CS4220 PS5

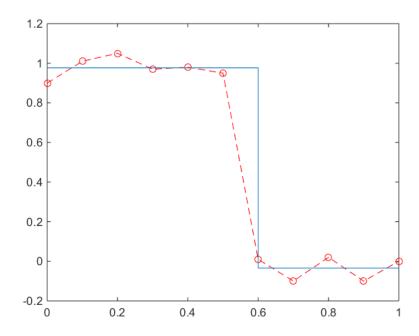
Due: March 2, 2015

1 (Ascher and Greif, 6.4, Problem 1) The given data:

$$t \quad 0.0 \quad 0.1 \quad 0.2 \quad 0.3 \quad 0.4 \quad 0.5 \quad 0.6 \quad 0.7 \quad 0.8 \quad 0.9 \quad 1.0$$
 $b \quad 0.9 \quad 1.01 \quad 1.05 \quad 0.97 \quad 0.98 \quad 0.95 \quad 0.01 \quad -0.1 \quad 0.02 \quad -0.1 \quad 0.0$

Solution:

1. From the plot, we can see the break approximately occurs at 0.5 to 0.6. The red data points are the data.



2. For each segment in the piecewise constant function, $p_0(t) = v(t) = x_1$, where t and v(t) (which is b here) are the independent and dependent variables, respectively, and x_1 is the constant term of $p_0(t)$ to be determined by the least-squares method. We write out the equation and obtain x in

A is an $n \times 1$ matrix with all elements being 1. We can compute either by MATLAB or by hand calculation to get the constants. Here is the MATLAB code:

$$v(t) = 0.9767, \quad 0 \le t \le 0.6,$$

 $v(t) = -0.0340, \quad 0.6 \le t \le 1.0.$

The piecewise constant fit is plotted as the blue lines in the figure.

2. QR to **SVD** Suppose A = QR is an economy QR factorization. Show that the singular values of A are those of R.

Solution: Let $A \in \mathbb{R}^{m \times n}$, m > n. An economy QR factorization produces A = QR, where $Q \in \mathbb{R}^{m \times n}$ is orthogonal, and $R \in \mathbb{R}^{n \times n}$. The singular values of A are the square of the eigenvalues of the symmetric matrix $A^TA \in \mathbb{R}^{n \times n}$. Because $Q^TQ = I$ (Q is orthogonal), we have

$$A^T A = (QR)^T QR = R^T Q^T QR = R^T R.$$

So we see $A^TA = R^TR$, therefore the singular values of A are the same as the singular values of $R^TR \in \mathbb{R}^{n \times n}$.

3: Vector projector Suppose $A \in \mathbb{R}^{m \times n}$ where m > n has full column rank. Given A and a vector b, write one line of MATLAB to compute the element c in the range space of A that is nearest to b (in the Euclidean norm).

Solution: We want to solve the normal equation, which guarantees that c is the normal projection of b in the range space of A:

$$(A^T A)c = A^T b,$$

and the one-line MATLAB code is:

$$c = (A'*A)\setminus (A'*b);$$

4: Generally speaking Often, we use least squares to construct models of the world. We assume that the "truth" is

$$Ax = b$$
,

but what we measure is the first few rows of A and b (which we write as A_1 and b_1), and those measurements are corrupted by noise. Suppose we have A exactly, but only get the noisy partial right hand side $\hat{b}_1 = b_1 + e_1$, from which we form

minimize
$$||A_1\hat{x} - \hat{b}_1||^2$$
.

Our goal in this problem is to use the error analysis ideas in Section 6.2 to figure out the inherited error in the reconstruction of $\hat{b}_2 = A_2 \hat{x}$.

- 1. Let $e_2 = \hat{b}_2 b_2$. Argue briefly that $e_2 = A_2 A_1^{\dagger} e_1$.
- 2. Show that

$$\frac{\|e_2\|}{\|b_2\|} \le \kappa (A_2 A_1^{\dagger}) \frac{\|e_1\|}{\|b_1\|}.$$

Things get somewhat more complicated if we also allow the entries of A to be contaminated by error, though the same basic ingredients come into play.

Solution:

1. The truth of the model is represented by

$$A_1x = b_1, \quad A_2x = b_2 \quad \dots$$

The noise or error is defined as

$$e_1 = \hat{b}_1 - b_1, \quad e_1 = \hat{b}_2 - b_2, \quad \dots$$

The least-squares approximation method provides the solution to $A_1\hat{x} = \hat{b}_1$ as follows:

$$\hat{x} = (A_1^T A_1)^{-1} A_1^T x = A_1^{\dagger} b_1,$$

where $A_1^{\dagger} = (A_1^T A_1)^{-1} A_1^T$ is called the *pseudo-inverse* of matrix A_1 , and obviously

$$A_1^{\dagger} A_1 = (A_1^T A_1)^{-1} A_1^T A_1 = I.$$

But in general $A_1 A_1^{\dagger} \neq I$ unless A_1 is invertible.

Now from the definition of e_2 and the least-squares solution, we get

$$e_{2} = \hat{b}_{2} - b_{2} = A_{2}\hat{x} - b_{2}$$

$$= A_{2}(A_{1}^{\dagger}b_{1}) - b_{2}$$

$$= A_{2}A_{1}^{\dagger}b_{1} - A_{2}x$$

$$= A_{2}(A_{1}^{\dagger}b_{1} - x)$$
(1)

Similarly to Eq.(1), we have:

$$e_1 = \hat{b}_1 - b_1 = A_1 \hat{x} - b_1 = A_1 (A_1^{\dagger} b_1 - x).$$
 (2)

Now left multiply A_1^{\dagger} to Eq.(2):

$$A_1^{\dagger} e_1 = A_1^{\dagger} A_1 (A_1^{\dagger} b_1 - x) = I(A_1^{\dagger} b_1 - x) = (A_1^{\dagger} b_1 - x). \tag{3}$$

Substituting Eq.(3) into Eq.(1), we arrive at the result for the inherited error e_2 :

$$e_2 = A_2 A_1^{\dagger} e_1.$$

2. Show that

$$\frac{\|e_2\|}{\|b_2\|} \le \kappa (A_2 A_1^{\dagger}) \frac{\|e_1\|}{\|b_1\|}.$$

Proof. We consider 2-norms throughout this part of the problem. For any vector u, we can use the following inequality

$$\sigma_{\min}(A_2 A_1^{\dagger}) \|u\| \le \|A_2 A_1^{\dagger} u\| \le \sigma_{\max}(A_2 A_1^{\dagger}) \|u\|,$$
 (4)

where $\sigma(A_2A_1^{\dagger})$ stands for the singular value of matrix $A_2A_1^{\dagger}$.

Substituting $u = e_1$ into Eq.(4) and use the result $e_2 = A_2 A_1^{\dagger} e_1$ obtained in the first part of the problem, we have

$$\sigma_{\min}(A_2 A_1^{\dagger}) \|e_1\| \le \|A_2 A_1^{\dagger} e_1\| = \|e_2\| \le \sigma_{\max}(A_2 A_1^{\dagger}) \|e_1\|,$$

hence we establish

$$||e_2|| \le \sigma_{\max}(A_2 A_1^{\dagger}) ||e_1||.$$
 (5)

Now substituting $u = b_1$ into Eq.(4), and recognizing $A_2 A_1^{\dagger} b_1 = b_2$, we have

$$\sigma_{\min}(A_2 A_1^{\dagger}) \|b_1\| \le \|A_2 A_1^{\dagger} b_1\| = \|A_2 (A_1^{\dagger} A_1 x)\|$$

$$= \|A_2 x\| = \|b_2\| \le \sigma_{\max}(A_2 A_1^{\dagger}) \|b_1\|,$$

therefore we establish

$$||b_2|| \ge \sigma_{\min}(A_2 A_1^{\dagger}) ||b_1||.$$
 (6)

Dividing Eq.(5) by Eq.(6), we obtain the following

$$\frac{\|e_2\|}{\|b_2\|} \le \frac{\sigma_{\max}(A_2 A_1^{\dagger})}{\sigma_{\min}(A_2 A_1^{\dagger})} \frac{\|e_1\|}{\|b_1\|}.$$
 (7)

By definition, the condition number of a non-invertible matrix, like $A_2A_1^{\dagger}$, is the ratio of the maximum singular value to the minimum singular value:

$$\kappa(A_2 A_1^{\dagger}) \equiv \frac{\sigma_{\max}(A_2 A_1^{\dagger})}{\sigma_{\min}(A_2 A_1^{\dagger})}.$$

After plugging in the definition of the condition number into Eq.(7), we have completed the proof:

$$\frac{\|e_2\|}{\|b_2\|} \le \kappa (A_2 A_1^{\dagger}) \frac{\|e_1\|}{\|b_1\|}.$$