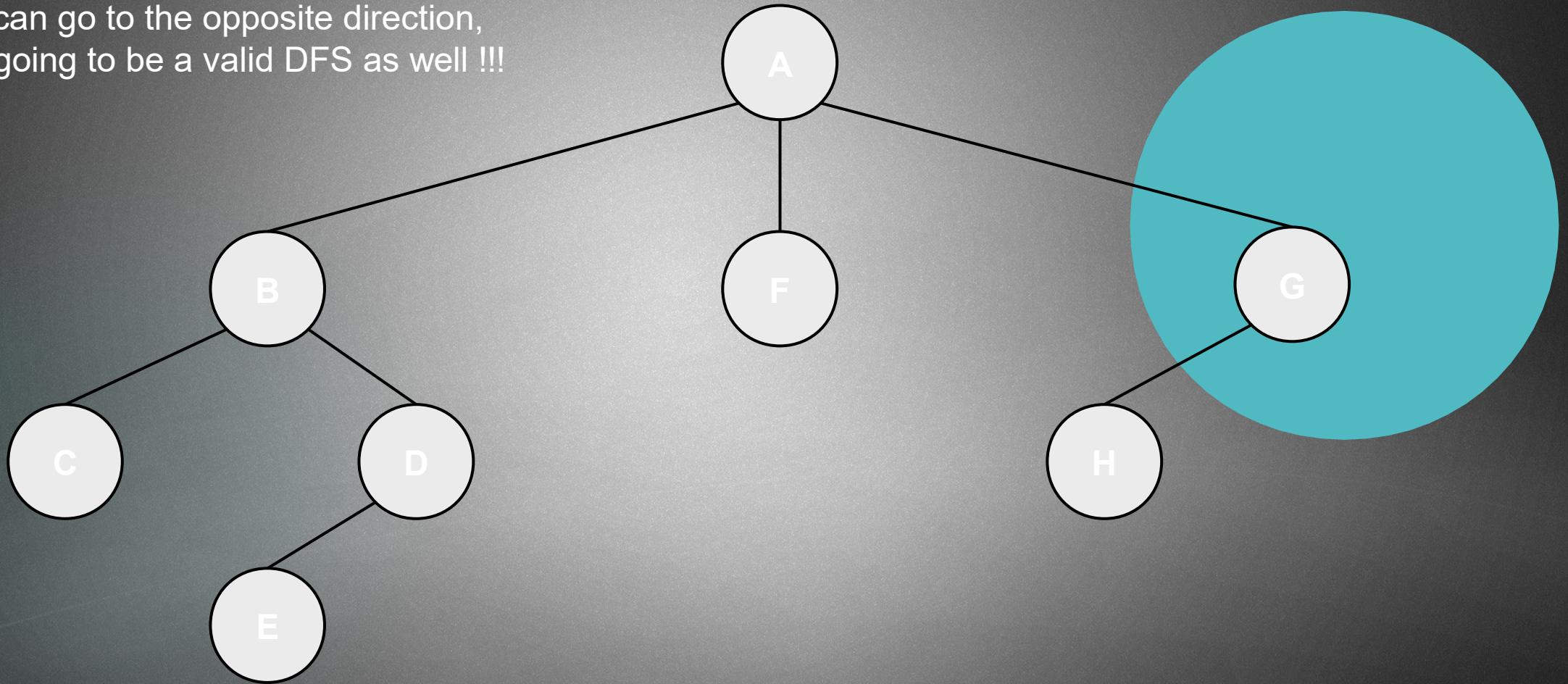
# Revisiting breadth-first search





# Symmetry in DFS

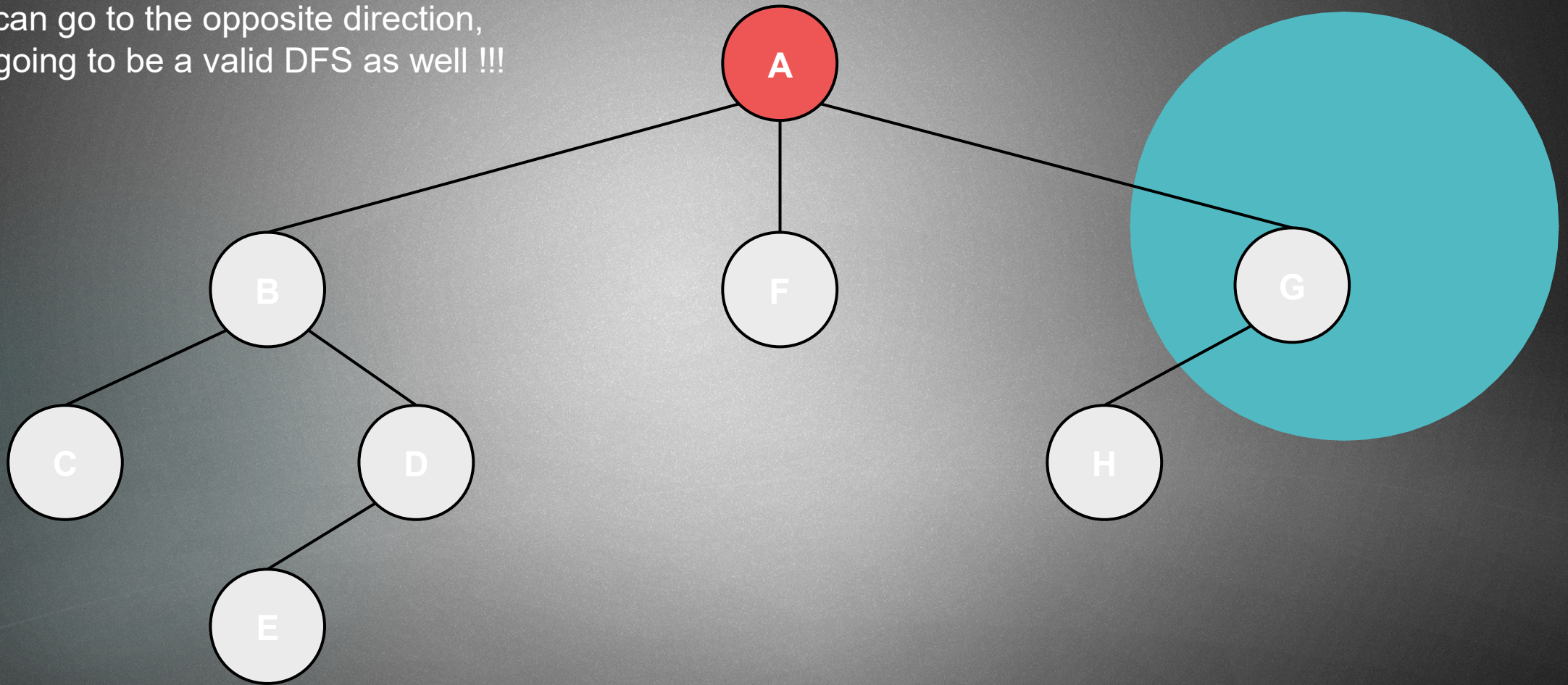
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

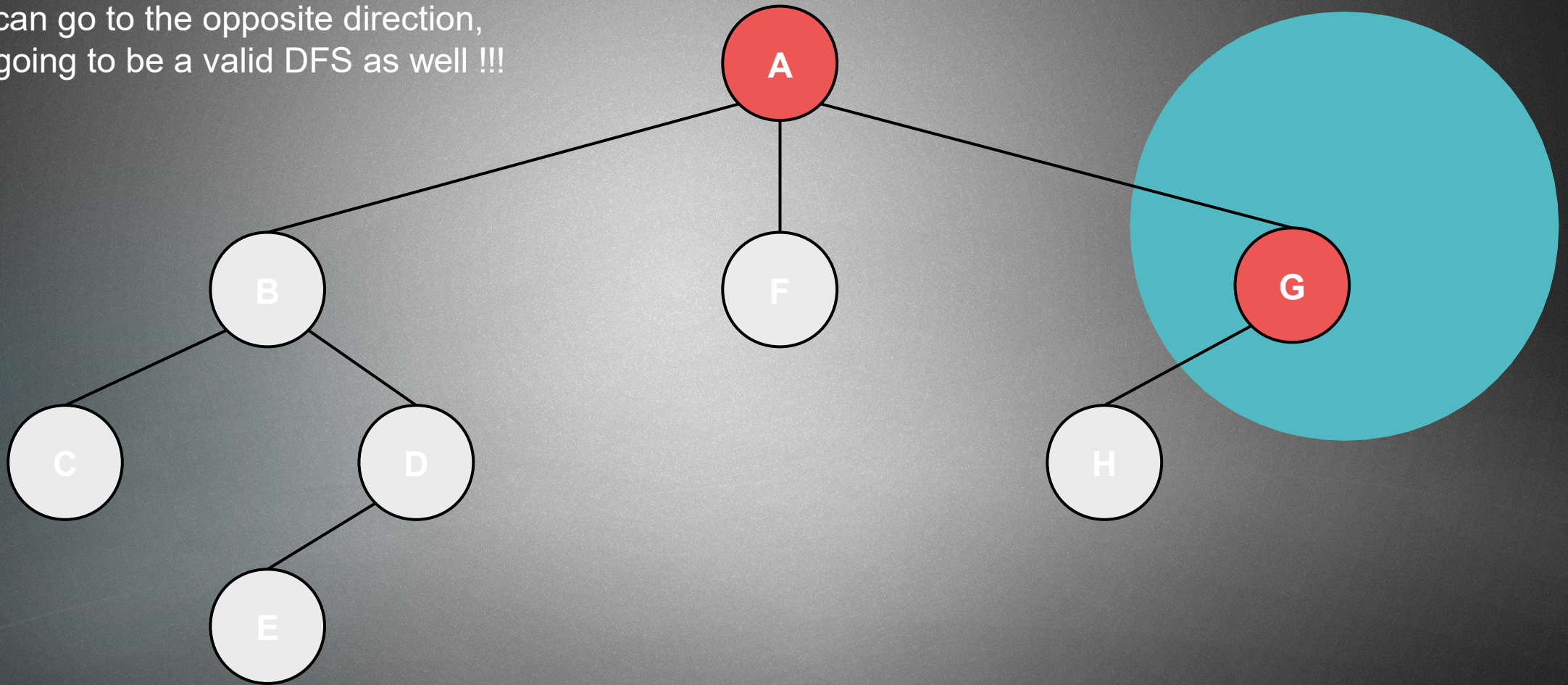
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

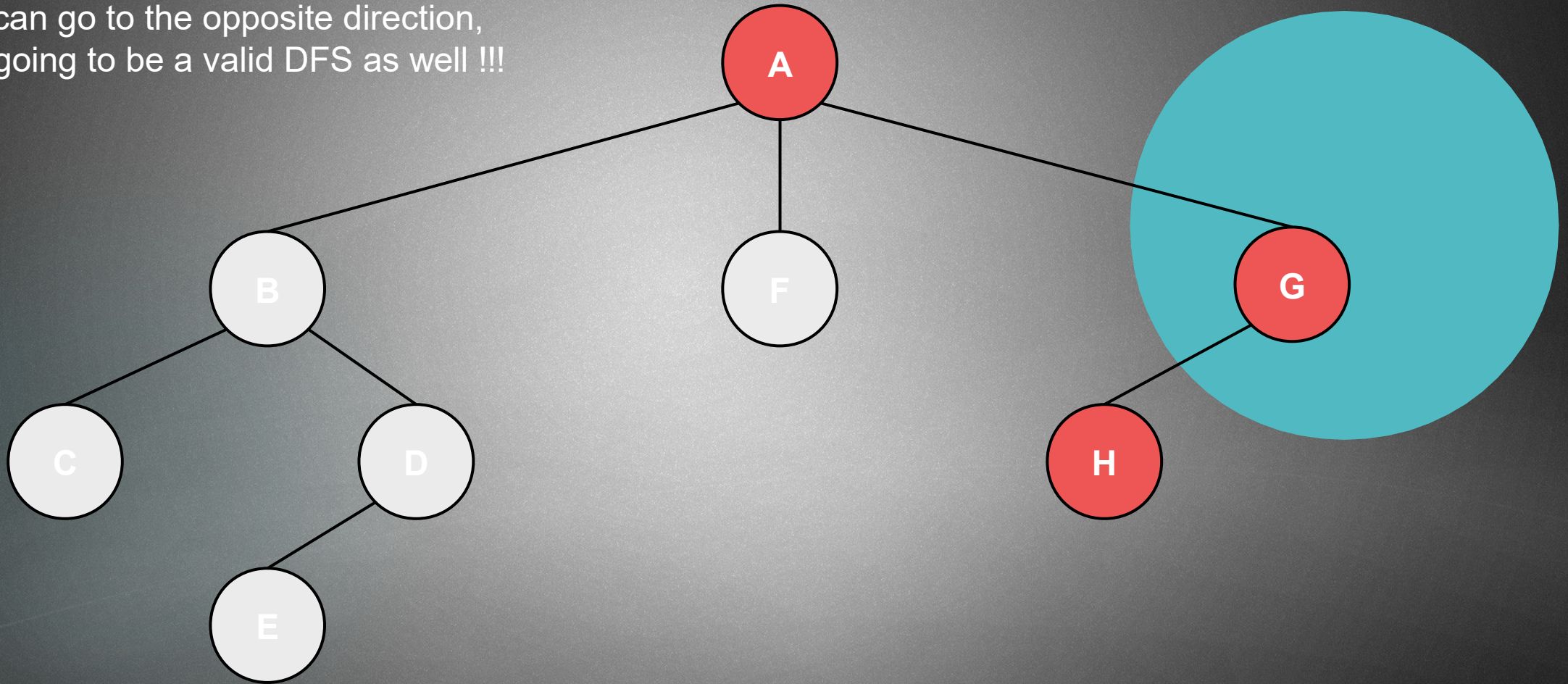
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

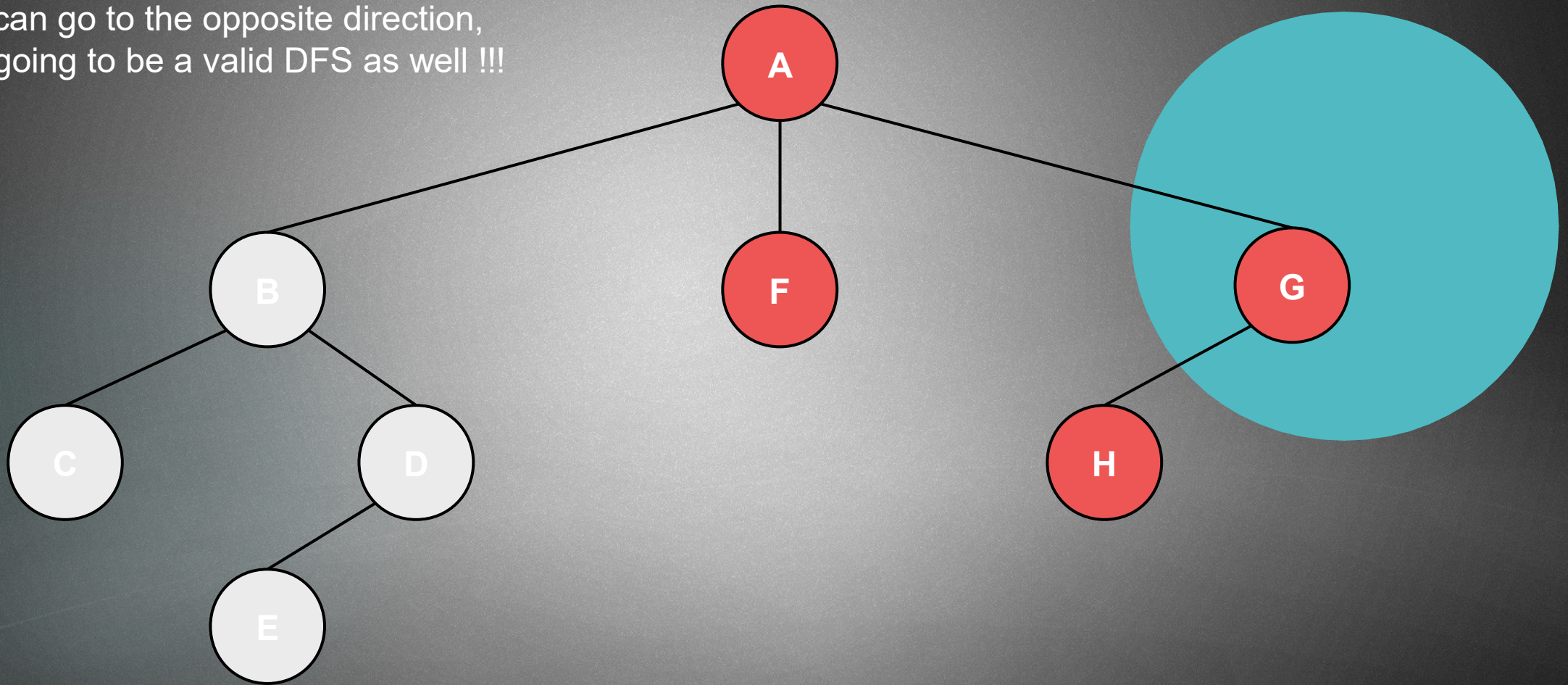
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

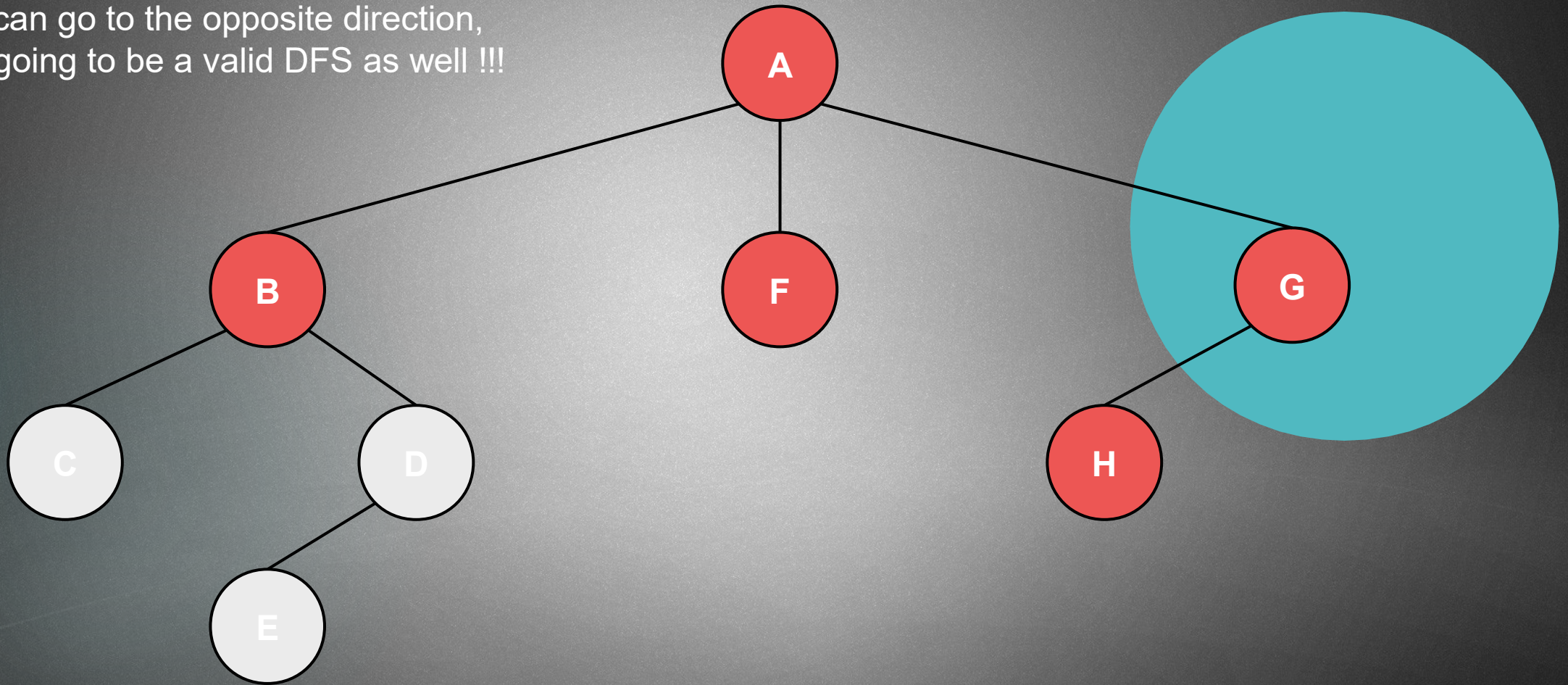
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

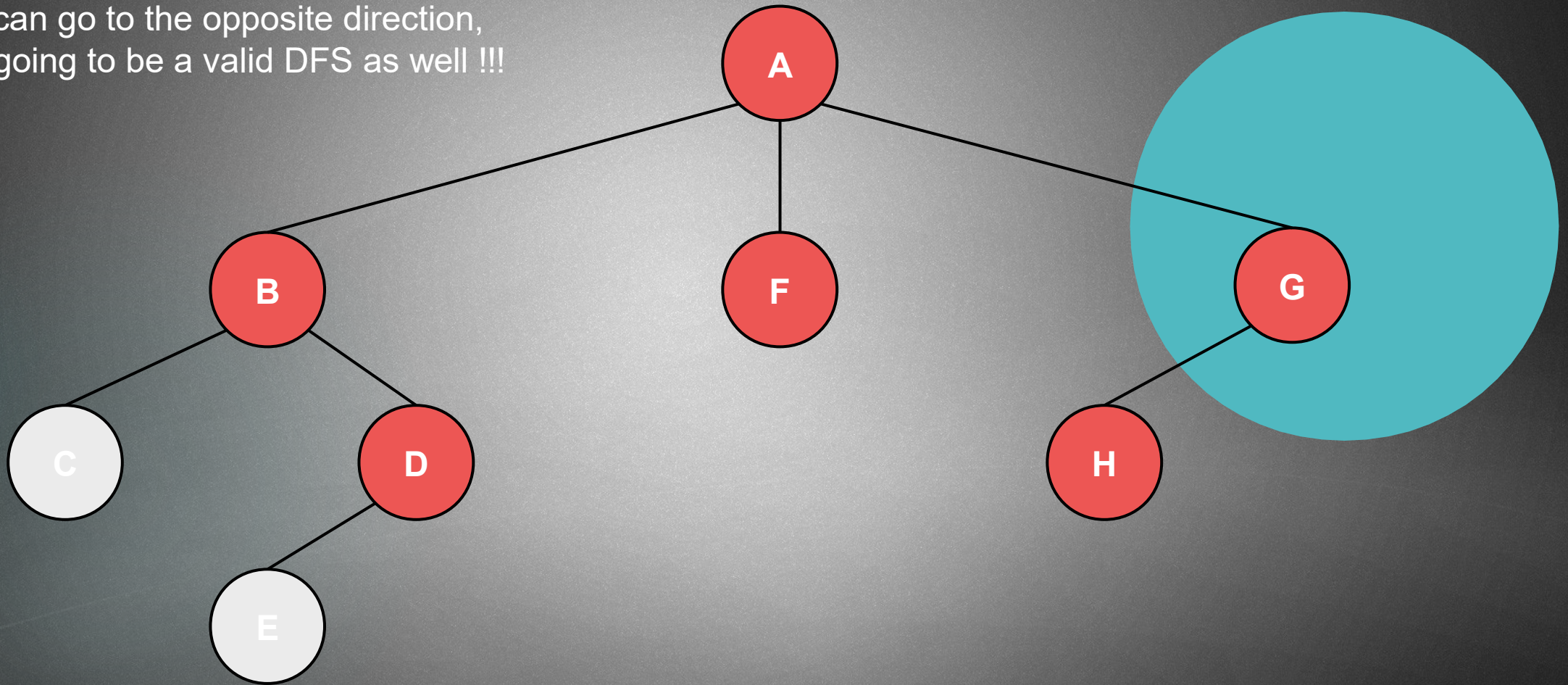
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

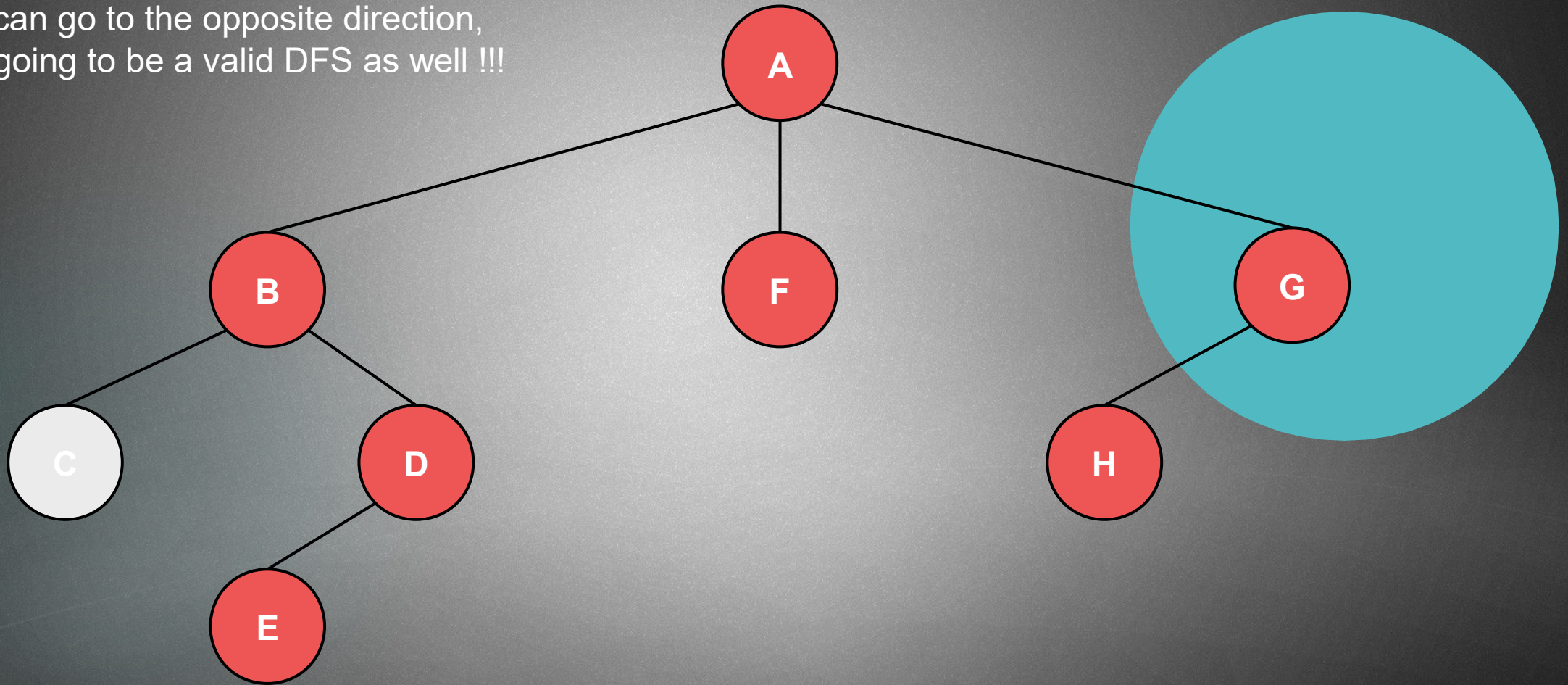
We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

We can go to the opposite direction,  
it is going to be a valid DFS as well !!!





# Symmetry in DFS

We can go to the opposite direction,  
it is going to be a valid DFS as well !!!

