

Steady State AC Analysis

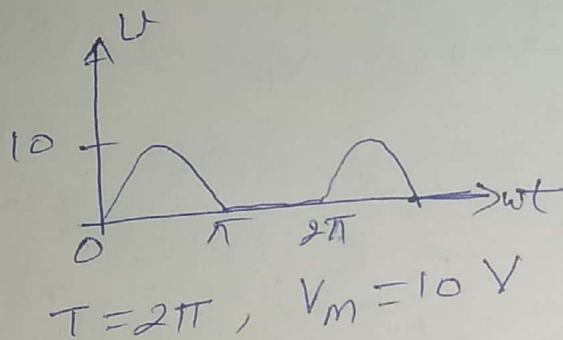
Tutorial sheet No. 2

1) $f = 50 \text{ Hz}$, $I_{\text{rms}} = 20 \text{ A}$
 $I_m = \sqrt{2} I_{\text{rms}} = 20\sqrt{2}$
 $\omega = 2\pi f = 2\pi \times 50 = 100\pi$

$$i = I_m \sin \omega t$$

$$= 20\sqrt{2} \sin(100\pi t) \quad \underline{\text{Ans}}$$

2)



$$V_{\text{av}} = \frac{1}{T} \int_0^T u \, dwt$$

$$= \frac{1}{2\pi} \left[\int_0^{\pi} V_m \sin \omega t \, dwt + \int_{\pi}^{2\pi} 0 \, dwt \right]$$

$$= \frac{1}{2\pi} \times V_m \left[\int_0^{\pi} \sin \omega t \, dwt \right] = \frac{V_m}{2\pi} \left(-\cos \omega t \right)_0^{\pi}$$

$$= \frac{V_m}{2\pi} [-\cos \pi + \cos 0]$$

$$= \frac{V_m}{2\pi} [1 + 1] = \frac{V_m}{\pi} = \frac{10}{\pi} = 3.18 \text{ V} \quad \underline{\text{Ans}}$$

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T u^2 \, dwt} = \sqrt{\frac{1}{2\pi} \int_0^{\pi} (V_m \sin \omega t)^2 \, dwt + 0}$$

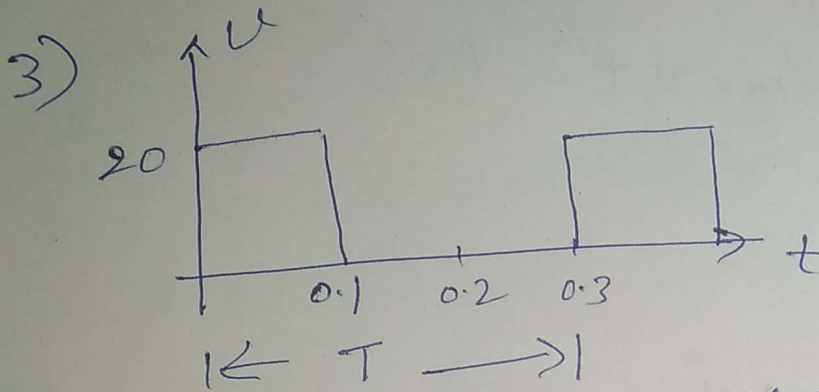
$$= \left[\frac{V_m^2}{2\pi} \int_0^{\pi} \sin^2 \omega t \, dwt \right]^{\frac{1}{2}} = \left(\frac{V_m^2}{2\pi} \int_0^{\pi} \frac{1 - \cos 2\omega t}{2} \, dwt \right)^{\frac{1}{2}}$$

$$= \left[\frac{V_m^2}{2\pi} \left[\frac{\omega t}{2} - \frac{\sin 2\omega t}{4} \right]_0^{\pi} \right]^{\frac{1}{2}} = \left[\frac{V_m^2}{2\pi} \left[\frac{\pi}{2} - 0 - \frac{0}{4} + \frac{0}{4} \right] \right]^{\frac{1}{2}}$$

$$V_{\text{rms}} = \frac{V_m}{2} = \frac{10}{2} = 5 \text{ V} \quad \underline{\text{Ans}}$$

$$k_f = \frac{V_{\text{rms}}}{V_{\text{av}}} = \frac{5}{3.18} = 1.57 \quad \underline{\text{Ans.}}$$

$$R_p = \frac{V_m}{V_{\text{rms}}} = \frac{10}{5} = 2 \quad \underline{\text{Ans}}$$



$$T = 0.3 \text{ Sec}$$

$$V_m = 20 \text{ V}$$

$$u = 20 \quad 0 \leq t < 0.1$$

$$= 0 \quad 0.1 \leq t < 0.3$$

$$V_{\text{av}} = \frac{1}{T} \int_0^T u \, dt = \frac{1}{0.3} \int_0^{0.3} u \, dt = \frac{1}{0.3} \left[\int_0^{0.1} 20 \, dt + 0 \right]$$

$$= \frac{1}{0.3} \times 20 \left[\int_0^{0.1} dt \right] = \frac{20 \times 0.1}{0.3} = \frac{20}{3}$$

$$V_{\text{av}} = 6.67 \text{ V}$$

Ans

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T u^2 \, dt} = \sqrt{\frac{1}{0.3} \left(\int_0^{0.1} 20^2 \, dt \right)}$$

$$= \sqrt{\frac{400 \times 0.1}{0.3}}$$

$$= 11.5 \text{ V} \quad \underline{\text{Ans}}$$

4) (A) $v = \sqrt{2}(50) \sin(377t - 35^\circ)$

$$V_{rms} = \frac{V_m}{\sqrt{2}} ; V_m = \sqrt{2} \times 50 \quad \left| \begin{array}{l} \text{Compare with} \\ v = V_m \sin(\omega t + \theta) \\ \theta = -35^\circ \end{array} \right.$$

$$= 50V$$

$$\text{Phase} = -35^\circ$$

(B) $v = 83.3 \sqrt{2} \times (90.4) \sin(754t + 48^\circ)$

$$V_m = \sqrt{2} \times 90.4$$

$$V_{rms} = \frac{V_m}{\sqrt{2}} = 90.4V$$

$$\theta = 48^\circ$$

(C) $v = 83.6 \cos(400t - 15^\circ)$

$$v = 83.6 \sin(400t - 15^\circ + 90^\circ) ; \sin(90^\circ + \theta) = \cos \theta$$

$$v = 83.6 \sin(400t + 75^\circ)$$

$$V_m = 83.6 , \theta = 75^\circ$$

$$V_{rms} = \frac{83.6}{\sqrt{2}} = 59.1V$$

(D) $i = 3.46 \cos(815t + 30^\circ) = 3.46 \sin(815t + 30^\circ + 90^\circ)$

$$= 3.46 \sin(815t + 120^\circ)$$

$$I_m = 3.46 A , \theta = 120^\circ$$

$$I_{rms} = \frac{3.46}{\sqrt{2}} , \theta = 120^\circ$$

$$= 2.45 A , \theta = 120^\circ$$

(5) (a) $6 + j9 = 10.8 \angle 56.3^\circ \rightarrow$ use scientific calculator to convert

(b) $-21.4 + j33.3 = 39.6 \angle 122.7^\circ$

(6) (a) $6.21 + j3.24 + 4.134 - j9.47$

$$= 6.21 + 4.13 + j(3.24 - 9.47)$$

$$= 10.34 - 6.23j$$

$$\begin{aligned}
 \textcircled{b} \quad & 7.34 - j1.29 - (5.62 + j0.92) \\
 & = 7.34 + (-5.62) - j1.29 - j0.92 \\
 & = 1.72 - j6.23
 \end{aligned}$$

$$\begin{aligned}
 \textcircled{c} \quad & -24 + j12 - (-36 - j16) - (17 - j24) \\
 & = -24 + 36 - 17 + j(12 + 16 + 24) \\
 & = -5 + j52
 \end{aligned}$$

$$\begin{aligned}
 \textcircled{7} \quad (a) \quad & (4 + j2)(3 + j4) = 4.472 \angle 26.56^\circ \times 5 \angle 53.13^\circ \\
 & = 22.36 \angle 79.69^\circ = 4 + j21.998 \\
 & * \text{use scientific calculator}
 \end{aligned}$$

$$\begin{aligned}
 \textcircled{b} \quad & (6 + j2)(3 - j5)(2 - j3) \\
 & = (6.3245 \angle 18.4349^\circ)(5.83 \angle -59.036^\circ)(3.6 \angle -56.31^\circ) \\
 & = 132.644 \angle -96.9111^\circ \\
 & = -15.96 - j131.68
 \end{aligned}$$