

17 Inter Process Communication (IPC)

Inter process communication is a mechanism for processes to communicate and to synchronize their actions.

There are two main models of IPC

1. Shared memory: A region of memory is shared between processes. Each can read/write to it.
2. Message passing: Processes send and receive messages to communicate without shared memory.

If processes don't share memory, they use message passing (pipes, queues, sockets). If they can share memory, they use shared memory and synchronization mechanisms. OS provides IPC facilities to make this safe and efficient.

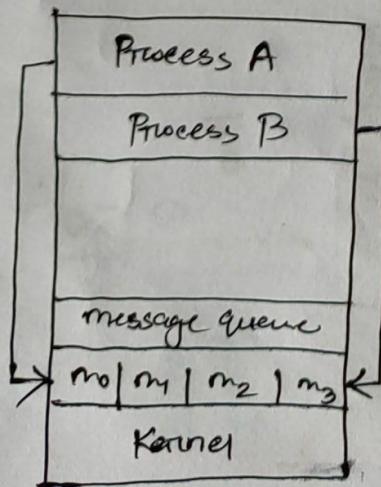


Fig: message passing

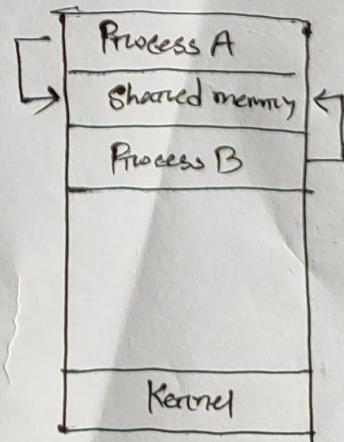


Fig: shared memory

Remote Procedure Call (RPC)

Remote Procedure Call (RPC) is a method that allows a program on one machine (client) to call a procedure on another machine (server) like a local procedure call.

It hides the details of network communication using stubs and message passing to transfer data between client and server.

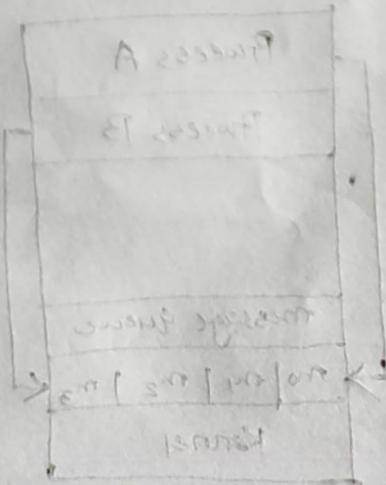
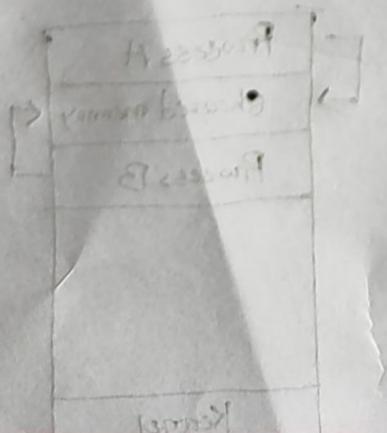
The remote procedure call contains

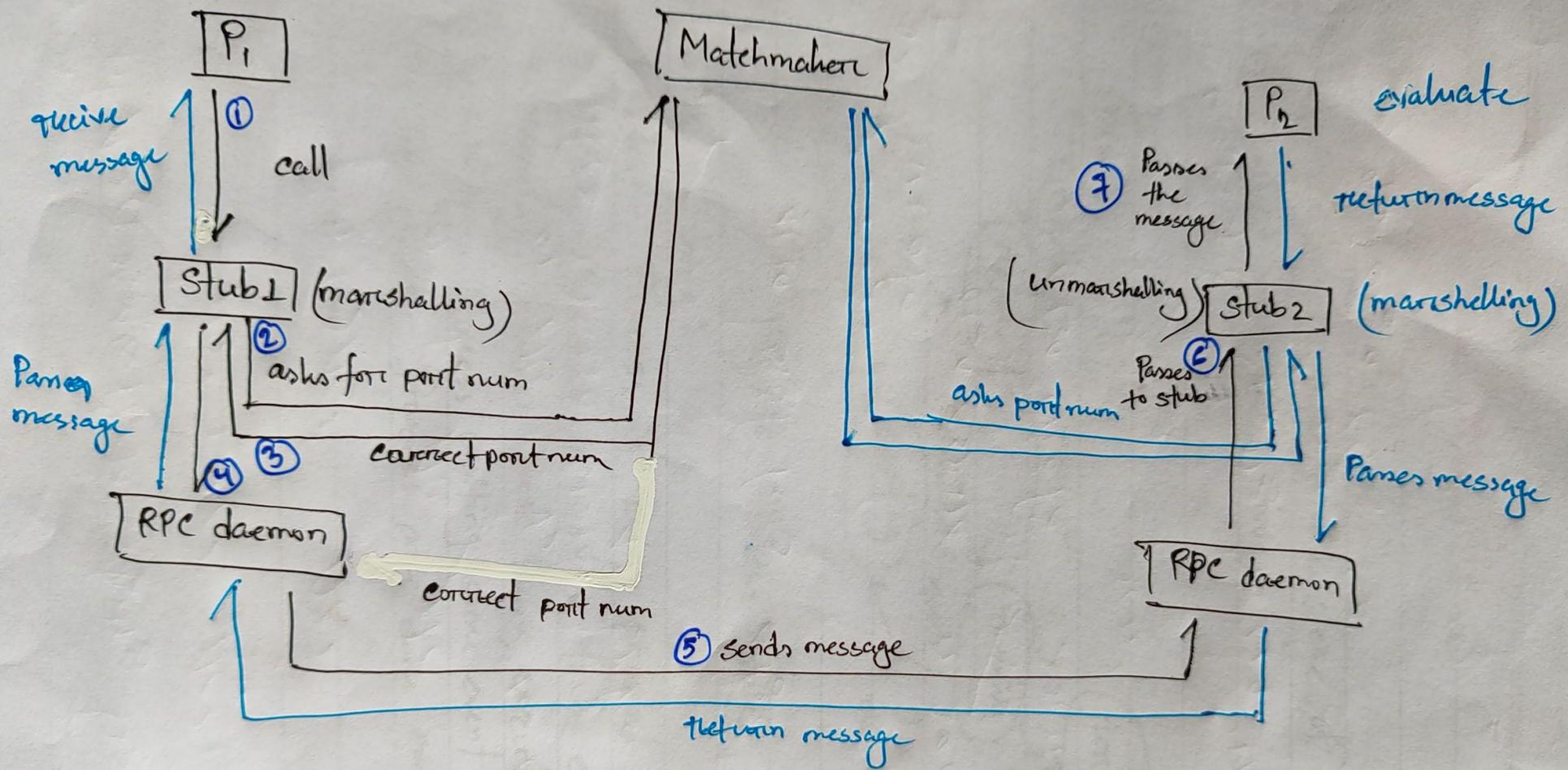
Stub - acts as local proxy, Pads & unpacks (marshalls and unmarshalls) messages

Matchmaker - finds correct server and port

Daemon - acts as listener component

A request bus stub with address at address





বিষয় :
তারিখ : সময় :

Process State

What is Process State? Process state represents the stage of execution of a process at any given time.

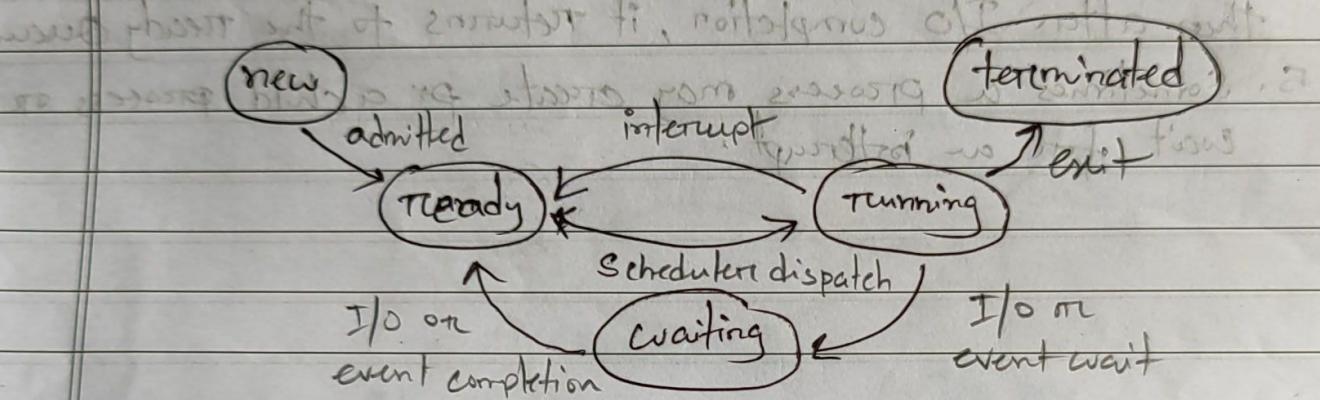


Figure: Process State

How its working?

1. New - Process is being created
2. Ready - Process is waiting to be executed by the CPU
3. Running - Process are being executed by the CPU
4. Waiting - Process waiting some event to finish.
5. Terminated - Process are done comp execution.

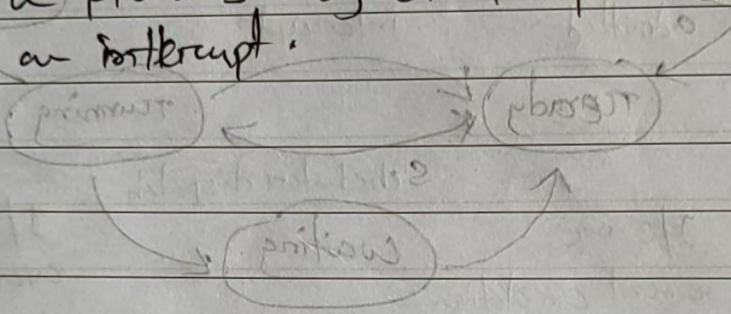
How it works?

বিষয় :

তারিখ :

সময় :

১. Processes first go into ready queue.
২. The CPU executes one process at a time.
৩. If the time slice expires → Process goes back to Ready Queue.
৪. If the process needs I/O → it moves to I/O queue, waits then after I/O completion, it returns to the ready queue.
৫. Sometimes a process may create or a child process or wait for an interrupt.



নথি দেখো সহজ

between period এই ক্ষেত্রে - work . ।

প্রথম অন্তর্বর্তীক মধ্যে ক্ষেত্রে - p100 . ২

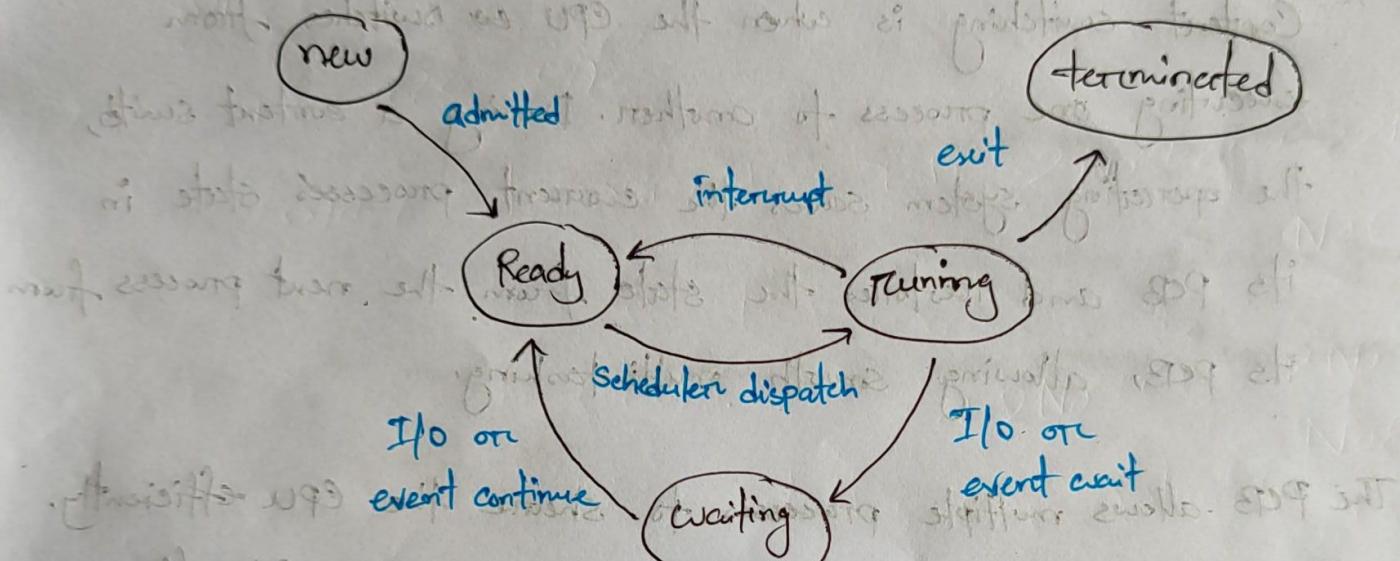
প্রথম অন্তর্বর্তীক মধ্যে ক্ষেত্রে - p200 . ৩

দ্বিতীয় মধ্যে ক্ষেত্রে - p300 . ৪

তৃতীয় মধ্যে ক্ষেত্রে - p400 . ৫

(839) Process State

Process state represents the stage of execution of a process at any given time.



As a process executes, it changes state.

New: Process is being created

Running:

Ready: Process is waiting to be executed by the CPU

Running: Process instructions are being executed by the CPU

Waiting: Process waiting for some event to finish.

Terminated: Process are done execution

Process Control Block (PCB)

— A process control Block or PCB is a data structure used by the operating system to manage process by storing critical information about each process's execution.

Context switching is when the CPU switches from executing one process to another. During a context switch, the operating system saves the current process's state in its PCB and restores the state of the next process from its PCB, allowing smooth multitasking.

The PCB allows multiple processes to share the CPU efficiently. Without PCB, the process would "forget" where it left off. Since each process has its own PCB, they don't interfere with each other.

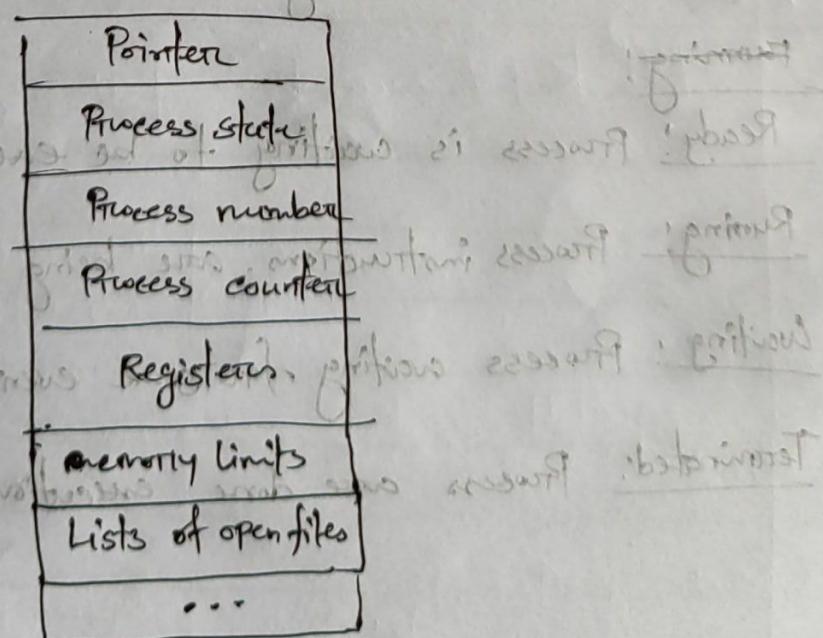


Fig: Process Control Block (PCB)

Context switch

A context switch is a mechanism which allows the CPU to switch execution between processes, ensuring multitasking and efficient CPU utilization.

Steps:

1. Save the state of the current running process
2. Load the save state of the next scheduled process.
3. Continue execution of the new process from where it left off.

Socket.

A socket is an endpoint for communication between two machines over a network.

Socket = IP Address + Port

How it works?

Client creates a socket



Server has a socket open



Connection happens



Data is sent and received



Connection closes

Process Scheduling

Process scheduling is mechanism of deciding which process will run on the CPU next.

It chooses processes from ready queue.

Types of Queues: Scheduling \leftarrow various with diff. eff.

- 1. Job queue: set of All processes in the system.
- sometimes the only schedule
 - 2. Ready queue: set of processes in the memory waiting to be executed.
 - 3. Device queues set of processes waiting for an I/O devices

Representation of process scheduling

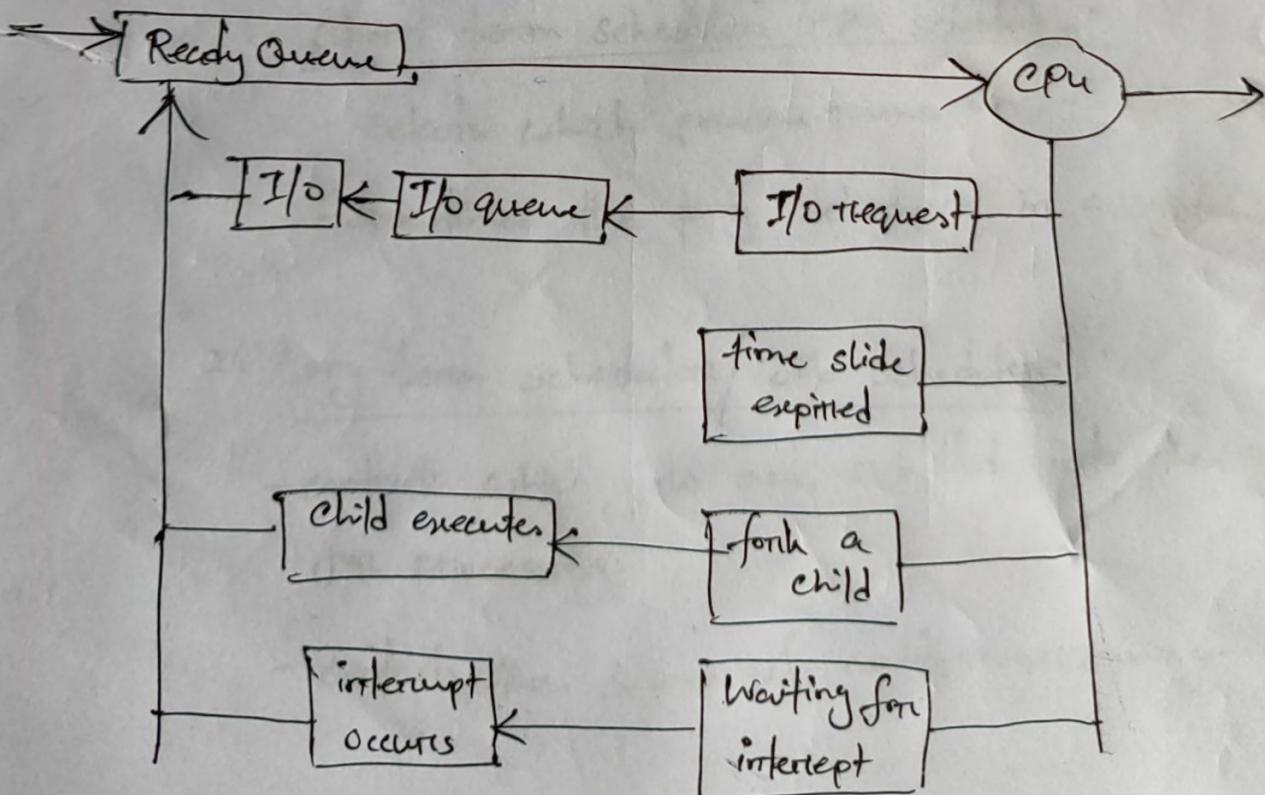


Fig: Queueing diagram

Scheduler

A scheduler is a key component of an operating system that determines which process should run at any given time. The main role is to optimize CPU utilization.

Scheduler decides which process runs on the CPU, while process goes to the ready queue. [existing two because] which waits for I/O

Scheduler is critical in time-slicing system and multiprogramming environments.

Types of Schedulers

CF

1. Short term scheduler / CPU scheduler:

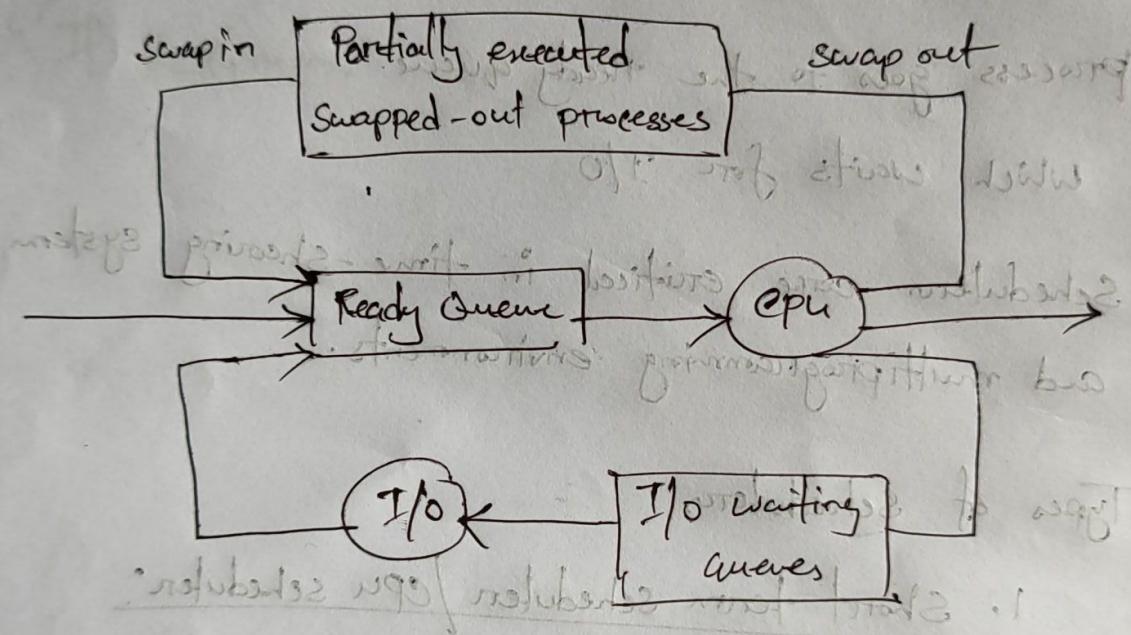
- selects which process runs on the CPU next.
- sometimes the only scheduler in a system.

2. Long term scheduler / Job scheduler

- controls which jobs are admitted into the system for processing.
- controls the degree of multiprogramming

iii) Medium term scheduler

using CPU to swap blocks between processes to balance CPU utilization and I/O usage.



changes in no error message details etc.

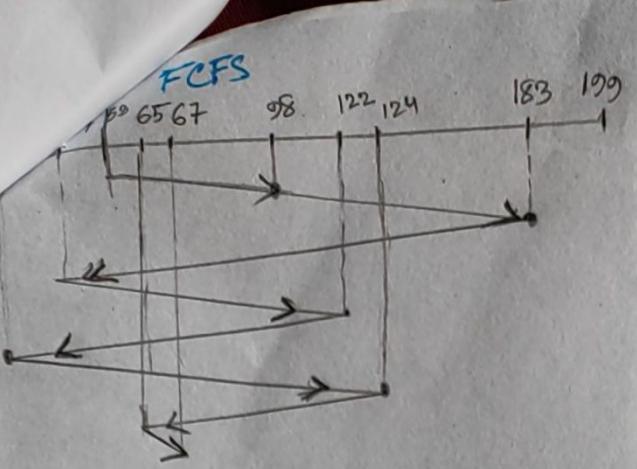
changes in I/O with conditions -

changes do not affect program -

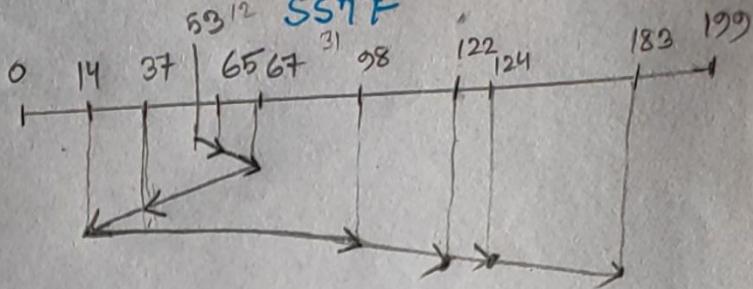
changes in disk controller and disk start time -

processing job

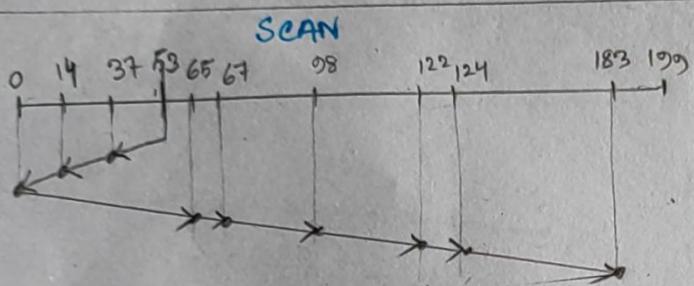
transformation of swapped out starting -



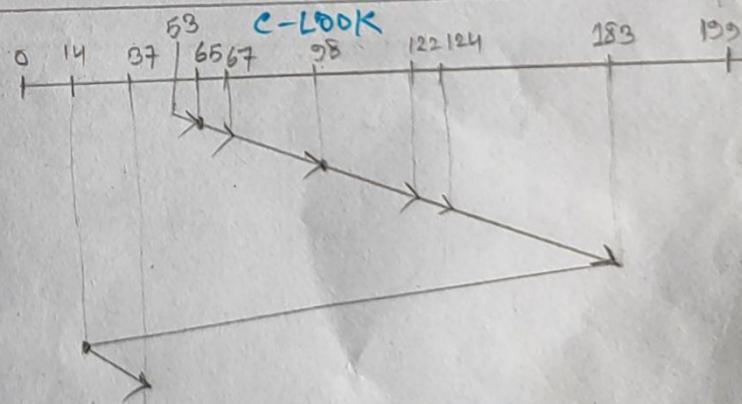
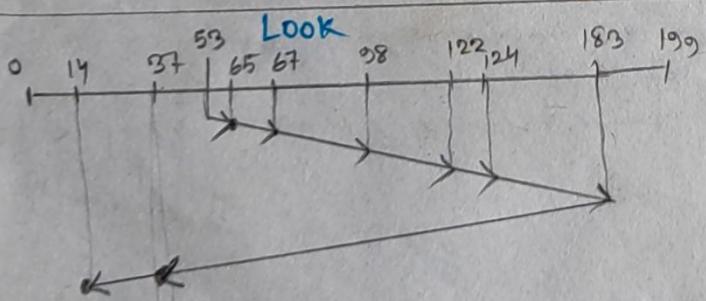
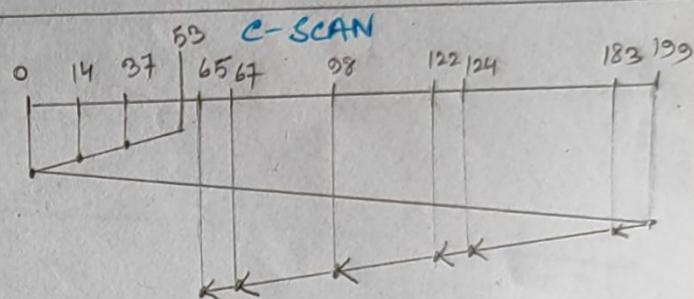
* যে আজ আব্দুর সান্ত আজ Touch করলে



* বাইকারি প্র ওয়ে, তাৰ আপ্ত Touch কৰলে।



* যদিক যাব, তবম্বলো Touch কৰে **edge** এ যাব,
then তাম্বলো আব্দুর তাৰ �sea touch কৰিব।



Illustrate scheduling algo
with a req. quest queue

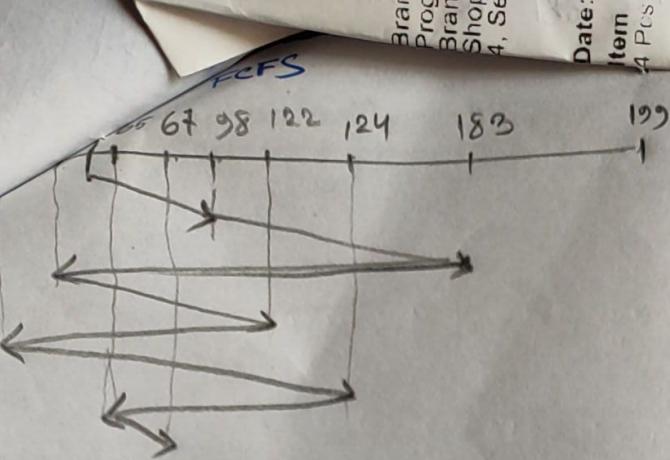
98, 183, 37, 122, 14, 124, 65, 67

Head pointer 53

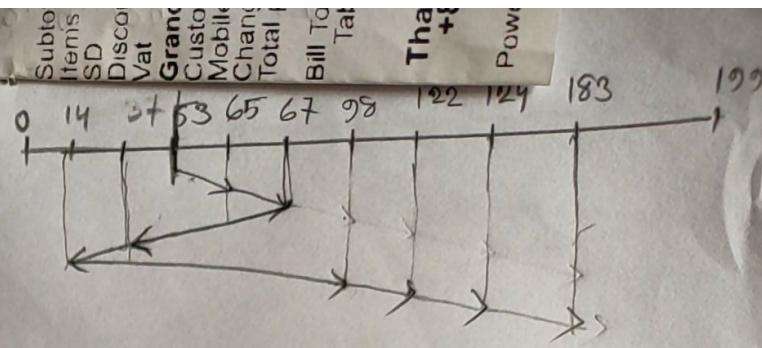
→ 14, 37, 65, 67, 98, 122, 124, 183

* Total num of head movement
=

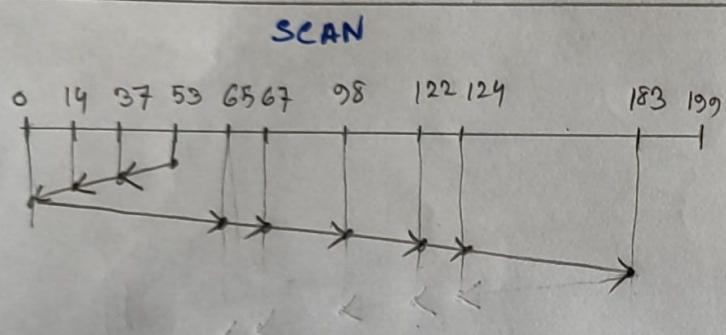
* Total Time = Total num of head movement
X per head movement



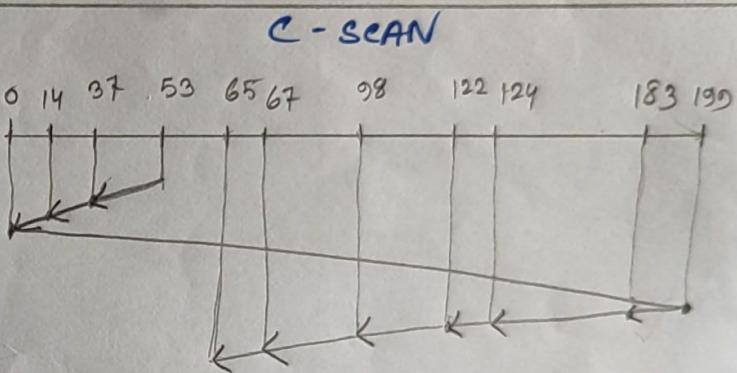
* মেটা ওজন অন্তর্ভুক্ত স্টিম্ব লেবেল touch করবে।



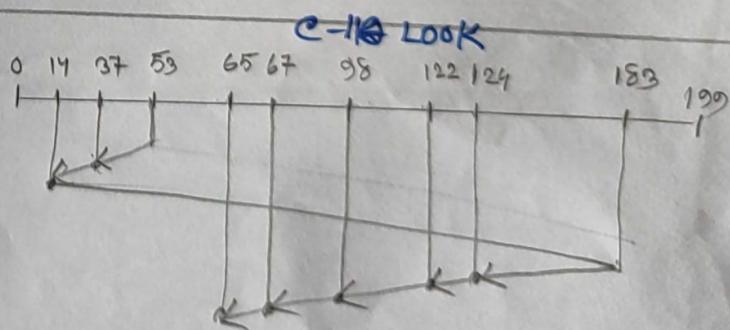
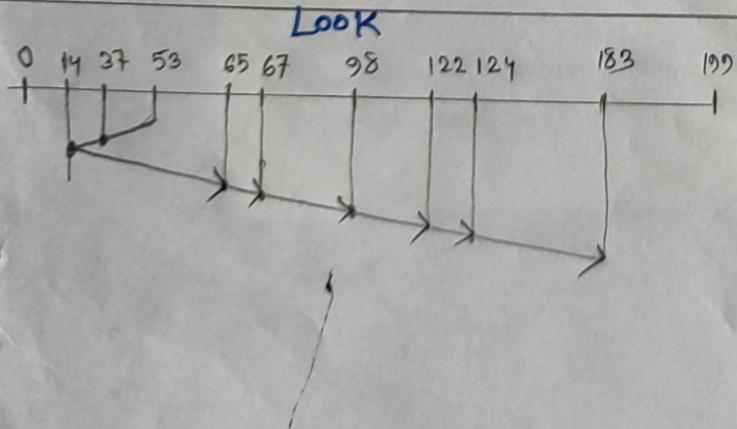
* starting point এরে পৰি কাহো আছে, প্ৰথম গুৰুত্ব
পৰাপৰ।

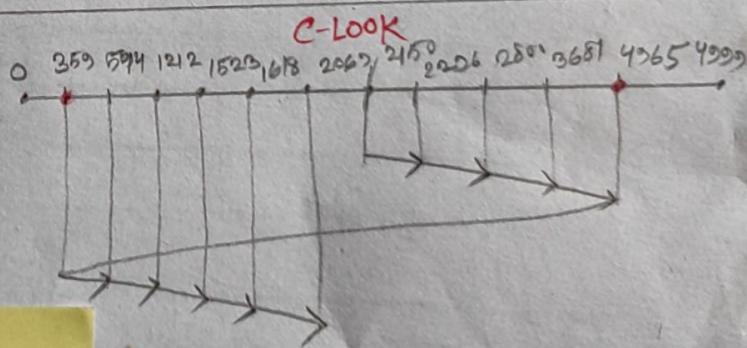
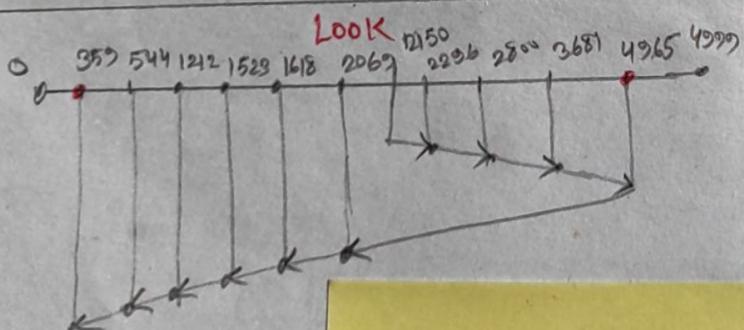
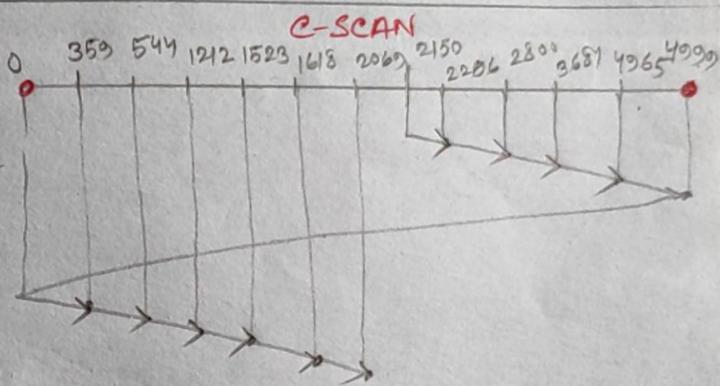
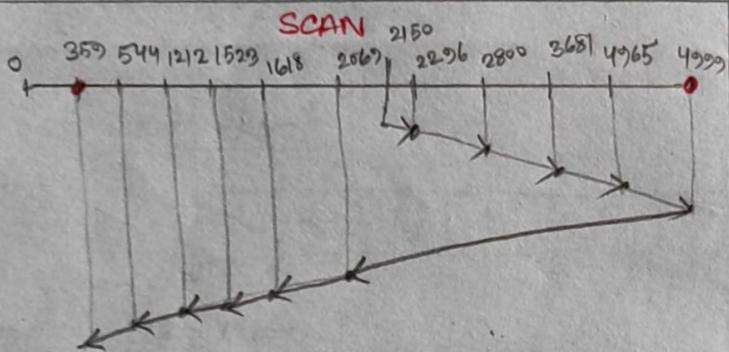
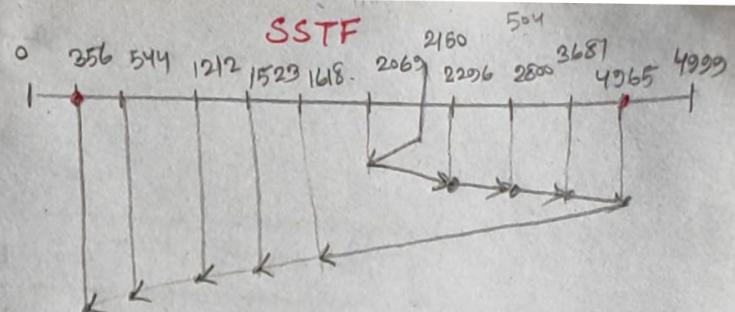
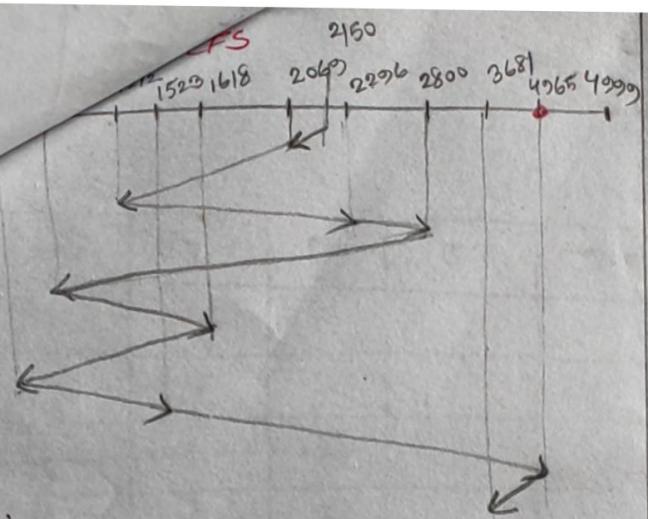


* পৰিকল্পনা প্ৰয়োগ কৰতে, একদম কেবল
কানাম স্থান,



* কুইডি স্থান লেবেল touch কৰবে





Cylinders (0-4999)

head pointer 2150

2069, 1212, 2296, 2800, 544,
1618, 356, 1523, 4965, 3681

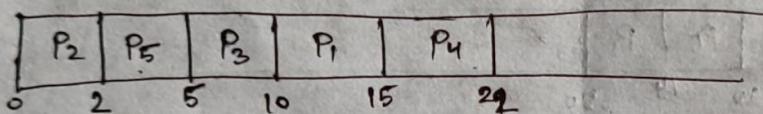
CSorted

356, 544, 1212, 1523, 1618, 2069,
2296, 2800, 3681, 4965

SJF
 (Non-Preemptive)

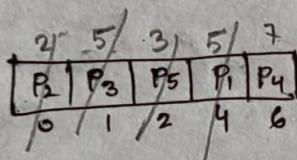
Process	AT	BT	CT	TAT	Wait	ResponseT
P ₁	4	5				
P ₂	0	2				
P ₃	1	5				
P ₄	6	7				
P ₅	2	3				

Gantt chart



*Burst time calculation
 -3x8=24

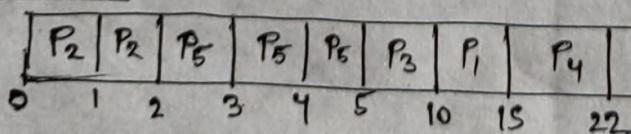
Ready Queue:



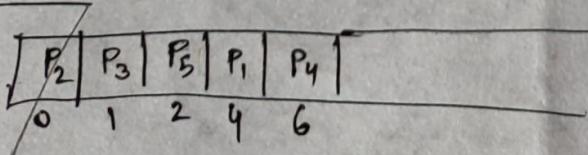
(Pre-emptive)

Process	AT	BT	CT	TAT	WAT	RT
P ₁	4	5				
P ₂	0	2				
P ₃	1	5				
P ₄	6	7				
P ₅	2	3				

Gantt chart:



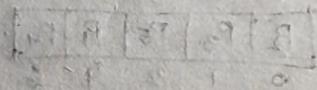
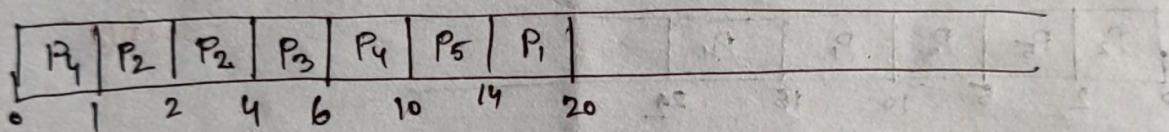
Ready Queue:



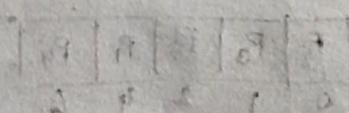
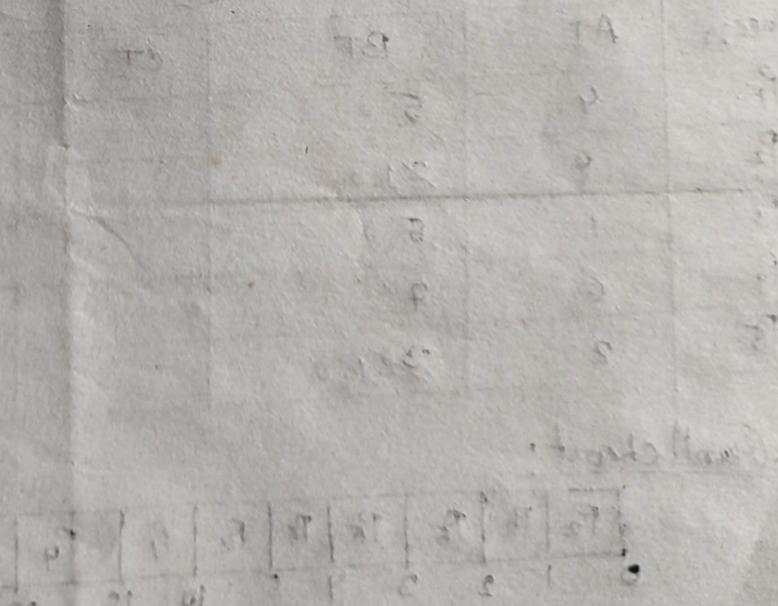
(SRTF)
(Pre-emptive)

Process	AT	BT	CT	TAT	DWT	RT
P ₁	2	6				
P ₂	1	3 2 0				
P ₃	4	2 0				
P ₄	0	5 4 0				
P ₅	6	4 0				

Gantt chart:



(non pre-emptive)



Operating System

Chapter-6

CPU Scheduling

CPU Scheduling: it is the process used by the operating system to choose which process/task will use the CPU next from the queue.

- It is the basis for multiprogrammed operating system. Where multiple processors are ready to run but only one can use the CPU at a time.
- The goal is to maximize the CPU utilization and ensure fair and efficient process management.

Terms we'll use:

Throughput - Number of processes that complete their execution per time unit.
$$\frac{\text{No. of Processes}}{\text{Total unit of Time}}$$

Turnaround Time - amount of time to execute a particular process.
Completion time - Arrival time

Waiting Time - amount of time a process has been waiting in the ready queue
Turnaround time - Burst time

Response Time - time from when a process arrives to when it starts executing.

Start of process execution - Arrival of process

Scheduling Algorithm Optimization criteria

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting response
- Min response time

Turn Around Time = Completion - Arrival
 Waiting Time = T.A.T - Burst Time
 Response time =
 1st time Processor gets the CPU — Arrival time

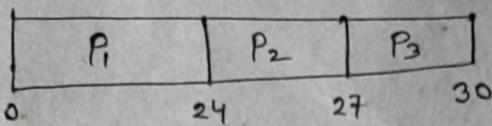
First Come First Served

[FCFS]

Process ID	Burst Time	Arrival Time
P ₁	24	0
P ₂	3	0
P ₃	3	0

Q: The order of arrival is P₁, P₂, P₃. Calculate Average Waiting time, Turnaround time and Avg Response time

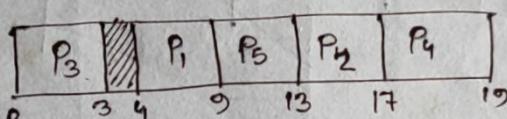
Gantt chart



Process ID	Burst Time	Arrival Time	Turnaround Time	Waiting time	Response time
P ₁	24	0	24 - 0 = 24	0	0
P ₂	3	0	27 - 0 = 27	27 - 3 = 24	24
P ₃	3	0	30 - 0 = 30	30 - 3 = 27	27
		Avg = 27	Avg = 27	Avg = 17	Avg = 17

Q. 2.

Gantt chart



Process ID	Burst time	Arrival time	Turnaround time	Waiting time	Response time
P ₁	5	4	0 - 4 = 5	5 - 5 = 0	4 - 4 = 0
P ₂	4	6	17 - 6 = 11	11 - 4 = 7	13 - 6 = 7
P ₃	3	0	3 - 0 = 3	3 - 3 = 0	0 - 0 = 0
P ₄	2	6	19 - 6 = 13	13 - 2 = 11	17 - 6 = 11
P ₅	4	5	13 - 5 = 8	8 - 4 = 4	0 - 5 = 4
			Avg = 8	Avg = 4.4	Avg = 4.4

Process ID	Burst time	Arrival time
P ₁	5	4
P ₂	4	6
P ₃	3	0
P ₄	2	6
P ₅	4	5

Q. Draw a Gantt chart of the

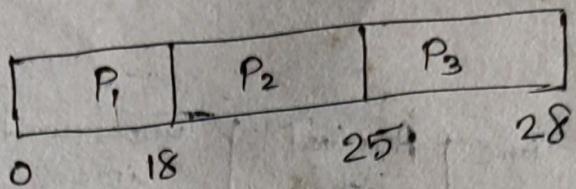
process.
Calculate Avg waiting time,
Turnaround time, Response time.

$$(1+8+10+12+14) / 5 = 8.8$$

$$(1+3+5+7+9) + \frac{3}{5} (0+4+6+8)$$

FCFS → always non-pre-emptive

Gantt Chart:



Process	BT Burst	AT Arrival	CT Completion time	TAT Turn Around Time	WT Waiting	RT Response
P ₁	18	0	18			
P ₂	7	0	25			
P ₃	3	0	28			

$$TAT = CT - AT$$

$$WT = TAT - BT$$

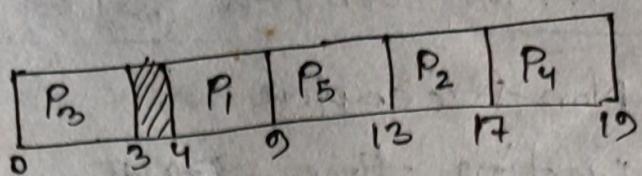
$$RT = WT \leftarrow \boxed{\text{Non-Pre-emptive}}$$

$$RT = ICT - AT \leftarrow \text{Arrival Time} \quad \boxed{\text{Pre-emptive}}$$

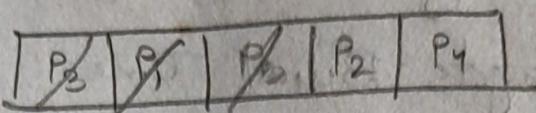
↳ Initial CPU Time

Practice

Grantt chart



Ready Queue



Process	AT	BT.	CT	TAT	WT	RT
P ₁	4	5	9	5	0	0
P ₂	6	4	17	11	7	7
P ₃	0	3	3	3	0	0
P ₄	6	2	19	13	11	11
P ₅	5	4	13	8	4	4

Avg

$$\text{Throughput} = \frac{5}{10} = 0.26$$

CPU



process for 0.26

into 5 units

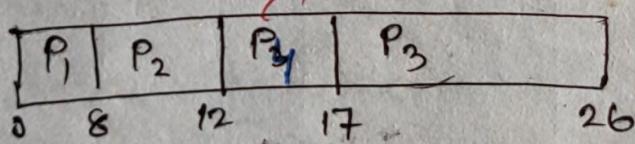
Shortest Job First (SJF)

- ↳ Non-preemptive
- ↳ waiting time \rightarrow wait
- ↳ Targets Burst Time

SJF (Slide Example)

Process	Arrival Time	Burst Time	Completion Time	TAT	WT	RT
P ₁	0	8	8	8	0	0
P ₂	1	4	12	11	7	7
P ₃	2	9	28	24	15	15
P ₄	3	5	17	14	9	9
				Avg = 14.25	Avg 7.75	Avg

Gantt Chart:



→ BTW Burst time \rightarrow 25

Throughput = $\frac{4}{26} = \frac{\text{No of Process}}{\text{Total unit of time}}$

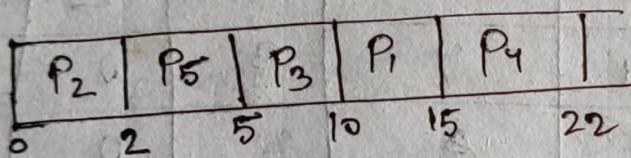
Ready Queue: $\boxed{\quad}$

$$= \frac{4}{26}$$

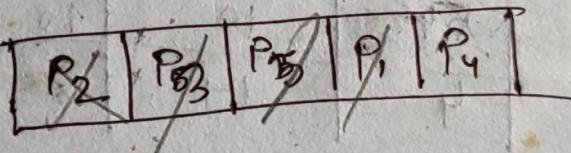
SJF Practice

Process	Arrival	Burst	Completion	TAT	WT	RT
P ₁	4	5	15	11	6	6
P ₂	0	2	2	2	0	0
P ₃	1	5	10	9	4	4
P ₄	6	7	22	16	9	9
P ₅	2	3	5	3	0	0
				Avg=8.2	Avg=3.8	

Gantt chart:



Ready Queue:



From Throughput = $\frac{5}{22}$

CPU overhead

SRTF: Shortest Remaining Time First

↳ SJF ও সামাজিক অভিযন্তা

SRTF

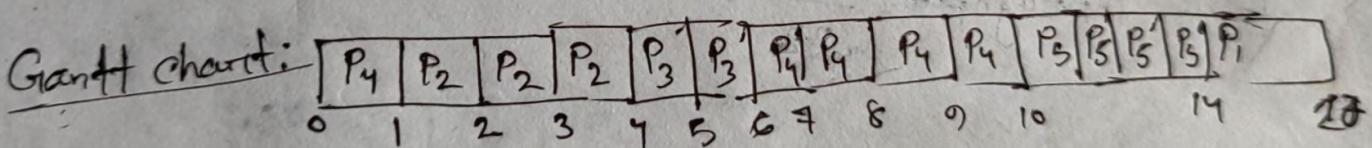
Pre-emptive

(1 TU)

SJF

Non-pre-emptive

Process	Arrived	Burst	Completion	TAT	WT	RT
P ₁	2	6	20	18	12	14 - 2 = 12
P ₂	1	3 2 X	9	3	0	1 - 1 = 0
P ₃	4	2 X	6	2	0	4 - 4 = 0
P ₄	0	5 4 3 2 X	10	10	3	0 - 0 = 0
P ₅	6	4	14	8	7	10 - 6 = 4



Ready Queue: P₄ P₂ P₁

0 (মুক্ত স্থিতি) 2 (র একটি উপরের রেখার পাশে)

