Kanishk Jain

□ mobile | ② email | in linkedin | ♀ github | ❖ webpage

EDUCATION

Université de Montréal

PhD in CSE; GPA: 4.3

International Institute of Information Technology

MS by Research in CSE; GPA: 9.33/10

International Institute of Information Technology

B. Tech (Honors) in ECE; GPA: 6.73/10

Montréal, Canada Sep 2023 – present Hyderabad, India Aug 2021 – Dec 2022 Hyderabad, India Aug 2013 – Jun 2017

Research Publications

Test-Time Amendment with a Coarse Classifier for Fine-Grained Classification

Paper

Kanishk Jain, Shyamgopal Karthik, Vineet Gandhi

NeurIPS 2023

• Introduced a post-hoc correction strategy that leverages coarse-grained predictions at test-time to reduce mistake severity and improve the accuracy of fine-grained classification

Instance-Level Semantic Maps for Vision Language Navigation

Paper

Laksh Nanwani, Anmol Agarwal, Kanishk Jain, et al.

ROMAN 2023

• Designed instance-level semantic maps enabling robust language-directed navigation across diverse environments.

Ground then Navigate: Language-guided Navigation in Dynamic Scenes

Paper

Kanishk Jain*, Varun Chhangani*, Amogh Tiwari, K Madhava Krishna, Vineet Gandhi

ICRA 2023

• Developed a novel visual-grounding approach for language-guided navigation in dynamic outdoor environments

Bringing Generalization to Deep Multi-View Pedestrian Detection

Papei

Jeet Vora, Swetanjal Dutta, Kanishk Jain, Shyamgopal Karthik, Vineet Gandhi

WACV-W 2023

 Formulated an innovative evaluation framework and dataset for benchmarking generalization in multi-view pedestrian detection systems.

Comprehensive Multi-Modal Interactions for Referring Image Segmentation

Paper

Kanishk Jain, Vineet Gandhi

ACL Findings 2022

• Proposed a novel architecture for Referring Image Segmentation, leveraging synchronous multi-modal interactions and hierarchical aggregation to enhance performance.

Grounding Linguistic Commands to Navigable Regions

Paper

Kanishk Jain*, Nivedita Rufus*, Unni Krishnan*, Vineet Gandhi, K Madhava Krishna

IROS 2021

• Introduced the task of Referring Navigable Regions (RNR), which involves grounding navigable road regions based on linguistic commands to facilitate language-guided autonomous navigation.

WORK EXPERIENCE

Université de Montréal | Mila

PhD Student

Sep 2023 - present

- Developing methods to automatically discover failure modes in Vision Language Models using Large Language Models in adversarial attack setups.
- Analyzing state space models to improve the efficiency of text-to-image generation.
- Investigating cultural understanding in Vision Language Models across diverse cultural contexts.

CVIT, IIIT Hyderabad

Research Engineer

Mar 2023 - Aug 2023

- Conducted research on reducing mistake severity in fine-grained classification using Hierarchical Ensembles, demonstrating significant improvements in both fully supervised and semi-supervised settings.
- Developed and deployed a player tracking solution in Bird's Eye View for live use during the 2022 Asia Cup.

CVIT, IIIT Hyderabad

Research Assistant Sep 2019 – Dec 2022

- Conducted research on language-guided autonomous navigation, focusing on explicit grounding of navigable regions and the integration of visual feedback.
- Developed multi-modal interaction techniques for referring image segmentation, enhancing the accuracy and efficiency of visual-linguistic model interactions.
- Developed an analytics tool for CSGO games, providing insights into winning strategies.

Turvo

Software Engineer

Jul 2017 - Aug 2019

- Integrated Xero Accounting Platform with Turvo platform using Pub-Sub messaging pattern for handling different accounting scenarios.
- Added capability of Batch Payment Processing to allow users to schedule and process multiple payments at once.
- OCR over Document Images using active learning based template detection for extracting information from unstructured documents.

Selected Projects

Top-View Player Tracking: Developed a player tracking solution in Bird's Eye View, deployed live during the 2022 Asia Cup Cricket Tournament.

Stereo SLAM: Generated 3D point clouds using stereo images and estimated motion/pose through 2D-3D correspondences with the iterative Perspective-n-Point (PnP) algorithm.

Pose Graph Optimization: Applied the Levenberg–Marquardt algorithm to optimize robot poses using Odometry and Loop Closure constraints for 1D and 2D SLAM.

Unity Game for Amblyopia: Developed a Unity game for diagnosing Amblyopia, controlled using eye gaze movements captured by an eye tracker.

Neuro Rehab Systems: Created a rehabilitation tool aimed at aiding recovery from nervous system injuries and minimizing functional alterations.

TECHNICAL STRENGTHS

Languages: Python, Java, C++, C#, Node JS, Javascript

Frameworks: PyTorch, Keras, Tensorflow, OpenCV, scikit-learn, scikit-image

Tools: CARLA, TensorRT, Open3D, Unity 3D, Matlab, Spring Boot, Maven, REST

Databases: MySQL, Mongo DB, ElasticSearch, Apache Solr, Redis

Relevant Courses

ML/AI Courses: Statistical Methods in AI, Computer Vision, Mobile Robotics, Topics in Optimization Methods, Topics in ML, Cognitive Science and AI

Core Science: Computer Programming, Operating Systems and Algorithms, Data Structures

Other Courses: Digital Image Processing, Digital Signal Processing, Linear Algebra, Probability and Random Processes, Discrete Mathematics

ACADEMIC SERVICE

Reviewer: ACL 2024, ECCV 2024, WACV 2024, ICRA 2024

ACHIEVEMENTS

Morocco Solidarity Hackathon: Member of the winning team; developed a solution to predict human trafficking behavior from social media posts.

Qualcomm Innovation Fellowship: Led the winning team of the Qualcomm Innovation Fellowship (QIF) 2020 in India.

JEE Mains: Ranked in the top 0.2% nationally among 1,200,000 candidates in JEE Mains.

JEE Advanced: Secured a rank of 4539 among 150,000 candidates in JEE Advanced.

R&D Showcase: Presented the Amblyopia Game at the college's annual R&D showcase.

References