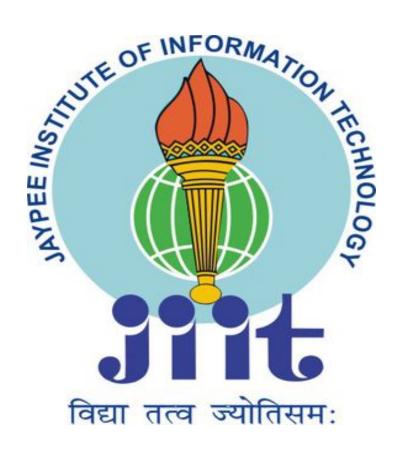
MINOR PROJECT 2

Mid Evaluation Report - Spatial Data Mining Lab



Ambulance Allocation and Accident Data Analysis

Minor Project 2

Spatial Data Mining Lab

23.03.2019

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INTRODUCTION

In this fast moving world where Cab, Food, Electrician all are just a click away, we tend to forget about taking use of this Technology in our Safety and Health. This project will focus on analyzing some trends in requirement of Healthcare Facility like Accident Prone areas. We will further plot the coordinates of the most appropriate place for planting an Ambulance Centre. We will be reading various Research papers for this purpose as mentioned below and will therefore try to bring up a good and unified solution.

So, our project was based on plotting the Ambulance Centres and doing Accident Data Analysis to make these Centres, more efficient.

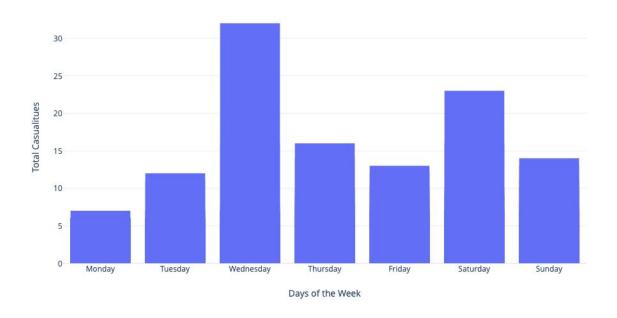
DATASET DESCRIPTION

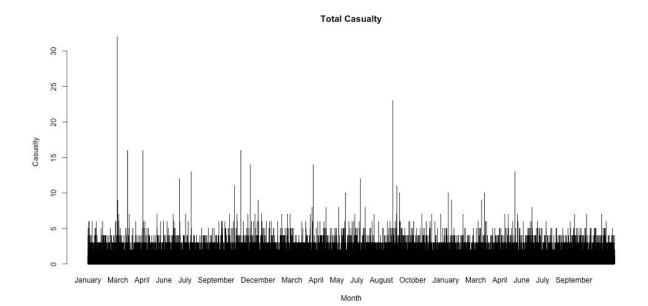
It is an Accident Dataset of Australia with the following features:

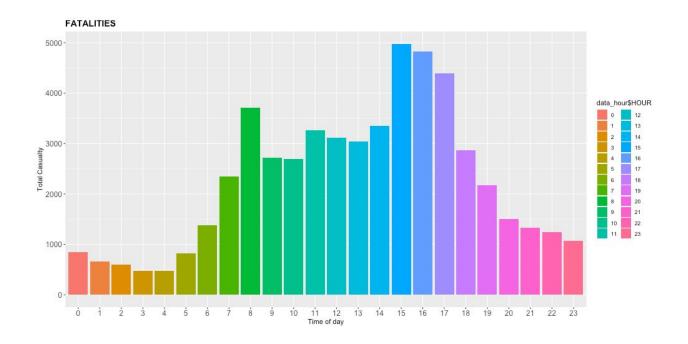
S. No.	Name of the Field	28	Crash_Roadway_Feature
1	Crash_Ref_Number	29	Crash_Traffic_Control
2	Crash_Severity	30	Crash Speed Limit
3	Crash_Year		
4	Crash_Month	31	Crash_Road_Surface_Condition
5	Crash_Day_Of_Week	32	Crash_Atmospheric_Condition
6	Crash_Hour	33	Crash_Lighting_Condition
7	Crash_Nature	34	Crash Road Horiz Align
8	Crash_Type	35	Crash Road Vert Align
9	Crash_Longitude_GDA94		
10	Crash_Latitude_GDA94	36	Crash_DCA_Code
11	Crash_Street	37	Crash_DCA_Description
12	Crash_Street_Intersecting	38	Crash_DCA_Group_Description
13	Loc_Suburb	39	Count Casualty Fatality
14	Loc_Local_Government_Area		THE THERE IS NOT THE AT
15	Loc_Post_Code	40	Count_Casualty_Hospitalised
16	Loc_Police_Division	41	Count_Casualty_MedicallyTreated
17	Loc_Police_District	42	Count_Casualty_MinorInjury
18	Loc_Police_Region	43	Count_Casualty_Total
19	Loc_Queensland_Transport_Region	44	Count Unit Car
20	Loc_Main_Roads_Region		2000 100 - 1
21	Loc_ABS_Statistical_Area_2	45	Count_Unit_Motorcycle_Moped
22	Loc_ABS_Statistical_Area_3	46	Count_Unit_Truck
23	Loc_ABS_Statistical_Area_4	47	Count_Unit_Bus
24	Loc_ABS_Remoteness	48	Count Unit Bicycle
25	Loc_State_Electorate		
26	Loc_Federal_Electorate	49	Count_Unit_Pedestrian
27	Crash_Controlling_Authority	50	Count_Unit_Other

WORKING

Phase 1: Visualizing of Dataset using R:







R Code:

```
data<-read.csv("locations_data.csv", header=T)
 names(data)
 ##creating subset of data
 accident <- data
 names(accident)
 #month
 accident$Crash_Month <- factor(accident$Crash_Month
                               nactor(acctaents_rash_Monton
, levels=c(1,2,3,4,5,6,7,8,9,10,11,12)
, labels=c( "January","Feburary","March","April"
,"May","June","July","August"
,"September","October","November","December"))
 accident$Crash_Severity <- factor(accident$Crash_Severity
                                     , levels=c(1,2,3,4,5)
, labels=c( "Property damage only", "Minor injury", "Medical treatment", "Hospitalisation"
, "Fatal"))
 #Lighting Condition
 accident \$ Crash\_Lighting\_Condition <- factor(accident \$ Crash\_Lighting\_Condition)
                                         , levels=c(1,2,3,4,5)
, labels=c( "Unknown", "Daylight", "Dawn/Dusk", "Darkness - Lighted"
, "Darkness - Not lighted"))
 #Lighting Condition
 accident$Crash_Speed_Limit <- factor(accident$Crash_Speed_Limit
                                                     , levels=c(1,2,3,4,5)
, labels=c( "0 - 50 km/h","60 km/h","70 km/h","80 - 90 km/h"
,"100 - 110 km/h"))
 #Removing null values
accident <- accident[rowSums(is.na(accident)) == 0,]
png(file = "barchart_stacked.png")</pre>
 barplot(accident$Count_Casualty_Total, main = "Total Casualty", names.arg = accident$Crash_Month, xlab = "Month", ylab = "Casualty", col="blue")
 dev.off()
 ##### Fatalities by hour ###########
 library(gaplot2)
library(data.table)
                                      ,legend.position="right"
(Tan Lauri) A
```

Phase 2:

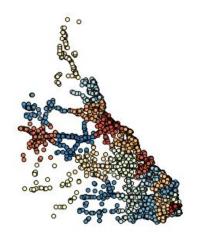
Applying DBSCAN and K- Mean Clustering to our data.

```
#Importing Libraries
 #DBSCAN
 import numpy as np
 import matplotlib.pyplot as plt
 import pandas as pd
 import scipy
 from sklearn.cluster import DBSCAN
 from sklearn import metrics
 #Importing Dataset
dataset = pd.read_csv('locations_data.csv')
 X = dataset.iloc[:,[8,9]].values
 db = DBSCAN(eps=0.3, min_samples=10).fit(X)
 core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
 core_samples_mask[db.core_sample_indices_] = True
 labels = db.labels_
 n_clusters_ = len(set(labels)) - (1 if -1 in labels else 0)
 print('Estimated number of clusters: %d' % n_clusters_)
#PLOT
 import matplotlib.pyplot as plt
   # Black removed and is used for noise instead.
 unique_labels = set(labels)
 colors = plt.cm.Spectral(np.linspace(0, 1, len(unique_labels)))
 for k, col in zip(unique_labels, colors):
    if k == -1:
         col = 'k'
     class_member_mask = (labels == k)
     xy = X[class_member_mask & core_samples_mask]
     plt.plot(xy[:, 0], xy[:, 1], 'o', markerfacecolor=col,markeredgecolor='k', markersize=14)
xy = X[class_member_mask & ~core_samples_mask]
     plt.plot(xy[:, 0], xy[:, 1], 'o', markerfacecolor=col,markeredgecolor='k', markersize=6)
 plt.title('Estimated number of clusters: %d' % n_clusters_)
 plt.show()
```

```
#Importing Libraries
#KMEANS
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.cluster import KMeans
from collections import Counter
#Importing Dataset
dataset = pd.read_csv('locations_data.csv')
X = dataset.loc[:,['Crash_Longitude_GDA94','Crash_Latitude_GDA94']]
kmeans = KMeans(n_clusters=id_n, random_state=0).fit(X)
id_label=kmeans.labels_
ptsymb = np.array(['b.','r.','m.','g.','c.','k.','b*','r*','m*','r^']);
plt.figure(figsize=(12,12))
plt.ylabel('Longitude', fontsize=12)
plt.xlabel('Latitude', fontsize=12)
for i in range(id_n):
    cluster=np.where(id_label==i)[0]
    plt.plot(X.Crash_Longitude_GDA94[cluster].values,X.Crash_Latitude_GDA94[cluster].values,ptsymb[i])
plt.show()
#Adding to the main dataset
import csv
rows=[]
fields=[]
with open('locations_data.csv','r') as csv_input:
    csvreader= csv.reader(csv_input)
    fields=next(csvreader)
    for row in csvreader:
         rows.append(row)
fields.append("CLUSTERS_with_KMEAN")
i=0
for row in rows:
    row.append(id_label[i])
with open('locations_data.csv', 'w') as csvfile:
    csvwriter=csv.writer(csvfile)
    csvwriter.writerow(fields)
    csvwriter.writerows(rows)
```

Phase 3:

Visualizing The Results of our Clusters in QGIS.



Phase 4:

Read some Research Papers and Working on Possibilities of:

- 1. Spatial Decision Tree (ID3 or CART)
- 2. SPODT: Spatial Oblique Decision Tree in R
- 3. Hidden Markov Model on Accident Data Analysis

REFERENCES (RESEARCH WORK)

1. Analysis of Road Traffic Fatal Accidents Using Data Mining Techniques

This paper follows the Approach of:

Statistical Analysis + Associative Rule Learning + Classification + Clustering on Accident Data.

2. Geographical Information System for Mapping Accident-Prone Roads and Development of New Road Using Multi-Attribute Utility Method

This paper follows the Approach of:

Multi Attribute Utility Theory with Spatial

3. Analyzing the Road Traffic and Accidents with Classification Techniques

This paper follows the Approach of:

Comparing many Classifiers like:

Naive Bayesian Classifier, Decision Tree Classifier, AdaBoostM1 Classifier

4. A Decision Tree for Multi-Layered Spatial Data

This paper offers an Algorithm for Spatial Decision Tree with CART (SCART)

5. A Spatial Entropy-Based Decision Tree for Classification of Geographical Information

This paper offered the approach of Spatial Decision Tree in 2006.

6. Spatial Decision Tree for Accident Data Analysis

This paper by IITK students applied the approach of above paper on Accident Data.

7. SPODT: An R Package to Perform Spatial Partitioning

This paper introduces a built-in R package for Spatial Oblique Decision Trees.

8. Crash Detection System Using Hidden Markov Models

This paper offers Approach of discrete Hidden Markov Models on real time accident Data using Jack-Knifing Cross validation.

9. Using Hidden Markov Models in Vehicular Crash Detection

This paper has presented a methodology for building a crash detection system using continuous-mode HMMs and has established the proposed strategy to be a robust methodology for early detection of automotive crashes.

10. Traffic Incident Prediction on Intersections Based on HMM

This paper uses HMM on input from Video Cameras at traffic Intersection to improve the detection rate of accidents, ease traffic jams, and reduce traffic accidents