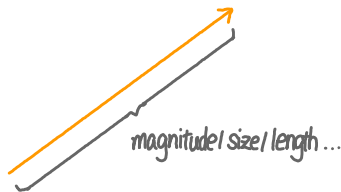


# Geometry of Vectors in $\mathbb{R}^3$

Reading: Textbook, §12.1 - 12.5

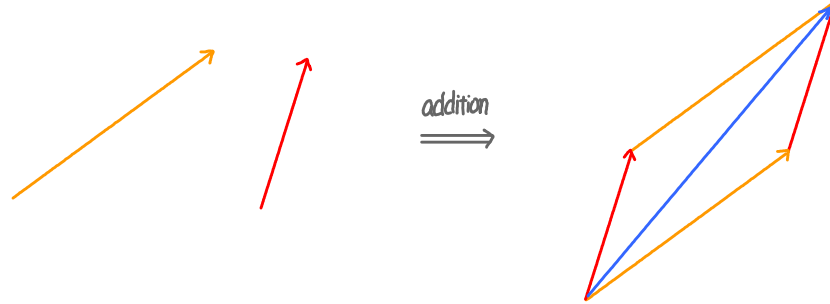
## §1. Vectors in $\mathbb{R}^3$

- A vector is a mathematical quantity that has a **magnitude** and a **direction**.



- A vector can be rescaled by **scalars** (numbers in  $\mathbb{R}$ ) to make new vectors, only affecting its size.  
(What about rescaling by negative scalars?)

- Unlike scalars, vector addition obeys the parallelogram/triangle rule



(Q: How to perform subtraction?)

- To mathematically describe vectors, we introduce *Cartesian coordinates*. Thus a vector in 3-dim'l space is described by 3 numbers: its projections onto the  $x, y, z$ -axis.

$$\vec{v} = (v_x, v_y, v_z)$$

Then: addition and scalar multiplication are done coordinatewise:

$$\vec{v} = (v_x, v_y, v_z) \quad , \quad \vec{u} = (u_x, u_y, u_z) \quad , \quad a \in \mathbb{R}$$

$$\Rightarrow \begin{cases} \vec{v} + \vec{u} = (v_x + u_x, v_y + u_y, v_z + u_z) \\ a\vec{v} = (av_x, av_y, av_z) \end{cases}$$

Eg. How do we add the vectors  $(4, 5, 6)$  and  $(1, 2, 3)$ ?

How do we subtract  $(4, 5, 6)$  from  $(1, 2, 3)$ ?

- It's convenient to give some standard vectors special names:

$$\vec{i} = (1, 0, 0), \quad \vec{j} = (0, 1, 0), \quad \vec{k} = (0, 0, 1)$$

Then any vector  $\vec{v} = (a, b, c)$  can be rewritten as

$$\begin{aligned}\vec{v} &= a(1, 0, 0) + b(0, 1, 0) + c(0, 0, 1) \\ &= a\vec{i} + b\vec{j} + c\vec{k}\end{aligned}$$

- The Pythagorean Theorem tells us that the magnitude/length of a vector  $\vec{v} = (a, b, c)$  is given by

$$\|\vec{v}\| = \sqrt{a^2 + b^2 + c^2}$$

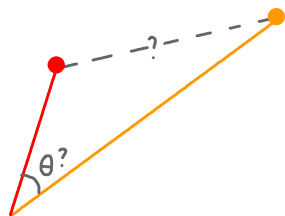
E.g. Draw all vectors of length 1 in  $\mathbb{R}^3$ .

E.g. What's the length of the vector  $\frac{\vec{v}}{\|\vec{v}\|}$  if  $\vec{v} \neq \vec{0}$ ?

(This vector is called the direction vector of  $\vec{v}$ , of length 1).

## §2. Dot/inner product

The notion of length of a vector is closely related to distance between two points in  $\mathbb{R}^3$  and angles between two vectors.



Def. If  $\vec{u} = (u_x, u_y, u_z)$  and  $\vec{v} = (v_x, v_y, v_z)$  are vectors in  $\mathbb{R}^3$ , then

$$\vec{u} \cdot \vec{v} := u_x v_x + u_y v_y + u_z v_z \in \mathbb{R}$$

### Basic properties.

- For any vector  $\vec{u} = (a, b, c) \in \mathbb{R}^3$

$$\vec{u} \cdot \vec{u} = a^2 + b^2 + c^2 = (\sqrt{a^2 + b^2 + c^2})^2 = \|\vec{u}\|^2.$$

- $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$  (commutativity).

- $\vec{u} \cdot (a\vec{v} + b\vec{w}) = a\vec{u} \cdot \vec{v} + b\vec{u} \cdot \vec{w}$  (distributivity)

- Generalized Pythagorean Theorem : if  $\vec{u}, \vec{v}$  make an angle  $\theta$  :

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$



$\implies$  If  $\vec{u}, \vec{v}$  are non-zero vectors making an angle  $\theta$ ,

$$\cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|}.$$

(Here we usually assume  $\theta \in (0, \pi)$ . If  $\theta = 0$  or  $\pi$ , the two vectors are called parallel).

E.g. Show that the triangles with vertices  $(1, -3, -2)$ ,  $(2, 0, -4)$  and  $(6, -2, -5)$  is right angled.

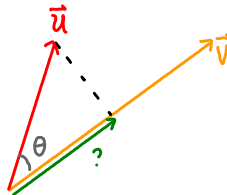
Using dot product, if  $\vec{u} = (u_x, u_y, u_z)$  is a vector, then

$$u_x = \vec{u} \cdot \vec{i}, \quad u_y = \vec{u} \cdot \vec{j}, \quad u_z = \vec{u} \cdot \vec{k}$$

$\Rightarrow$

$$\vec{u} = (\vec{u} \cdot \vec{i})\vec{i} + (\vec{u} \cdot \vec{j})\vec{j} + (\vec{u} \cdot \vec{k})\vec{k}$$

Application: Project one vector  $\vec{u}$  in the direction of another.



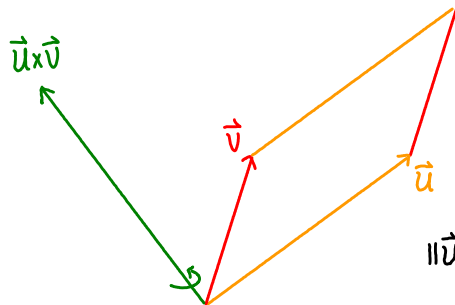
$$\text{Proj}_{\vec{v}}(\vec{u}) = \|\vec{u}\| \cos \theta \frac{\vec{v}}{\|\vec{v}\|} = \|\vec{u}\| \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \frac{\vec{v}}{\|\vec{v}\|} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{v}\|^2} \vec{v}.$$

Eg. Find the projection of  $(1, 2, 3)$  in the direction of the vector  $(3, 4, 0)$ , and the length of this projected vector.

### §3. Cross product

Def. The cross product of two vectors  $\vec{u}$  and  $\vec{v}$  has

- magnitude = area of parallelogram formed by  $\vec{u}$  and  $\vec{v}$
- direction = perpendicular to  $\vec{u}$  and  $\vec{v}$  via the right hand rule.

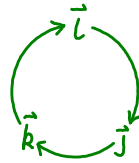


$$\|\vec{u} \times \vec{v}\| = \text{Area of parallelogram}$$

- Helpful computational rule: the cross product is distributive and anti-commutative, and determined by

$$\vec{i} \times \vec{i} = \vec{j} \times \vec{j} = \vec{k} \times \vec{k} = 0$$

$$\vec{i} \times \vec{j} = \vec{k} = -\vec{j} \times \vec{i}, \quad \vec{j} \times \vec{k} = \vec{i} = -\vec{k} \times \vec{j}, \quad \vec{k} \times \vec{i} = \vec{j} = -\vec{i} \times \vec{k}$$



Eg.  $(1, 2, 0) \times (0, 4, 6) = (1\vec{i} + 2\vec{j}) \times (4\vec{j} + 6\vec{k})$

More generally, if  $\vec{u} = (a_1, b_1, c_1)$ ,  $\vec{v} = (a_2, b_2, c_2)$ , then

$$\begin{aligned}\vec{u} \times \vec{v} &= (a_1 \vec{i} + b_1 \vec{j} + c_1 \vec{k}) \times (a_2 \vec{i} + b_2 \vec{j} + c_2 \vec{k}) \\ &= (b_1 c_2 - b_2 c_1) \vec{i} - (a_1 c_2 - a_2 c_1) \vec{j} + (a_1 b_2 - a_2 b_1) \vec{k}\end{aligned}$$

A useful way to memorize the determinantal formula in linear algebra. if  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is a  $2 \times 2$  matrix, then

$$|A| = \left| \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right| = ad - bc.$$

So we can rewrite:

$$\begin{aligned}\vec{u} \times \vec{v} &= \begin{vmatrix} b_1 & c_1 \\ b_2 & c_2 \end{vmatrix} \vec{i} - \begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix} \vec{j} + \begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} \vec{k} \\ &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}\end{aligned}$$

using the  $3 \times 3$  determinantal formula.

Eg. Double check that  $\vec{i} \times \vec{j} = \vec{k}$  etc.

E.g. Compute  $\vec{u} \times \vec{v}$  for  $\vec{u} = (1, 2, 3)$  and  $\vec{v} = (4, 5, 6)$ , and verify that  $\vec{u}, \vec{v}$  are perpendicular to  $\vec{u} \times \vec{v}$ .

**Thm** (1) The vector  $\vec{u} \times \vec{v}$  is perpendicular to both  $\vec{u}$  &  $\vec{v}$ .

(2). The length of  $\vec{u} \times \vec{v}$  is equal to  $\|\vec{u}\| \|\vec{v}\| \sin \theta$ , where  $\theta \in [0, \pi]$  is the angle between  $\vec{u}$  &  $\vec{v}$ .



E.g. Find a nonzero vector that is orthogonal to the plane containing the points  $(1,0,1)$ ,  $(-2,1,3)$  and  $(4,2,5)$ .

Thm. (Properties of  $\times$ ). For any vectors  $\vec{u}, \vec{v}, \vec{w}$ , we have

1.  $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u} \quad (\Rightarrow \vec{u} \times \vec{u} = \vec{0})$ .
2.  $(r\vec{u}) \times \vec{v} = r(\vec{u} \times \vec{v}) = \vec{u} \times (r\vec{v})$ .
3.  $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$ ,  $(\vec{v} + \vec{w}) \times \vec{u} = \vec{v} \times \vec{u} + \vec{w} \times \vec{u}$ .
4.  $\vec{u} \cdot (\vec{v} \times \vec{w}) = \vec{v} \cdot (\vec{w} \times \vec{u}) = \vec{w} \cdot (\vec{u} \times \vec{v})$ .
5.  $\vec{u} \times (\vec{v} \times \vec{w}) = (\vec{u} \cdot \vec{w})\vec{v} - (\vec{u} \cdot \vec{v})\vec{w}$ .

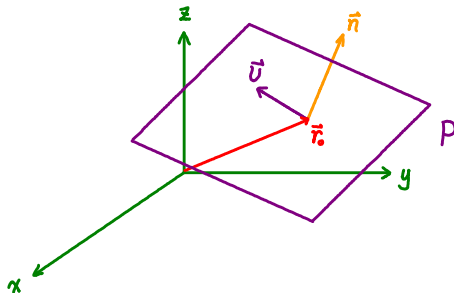
The quantity  $\vec{u} \cdot (\vec{v} \times \vec{w})$  is also called the **triple product** of  $\vec{u}$ ,  $\vec{v}$  and  $\vec{w}$ . It is equal to the signed/oriented volume of the parallelepiped formed by  $\vec{u}$ ,  $\vec{v}$  &  $\vec{w}$ :

$$\vec{u} \cdot (\vec{v} \times \vec{w}) = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix}.$$

E.g. Determine if the vectors  $(2, 8, -14)$ ,  $(2, -1, 4)$  and  $(10, 1, -2)$  are coplanar or not.

## §4. Equations of planes and lines

As applications, we give several ways to describe lines in  $\mathbb{R}^3$ .



$$P = \{ \vec{r}_0 + \vec{v} \mid \vec{v} \perp \vec{n} \} = \{ \vec{r} \mid (\vec{r} - \vec{r}_0) \perp \vec{n} \} = \{ \vec{r} \mid \vec{n} \cdot (\vec{r} - \vec{r}_0) = 0 \}.$$

The vector  $\vec{n}$  is called the *normal direction* of  $P$ .

In coordinates, if  $\vec{n} = (a, b, c)$ ,  $\vec{r}_0 = (x_0, y_0, z_0)$ , then  $(x, y, z) \in P$  means

$$0 = (\vec{r} - \vec{r}_0) \cdot \vec{n} = (x, y, z) - (x_0, y_0, z_0) \cdot (a, b, c)$$

$\Rightarrow$

$$\boxed{a(x - x_0) + b(y - y_0) + c(z - z_0) = 0}$$

Next, we describe lines. The easiest way to describe a line is to use the *vector parametric form*

$$\vec{v}(t) = \vec{r}_0 + t\vec{u} \quad (t \in \mathbb{R})$$

Componentwise, if  $\vec{v}(t) = (x(t), y(t), z(t))$ ,  $\vec{r}_0 = (x_0, y_0, z_0)$  and  $\vec{v} = (a, b, c)$ , then

$$x(t) = x_0 + at, \quad y(t) = y_0 + bt, \quad z(t) = z_0 + ct.$$

Note that there are different ways to describe the same line by choosing different  $\vec{r}_0$ 's and (parallel)  $\vec{v}$ 's.

Assume  $a \neq 0, b \neq 0, c \neq 0 \implies$  *symmetric form* of the line

$$(t=) \quad \boxed{\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}}$$

This form is essentially describing the line as the intersection of 2 planes :

$$P_1 : \frac{x-x_0}{a} = \frac{y-y_0}{b} \qquad P_2 : \frac{y-y_0}{b} = \frac{z-z_0}{c}$$

More generally, two non-parallel planes always intersect at a line.

E.g. What is the relationship between the planes

$$P_1 : 2x - 3y + 4z = 5 \qquad P_2 : x + 6y + 4z = 3$$

Find a parametric form of  $P_1 \cap P_2$

E.g Can you give a condition for a line

$$L: x(t) = x_0 + at, \quad y(t) = y_0 + bt, \quad z(t) = z_0 + ct$$

to be parallel to a plane

$$P: ux + vy + wz = d$$

Under what conditions will  $L$  and  $P$  intersect each other?